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import os
import torch
import torch.nn as nn
import torch.optim as optim
from torchvision import datasets, transforms
from torchvision.utils import save_image, make_grid
import matplotlib.pyplot as plt

dataset_choice = "mnist"
epochs = 60
batch_size = 64
noise_dim = 100
learning_rate = 0.0002
sample_interval = 5
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")

os.makedirs("generated_samples", exist_ok=True)
os.makedirs("final_generated_images", exist_ok=True)

transform = transforms.Compose([
    transforms.ToTensor(),
    transforms.Normalize((0.5,), (0.5,)) # [-1, 1]
])

train_loader = torch.utils.data.DataLoader(
    datasets.MNIST(
        root='./data',
        train=True,
        transform=transform,
        download=True
    ),
    batch_size=batch_size,
    shuffle=True
)

100%|██████████| 9.91M/9.91M [00:00<00:00, 42.7MB/s]
100%|██████████| 28.9k/28.9k [00:00<00:00, 1.15MB/s]
100%|██████████| 1.65M/1.65M [00:00<00:00, 10.4MB/s]
100%|██████████| 4.54k/4.54k [00:00<00:00, 9.33MB/s]

class Generator(nn.Module):
    def __init__(self):
        super().__init__()
        self.model = nn.Sequential(
            nn.Linear(noise_dim, 256),
            nn.ReLU(True),
            nn.Linear(256, 512),
            nn.ReLU(True),
            nn.Linear(512, 1024),
            nn.ReLU(True),

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        nn.Linear(1024, 28 * 28),
        nn.Tanh()
    )

    def forward(self, z):
        img = self.model(z)
        return img.view(img.size(0), 1, 28, 28)

class Discriminator(nn.Module):
    def __init__(self):
        super().__init__()
        self.model = nn.Sequential(
            nn.Linear(28 * 28, 512),
            nn.LeakyReLU(0.2, inplace=True),
            nn.Linear(512, 256),
            nn.LeakyReLU(0.2, inplace=True),
            nn.Linear(256, 1),
            nn.Sigmoid()
        )

    def forward(self, img):
        img_flat = img.view(img.size(0), -1)
        return self.model(img_flat)

generator = Generator().to(device)
discriminator = Discriminator().to(device)

criterion = nn.BCELoss()
optimizer_G = optim.Adam(generator.parameters(), lr=learning_rate,
betas=(0.5, 0.999))
optimizer_D = optim.Adam(discriminator.parameters(), lr=learning_rate,
betas=(0.5, 0.999))

for epoch in range(1, epochs + 1):
    for imgs, _ in train_loader:

        real_imgs = imgs.to(device)
        batch_size_curr = real_imgs.size(0)

        real_labels = torch.ones(batch_size_curr, 1).to(device)
        fake_labels = torch.zeros(batch_size_curr, 1).to(device)

        optimizer_D.zero_grad()

        real_loss = criterion(discriminator(real_imgs), real_labels)

        z = torch.randn(batch_size_curr, noise_dim).to(device)
        fake_imgs = generator(z)
        fake_loss = criterion(discriminator(fake_imgs.detach()), fake_labels)

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        d_loss = real_loss + fake_loss
        d_loss.backward()
        optimizer_D.step()

        optimizer_G.zero_grad()

        g_loss = criterion(discriminator(fake_imgs), real_labels)
        g_loss.backward()
        optimizer_G.step()

    print(
        f"Epoch [{epoch}/{epochs}] "
        f"D_loss: {d_loss.item():.4f} "
        f"G_loss: {g_loss.item():.4f}"
    )

    if epoch % sample_interval == 0:
        z = torch.randn(25, noise_dim).to(device)
        samples = generator(z)
        grid = make_grid(samples, nrow=5, normalize=True)
        save_image(grid, f"generated_samples/epoch_{epoch}.png")

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Epoch [1/60] D\_loss: 0.5350 G\_loss: 2.7592  
Epoch [2/60] D\_loss: 0.4880 G\_loss: 2.7096  
Epoch [3/60] D\_loss: 0.7909 G\_loss: 2.2309  
Epoch [4/60] D\_loss: 0.5481 G\_loss: 6.6821  
Epoch [5/60] D\_loss: 0.2792 G\_loss: 2.6744  
Epoch [6/60] D\_loss: 0.4030 G\_loss: 3.2335  
Epoch [7/60] D\_loss: 0.5100 G\_loss: 2.0086  
Epoch [8/60] D\_loss: 0.6154 G\_loss: 2.7481  
Epoch [9/60] D\_loss: 0.4526 G\_loss: 2.2762  
Epoch [10/60] D\_loss: 0.4825 G\_loss: 1.7391  
Epoch [11/60] D\_loss: 0.4271 G\_loss: 3.2600  
Epoch [12/60] D\_loss: 0.7513 G\_loss: 2.1153  
Epoch [13/60] D\_loss: 0.7079 G\_loss: 1.6536  
Epoch [14/60] D\_loss: 0.8141 G\_loss: 2.1013  
Epoch [15/60] D\_loss: 0.9779 G\_loss: 1.5700  
Epoch [16/60] D\_loss: 0.7345 G\_loss: 1.4250  
Epoch [17/60] D\_loss: 0.7026 G\_loss: 2.0756  
Epoch [18/60] D\_loss: 1.5449 G\_loss: 0.6917  
Epoch [19/60] D\_loss: 0.8004 G\_loss: 1.1104  
Epoch [20/60] D\_loss: 0.8910 G\_loss: 2.1130  
Epoch [21/60] D\_loss: 0.9383 G\_loss: 1.7337  
Epoch [22/60] D\_loss: 1.0084 G\_loss: 2.3963  
Epoch [23/60] D\_loss: 0.7095 G\_loss: 2.0412  
Epoch [24/60] D\_loss: 0.9641 G\_loss: 1.2549  
Epoch [25/60] D\_loss: 0.8393 G\_loss: 1.7012

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Epoch [26/60] D_loss: 0.9973 G_loss: 1.7027
Epoch [27/60] D_loss: 0.9346 G_loss: 1.1492
Epoch [28/60] D_loss: 1.4075 G_loss: 2.6337
Epoch [29/60] D_loss: 0.9231 G_loss: 1.0780
Epoch [30/60] D_loss: 1.5406 G_loss: 2.6821
Epoch [31/60] D_loss: 0.8955 G_loss: 1.0063
Epoch [32/60] D_loss: 1.0150 G_loss: 0.8369
Epoch [33/60] D_loss: 0.8468 G_loss: 1.6008
Epoch [34/60] D_loss: 0.9638 G_loss: 2.3208
Epoch [35/60] D_loss: 0.7214 G_loss: 2.1783
Epoch [36/60] D_loss: 0.8270 G_loss: 1.5569
Epoch [37/60] D_loss: 0.7547 G_loss: 1.5775
Epoch [38/60] D_loss: 1.0198 G_loss: 2.1004
Epoch [39/60] D_loss: 0.6759 G_loss: 1.9006
Epoch [40/60] D_loss: 0.8004 G_loss: 1.4302
Epoch [41/60] D_loss: 0.9478 G_loss: 1.3309
Epoch [42/60] D_loss: 0.6725 G_loss: 1.6827
Epoch [43/60] D_loss: 0.7653 G_loss: 2.3677
Epoch [44/60] D_loss: 1.0512 G_loss: 2.0542
Epoch [45/60] D_loss: 0.8790 G_loss: 1.7830
Epoch [46/60] D_loss: 0.7006 G_loss: 1.7437
Epoch [47/60] D_loss: 0.8343 G_loss: 1.2808
Epoch [48/60] D_loss: 0.8786 G_loss: 1.7853
Epoch [49/60] D_loss: 1.0019 G_loss: 1.5550
Epoch [50/60] D_loss: 0.8583 G_loss: 1.5739
Epoch [51/60] D_loss: 1.0285 G_loss: 1.5345
Epoch [52/60] D_loss: 0.7620 G_loss: 1.7567
Epoch [53/60] D_loss: 0.6422 G_loss: 1.6810
Epoch [54/60] D_loss: 0.8490 G_loss: 1.2955
Epoch [55/60] D_loss: 1.1971 G_loss: 1.8683
Epoch [56/60] D_loss: 0.9999 G_loss: 1.3301
Epoch [57/60] D_loss: 0.8387 G_loss: 1.0997
Epoch [58/60] D_loss: 0.7939 G_loss: 1.5020
Epoch [59/60] D_loss: 0.8201 G_loss: 1.6628
Epoch [60/60] D_loss: 1.1057 G_loss: 0.8841

z = torch.randn(100, noise_dim).to(device)
final_images = generator(z)

for i in range(100):
    save_image(
        final_images[i],
        f"final_generated_images/image_{i+1}.png",
        normalize=True
    )

print("Training complete. Final images saved.")

Training complete. Final images saved.
```

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class MNISTClassifier(nn.Module):
    def __init__(self):
        super().__init__()
        self.net = nn.Sequential(
            nn.Flatten(),
            nn.Linear(28 * 28, 128),
            nn.ReLU(),
            nn.Linear(128, 10)
        )

    def forward(self, x):
        return self.net(x)

classifier = MNISTClassifier().to(device)

optimizer_C = optim.Adam(classifier.parameters(), lr=0.001)
criterion_C = nn.CrossEntropyLoss()

classifier.train()
for epoch in range(3):
    for imgs, labels in train_loader:
        imgs, labels = imgs.to(device), labels.to(device)
        optimizer_C.zero_grad()
        loss = criterion_C(classifier(imgs), labels)
        loss.backward()
        optimizer_C.step()

import torch.nn.functional as F

# Convert range [-1,1] → [0,1]
gan_images = (final_images + 1) / 2

# 1 channel → 3 channels
gan_images = gan_images.repeat(1, 3, 1, 1)

# Resize 28×28 → 224×224
gan_images = F.interpolate(
    gan_images, size=(224, 224), mode="bilinear", align_corners=False
)

gan_images = gan_images.to(device)

classifier = classifier.to(device)
classifier.eval()

for p in classifier.parameters():
    p.requires_grad = False

gan_images = gan_images.to(device)

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import matplotlib.pyplot as plt
from PIL import Image

epochs = [5, 10, 20, 30, 40, 50]

plt.figure(figsize=(12, 8))

for i, ep in enumerate(epochs):
    img = Image.open(f"generated_samples/epoch_{ep}.png")
    plt.subplot(2, 3, i + 1)
    plt.imshow(img)
    plt.axis("off")
    plt.title(f"Epoch {ep}")

plt.tight_layout()
plt.show()

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