Week-R

NPTEL CS133 - Data Science for Engineers

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Today's Topics:

- 1. Linear Algebra
- 2. Solving linear Equations
- 3 Distances Hyperplanes 2 Half Space (if time permits)
- 4. Eigen Values Eigen Vectors

- → Session is being recorded
- → 3-5 min break every half hour \$ 10 min break every hour.
- -> If you would like me to cover more topics in next sexion please let me know at the end.
- Be respectful ouring the session, I will not hesitate to remove you from the session

* dinear Algebra

Recap: Vectors

Mat rices

Basic Operations (+,-, x)

Addl: Determinants

Example		
Apples	Banavas	Bread
2/-	1/-	3/-
3	2	1
Total	cost —	?

Vector: [2 1 3]
$$\rightarrow$$
 []
$$\begin{bmatrix} 3 & 2 & 1 \end{bmatrix} \rightarrow \textcircled{2}.$$

$$\begin{bmatrix} 3 & 1 & 3 \\ 1 & 3 & 1 \end{bmatrix} \xrightarrow{3 \times 1}$$

= ///-

Addition
$$\begin{bmatrix}
0 & 2 & 3 \\
4 & 5 & 5
\end{bmatrix} + \begin{bmatrix}
3 & 2 & 1 \\
1 & 2 & 3
\end{bmatrix} = \begin{bmatrix}
4 & 4 & 4 \\
5 & 7 & 9
\end{bmatrix}$$

Multiplication

 $A = \begin{bmatrix} 2 & 1 \\ 3 & 4 \end{bmatrix}$

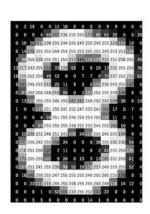
$$|A| = (A \times A - 3 \times 1)$$

$$= 8 - 3$$

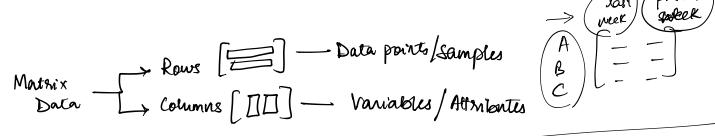
$$= 8 - 3$$

Image as a sepresentation of Marrix





0-285



Ex! Sales Matrix.

-> Rank

It linearly independent variables.

Pootin Conto fats

A 2 3 1

B 4 1 2

C 3 2 1

Rank=3

- Null Space

Multiplied by a -matrix results zero vector.

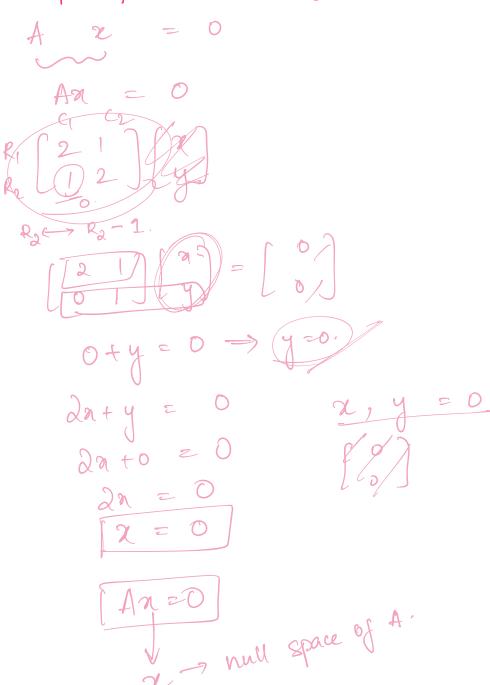
> Rank-Nullity Theorem

Rank (Materia) + din (null space) = No. of col.

----R Code

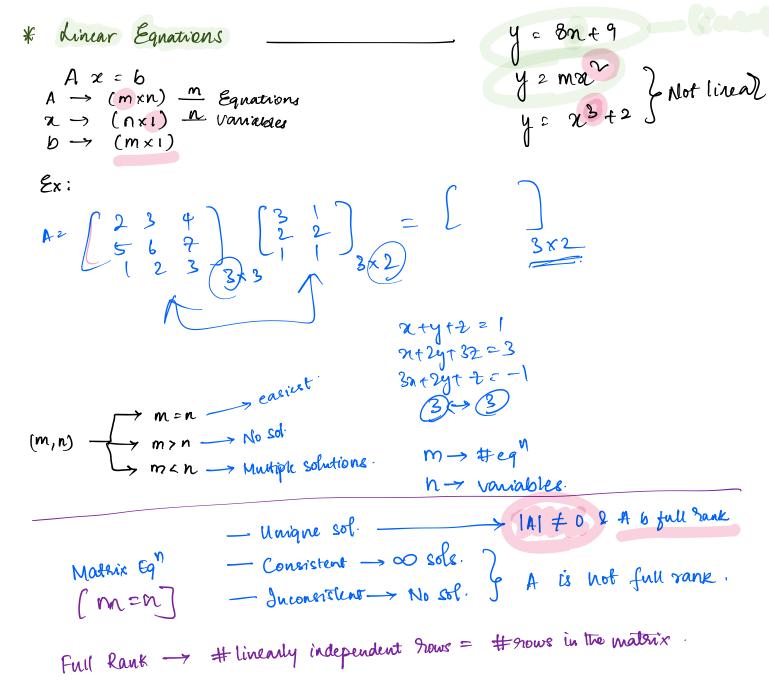
Null Space of a Matrix

Multiplied by a -matrix results zero vector.



Rank (A) +
$$ncol(N) = ncol(A)$$

3 0 3
2 1 3



$$X \longrightarrow Dalapoint$$

$$X = \begin{cases} x_1 \\ y_2 \end{cases}$$

$$x_1, x_2 \longrightarrow \text{distances from } X_1, X_2 \text{ axes}$$

$$\int_{0}^{\infty} x^{1} = \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix} \qquad x_{2} = \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix} \\
l = ? \\
\int_{0}^{\infty} (x_{1}^{1} - x_{1}^{1})^{\gamma} + (x_{2}^{1} - x_{2}^{1})^{\gamma}$$
Thy:

$$A_{1} = \begin{bmatrix} x_{1} \\ h_{2} \end{bmatrix} \quad X_{2} = \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix}$$

$$A_{2} = \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix}$$

$$A_{3} = \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix}$$

$$A_{4} = \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix}$$

$$A_{5} = \begin{bmatrix} x_{1} \\ x_{2} \end{bmatrix}$$

$$A_{7} = \begin{bmatrix} x_{1}$$

Unit Vector

Magnitude
$$\stackrel{?}{=}$$
 $\stackrel{|}{\stackrel{|}{=}}$ $\stackrel{|}{\stackrel{|}{=}}$ $\stackrel{|}{\stackrel{|}{=}}$ $\stackrel{|}{\stackrel{|}{=}}$ $\stackrel{|}{\stackrel{|}{=}}$ $\stackrel{|}{\stackrel{|}{=}}$ $\stackrel{|}{\stackrel{|}{=}}$ $\stackrel{|}{\stackrel{|}{=}}$ $\stackrel{|}{\stackrel{|}{=}}$ $\stackrel{|}{\stackrel{|}{=}}$

Orthogonal Vectors

dot product = 0

$$A^{T}B = 0$$

$$A^{T} = \begin{bmatrix} 3x1 \\ 1x3 \end{bmatrix}$$

$$A^{T}B = \begin{bmatrix} 3x1 \\ 1x1 \end{bmatrix}$$