Classification and Regression

Classification and regression

- What is classification? What is regression?
- Issues regarding classification and regression
- Classification by decision tree induction
- Bayesian Classification
- Other Classification Methods
- regression

What is Bayesian Classification?

- Bayesian classifiers are statistical classifiers
- For each new sample they provide a probability that the sample belongs to a class (for all classes)

Bayes' Theorem: Basics

- Let **X** be a data sample ("*evidence*"): class label is unknown
- Let H be a *hypothesis* that X belongs to class C
- Classification is to determine P(H|**X**), the probability that the hypothesis holds given the observed data sample **X**
- P(H) (*prior probability*), the initial probability
  - E.g., **X** will buy computer, regardless of age, income, …
- P(**X**): probability that sample data is observed

- P(**X**|H) (*posteriori probability*), the probability of observing the sample **X**, given that the hypothesis holds
  - E.g., Given that **X** will buy computer, the prob. that X is 31..40, medium income

Bayes' Theorem

- Given training data **X**, *posteriori probability of a hypothesis* H, P(H|**X**), follows the Bayes theorem

$$P(H|\mathbf{X}) = \frac{P(\mathbf{X}|H)P(H)}{P(\mathbf{X})}$$

- Informally, this can be written as

  posteriori = likelihood x prior/evidence

- Predicts **X** belongs to C_2 iff the probability $P(C_i|\mathbf{X})$ is the highest among all the $P(C_k|X)$ for all the *k* classes
- Practical difficulty: require initial knowledge of many probabilities, significant computational cost

Towards Naïve Bayesian Classifiers

- Let D be a training set of tuples and their associated class labels, and each tuple is represented by an n-D attribute vector **X** = $(x_1, x_2, \ldots, x_n)$
- Suppose there are *m* classes $C_1, C_2, \ldots, C_m$.
- Classification is to derive the maximum posteriori, i.e., the maximal $P(C_i|\mathbf{X})$
- This can be derived from Bayes' theorem

$$P(C_i|\mathbf{X}) = \frac{P(\mathbf{X}|C_i)P(C_i)}{P(\mathbf{X})}$$

- Since P(X) is constant for all classes, only

$$P(C_i|\mathbf{X}) = P(\mathbf{X}|C_i)P(C_i)$$

needs to be maximized

Derivation of Naïve Bayesian Classifier

- A simplified assumption: attributes are conditionally independent (i.e., no dependence relation between attributes):

$$P(\mathbf{X}|C_i) = \prod_{k=1}^{n} P(x_k|C_i) = P(x_1|C_i) \times P(x_2|C_i) \times \ldots \times P(x_n|C_i)$$

- This greatly reduces the computation cost: Only counts the class distribution
- If A_k is categorical, $P(x_k|C_i)$ is the # of tuples in C_i having value x_k for A_k divided by $|C_{i, D}|$ (# of tuples of C_i in D)
- If A_k is continous-valued, $P(x_k|C_i)$ is usually computed based on Gaussian distribution with a mean μ and standard deviation σ

$$g(x,\mu,\sigma) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}}$$

and $P(x_k|C_i)$ is

$$P(\mathbf{X}|C_i) = g(x_k, \mu_{C_i}, \sigma_{C_i})$$

NBC: Training Dataset

Class:
C1:buys_computer = 'yes'
C2:buys_computer = 'no'

Data sample
X = (age <=30,
Income = medium,
Student = yes
Credit_rating = Fair)

age	income	student	credit rating	comp
<=30	high	no	fair	no
<=30	high	no	excellent	no
31…40	high	no	fair	yes
>40	medium	no	fair	yes
>40	low	yes	fair	yes
>40	low	yes	excellent	no
31…40	low	yes	excellent	yes
<=30	medium	no	fair	no
<=30	low	yes	fair	yes
>40	medium	yes	fair	yes
<=30	medium	yes	excellent	yes
31…40	medium	no	excellent	yes
31…40	high	yes	fair	yes
>40	medium	no	excellent	no

NBC: An Example

- $P(C_i)$: P(buys_computer = "yes") = 9/14 = 0.643
  P(buys_computer = "no") = 5/14= 0.357

- Compute $P(X|C_i)$ for each class
  P(age = "<=30" | buys_computer = "yes") = 2/9 = 0.222
  P(age = "<= 30" | buys_computer = "no") = 3/5 = 0.6
  P(income = "medium" | buys_computer = "yes") = 4/9 = 0.444
  P(income = "medium" | buys_computer = "no") = 2/5 = 0.4
  P(student = "yes" | buys_computer = "yes) = 6/9 = 0.667
  P(student = "yes" | buys_computer = "no") = 1/5 = 0.2
  P(credit_rating = "fair" | buys_computer = "yes") = 6/9 = 0.667
  P(credit_rating = "fair" | buys_computer = "no") = 2/5 = 0.4

- **X = (age <= 30 , income = medium, student = yes, credit_rating = fair)**

$P(X|C_i)$: P(X|buys_computer = "yes") = 0.222 x 0.444 x 0.667 x 0.667 = 0.044
P(X|buys_computer = "no") = 0.6 x 0.4 x 0.2 x 0.4 = 0.019

$P(X|C_i)*P(C_i)$: P(X|buys_computer = "yes") * P(buys_computer = "yes") = 0.028
P(X|buys_computer = "no") * P(buys_computer = "no") = 0.007

Therefore, X belongs to class ("buys_computer = yes")

play tennis?

Naive Bayesian Classifier Example

Outlook	Temperature	Humidity	Windy	Class
sunny	hot	high	false	N
sunny	hot	high	true	N
overcast	hot	high	false	P
rain	mild	high	false	P
rain	cool	normal	false	P
rain	cool	normal	true	N
overcast	cool	normal	true	P
sunny	mild	high	false	N
sunny	cool	normal	false	P
rain	mild	normal	false	P
sunny	mild	normal	true	P
overcast	mild	high	true	P
overcast	hot	normal	false	P
rain	mild	high	true	N

Naive Bayesian Classifier Example

Outlook	Temperature	Humidity	Windy	Class
overcast	hot	high	false	P
rain	mild	high	false	P
rain	cool	normal	false	P
overcast	cool	normal	true	P
sunny	cool	normal	false	P
rain	mild	normal	false	P
sunny	mild	normal	true	P
overcast	mild	high	true	P
overcast	hot	normal	false	P

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Outlook	Temperature	Humidity	Windy	Class
sunny	hot	high	false	N
sunny	hot	high	true	N
rain	cool	normal	true	N
sunny	mild	high	false	N
rain	mild	high	true	N

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Naive Bayesian Classifier Example

- Given the training set, we compute the probabilities:

Outlook	P	N		Humidity	P	N
sunny	2/9	3/5		high	3/9	4/5
overcast	4/9	0		normal	6/9	1/5
rain	3/9	2/5				
Tempreature				Windy		
hot	2/9	2/5		true	3/9	3/5
mild	4/9	2/5		false	6/9	2/5
cool	3/9	1/5				

- We also have the probabilities
  - P = 9/14
  - N = 5/14

Naive Bayesian Classifier Example

- To classify a new sample X:
  - outlook = sunny
  - temperature = cool
  - humidity = high
  - windy = false
- Prob(P|X) = Prob(P)*Prob(sunny|P)*Prob(cool|P)* Prob(high|P)*Prob(false|P) = 9/14*2/9*3/9*3/9*6/9 = 0.01
- Prob(N|X) = Prob(N)*Prob(sunny|N)*Prob(cool|N)* Prob(high|N)*Prob(false|N) = 5/14*3/5*1/5*4/5*2/5 = 0.013
- Therefore X takes class label N

Naive Bayesian Classifier Example

- Second example X = <rain, hot, high, false>

- P(X|p)·P(p) = P(rain|p)·P(hot|p)·P(high|p)·P(false|p)·P(p) = 3/9·2/9·3/9·6/9·9/14 = 0.010582
- P(X|n)·P(n) = P(rain|n)·P(hot|n)·P(high|n)·P(false|n)·P(n) = 2/5·2/5·4/5·2/5·5/14 = 0.018286

- Sample X is classified in class N (don't play)

Avoiding the 0-Probability Problem

- Naïve Bayesian prediction requires each conditional prob. be non-zero. Otherwise, the predicted prob. will be zero

$$P(X \mid C_i) = \prod_{k=1}^{n} P(x_k \mid C_i)$$

- Ex. Suppose a dataset with 1000 tuples, income=low (0), income= medium (990), and income = high (10),
- Use Laplacian correction (or Laplacian estimator)
  - Adding 1 to each case

    Prob(income = low) = 1/1003

    Prob(income = medium) = 991/1003

    Prob(income = high) = 11/1003
  - The "corrected" prob. estimates are close to their "uncorrected" counterparts

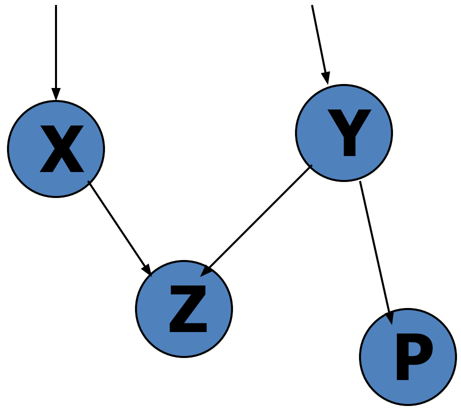
NBC: Comments

- Advantages
  - Easy to implement
  - Good results obtained in most of the cases
- Disadvantages
  - Assumption: class conditional independence, therefore loss of accuracy
  - Practically, dependencies exist among variables
    - E.g., hospitals: patients: Profile: age, family history, etc.

    Symptoms: fever, cough etc., Disease: lung cancer, diabetes, etc.
    - Dependencies among these cannot be modeled by Naïve Bayesian Classifier
- How to deal with these dependencies?
  - Bayesian Belief Networks

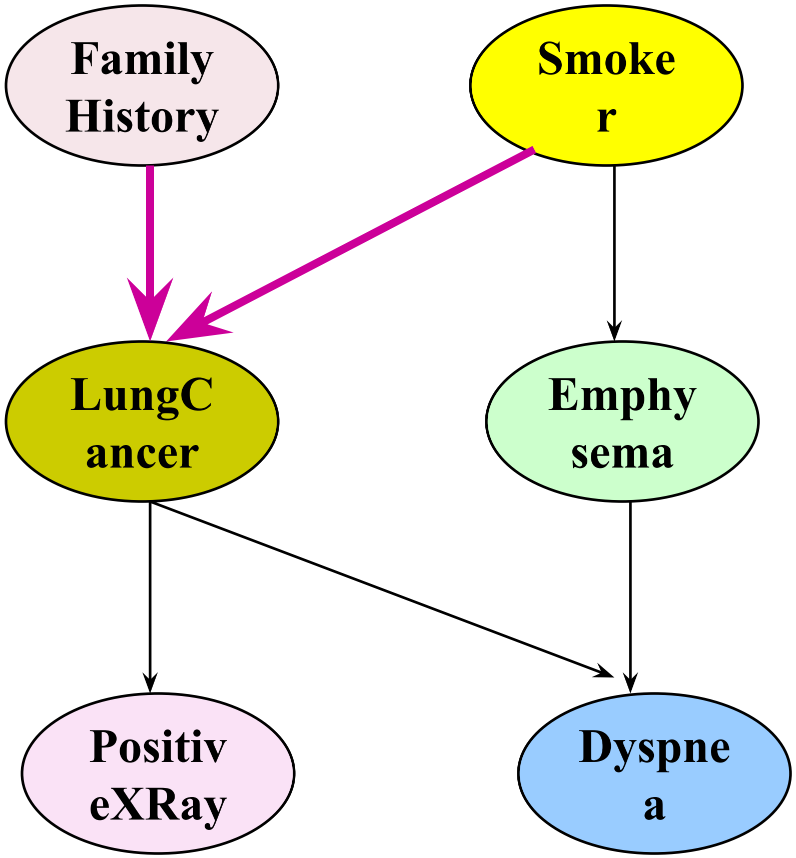
Bayesian Belief Networks

- Bayesian belief network allows a *subset* of the variables conditionally independent
- A graphical model of causal relationships
  - Represents dependency among the variables
  - Gives a specification of joint probability distribution



- ❑ Nodes: random variables
- ❑ Links: dependency
- ❑ X and Y are the parents of Z, and Y is the parent of P
- ❑ No dependency between Z and P
- ❑ Has no loops or cycles

Bayesian Belief Network: An Example



Bayesian Belief Networks

The **conditional probability table** (**CPT**) for variable LungCancer:

	(FH, S)	(FH, ~S)	(~FH, S)	(~FH, ~S)
LC	0.8	0.5	0.7	0.1
~LC	0.2	0.5	0.3	0.9

CPT shows the conditional probability for each possible combination of its parents

Derivation of the probability of a particular combination of values of **X**, from CPT:

$$P(x_1,\ldots,x_n) = \prod_{i=1}^{n} P(x_i \mid Parents(Y_i))$$

Bayesian Belief Networks

- Using Bayesian Belief Networks:
  - $P(v_1, \ldots, v_n) = \prod P(v_i/\text{Parents}(v_i))$
- Example:
  - P(LC = yes $\wedge$ FH = yes $\wedge$ S = yes) =

    P(FH = yes)* P(S = yes)*

    P(LC = yes|FH = yes $\wedge$ S = yes) =

    P(FH = yes)* P(S = yes)*0.8

Training Bayesian Networks

- Several scenarios:
  - Given both the network structure and all variables observable: *learn only the CPTs*
  - Network structure known, some hidden variables: *gradient descent* (greedy hill-climbing) method
  - Network structure unknown, all variables observable: search through the model space to *reconstruct network topology*
  - Unknown structure, all hidden variables: No good algorithms known for this purpose

Using IF-THEN Rules for Classification

- Represent the knowledge in the form of IF-THEN rules

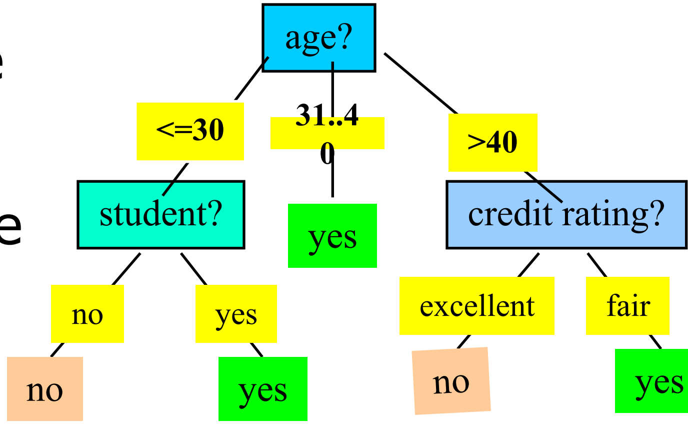
  R: IF *age* = youth AND *student* = yes THEN *buys_computer* = yes

  - Rule antecedent/precondition vs. rule consequent
- Assessment of a rule: *coverage* and *accuracy*
  - n_{covers} = # of tuples covered by R
  - $n_{correct}$ = # of tuples correctly classified by R

  coverage(R) = n_{covers} /|D| /* D: training data set */

  accuracy(R) = $n_{correct}$ / n_{covers}
- If more than one rule is triggered, need **conflict resolution**
  - Size ordering: assign the highest priority to the triggering rules that has the "toughest" requirement (i.e., with the *most attribute test*)
  - Class-based ordering: decreasing order of *prevalence or misclassification cost per class*
  - Rule-based ordering (**decision list**): rules are organized into one long priority list, according to some measure of rule quality or by experts

Rule Extraction from a Decision Tree



- Rules are easier to understand than large trees
- One rule is created for each path from the root to a leaf
- Each attribute-value pair along a path forms a conjunction: the leaf holds the class prediction
- Rules are mutually exclusive and exhaustive

- Example: Rule extraction from our *buys_computer* decision-tree

  IF *age* = young AND *student* = *no* THEN *buys_computer* = *no*

  IF *age* = young AND *student* = *yes* THEN *buys_computer* = *yes*

  IF *age* = mid-age THEN *buys_computer* = *yes*

  IF *age* = old AND *credit_rating* = *excellent* THEN *buys_computer* = *yes*

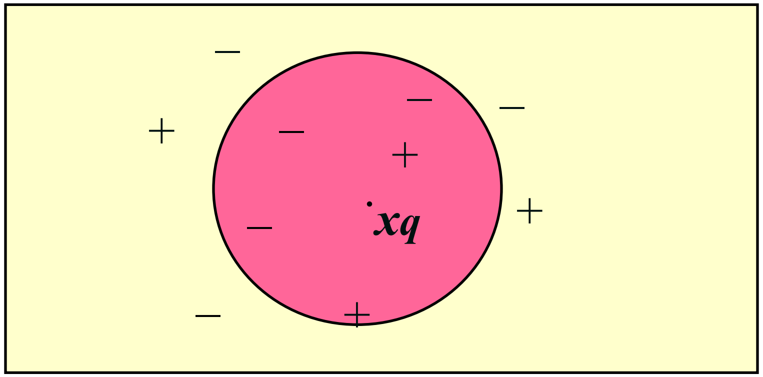
  IF *age* = young AND *credit_rating* = *fair* THEN *buys_computer* = *no*

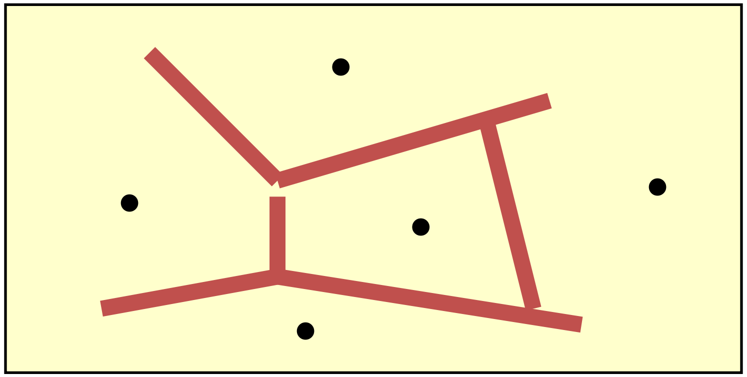
Instance-Based Methods

- Instance-based learning:
  - Store training examples and delay the processing (“lazy evaluation”) until a new instance must be classified
- Typical approaches
  - *k*-nearest neighbor approach
    - Instances represented as points in a Euclidean space.

The *k*-Nearest Neighbor Algorithm

- All instances correspond to points in the n-D space.
- The nearest neighbor are defined in terms of Euclidean distance.
- The target function could be discrete- or real- valued.
- For discrete-valued function, the *k*-NN returns the most common value among the k training examples nearest to *xq*.
- Vonoroi diagram: the decision surface induced by 1-NN for a typical set of training examples.





Discussion on the *k*-NN Algorithm

- Distance-weighted nearest neighbor algorithm
  - Weight the contribution of each of the k neighbors according to their distance to the query point x_q
    - give greater weight to closer neighbors

$$w \equiv \frac{1}{d(x_q, x_i)^2}$$

  - Similarly, for real-valued target functions
- Robust to noisy data by averaging k-nearest neighbors
- Curse of dimensionality: distance between neighbors could be dominated by irrelevant attributes.
  - To overcome it, axes stretch or elimination of the least relevant attributes.