Problem 12.141

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Problem

Let **A** be a 3×3 matrix. Suppose that the eigenvalues of **A** are -1, 0, 1 with respective eigenvectors $(1,-1,0)^{\top},(1,1,-2)^{\top}$ and $(1,1,1)^{\top}$. Then 6**A** equals

Equation

For an invertible matrix **P**

$$\mathbf{A} = \mathbf{P}\mathbf{D}\mathbf{P}^{-1} \tag{3.1}$$

Given eigen values are

$$\lambda_1 = -1, \lambda_2 = 0, \lambda_3 = 1$$
 (3.2)

Given eigen vectors are

$$\mathbf{x_1} = \begin{pmatrix} 1 \\ -1 \\ 0 \end{pmatrix}, \mathbf{x_2} = \begin{pmatrix} 1 \\ 1 \\ -2 \end{pmatrix}, \mathbf{x_3} = \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$
 (3.3)

where

$$\mathbf{D} = \begin{pmatrix} \lambda_1 & 0 & 0 \\ 0 & \lambda_2 & 0 \\ 0 & 0 & \lambda_3 \end{pmatrix} = \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$
(3.4)

(3.5)

Augmented matrix

$$\mathbf{P} = \begin{pmatrix} \mathbf{x_1} & \mathbf{x_2} & \mathbf{x_3} \end{pmatrix} = \begin{pmatrix} 1 & 1 & 1 \\ -1 & 1 & 1 \\ 0 & -2 & 1 \end{pmatrix}$$
 (3.6)

$$|\mathbf{P}| = 1(1+2) - 1(-1+0) + 1(2+0) = 3+1+2 = 6 \neq 0$$
 (3.7)

$$\mathbf{PP}^{-1} = \mathbf{I} \tag{3.8}$$

Augmented matrix of $\left(\mathbf{P}\mid\mathbf{I}\right)$ is given by

$$\begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ -1 & 1 & 1 & 0 & 1 & 0 \\ 0 & -2 & 1 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_2 \to \frac{1}{2}(R_1 + R_2)} \begin{pmatrix} 1 & 1 & 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & \frac{1}{2} & \frac{1}{2} & 0 \\ 0 & -2 & 1 & 0 & 0 & 1 \end{pmatrix}$$
(3.9)

(3.10)

Operations

$$\begin{pmatrix}
1 & 1 & 1 & 1 & 0 & 0 \\
0 & 1 & 1 & \frac{1}{2} & \frac{1}{2} & 0 \\
0 & -2 & 1 & 0 & 0 & 1
\end{pmatrix}
\xrightarrow{R_3 \to R_3 + 2R_2}
\begin{pmatrix}
1 & 0 & 0 & \frac{1}{2} & -\frac{1}{2} & 0 \\
0 & 1 & 1 & \frac{1}{2} & \frac{1}{2} & 0 \\
0 & 0 & 3 & 1 & 1 & 1
\end{pmatrix}$$

$$\begin{pmatrix}
1 & 0 & 0 & \frac{1}{2} & -\frac{1}{2} & 0 \\
0 & 1 & 1 & \frac{1}{2} & \frac{1}{2} & 0 \\
0 & 1 & 1 & \frac{1}{2} & \frac{1}{2} & 0 \\
0 & 0 & 3 & 1 & 1 & 1
\end{pmatrix}
\xrightarrow{R_2 \to R_2 - \frac{1}{3}R_3}
\begin{pmatrix}
1 & 0 & 0 & \frac{1}{2} & -\frac{1}{2} & 0 \\
0 & 1 & 0 & \frac{1}{6} & \frac{1}{6} & -\frac{1}{3} \\
0 & 0 & 1 & \frac{1}{3} & \frac{1}{3} & \frac{1}{3}
\end{pmatrix}$$
(3.11)

$$\mathbf{P}^{-1} = \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} & 0\\ \frac{1}{6} & \frac{1}{6} & -\frac{1}{3}\\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{pmatrix}$$
(3.13)

$$6A = 6PDP^{-1} = (PD)(6P^{-1})$$
(3.14)



Conclusion

$$6\mathbf{A} = \begin{pmatrix} 1 & 1 & 1 \\ -1 & 1 & 1 \\ 0 & -2 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \end{pmatrix} \begin{pmatrix} 6 \begin{pmatrix} \frac{1}{2} & -\frac{1}{2} & 0 \\ \frac{1}{6} & \frac{1}{6} & -\frac{1}{3} \\ \frac{1}{3} & \frac{1}{3} & \frac{1}{3} \end{pmatrix} \end{pmatrix}$$
(3.15)

$$= \begin{pmatrix} 1 & 1 & 1 \\ -1 & 1 & 1 \\ 0 & -2 & 1 \end{pmatrix} \begin{pmatrix} -1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{pmatrix} \end{pmatrix} \begin{pmatrix} 3 & -3 & 0 \\ 1 & 1 & -2 \\ 2 & 2 & 2 \end{pmatrix}$$
(3.16)

$$= \begin{pmatrix} -1 & 0 & 1 \\ 1 & 0 & 1 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 3 & -3 & 0 \\ 1 & 1 & -2 \\ 2 & 2 & 2 \end{pmatrix} = \begin{pmatrix} -3+2 & 3+2 & 0+2 \\ 3+2 & -3+2 & 0+2 \\ 0+2 & 0+2 & 0+2 \end{pmatrix}$$
(3.17)

$$= \begin{pmatrix} -1 & 5 & 2 \\ 5 & -1 & 2 \\ 2 & 2 & 2 \end{pmatrix}$$

C Code

```
void get_eigen_data(double* out_data) {
   // Eigenvalues
   out data[0] = -1.0;
   out data[1] = 0.0;
   out data[2] = 1.0;
   // Eigenvector 1,
   out data[3] = 1.0;
   out data[4] = -1.0;
   out data[5] = 0.0;
   // Eigenvector 2
   out data[6] = 1.0;
   out data[7] = 1.0;
   out data[8] = -2.0;
   // Eigenvector 3
   out_data[9] = 1.0;
   out_data[10] = 1.0;
   out_data[11] = 1.0;
```

Python Code for Solving

```
import ctypes
import numpy as np
def calculate():
   lib = ctypes.CDLL('./code.so')
   double_array_12 = ctypes.c_double * 12
   lib.get_eigen_data.argtypes = [ctypes.POINTER(ctypes.c_double
   out data c = double array 12()
   lib.get eigen data(out data c)
   raw data = np.array(list(out data c))
   eigenvalues = raw data[0:3]
   v1 = raw_data[3:6]
   v2 = raw data[6:9]
   v3 = raw_data[9:12]
```

Python Code for Solving

```
D = np.diag(eigenvalues)
   P = np.vstack([v1, v2, v3]).T
   P_inv = np.linalg.inv(P)
   A = P @ D @ P inv
   result 6A = 6 * A
   return result_6A
if __name__ == '__main__':
   final_result = calculate()
   print(\n 6A =\n, final_result)
```