

Control Systems

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Consider the positive-feedback circuit shown in Figure: 1.

- 1) Find the loop transmission $L(s)$ and the characteristic equation
- 2) Find the expressions for resulting pole frequency ω_o and Q factor?
- 3) Sketch a Pole-Zero plot for varying K. For what value of K do the poles coincide? For what value of K does the response becomes maximally flat? For what value of K does the circuit oscillate?

Assume that the amplifier has frequency-independent gain, infinite input impedance, and zero output impedance.

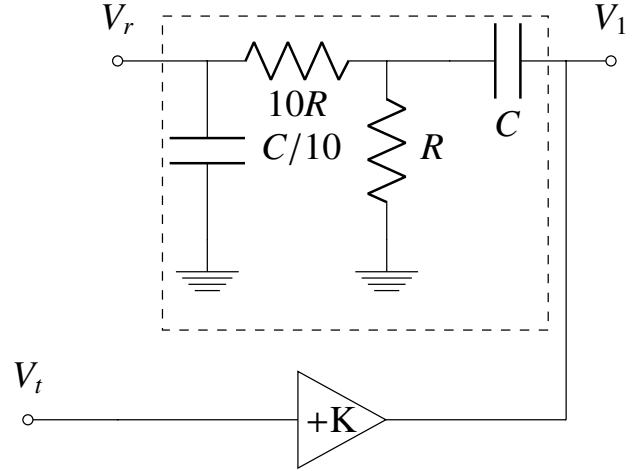


Fig. 1

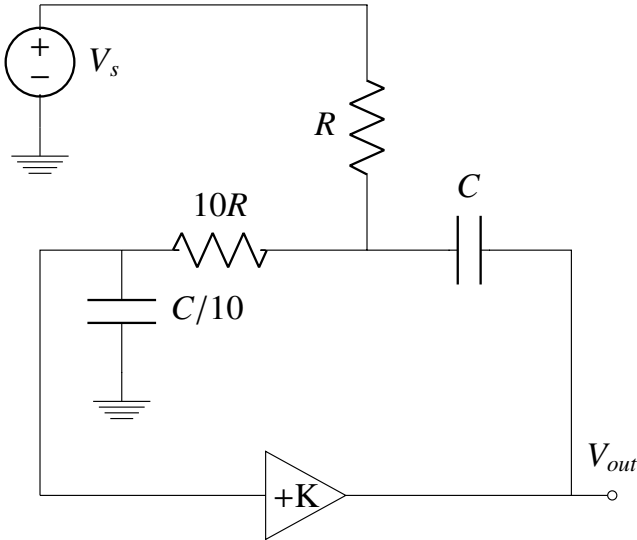


Fig. 3: Positive Feedback Circuit

1. **Solution:** To obtain the loop transmission $L(s)$,
 - Short-circuit the signal source V_s .
 - Break the loop at the Amplifier input.
 - Then apply a test voltage V_t and find the returned voltage V_r , as indicated in Figure: 1.

The loop transmission is given by

$$L(s) = -\frac{V_r(s)}{V_t(s)} = -KT(s) \quad (1.1)$$

where $T(s)$ is the transfer function of the two-port RC network shown inside the broken-line box in Figure: 1.

$$T(s) = \frac{V_r(s)}{V_1(s)} \quad (1.2)$$

Applying KCL at nodes present in the RC network yields

$$T(s) = \frac{s(\frac{1}{CR})}{s^2 + s(\frac{2.1}{CR}) + (\frac{1}{CR})^2} \quad (1.3)$$

Substituting $T(s)$ in Eq: 1.1

$$L(s) = \frac{-s(\frac{K}{CR})}{s^2 + s(\frac{2.1}{CR}) + (\frac{1}{CR})^2} \quad (1.4)$$

The characteristic equation is

$$1 + L(s) = 0 \quad (1.5)$$

$$s^2 + s(\frac{2.1 - K}{CR}) + (\frac{1}{CR})^2 = 0 \quad (1.6)$$

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The standard characteristic equation of a second order network can be written as

$$s^2 + \frac{\omega_o}{Q}s + \omega_o^2 = 0 \quad (1.7)$$

ω_o is called pole frequency, Q is called pole Qfactor. By comparing the Eq:1.6 with the standard characteristic equation Eq:1.7

$$\omega_o = \frac{1}{RC}; Q = \frac{1}{2.1 - K} \quad (1.8)$$

Closed Loop gain

$$T = \frac{s(\frac{-K}{RC})}{s^2 + s(\frac{2.1-K}{CR}) + (\frac{1}{CR})^2} \quad (1.9)$$

2. Sketch the Normalised closed loop gain of above two pole feedback amplifier for various Q values

Solution:

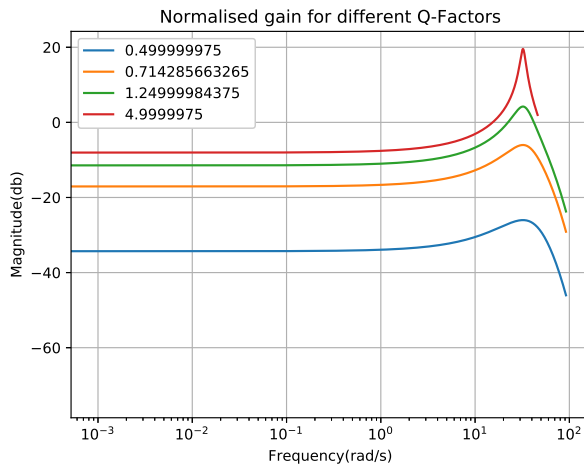


Fig. 2

The following is code for the plot

```
codes/ee18btech11030/ee18btech11030.py
```

From Figure:2 ,

- It is observed that maximally flat response is obtained when $Q = 0.71$
- It will be seen that response of the feedback amplifier under consideration shows almost no peaking for $Q \leq 0.71$

3. Sketch a Pole-Zero Plot to Eq:1.9 for a varying K

Solution:

The following is code for the plot

```
codes/ee18btech11030/ee18btech11030_1.py
```

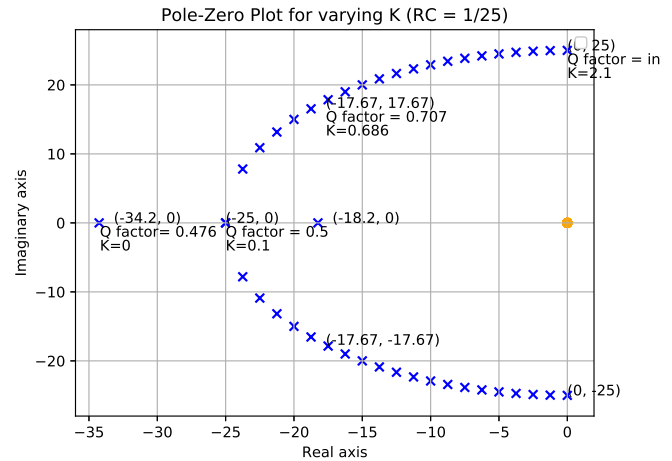


Fig. 3

From Figure : 3

- For $K = 0$, the poles have $Q = 0.476$ and therefore located on negative real axis.
 - As K increases poles are brought closer together and eventually coincide at $K = 0.1$ and $Q = 0.5$
 - Further increase in K results in poles becoming complex conjugate
 - Maximally flat response is obtained when $Q = 0.707$, which results when $K = 0.686$. In this case poles are at 45° .
 - Oscillating response is obtained when poles are completely imaginary when $Q = \infty$ which results when $K = 2.1$
4. Verify the response in time domain for a unit impulse input

Solution:

The following is code for the plot

```
codes/ee18btech11030/ee18btech11030_2.py
```

Q-Factor	K	Requirement
0.5	0.1	Poles are coincident
0.707	0.686	Maximally flat response
∞	2.1	Oscillatory response

TABLE 4

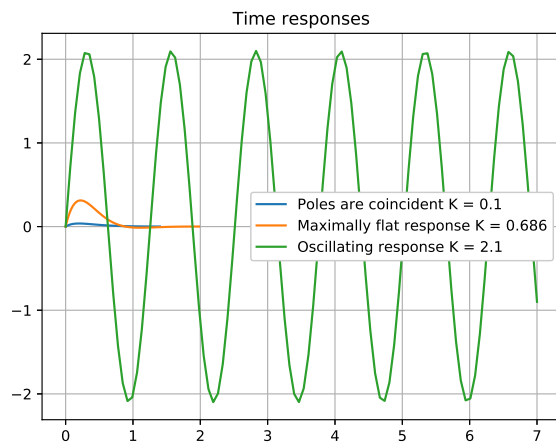


Fig. 4