## **Caffe Workshop**

Install and run caffe: (Completed)

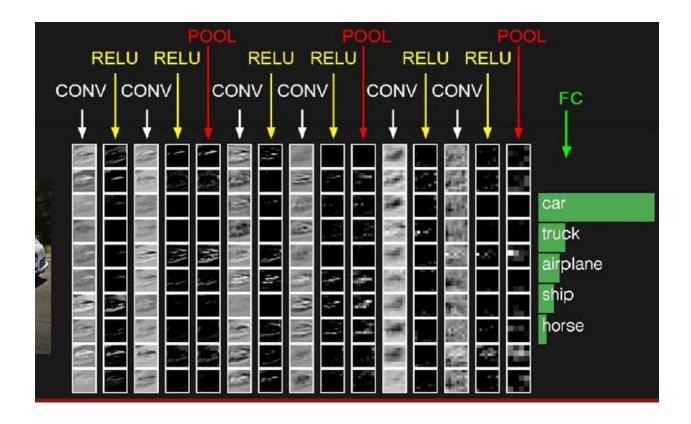
- 1. install Oracle VM VirtualBOX
- 2. download Ubuntu 14.04 and put it in the virtualbox. After that, tune up the default memory set to at least 4 GB for the later use. (I experienced being informed of lack of memory when do the compilation.)
- 3. set prerequisites for caffe installation.(dependencies) -----type all the listed necessary command in the terminal. ( <a href="http://caffe.berkeleyvision.org/install\_apt.html">http://caffe.berkeleyvision.org/install\_apt.html</a>
- 4. download caffe package from github
- 5. compile all
- 6. set the caffe path to environment

To train model with caffe:

(sample: http://caffe.berkeleyvision.org/gathered/examples/mnist.html)

- 1. prepare Datasets. (create Imdb)----two commands (Completed)
- 2. write the network definition protobuf and solver protobuf files.( the most complicated and obscure part)
- 3. train the model with several commands

How to configure the Conv layers: (3 layers: conv; POOL; FC)



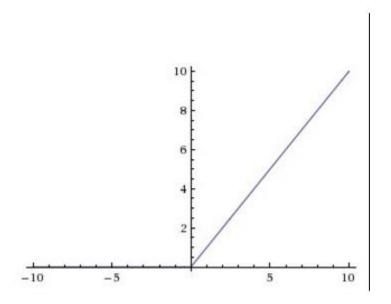
# 1. convolution layer:

bottom: where the input data goes top: where the output data comes Ir\_mult: learning rate multipliers decay\_mult: decay multipliers convolution parameters include:

num\_output: the number of filters
kernel\_size: size of each filter

stride: number of pixels to step between each filter application

### • RELU: Rectified Linear Unit activation function



\* In biologically inspired neural networks, the **activation function** is usually an abstraction representing the rate of action potential firing in the cell. In its simplest form, this **function** is binary—that is, either the neuron is firing or not.

### 2. pooling layer:

to make the representations smaller and more manageable operates over each activation map independently

the most common type: max pooling: three Parameters: their spatial extent F(always set 2 or 3) the stride S (always set 2) zero-padding

- Accepts a volume of size  $W_1 imes H_1 imes D_1$
- · Requires three hyperparameters:
  - · their spatial extent F,
  - $\circ$  the stride S,
- Produces a volume of size  $W_2 imes H_2 imes D_2$  where:

$$W_2 = (W_1 - F)/S + 1$$

$$H_2 = (H_1 - F)/S + 1$$

$$Oldsymbol{0} Oldsymbol{0} Old$$

- · Introduces zero parameters since it computes a fixed function of the input
- · Note that it is not common to use zero-padding for Pooling layers
- 3. Fully connected Layer (FC layer): contains neurons that connect to the entire input volume, as in ordinary Neural Networks. In other words, neurons between two adjacent layers are fully pairwise connected, but neurons within a single layer share no connections

The architecture of Memnet model is:

Conv-RELU-POOL-LRN(Normalization Layer) - Conv-RELU-Conv-RELU-Conv-RELU-POOL-InnerProduct-RELU-Dropout-InnerProduct-RELU-Dropout-InnerProduct

#### (Dropout:

\*dropout units in the neural network, along with their incoming and outgoing connections \*prevent neural network from overfitting and provides a way of approximately combining many different neural network architectures efficiently.)

#### Trends of Architecture of ConvNets:

- 1. smaller filters and deeper architectures
- 2. getting rid of POOL and FC layers