

Fitting Data To models

EE16B014

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Abstract

In this report we are going to discuss about fitting of data by taking example of Bessel function and approximate it to two function:1) $A\cos(x_i)+B\sin(x_i)$ and 2) $A\frac{\cos(x_i)}{\sqrt{x_i}}+B\frac{\sin(x_i)}{\sqrt{x_i}}$ which are near functions to Bessel function, and we will evaluate their coefficients by best fitting method and we will see the effect of noise in the fitting.

1 Bessel Function:

Bessel function is generally the a solution to the differential equation:

$$x^2 \frac{d^2 y}{dx^2} + x \frac{dy}{dx} + (x^2 - \alpha^2)y = 0$$

- The function is in such away that the output is same for both $+\alpha$ and $-\alpha$ and its a smooth function with α .
- The most important cases are when α is an integer or half-integer. Bessel functions for integer α are also known as cylinder functions or the cylindrical harmonics because they appear in the solution to Laplace's equation in cylindrical coordinates. Spherical Bessel functions with half-integer α are obtained when the Helmholtz equation is solved in spherical coordinates.

Lets take α as v and proceed. Now we have approximate form for the Bessel function as given below:

$$J_v(x) \approx \sqrt{\frac{2}{\pi x}} \cos\left(x - \frac{v\pi}{2} - \frac{\pi}{4}\right)$$

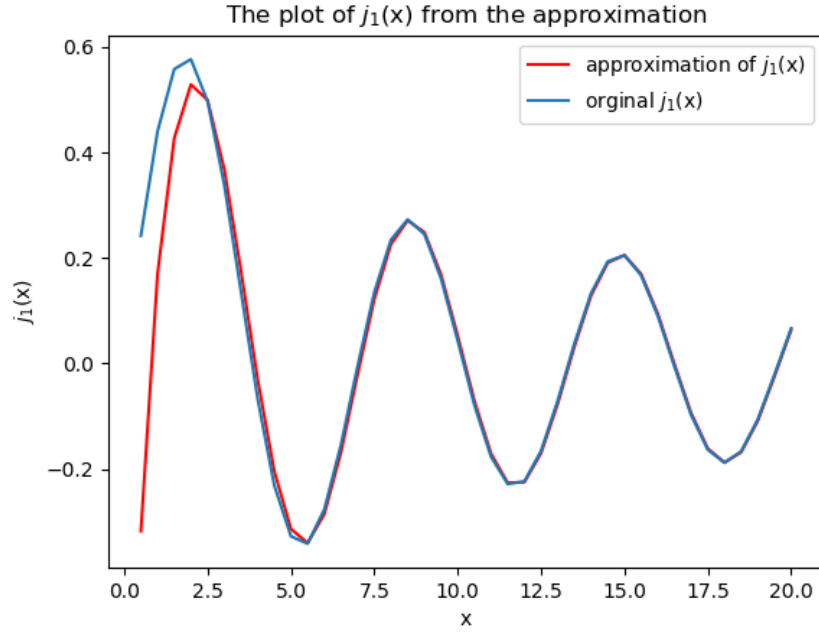
Now we first plot the approximation of Bessel function along with the original one.

```
from numpy import *
from pylab import *
from math import *
from scipy import *
from scipy.special import j1
x=linspace(0,20,41)
x=x[1:]

jk=((2/pi)**(1/2))*cos(x-(3*pi/4))/(x**(1/2.0))

plot(x,jk,"r",label="approximation of $j_1(x)$")
plot(x,j1(x),label="original $j_1(x)$")
legend(loc="upper right")
xlabel('x')
ylabel('$j_1(x)$')
title('The plot of $j_1(x)$ from the approximation')
show()
```

Plot:



As we can see the approximation graph is slightly distorted from the original one which means our approximate function is not that accurate for less values of x .

Now let's define a function called *calcnu* Which can calculate the coefficients of A,B for our required functions when approximated as shown below:

$$A \cos(x_i) + B \sin(x_i) \approx J_1(x_i)$$

$$A \frac{\cos(x_i)}{\sqrt{x_i}} + B \frac{\sin(x_i)}{\sqrt{x_i}} \approx J_1(x_i)$$

Calcnu:

Here is the function which we have defined:

```
calcnu(y,xo,k,eps,model)
```

It takes the input arguments y , which defines the vector range for our approximation; x_0 defines from which point of vector y to begin with, k is the Bessel function v value, eps

is the error to be added to the function ,model defines the approximation to be considered whether to take the first or the second one.

```
def calcnu(y,xo,k,eps,model):
    l=where(y>=xo)
    y1=y[l]
    l1=len(y1)
    A=zeros((l1,2))
    b=j1(y1)+eps*(rand(len(y1)))
    if model==0:
        A[:,0]=cos(y1)
        A[:,1]=sin(y1)
    if model==1:
        A[:,0]=cos(y1)/(y1**(0.5))
        A[:,1]=sin(y1)/(y1**(0.5))
    c=lstsq(A,b)[0]
    i1=arccos(c[0]/((c[0])**2+(c[1])**2)**(0.5))
    v1=-1*(-2*i1/pi+0.5)
    return v1
```

It returns the value of v (v is the subscript of $J_v(x)$), So that we can know that the approximation is very good if v value is very near to *one*. (Because we have considered the function to be $J_1(x)$).

The function is basically calculating coefficients then getting the angle ϕ when our function is written in the form $\sqrt{A^2+B^2}\cos(x_i+\phi)$ where ϕ is nothing but $\cos^{-1}\left(\frac{A}{\sqrt{A^2+B^2}}\right)$ so that we can get v value from the approximate Bessel function $\sqrt{\frac{2}{\pi x}}\cos\left(x-\frac{v\pi}{2}-\frac{\pi}{4}\right)$. By equating $\phi = \frac{v\pi}{2} + \frac{\pi}{4}$.

Calling the calcnu function for the v values and plotting:

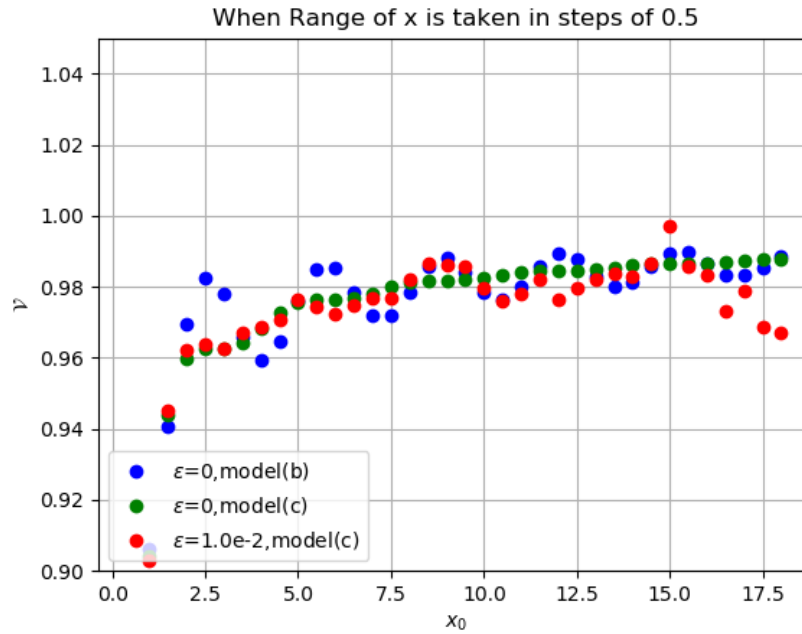
```
y=arange(0.5,20.5,0.000625)
for xo in y3:
    nu=calcnu(y,xo,0,0,0)
    v1.append(nu)
for xo in y3:
    nu=calcnu(y,xo,0,0,1)
    v2.append(nu)
for xo in y3:
    nu=calcnu(y,xo,0,0.01,1)
    v3.append(nu)
```

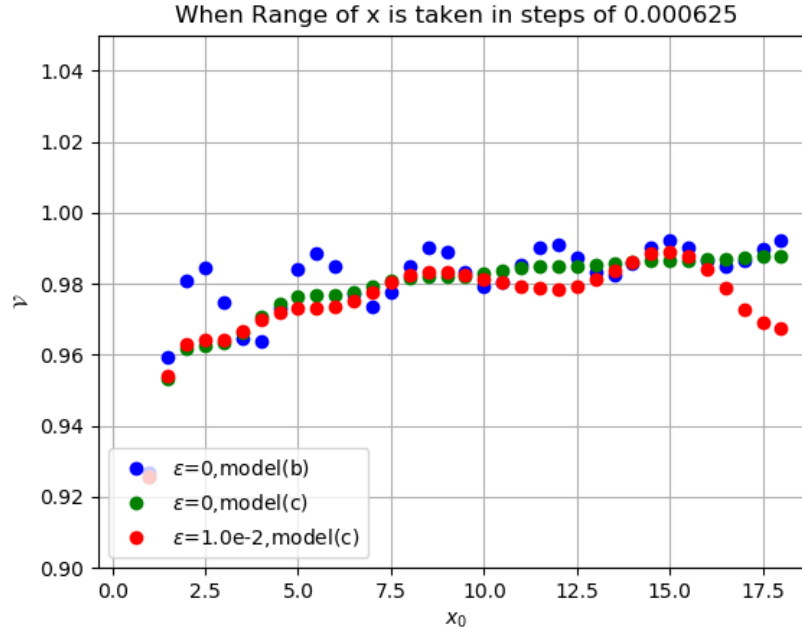
```

#Plots
fig1=figure(2)
plot(y3,v1,'bo',label="\epsilon=0,model(b)")
plot(y3,v2,'go',label="\epsilon=0,model(c)")
plot(y3,v3,'ro',label="\epsilon=1.0e-2,model(c)")
title("Range of x in steps of 0.000625")
xlabel("$x_0$")
ylabel("$\mathcal{V}$")
grid()
axes=plt.gca()
axes.set_ylim([0.9,1.05])
legend(loc="lower left")
show()

```

Graph of v values for both approximate functions :





Conclusions:

- Looking at the Plots v vs x_0 we can say that model(c) is more accurate than model(b).
- By Varying the no of measurements by not changing the steps taken for *range of x* change from 0.5 to 0.000625 we can say that the effect of noise in the graph for model(c) is considerably less.
- Moreover quality fit of error is very poor in the end values of x_0 because of only less values are given for leastsq approximation.
- There is also a large deviation from “v” value “one” in the beginning, this is because the Bessel function is more near to the $\sqrt{\frac{2}{\pi x}} \cos\left(x - \frac{v\pi}{2} - \frac{\pi}{4}\right)$ approximation from higher values of “x” so the approximate value is not near to one in the beginning.