

# Topic 4: Modelling (for CP & LCG)

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Course 1DL441:  
Combinatorial Optimisation and Constraint Programming,  
whose part 1 is Course 1DL451:  
Modelling for Combinatorial Optimisation



# Outline

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Viewpoints

Implied  
Constraints

Redundant  
Variables &  
Channelling  
Constraints

Pre-  
Computation

## 1. Viewpoints

## 2. Implied Constraints

## 3. Redundant Variables & Channelling Constraints

## 4. Pre-Computation



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# Recap

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## Viewpoints

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1 **Modelling**: express problem in terms of

- parameters,
- decision variables,
- constraints, and
- objective.

2 **Solving**: solve using a state-of-the-art solver.



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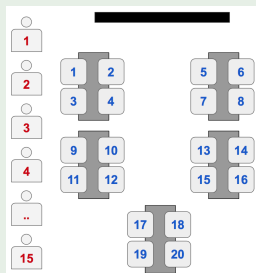
## Example (Student Seating Problem)

Given:

- $s$  students, and
- $c$  chairs positioned around tables.

Find a seating arrangement such that:

- Each table has either at least half its chairs occupied, or none.
- Each table has at least as many students as any table behind it.
- A maximum number of student preferences on being seated at the same table are satisfied.



$s = 15$  students

$c = 20$  chairs

What are suitable decision variables for this problem?



A **viewpoint** is a choice of decision variables.

## Example (Student Seating Problem)

### Viewpoint 1:

For each student, which chair is the student assigned to?

```
% Chair[i] = the chair of student i:  
array[1..s] of var 1..c: Chair;  
constraint alldifferent(Chair);
```

### Viewpoint 2:

For each chair, which student, if any, is seated on it?

```
% Student[i] = the student on chair i:  
array[1..c] of var 0..s: Student; % dummy 0  
constraint alldifferent_except_0(Student);
```

Let us now look at a generic problem in order to see how viewpoints differ when we start formulating constraints.



## Example (Objects, Shapes, and Colours)

There are  $n$  objects,  $s$  shapes, and  $c$  colours, with  $s \geq n$ .  
Assign a shape and a colour to each object such that:

- 1 the objects have distinct shapes;
- 2 the numbers of objects of the used colours are distinct;
- 3 other constraints, yielding NP-hardness and distinguishing objects and shapes, are satisfied.

This problem can be modelled from different viewpoints:

- 1 Which colour, if any, does each shape have?
- 2 Which shapes, if any, does each colour have?
- 3 Which shape and colour does each object have?
- 4 ...

Each viewpoint comes with benefits and drawbacks.



## Viewpoints

### Implied Constraints

### Redundant Variables & Channelling Constraints

### Pre- Computation

## Example (Objects, Shapes, and Colours)

Viewpoint 1: Which colour, if any, does each shape have?

```
1 int: n; % number of objects
2 int: s; % number of shapes
3 int: c; % number of colours
4 constraint assert(s >= n, "Not enough shapes");
5 % Colour[i] = the colour of the object of shape i:
6 array[1..s] of var 0..c: Colour; % 0 is a dummy colour
7 % There are n objects:
8 constraint exactly(s-n, Colour, 0);
9 % The numbers of objects of the used colours are distinct:
10 constraint
    alldifferent_except_0(global_cardinality(Colour, 1..c));
11 % The objects have distinct shapes:
12 %   implied by lines 6 and 8!
13 % ... add here the other constraints ...
14 solve satisfy;
```

Colour 0 is used when there is no object of the given shape.  
So what are the shape and colour of a particular object?!

👉 Map the objects onto the shapes with a non-0 colour!





## Example (Objects, Shapes, and Colours)

Viewpoint 2: Which shapes, if any, does each colour have?

```
1 int: n; % number of objects
2 int: s; % number of shapes
3 int: c; % number of colours
4 constraint assert(s >= n, "Not enough shapes");
5 % Shapes[i] = the set of shapes of colour i:
6 array[1..c] of var set of 1..s: Shapes;
7 % There are n objects:
8 constraint n = sum(colour in 1..c) (card(Shapes[colour]));
9 % The numbers of objects of the used colours are distinct:
10 constraint alldifferent_except_0(colour in 1..c)
    (card(Shapes[colour]));
11 % The objects have distinct shapes:
12 constraint n = card(array_union(Shapes));
13 % ... add here the other constraints ...
14 solve satisfy;
```

Post-process: map the objects onto actually used shapes.  
Can we also model this viewpoint without set variables?

☞ Yes, see the next slide!



## Viewpoints

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## Example (Objects, Shapes, and Colours)

Viewpoint 2: Which shapes, if any, does each colour have?

```
1 int: n; % number of objects
2 int: s; % number of shapes
3 int: c; % number of colours
4 constraint assert(s >= n, "Not enough shapes");
5 % NbrObj[i,j] = the number of objects of colour i & shape j:
6 array[1..c,1..s] of var 0..1: NbrObj;
7 % There are n objects:
8 constraint n = sum(NbrObj);
9 % The numbers of objects of the used colours are distinct:
10 constraint alldifferent_except_0(colour in 1..c)
    (sum(NbrObj[colour, ..]));
11 % The objects have distinct shapes:
12 constraint forall(shape in 1..s) (sum(NbrObj[., shape]) <= 1);
13 % ... add here the other constraints ...
14 solve satisfy;
```

Which model for viewpoint 2 is clearer or better?

👉 Ask and try!



## Example (Objects, Shapes, and Colours)

Viewpoint 3: Which shape & colour does each object have?

```
1 int: n; % number of objects
2 int: s; % number of shapes
3 int: c; % number of colours
4 constraint assert(s >= n, "Not enough shapes");
5 array[1..n] of var 1..s: Shape; % Shape[i] = shape of obj. i
6 array[1..n] of var 1..c: Colour; % Colour[i] = colour of i
7 % There are n objects:
8 %   implied by lines 5 and 6!
9 % The numbers of objects of the used colours are distinct:
10 constraint alldifferent_except_0
    (global_cardinality_closed(Colour, 1..c));
11 % The objects have distinct shapes:
12 constraint alldifferent(Shape);
13 % ... add here the other constraints ...
14 solve satisfy;
```

We have used two **parallel arrays** with the same index set but different domains in order to represent **pair variables**.

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Which viewpoint is better in terms of:

- Size of the search space

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- Ease of formulating the constraints and the objective
- Performance
- Readability



Which viewpoint is better in terms of:

■ Size of the search space:

- Viewpoint 1:  $\mathcal{O}((c + 1)^s)$ , which is independent of  $n$
- Viewpoint 2:  $\mathcal{O}(2^{s \cdot c})$ , which is independent of  $n$
- Viewpoint 3:  $\mathcal{O}(s^n \cdot c^n)$

■ Ease of formulating the constraints and the objective

■ Performance

■ Readability



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Does this actually matter?

■ Ease of formulating the constraints and the objective

■ Performance

■ Readability



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Does this actually matter?

■ Ease of formulating the constraints and the objective:

- It depends on the unstated other constraints.
- Ideally, we want a viewpoint that allows global-constraint predicates to be used.

■ Performance

■ Readability



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■ Performance:

- Hard to tell: we have to run experiments!

■ Readability





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■ Performance:

- Hard to tell: we have to run experiments!

■ Readability:

- Who is going to read the model?
- What is their background?



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Does this actually matter?

■ Ease of formulating the constraints and the objective:

- It depends on the unstated other constraints.
- Ideally, we want a viewpoint that allows global-constraint predicates to be used.

■ Performance:

- Hard to tell: we have to run experiments!

■ Readability:

- Who is going to read the model?
- What is their background?

There are no correct answers here:

we actually need to think about this and run experiments.



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## Example (The Magic Series Problem)

The element at index  $i$  in  $I = 0..(n-1)$  is the number of occurrences of  $i$ . Solution: Magic = [1, 2, 1, 0] for  $n=4$ .

**Variables:** Magic =

0	1	...	$n-1$
$\in 0..n$	$\in 0..n$	...	$\in 0..n$

### Constraint:

```
forall(i in I) (Magic[i] = sum(j in I) (bool2int (Magic[j]=i)))
```

or, logically equivalently but better:

```
forall(i in I) (count (Magic, i, Magic[i]))
```

or, logically equivalently and even better:

```
global_cardinality_closed (Magic, I, Magic)
```

### Implied Constraint:

```
sum (Magic) = n /\ sum(i in I) (Magic[i] * i) = n
```

For  $n=80$ , using a CP solver: only 7 search nodes are explored instead of 302; the solving is 1,000 times faster.



## Definition

An **implied constraint**, also called a **redundant constraint**, is a constraint that logically follows from other constraints.

### Benefit:

Solving may be faster, without losing any solutions.  
However, not all implied constraints accelerate the solving.

### Good practice in MiniZinc:

Flag implied constraints using the `implied_constraint` predicate. This allows backends to handle them differently, if wanted (see Topic 9: Modelling for CBLS):

```
predicate implied_constraint (var bool: c) = c; VS  
predicate implied_constraint (var bool: c) = true;
```

## Example

```
constraint implied_constraint (sum (Magic) = n);
```

In Topic 5: Symmetry, we will see the equally recommended `symmetry_breaking_constraint` predicate.



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# Redundant Decision Variables

## Example ( $n$ -queens)

Use **both** the  $n^2$  decision variables  $\text{Queen}[i, j]$  in  $0 \dots 1$  **and** the  $n$  decision variables  $\text{Row}[q]$  in  $1 \dots n$ .

## Definition

A **redundant decision variable** is a decision variable that represents information that is already represented by some other decision variables. It reflects a different viewpoint.

**Benefit:** Easier modelling of some constraints, or faster solving, or both.

## Examples (see Topic 6: Case Studies)

- Model of Black-Hole Patience
- Models 1 & 3 of Warehouse Location Problem



# Channelling Constraints

## Example ( $n$ -queens)

Channelling between the  $n$  decision variables  $\text{Row}[i]$  in  $1..n$  and the  $n^2$  decision variables  $\text{Queen}[i, j]$  in  $0..1$ :

```
forall (i in 1..n) (Row[i] = sum (j in 1..n) (j * Queen[i, j]))
```

## Definition

A **channelling constraint** establishes the coherence of the values of mutually redundant decision variables.

## Examples (see Topic 6: Case Studies)

- Model of Black-Hole Patience
- Models 1 & 3 of Warehouse Location Problem
- Experiment with channelling between the viewpoints for the *Objects, Shapes, and Colours* problem (slide 7).





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## Example (Prize-Pool Division)

Consider a maximisation problem where the objective function is the division of an unknown prize pool by an unknown number of winners:

```
1 ...  
2 array[1..5] of int: Pools = [1000,5000,15000,20000,25000];  
3 var 1..5: x; % index of the actual prize pool within Pools  
4 var 1..500: nbrWinners; % the number of winners  
5 ...  
6 solve maximize Pools[x] div nbrWinners; % implicit: element!
```

**Observation:** We should avoid using the `div` function on decision variables, because:

- It yields weak **inference**, at least in CP & LCG solvers.
- Its **inference** takes unnecessary time and memory.
- It is not supported by all MiniZinc backends.

**Idea:** We can pre-compute all possible objective values.



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### Example (Prize-Pool Division, revisited)

Pre-compute a 2d array, indexed by  $1..5$  and  $1..500$ , for each possible value pair of  $x$  and  $\text{nbrWinners}$ :

```
1 ...
2 array[1..5] of int: Pools = [1000,5000,15000,20000,25000];
3 var 1..5: x; % index of the actual prize pool within Pools
4 var 1..500: nbrWinners; % the number of winners
5 ...
6 array[1..5,1..500] of int: objVal = array2d(1..5,1..500,
      [Pools[p] div n | p in 1..5, n in 1..500]);
7 solve maximize objVal[x,nbrWinners]; % implicit: 2d-element!
```