

```
In [1]: import os
import torch
import torch.nn as nn
import torch.optim as optim
from torchvision import datasets, transforms
from torchvision.utils import save_image, make_grid
import matplotlib.pyplot as plt
```

```
In [3]: dataset_choice = "mnist"
epochs = 60
batch_size = 64
noise_dim = 100
learning_rate = 0.0002
sample_interval = 5
device = torch.device("cuda" if torch.cuda.is_available() else "cpu")
```

```
In [4]: os.makedirs("generated_samples", exist_ok=True)
os.makedirs("final_generated_images", exist_ok=True)
```

```
In [5]: transform = transforms.Compose([
    transforms.ToTensor(),
    transforms.Normalize((0.5,), (0.5,)) # [-1, 1]
])

train_loader = torch.utils.data.DataLoader(
    datasets.MNIST(
        root='./data',
        train=True,
        transform=transform,
        download=True
    ),
    batch_size=batch_size,
    shuffle=True
)
```

100%|██████████| 9.91M/9.91M [00:00<00:00, 41.9MB/s]
100%|██████████| 28.9k/28.9k [00:00<00:00, 1.17MB/s]
100%|██████████| 1.65M/1.65M [00:00<00:00, 10.6MB/s]
100%|██████████| 4.54k/4.54k [00:00<00:00, 6.66MB/s]

```
In [6]: class Generator(nn.Module):
    def __init__(self):
        super().__init__()
        self.model = nn.Sequential(
            nn.Linear(noise_dim, 256),
            nn.ReLU(True),
            nn.Linear(256, 512),
            nn.ReLU(True),
            nn.Linear(512, 1024),
            nn.ReLU(True),
            nn.Linear(1024, 28 * 28),
            nn.Tanh()
        )
```

```
def forward(self, z):
    img = self.model(z)
    return img.view(img.size(0), 1, 28, 28)
```

```
In [7]: class Discriminator(nn.Module):
    def __init__(self):
        super().__init__()
        self.model = nn.Sequential(
            nn.Linear(28 * 28, 512),
            nn.LeakyReLU(0.2, inplace=True),
            nn.Linear(512, 256),
            nn.LeakyReLU(0.2, inplace=True),
            nn.Linear(256, 1),
            nn.Sigmoid()
        )

    def forward(self, img):
        img_flat = img.view(img.size(0), -1)
        return self.model(img_flat)
```

```
In [8]: generator = Generator().to(device)
discriminator = Discriminator().to(device)

criterion = nn.BCELoss()
optimizer_G = optim.Adam(generator.parameters(), lr=learning_rate, betas=(0.5,
optimizer_D = optim.Adam(discriminator.parameters(), lr=learning_rate, betas=(
```

```
In [9]: for epoch in range(1, epochs + 1):
    for imgs, _ in train_loader:

        real_imgs = imgs.to(device)
        batch_size_curr = real_imgs.size(0)

        real_labels = torch.ones(batch_size_curr, 1).to(device)
        fake_labels = torch.zeros(batch_size_curr, 1).to(device)

        optimizer_D.zero_grad()

        real_loss = criterion(discriminator(real_imgs), real_labels)

        z = torch.randn(batch_size_curr, noise_dim).to(device)
        fake_imgs = generator(z)
        fake_loss = criterion(discriminator(fake_imgs.detach()), fake_labels)

        d_loss = real_loss + fake_loss
        d_loss.backward()
        optimizer_D.step()

        optimizer_G.zero_grad()
```

```
g_loss = criterion(discriminator(fake_imgs), real_labels)
g_loss.backward()
optimizer_G.step()

print(
    f"Epoch [{epoch}/{epochs}] "
    f"D_loss: {d_loss.item():.4f} "
    f"G_loss: {g_loss.item():.4f}"
)

if epoch % sample_interval == 0:
    z = torch.randn(25, noise_dim).to(device)
    samples = generator(z)
    grid = make_grid(samples, nrow=5, normalize=True)
    save_image(grid, f"generated_samples/epoch_{epoch}.png")
```

Epoch [1/60] D_loss: 0.7004 G_loss: 3.7324
Epoch [2/60] D_loss: 0.5326 G_loss: 2.9053
Epoch [3/60] D_loss: 1.2331 G_loss: 8.1311
Epoch [4/60] D_loss: 0.3152 G_loss: 2.9801
Epoch [5/60] D_loss: 0.2135 G_loss: 5.1856
Epoch [6/60] D_loss: 0.4943 G_loss: 2.1400
Epoch [7/60] D_loss: 0.4919 G_loss: 1.6716
Epoch [8/60] D_loss: 0.3287 G_loss: 4.7240
Epoch [9/60] D_loss: 0.3991 G_loss: 5.6310
Epoch [10/60] D_loss: 0.3704 G_loss: 2.6351
Epoch [11/60] D_loss: 0.2632 G_loss: 2.8364
Epoch [12/60] D_loss: 0.3188 G_loss: 4.4236
Epoch [13/60] D_loss: 0.0799 G_loss: 5.0519
Epoch [14/60] D_loss: 0.0005 G_loss: 7.7686
Epoch [15/60] D_loss: 0.0001 G_loss: 9.5880
Epoch [16/60] D_loss: 0.2856 G_loss: 66.9035
Epoch [17/60] D_loss: 0.0001 G_loss: 9.4973
Epoch [18/60] D_loss: 0.0001 G_loss: 11.1097
Epoch [19/60] D_loss: 0.0000 G_loss: 11.3008
Epoch [20/60] D_loss: 0.0001 G_loss: 9.5653
Epoch [21/60] D_loss: 0.0016 G_loss: 7.0331
Epoch [22/60] D_loss: 0.0001 G_loss: 9.7998
Epoch [23/60] D_loss: 0.0001 G_loss: 10.5492
Epoch [24/60] D_loss: 0.0003 G_loss: 8.3341
Epoch [25/60] D_loss: 0.0000 G_loss: 12.3308
Epoch [26/60] D_loss: 0.0000 G_loss: 13.0293
Epoch [27/60] D_loss: 0.0000 G_loss: 12.8276
Epoch [28/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [29/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [30/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [31/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [32/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [33/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [34/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [35/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [36/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [37/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [38/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [39/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [40/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [41/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [42/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [43/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [44/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [45/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [46/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [47/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [48/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [49/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [50/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [51/60] D_loss: 100.0000 G_loss: 0.0000
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Epoch [54/60] D_loss: 100.0000 G_loss: 0.0000

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Epoch [55/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [56/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [57/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [58/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [59/60] D_loss: 100.0000 G_loss: 0.0000
Epoch [60/60] D_loss: 100.0000 G_loss: 0.0000
```

```
In [10]: z = torch.randn(100, noise_dim).to(device)
final_images = generator(z)

for i in range(100):
    save_image(
        final_images[i],
        f"final_generated_images/image_{i+1}.png",
        normalize=True
    )

print("Training complete. Final images saved.")
```

Training complete. Final images saved.

```
In [11]: class MNISTClassifier(nn.Module):
    def __init__(self):
        super().__init__()
        self.net = nn.Sequential(
            nn.Flatten(),
            nn.Linear(28 * 28, 128),
            nn.ReLU(),
            nn.Linear(128, 10)
        )

    def forward(self, x):
        return self.net(x)

classifier = MNISTClassifier().to(device)
```

```
In [12]: optimizer_C = optim.Adam(classifier.parameters(), lr=0.001)
criterion_C = nn.CrossEntropyLoss()

classifier.train()
for epoch in range(3):
    for imgs, labels in train_loader:
        imgs, labels = imgs.to(device), labels.to(device)
        optimizer_C.zero_grad()
        loss = criterion_C(classifier(imgs), labels)
        loss.backward()
        optimizer_C.step()
```

```
In [13]: import torch.nn.functional as F

# Convert range [-1,1] → [0,1]
gan_images = (final_images + 1) / 2
```

```
# 1 channel → 3 channels
gan_images = gan_images.repeat(1, 3, 1, 1)

# Resize 28×28 → 224×224
gan_images = F.interpolate(
    gan_images, size=(224, 224), mode="bilinear", align_corners=False
)

gan_images = gan_images.to(device)
```

```
In [14]: classifier = classifier.to(device)
classifier.eval()

for p in classifier.parameters():
    p.requires_grad = False
```

```
In [15]: gan_images = gan_images.to(device)
```

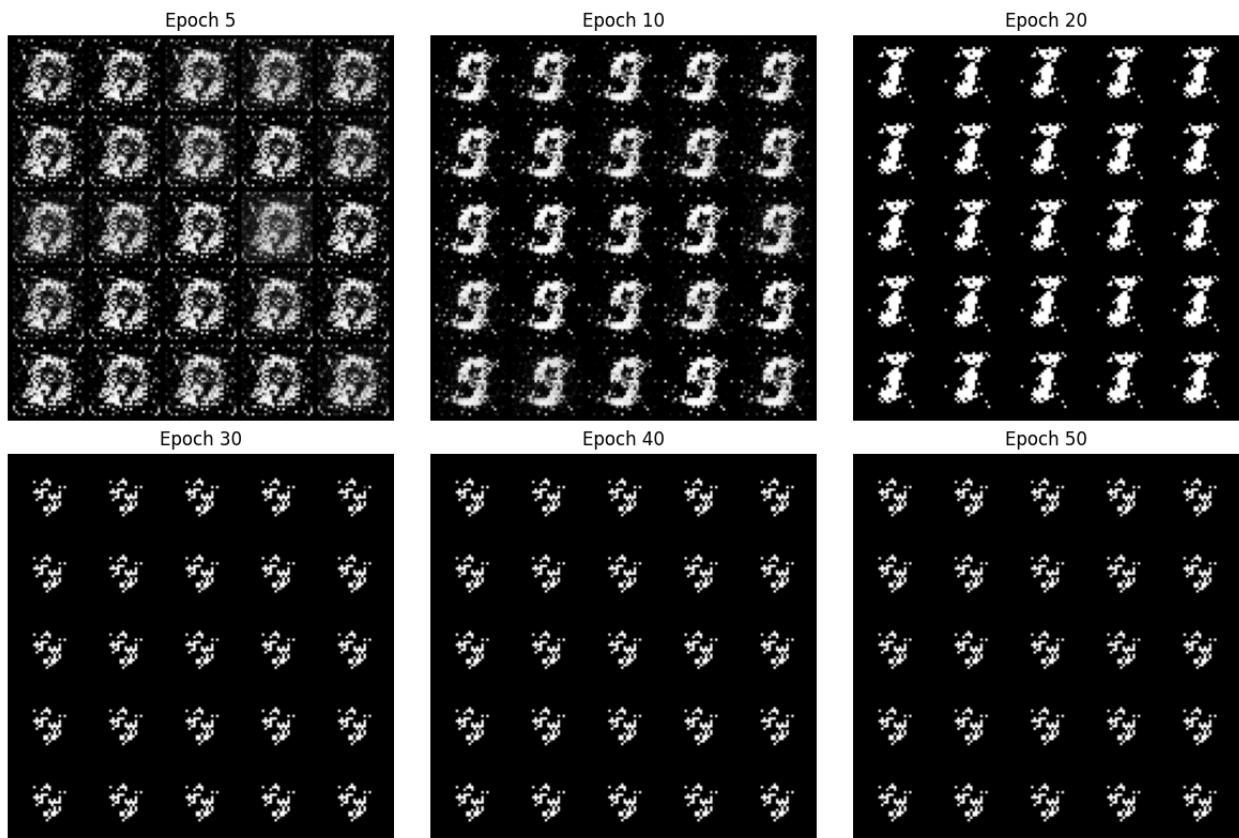
```
In [18]: import matplotlib.pyplot as plt
from PIL import Image

epochs = [5, 10, 20, 30, 40, 50]

plt.figure(figsize=(12, 8))

for i, ep in enumerate(epochs):
    img = Image.open(f"generated_samples/epoch_{ep}.png")
    plt.subplot(2, 3, i + 1)
    plt.imshow(img)
    plt.axis("off")
    plt.title(f"Epoch {ep}")

plt.tight_layout()
plt.show()
```



In []: