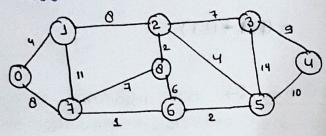
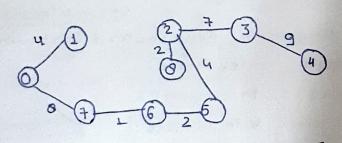
## TUTORIAL-06

Questo Cohat do you mean by minimum sponning Ture? commet are the approachance of MET?

Ans o+ A minimum spanning Tuee ox minimum weight spanning Toree jos a cueighted, connected, undirected graph is a Spanning Toree with weight less than or equal to the weight of every other spanning Thee The weight of spanning Toree is the sum of weights given to each edge of the Spanning Toree.





=> U+0+1+2+4+2+7+9=37

Our 2007 Please analyze the time and space complexity of Prism, Korush Kal, Digkstra and Beilman jord algorithm?

Ansir Digkstra algorithment This is used to solve single-source Shortest-paths problem on a weighted and directed

graph. dunction Digkstra (Graph, Source): Pseudo code ?> dist [source] + 0 algo

Create ventex set 0 for each ventex Vin Graph: 39 N = SOURCE

distEv] - undefined

Quadd with priority (V, dist EV)

U+ 0. extract\_men ()

80% each neighbors v of u:

alt & aistcu]+ length (u,v)

if alt < aistCu]

dist [u] & alt

Purev [v] & U

a decrease \_ priority (v, alt)

Time Complexity > For Best Case + O(child) 10g V)

average and coorst case + O(child) 10g V)

Space Complexity + 0 (W) + IEI)

Bellman-Ford Algorithm or This algorithm computes ShortestPaths from a Single source vertex to all other vertices
in a weighted directed graph.

Pseudo Code algo > junction Belliman-Ford Clist vertices, list edges, vertex Source)

-: distance [], predecessor []

dos each ventex & in ventices:

Poredecessor [v]: = noil

distance [ source] := 0

dos (î from 1 to size (vertice)-1):

for each edge (4,N) with weight win edges:

if distance cus + w < distance [1]:

distance [1] := distance [4]+w

Poredecessor [17:= U

dos each edge (uiv) with weight to in edges:

is distance [4] + a < distance [4]:

ereturn distance [], predecessor [].

Time Complexity > O(E) -> for best case

tor any & corst case - O(NE)

Space Complexity +

Kouskal's Algorithm of It is a greedy algorithm for finding minimum spanning Turee. It jinds a minimum weight.

Pseudo Code algo + Konuskal (G):

tos each VE G.V:

Make-set ( W)

Sout the edges in G.E in non-decreasing order by weight

dor each (u,v) in (n. E ordered by weight (u,v), nondecreasing.

if FIND\_SET (W) # FIND\_SET (V);

A= AU ( C41 V) 3

UNION (4IV)

vietorn

Time Complexity : (ElogV)

Space Complexity: O (log E)

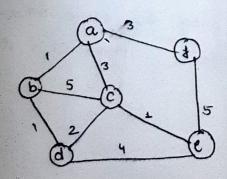
Purim's Algorithm &+ 9+ also finds MST in a graph and is closely vielated to Dijkstra algorithm. It's 9 mplementation is also based on 9 m plementing the priority queve,

Time Complexity :> 6(v2)

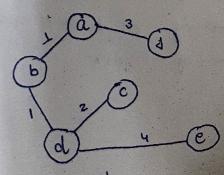
Space Complexity : + O(V+E)

Que 3 % Apply Knukal and Pulm's algorithm on graph given on wight side to compute MST and 9+3

Ans-



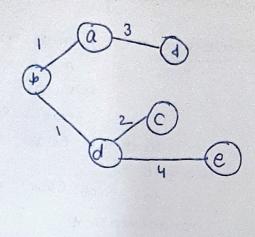
Pulm's algorithmo



D 1+3+1+2+4=1)

## Koruskal's algorithm?

u	<b>V</b>	weight
b	a	1
ь	d	1
C	e	1
da	C	2
a	C	3
a	4	3
d	e	4
4	8	5
Ь	C	5



Duers: Criven a disected graph (cheighted). You are also given the shortest path from a source vertex is to a destination vertex it. Does the shortest path remain same in the modified graph in following cases?

(i) by weight of every edge is encreased by 10 am units.

Ans: The shootest path may change The creason is, there may be different number of edges in different paths from Stot.

For example, let shootest path be of weight 15 and has 5 edges.

Let there be another path with 2 edges and total weight 25.

The weight of the shootest path is Increased by 5°10

and becomes 15+50 - weight of other path is Increased by 2°10 and become 25+20. So, the shootest path changes to the outer path with weight as 45.

(in of weight of every edge 95 multiplied by 10 un9ts.

Ansi g weights.

Ansi g weights all edge weights by 10, the shortest

path doesn't change. The vieason is simple, weights of all

paths from stot get multiplied by same amount. The

number of edges on a path doesn't matter. It is like changing

unit of weights.

given on sight side to compute showtest path to all nodes from hodes.

Ans

