

# 9-9.7-1.3

EE24BTECH11063 - Y. Harsha Vardhan Reddy

## Question:

Solve the differential equation:

$$\frac{d^4 y}{dx^4} - \sin\left(\frac{d^3 y}{dx^3}\right) = 0$$

## Solution:

### Theoretical solution:

The given differential equation is of degree 4 and cannot be solved using known methods. Let us compute the solution of the given differential equation computationally

### Computational Solution: Euler's method

By the first principle of derivative,

$$y'(x) = \lim_{h \rightarrow 0} \frac{y(x+h) - y(x)}{h} \quad (0.1)$$

$$y(x+h) = y(x) + h(y'(x)), h \rightarrow 0 \quad (0.2)$$

For a  $m^{\text{th}}$  order differential equation,

Let

$$y_1 = y, y_2 = y', y_3 = y'', \dots, y_m = y^{m-1} \quad (0.3)$$

then we obtain the system

$$\begin{pmatrix} y_1' \\ y_2' \\ \vdots \\ y_{m-1}' \\ y_m' \end{pmatrix} = \begin{pmatrix} y_2 \\ y_3 \\ \vdots \\ y_m \\ f(x, y_1, y_2, \dots, y_m) \end{pmatrix} \quad (0.4)$$

Here,  $f$  is described by the given differential equation. The initial conditions  $y_1(x_0) = K_1$ ,  $y_2(x_0) = K_2, \dots, y_m(x_0) = K_m$ .

Representing the system in Euler's form (using first principle of derivative),

$$\begin{pmatrix} y_1(x+h) \\ y_2(x+h) \\ \vdots \\ y_m(x+h) \end{pmatrix} = \begin{pmatrix} y_1(x) + hy_2(x) \\ y_2(x) + hy_3(x) \\ \vdots \\ y_m(x) + hf(x, y_1, y_2, \dots, y_m) \end{pmatrix} \quad (0.5)$$

$$\begin{pmatrix} y_1(x+h) \\ \vdots \\ y_{m-1}(x+h) \\ y_m(x+h) \end{pmatrix} = \begin{pmatrix} y_1(x) \\ \vdots \\ y_{m-1}(x) \\ y_m(x) \end{pmatrix} + h \begin{pmatrix} y_2(x) \\ \vdots \\ y_m(x) \\ f(x, y_1, y_2, \dots, y_m) \end{pmatrix} \quad (0.6)$$

$$\mathbf{y}(x+h) = \mathbf{y}(x) + h \begin{pmatrix} 0 & 1 & 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & 1 & 0 & \dots & 0 & 0 \\ 0 & 0 & 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 0 & 1 \\ 0 & 0 & 0 & 0 & \dots & 0 & \frac{f(x, y_1, y_2, \dots, y_m)}{y_m} \end{pmatrix} \mathbf{y}(x) \quad (0.7)$$

$$\mathbf{y}(x+h) = \begin{pmatrix} 1 & h & 0 & 0 & \dots & 0 & 0 \\ 0 & 1 & h & 0 & \dots & 0 & 0 \\ 0 & 0 & 1 & h & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1 & h \\ 0 & 0 & 0 & 0 & \dots & 0 & 1 + \frac{f(x, y_1, y_2, \dots, y_m)}{y_m} \end{pmatrix} \mathbf{y}(x) \quad (0.8)$$

Generalizing the system into an iterative format for plotting  $y(x)$ ,

$$\begin{pmatrix} y_{1,n+1} \\ y_{2,n+1} \\ \vdots \\ y_{m,n+1} \end{pmatrix} = \begin{pmatrix} y_{1,n} \\ y_{2,n} \\ \vdots \\ y_{m,n} \end{pmatrix} + h \begin{pmatrix} y_{2,n} \\ y_{3,n} \\ \vdots \\ f(x_n, y_{1,n}, y_{2,n}, \dots, y_{m,n}) \end{pmatrix} \quad (0.9)$$

$$\mathbf{y}_{n+1} = \mathbf{y}_n + h \begin{pmatrix} 0 & 1 & 0 & 0 & \dots & 0 & 0 \\ 0 & 0 & 1 & 0 & \dots & 0 & 0 \\ 0 & 0 & 0 & 1 & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 0 & 1 \\ 0 & 0 & 0 & 0 & \dots & 0 & \frac{f(x_n, y_{1,n}, y_{2,n}, \dots, y_{m,n})}{y_{m,n}} \end{pmatrix} \mathbf{y}_n, \text{ where } \mathbf{y}_n = \begin{pmatrix} y_{1,n}(x_n) \\ y_{2,n}(x_n) \\ \vdots \\ y_{m,n}(x_n) \end{pmatrix} \quad (0.10)$$

$$\mathbf{y}_{n+1} = \begin{pmatrix} 1 & h & 0 & 0 & \dots & 0 & 0 \\ 0 & 1 & h & 0 & \dots & 0 & 0 \\ 0 & 0 & 1 & h & \dots & 0 & 0 \\ \vdots & \vdots & \vdots & \vdots & \ddots & \vdots & \vdots \\ 0 & 0 & 0 & 0 & \dots & 1 & h \\ 0 & 0 & 0 & 0 & \dots & 0 & 1 + \frac{f(x_n, y_{1,n}, y_{2,n}, \dots, y_{m,n})}{y_{m,n}} \end{pmatrix} \mathbf{y}_n \quad (0.11)$$

$$x_{n+1} = x_n + h \quad (0.12)$$

Here, the vector  $\mathbf{y}_n$  is not to be confused with  $y_k$  which is the  $(k-1)^{\text{th}}$  derivative of  $y(x)$ . The given differential equation can be represented as,

$$y'''' - \sin(y''') = 0 \quad (0.13)$$

$$y'''' = \sin(y''') \quad (0.14)$$

We see that  $m = 4$ , thus,

$$y_5 = y'''' = \sin(y''') = \sin(y_4) \quad (0.15)$$

$$\begin{pmatrix} y_1' \\ y_2' \\ y_3' \\ y_4' \end{pmatrix} = \begin{pmatrix} y_2 \\ y_3 \\ y_4 \\ \sin(y_4) \end{pmatrix} \quad (0.16)$$

$$\begin{pmatrix} y_{1,n+1} \\ y_{2,n+1} \\ y_{4,n+1} \\ y_{4,n+1} \end{pmatrix} = \begin{pmatrix} y_{1,n} \\ y_{2,n} \\ y_{3,n} \\ y_{4,n} \end{pmatrix} + h \begin{pmatrix} y_{2,n} \\ y_{3,n} \\ y_{4,n} \\ \sin(y_{4,n}) \end{pmatrix} \quad (0.17)$$

$$\mathbf{y}_{n+1} = \begin{pmatrix} 1 & h & 0 & 0 \\ 0 & 1 & h & 0 \\ 0 & 0 & 1 & h \\ 0 & 0 & 0 & 1 + \sin y_{3,n} \end{pmatrix} \mathbf{y}_n \quad (0.18)$$

Iteratively plotting the above system taking initial conditions as

$$x_0 = 0, y_{1,0} = 0, y_{2,0} = 0, y_{3,0} = 0, y_{4,0} = 1 \quad (0.19)$$

we get the following plot 0.1.

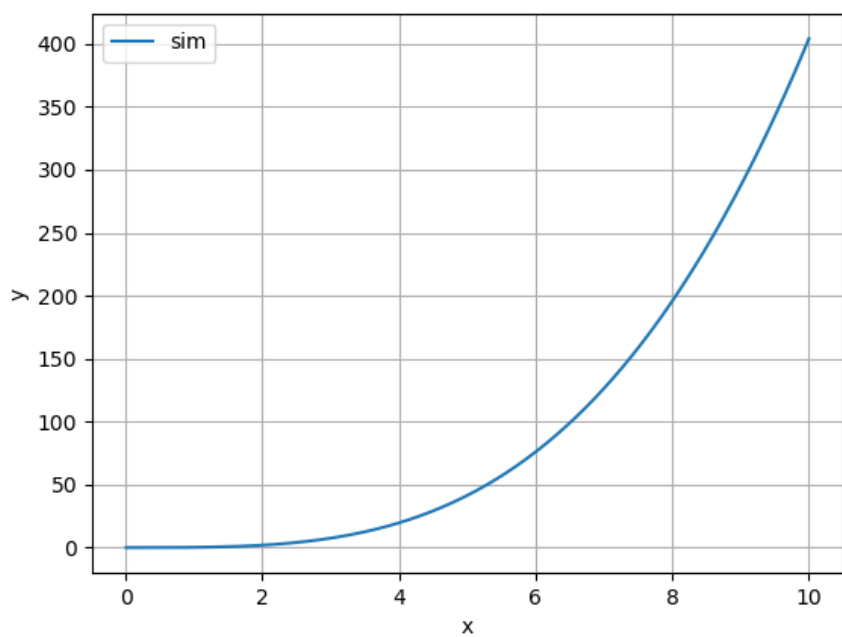


Fig. 0.1