### 4.2.16

### EE25BTECH11018 - Darisy Sreetej

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### Question

Let a, b, c, d be non-zero numbers. If the point of intersection of the lines  $4a\mathbf{x} + 2a\mathbf{y} + c = 0$  and  $5b\mathbf{x} + 2b\mathbf{y} + d = 0$  lies in the fourth quadrant and is equidistant from the two axes then

- 3bc 2ad = 0
- 2 bc 3ad = 0
- 3 bc + 2ad = 0
- 9 2bc + 3ad = 0

The two lines are

$$4a\mathbf{x} + 2a\mathbf{y} + c = 0, (1)$$

$$5b\mathbf{x} + 2b\mathbf{y} + d = 0 \tag{2}$$

According to the condition, the intersection point is equidistant from the axes and lies in the fourth quadrant, so its coordinates satisfy y = -x

$$\mathbf{x} + \mathbf{y} = 0 \tag{3}$$

This equation can be expressed in terms of matrices

$$\begin{pmatrix} 4a \\ 2a \end{pmatrix}^{\top} \begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} = -c \tag{4}$$

$$\begin{pmatrix} 1 \\ 1 \end{pmatrix}^{\top} \begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} = 0 \tag{6}$$

They can be represented as,

$$\begin{pmatrix} 4a & 5b \\ 2a & 2b \\ 1 & 1 \end{pmatrix}^{\top} \begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} = \begin{pmatrix} -c \\ -d \\ 0 \end{pmatrix} \tag{7}$$

Using augmented matrix,

$$\begin{pmatrix}
4a & 2a & -c \\
5b & 2b & -d \\
1 & 1 & 0
\end{pmatrix}$$
(8)

$$R_3 = R_3 - 4aR_1$$
$$R_2 = R_2 - 5bR_1$$



$$\begin{pmatrix}
1 & 1 & 0 \\
0 & -3b & -d \\
0 & -2a & -c
\end{pmatrix}$$
(9)

$$R_3 = R_3 - \frac{2a}{3b}R_2$$

$$\begin{pmatrix}
1 & 1 & 0 \\
0 & -3b & -d \\
0 & 0 & -c + \frac{2ad}{3b}
\end{pmatrix}$$
(10)

$$\begin{pmatrix}
1 & 1 & 0 \\
0 & -3b & -d \\
0 & 0 & \frac{2ad-3bc}{3b}
\end{pmatrix}$$
(11)

The last row of the matrix represents the equation

$$\mathbf{y}0 + \mathbf{x}0 = \frac{2ad - 3bc}{3b} \tag{12}$$

For the system to be consistent(i.e., to have a solution), the right-hand side must be zero.

$$\frac{2ad - 3bc}{3b} = 0 \tag{13}$$

$$2ad - 3bc = 0 (14)$$

Therefore,

$$3bc = 2ad \tag{15}$$

Therefore, option(a) is correct

For the point of intersection, solve the equations from (11),

The point of intersection is

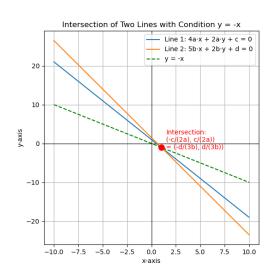
$$\begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} = \begin{pmatrix} \frac{-d}{3b} \\ \frac{d}{3b} \end{pmatrix} \tag{16}$$

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Also,

$$\begin{pmatrix} \mathbf{x} \\ \mathbf{y} \end{pmatrix} = \begin{pmatrix} \frac{-c}{2a} \\ \frac{c}{2a} \end{pmatrix} \quad (from(15)) \tag{17}$$

It can be clearly verified by the plot



#### C code

```
#include <stdio.h>
// Function to compute x from first line
double computeX1(double a, double c) {
   return -c / (2.0 * a);
// Function to compute x from second line
double computeX2(double b, double d) {
   return -d / (3.0 * b);
```

### C Code

```
// Function to compute y (since y = -x for equidistant from axes
    in 4th quadrant)
double computeY(double x) {
   return -x;
// Function to check relation 3bc - 2ad = 0
int checkRelation(double a, double b, double c, double d) {
   double relation = 3*b*c - 2*a*d;
   return (relation == 0) ? 1 : 0;
```

# Python + C Code

```
import ctypes
import matplotlib.pyplot as plt
import numpy as np
# Load the compiled C shared library
lib = ctypes.CDLL("./point.so")
# Set argument and return types
lib.computeX1.argtypes = [ctypes.c_double, ctypes.c_double]
lib.computeX1.restype = ctypes.c_double
lib.computeX2.argtypes = [ctypes.c_double, ctypes.c_double]
lib.computeX2.restype = ctypes.c_double
lib.computeY.argtypes = [ctypes.c double]
lib.computeY.restype = ctypes.c_double
lib.checkRelation.argtypes = [ctypes.c double, ctypes.c double,
    ctypes.c double, ctypes.c double]
```

## Python + C code

```
lib.checkRelation.restype = ctypes.c_int
# Example values (you can change these)
a, b, c, d = 1.0, 1.0, -2.0, -3.0
# Call C functions
x1 = lib.computeX1(a, c)
x2 = lib.computeX2(b, d)
if abs(x1 - x2) > 1e-6:
    print("Inconsistent intersection: x1 != x2")
    exit()
x = x1
y = lib.computeY(x)
print(f"Intersection Point: ({x:.3f}, {y:.3f})")
```

## Python + C code

```
# Check relation
 if lib.checkRelation(a, b, c, d):
     print("Relation satisfied: 3bc - 2ad = 0 ")
     else:
     print("Relation NOT satisfied ")
 |# ------ Plotting -----
 X = np.linspace(-10, 10, 400)
 \# Line1: 4ax + 2ay + c = 0 -> y = -(4aX + c)/(2a)
 Y1 = -(4*a*X + c) / (2*a)
 \# \text{ Line 2: } 5bx + 2by + d = 0 \rightarrow y = -(5*bX + d)/(2*b)
 Y2 = -(5*b*X + d) / (2*b)
plt.figure(figsize=(6,6))
 plt.axhline(0, color="black", linewidth=0.8)
 plt.axvline(0, color="black", linewidth=0.8)
```

# Python + C code

```
plt.plot(X, Y1, label="Line 1")
plt.plot(X, Y2, label="Line 2")
plt.scatter([x], [y], color="red", s=80, label="Intersection
    Point")
plt.title("Intersection of Two Lines")
plt.xlabel("x-axis")
plt.ylabel("y-axis")
plt.legend()
plt.grid(True)
plt.show()
```

# Python code

```
import matplotlib.pyplot as plt
 import numpy as np
 # Example coefficients (you can change these)
 a, b, c, d = 1.0, 1.0, -2.0, -3.0
 |# Intersection point (from condition y = -x)
 x = -c / (2 * a)
 v = -x
# Create range of x values for plotting
X = np.linspace(-10, 10, 400)
 \# Line1: 4ax + 2ay + c = 0 -> y = -(4aX + c)/(2a)
 Y1 = -(4 * a * X + c) / (2 * a)
s |# Line2: 5bx + 2by + d = 0 -> y = -(5 * b * X + d) / (2 * b)
|Y2 = -(5 * b * X + d) / (2 * b)
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```

### Python code

```
\# v = -x line
 Y_{diag} = -X
 |# ----- Plot -----
plt.figure(figsize=(6, 6))
plt.axhline(0, color="black", linewidth=0.8) # x-axis
plt.axvline(0, color="black", linewidth=0.8) # y-axis
 |plt.plot(X, Y1, label="Line 1: 4ax + 2ay + c = 0")
 |plt.plot(X, Y2, label="Line 2: 5bx + 2by + d = 0")
 plt.plot(X, Y diag, "g--", label="y = -x")
 # Mark intersection point with symbolic label
 plt.scatter([x], [y], color="red", s=80, zorder=5)
 plt.text(x + 0.5, y - 0.5,
          "Intersection: \ln(-c/(2a), c/(2a)) \ln (-d/(3b), d/(3b))",
         fontsize=10, color="red")
```

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# Python code

```
plt.title("Intersection of Two Lines with Condition y = -x")
plt.xlabel("x-axis")
plt.ylabel("y-axis")
plt.legend(loc="best")
plt.grid(True)
plt.show()
```