8.4.23

EE25BTECH11020 - Darsh Pankaj Gajare

Question:

The curve described parametrically by $x = t^2 + t + 1$ and $y = t^2 - t + 1$ represents:

- 1) a pair of straight lines
- 2) an ellipse3) a parabola
- 4) a hyperbola

Solution:

TABLE I

X	$\begin{pmatrix} x \\ y \end{pmatrix}$
a	$\begin{pmatrix} 1 \\ 1 \end{pmatrix}$
b	$\begin{pmatrix} 1 \\ -1 \end{pmatrix}$
с	$\begin{pmatrix} 1 \\ 1 \end{pmatrix}$

The parametric form can be written as

$$\mathbf{x} = \mathbf{a}t^2 + \mathbf{b}t + \mathbf{c}.\tag{1}$$

$$\mathbf{x} = \begin{pmatrix} \mathbf{a} \\ \mathbf{b} \end{pmatrix}^{\mathsf{T}} \begin{pmatrix} t^2 \\ t \end{pmatrix} + \mathbf{c} \tag{2}$$

$$\mathbf{x} = \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} t^2 \\ t \end{pmatrix} + \mathbf{c} \tag{3}$$

Let
$$\mathbf{e}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \ \mathbf{e}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix},$$
 (5)

$$\mathbf{M} = \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}, \ \mathbf{z} = \mathbf{x} - \mathbf{c}. \tag{6}$$

Then
$$\begin{pmatrix} t^2 \\ t \end{pmatrix} = \mathbf{M}\mathbf{z}, \quad t^2 = \mathbf{e}_1^{\mathsf{T}}\mathbf{M}\mathbf{z}, \quad t = \mathbf{e}_2^{\mathsf{T}}\mathbf{M}\mathbf{z}.$$
 (7)

Eliminate
$$t: \mathbf{e}_1^{\mathsf{T}} \mathbf{M} \mathbf{z} = (\mathbf{e}_2^{\mathsf{T}} \mathbf{M} \mathbf{z})^2$$
. (8)

Define
$$\mathbf{w} = \mathbf{M}\mathbf{z} \implies \mathbf{e}_1^{\mathsf{T}}\mathbf{w} = (\mathbf{e}_2^{\mathsf{T}}\mathbf{w})^2$$
. (9)

In matrix form:
$$\mathbf{z}^{\mathsf{T}} \mathbf{M}^{\mathsf{T}} \mathbf{e}_{1} \mathbf{e}_{1}^{\mathsf{T}} \mathbf{M} \mathbf{z} - \mathbf{z}^{\mathsf{T}} \mathbf{M}^{\mathsf{T}} \mathbf{e}_{2} \mathbf{e}_{2}^{\mathsf{T}} \mathbf{M} \mathbf{z} = 0.$$
 (10)

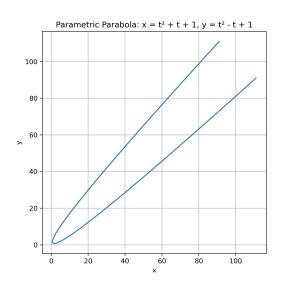
Let
$$\mathbf{E} = \mathbf{e}_1 \mathbf{e}_1^{\mathsf{T}} - \mathbf{e}_2 \mathbf{e}_2^{\mathsf{T}} = \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix}, \ \mathbf{Q} = \mathbf{M}^{\mathsf{T}} \mathbf{E} \mathbf{M}.$$
 (11)

$$\mathbf{Q} = \begin{pmatrix} \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \end{pmatrix}^{\mathsf{T}} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \frac{1}{2} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}. \tag{12}$$

$$\mathbf{z}^{\mathsf{T}}\mathbf{Q}\mathbf{z} = 0, \quad \mathbf{z} = \begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} 1 \\ 1 \end{pmatrix}.$$
 (13)

$$(x-1)(y-1) = \frac{1}{2}(y-x)^2 \iff (x-y)^2 = 2(x+y-2).$$
 (14)

Plot using C libraries:



Plot using Python:

