5.4.26

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Question

Using elementary transformations find the inverse of the given matrix

$$\begin{pmatrix}
1 & -3 & 2 \\
-3 & 0 & -5 \\
2 & 5 & 0
\end{pmatrix}$$

Given

$$\mathbf{A} = \begin{pmatrix} 1 & -3 & 2 \\ -3 & 0 & -5 \\ 2 & 5 & 0 \end{pmatrix} \tag{1}$$

To find the inverse, \mathbf{A}^{-1} , we augment the identity matrix \mathbf{I} to \mathbf{A} and apply row operations to this augmented matrix.

$$\begin{pmatrix} 1 & -3 & 2 & 1 & 0 & 0 \\ -3 & 0 & -5 & 0 & 1 & 0 \\ 2 & 5 & 0 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_2 \to R_2 + 3R_1} \begin{pmatrix} 1 & -3 & 2 & 1 & 0 & 0 \\ 0 & 9 & -11 & 3 & 1 & 0 \\ 2 & 5 & 0 & 0 & 0 & 1 \end{pmatrix}$$
(2)

$$\begin{pmatrix} 1 & -3 & 2 & 1 & 0 & 0 \\ 0 & 9 & -11 & 3 & 1 & 0 \\ 2 & 5 & 0 & 0 & 0 & 1 \end{pmatrix} \xrightarrow{R_3 \to R_3 - 2R_1} \begin{pmatrix} 1 & -3 & 2 & 1 & 0 & 0 \\ 0 & 9 & -11 & 3 & 1 & 0 \\ 0 & -1 & 4 & -2 & 0 & 1 \end{pmatrix} (3)$$

$$\begin{pmatrix} 1 & -3 & 2 & 1 & 0 & 0 \\ 0 & 9 & -11 & 3 & 1 & 0 \\ 0 & -1 & 4 & -2 & 0 & 1 \end{pmatrix} \xrightarrow{R_2 \to \frac{1}{9}R_2} \begin{pmatrix} 1 & -3 & 2 & 1 & 0 & 0 \\ 0 & 1 & \frac{-11}{9} & \frac{1}{3} & \frac{1}{9} & 0 \\ 0 & -1 & 4 & -2 & 0 & 1 \end{pmatrix}$$
(4)

$$\begin{pmatrix} 1 & -3 & 2 & 1 & 0 & 0 \\ 0 & 1 & \frac{-11}{9} & \frac{1}{3} & \frac{1}{9} & 0 \\ 0 & -1 & 4 & -2 & 0 & 1 \end{pmatrix} \xleftarrow{R_1 \to R_1 - 3R_2} \begin{pmatrix} 1 & 0 & \frac{5}{3} & 0 & \frac{-1}{3} & 0 \\ 0 & 1 & \frac{-11}{9} & \frac{1}{3} & \frac{1}{9} & 0 \\ 0 & -1 & 4 & -2 & 0 & 1 \end{pmatrix}$$

$$(5)$$

$$\begin{pmatrix}
1 & 0 & \frac{5}{3} & 0 & \frac{-1}{3} & 0 \\
0 & 1 & \frac{-11}{9} & \frac{1}{3} & \frac{1}{9} & 0 \\
0 & -1 & 4 & -2 & 0 & 1
\end{pmatrix}
\xrightarrow{R_3 \to R_3 + R_2}
\begin{pmatrix}
1 & 0 & \frac{5}{3} & 0 & \frac{-1}{3} & 0 \\
0 & 1 & \frac{-11}{9} & \frac{1}{3} & \frac{1}{9} & 0 \\
0 & 0 & \frac{25}{9} & \frac{-5}{3} & \frac{1}{9} & 1
\end{pmatrix}$$
(6)

$$\begin{pmatrix}
1 & 0 & \frac{5}{3} & 0 & \frac{-1}{3} & 0 \\
0 & 1 & \frac{-11}{9} & \frac{1}{3} & \frac{1}{9} & 0 \\
0 & 0 & \frac{25}{9} & \frac{-5}{3} & \frac{1}{9} & 1
\end{pmatrix}
\xrightarrow{R_3 \to \frac{9}{25}R_3}
\begin{pmatrix}
1 & 0 & \frac{5}{3} & 0 & \frac{-1}{3} & 0 \\
0 & 1 & \frac{-11}{9} & \frac{1}{3} & \frac{1}{9} & 0 \\
0 & 0 & 1 & \frac{-3}{5} & \frac{1}{25} & \frac{9}{25}
\end{pmatrix} (7)$$

$$\begin{pmatrix} 1 & 0 & \frac{5}{3} & 0 & \frac{-1}{3} & 0 \\ 0 & 1 & \frac{-11}{9} & \frac{1}{3} & \frac{1}{9} & 0 \\ 0 & 0 & 1 & \frac{-3}{5} & \frac{1}{25} & \frac{9}{25} \end{pmatrix} \stackrel{R_2 \to R_2 + \frac{11}{9}R_3}{\longleftarrow} \begin{pmatrix} 1 & 0 & \frac{5}{3} & 0 & \frac{-1}{3} & 0 \\ 0 & 1 & 0 & \frac{-2}{5} & \frac{4}{25} & \frac{11}{25} \\ 0 & 0 & 1 & \frac{-3}{5} & \frac{1}{25} & \frac{9}{25} \end{pmatrix}$$

$$(8)$$

$$\begin{pmatrix}
1 & 0 & \frac{5}{3} & 0 & \frac{-1}{3} & 0 \\
0 & 1 & 0 & \frac{-2}{5} & \frac{4}{25} & \frac{11}{25} \\
0 & 0 & 1 & \frac{-3}{5} & \frac{1}{25} & \frac{9}{25}
\end{pmatrix}
\xrightarrow{R_1 \to R_1 + \frac{5}{3}R_3}
\begin{pmatrix}
1 & 0 & 0 & 1 & \frac{-2}{5} & \frac{-3}{5} \\
0 & 1 & 0 & \frac{-2}{5} & \frac{4}{25} & \frac{11}{25} \\
0 & 0 & 1 & \frac{-3}{5} & \frac{1}{25} & \frac{9}{25}
\end{pmatrix} (9)$$

Therefore,

$$\mathbf{A}^{-1} = \begin{pmatrix} 1 & \frac{-2}{5} & \frac{-3}{5} \\ \frac{-2}{5} & \frac{4}{25} & \frac{11}{25} \\ \frac{-3}{5} & \frac{1}{25} & \frac{9}{25} \end{pmatrix}$$

```
#include <stdio.h>
void inverse(double (*matrix)[3]) {
   double I[3][3] = {
       \{1,0,0\},\
       \{0,1,0\},\
       \{0,0,1\}
   };
   double pivot = matrix[0][0];
    for(int i = 0; i < 3; i++) {
       matrix[0][i] /= pivot;
       I[0][i] /= pivot;
    }
```

```
double factor = matrix[1][0];
for(int i = 0; i < 3; i++) {
   matrix[1][i] -= factor * matrix[0][i];
   I[1][i] -= factor * I[0][i];
}
factor = matrix[2][0];
for(int i = 0; i < 3; i++) {</pre>
   matrix[2][i] -= factor * matrix[0][i];
   I[2][i] -= factor * I[0][i]:
}
pivot = matrix[1][1];
for(int i = 0; i < 3; i++) {
   matrix[1][i] /= pivot;
   I[1][i] /= pivot;
}
```

```
factor = matrix[0][1];
for(int i = 0; i < 3; i++) {
   matrix[0][i] -= factor * matrix[1][i]:
   I[0][i] -= factor * I[1][i];
factor = matrix[2][1];
for(int i = 0; i < 3; i++) {
   matrix[2][i] -= factor * matrix[1][i];
   I[2][i] -= factor * I[1][i];
pivot = matrix[2][2];
for(int i = 0; i < 3; i++) {
   matrix[2][i] /= pivot;
   I[2][i] /= pivot;
}
```

```
factor = matrix[0][2];
for(int i = 0; i < 3; i++) {
   matrix[0][i] -= factor * matrix[2][i]:
   I[0][i] -= factor * I[2][i];
factor = matrix[1][2];
for(int i = 0; i < 3; i++) {
   matrix[1][i] -= factor * matrix[2][i];
   I[1][i] -= factor * I[2][i]:
for (int i = 0; i < 3; i++) {
for (int j = 0; j < 3; j++) {
   matrix[i][j] = I[i][j];
```

Python Code - Using Shared Object

```
import numpy as np
import ctypes
c_lib = ctypes.CDLL("./code.so")
c_lib.inverse.argtypes = [ctypes.POINTER((ctypes.c_double * 3))]
A = np.array([
    [1.0, -3.0, 2.0],
   [-3.0, 0.0, -5.0],
    [2.0, 5.0, 0.0]
], dtype=np.float64)
```

Python Code - Using Shared Object

```
B = A.ctypes.data_as(ctypes.POINTER((ctypes.c_double * 3)))
c_lib.inverse(B)
np.set_printoptions(precision=2)
print(A)
```

Python Code

```
import numpy as np
import numpy.linalg as LA
A = np.array([
  [1.0, -3.0, 2.0],
   [-3.0, 0.0, -5.0],
   [2.0, 5.0, 0.0]
])
A_{inv} = LA.inv(A)
print(A inv)
```