### 2.5.25

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## Question

If  $\mathbf{a} = 2\hat{i} - \hat{j} - 2\hat{k}$  and  $\mathbf{b} = 7\hat{i} + 2\hat{j} - 3\hat{k}$ , then express  $\mathbf{b}$  in the form  $\mathbf{b} = \mathbf{b}_1 + \mathbf{b}_2$ , where  $\mathbf{b}_1$  is parallel to  $\mathbf{a}$  and  $\mathbf{b}_2$  is perpendicular to  $\mathbf{a}$ .

# Solution

Variable	Value
a	$2\hat{i} - \hat{j} - 2\hat{k}$
b	$7\hat{i} + 2\hat{j} - 3\hat{k}$

Table: Variables Used

### Solution

$$\mathbf{a} = \begin{pmatrix} 2 \\ -1 \\ -2 \end{pmatrix} \tag{1}$$

$$\mathbf{b} = \begin{pmatrix} 7\\2\\-3 \end{pmatrix} \tag{2}$$

### solution

Using the Gram-Schmidt approach  $\mathbf{b_1}$  is the projection of  $\mathbf{b}$  on  $\mathbf{a}$ 

$$\mathbf{b_1} = \frac{\mathbf{a^T b}}{\mathbf{a^T a}} \mathbf{a} \tag{3}$$

$$\mathbf{b_1} = \frac{18}{9} \mathbf{a} \tag{4}$$

$$\mathbf{b_1} = 2\mathbf{a} \tag{5}$$

$$\mathbf{p_1} = \frac{18}{9}\mathbf{a} \tag{4}$$

$$\mathbf{p_1} = 2\mathbf{a} \tag{5}$$

### Solution

$$\mathbf{b}_2 = \mathbf{b} - \mathbf{b}_1 = \begin{pmatrix} 7 \\ 2 \\ -3 \end{pmatrix} - \begin{pmatrix} 4 \\ -2 \\ -4 \end{pmatrix} = \begin{pmatrix} 3 \\ 4 \\ 1 \end{pmatrix} \tag{6}$$

$$\begin{pmatrix} 7\\2\\-3 \end{pmatrix} = \begin{pmatrix} 4\\-2\\-4 \end{pmatrix} + \begin{pmatrix} 3\\4\\1 \end{pmatrix} \tag{7}$$

Therefore,

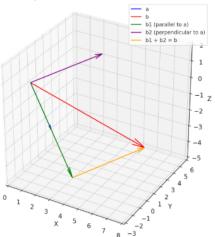
$$\mathbf{b_1} = \begin{pmatrix} 4 \\ -2 \\ -4 \end{pmatrix} \tag{8}$$

$$\mathbf{b_2} = \begin{pmatrix} 3 \\ 4 \\ 1 \end{pmatrix} \tag{9}$$

# Graph

### Refer to Figure





## Python Code

```
import matplotlib.pyplot as plt
 import numpy as np
# Define vectors
a = np.array([2, -1, -2])
b = np.array([7, 2, -3])
b1 = np.array([4, -2, -4])
b2 = np.array([3, 4, 1])
# Function to draw vectors
def draw_vector(ax, start, vec, color, label):
     ax.quiver(*start, *vec, color=color, label=label,
        arrow_length_ratio=0.1)
# Create 3D plot
fig = plt.figure(figsize=(10,8))
ax = fig.add_subplot(111, projection='3d')
```

# Python Code

# Python Code

```
# Labels and title
ax.set_xlabel('X', fontsize=12)
ax.set_ylabel('Y', fontsize=12)
ax.set_zlabel('Z', fontsize=12)
ax.set_title( 3D Representation of Vectors a, b, b1,
    and b2, fontsize=14)
ax.legend()
# Grid and aspect ratio
ax.grid(True)
ax.set box aspect([1,1,1])
# Axis limits
ax.set xlim(0,8)
ax.set ylim(-3,6)
ax.set zlim(-5,2)
 # Save figure
plt.savefig( <mark>Graph3.png</mark> , dpi=300, bbox_inches=<mark>!tight</mark>/<
```

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#### C Code

```
#include <stdio.h>
 int dotProduct(int a[], int b[], int size) {
     int dot = 0;
     for (int i = 0; i < size; i++) {</pre>
          dot += a[i] * b[i]:
     }
     return dot;
void scalarMultiply(int vector[], int scalar, int
     result[], int size) {
     for (int i = 0; i < size; i++) {</pre>
          result[i] = scalar * vector[i];
```

#### C Code

```
void vectorSubtract(int a[], int b[], int result[],
     int size) {
    for (int i = 0; i < size; i++) {</pre>
        result[i] = a[i] - b[i];
void solve_vectors() {
    int a[3] = \{2, -1, -2\};
    int b[3] = \{7, 2, -3\};
    int a_dot_b = dotProduct(a, b, 3);
    int a dot a = dotProduct(a, a, 3);
    int k = a dot b / a dot a;
```

#### C Code

```
int b1[3];
 scalarMultiply(a, k, b1, 3);
 int b2[3]:
 vectorSubtract(b, b1, b2, 3);
 printf( Vector a: [%d, %d, %d]\n , a[0], a[1], a
    [2]):
 printf( Vector b: [%d, %d, %d]\n , b[0], b[1], b
    [2]):
 printf( Scalar k: %d\n , k);
 printf( Vector b1 (parallel to a): [%d, %d, %d]\n
    , b1[0], b1[1], b1[2]);
 printf( Vector b2 (perpendicular to a): [%d, %d, %
    d] \setminus n, b2[0], b2[1], b2[2]);
```

## Python and C Code

```
import ctypes

# Load the shared object file
lib = ctypes.CDLL('./code.so')

# Call the solve_vectors function (no args, no return)
lib.solve_vectors()
```