

Tutorial 1

Introduction to MATLAB Simulink and HDL Coder

Introduction

In this tutorial exercise, you will learn how to use MATLAB Simulink and HDL Coder to build hardware designs from high-level dataflow models for both FPGA and ASIC targets.

Objectives

After completing this tutorial, you will be able to:

- Understand the design flow of MATLAB Simulink and HDL Coder.
- Model algorithms in Simulink as a dataflow system and perform bit-true cycle-accurate simulations for functional verification.
- Synthesize HDL codes from the Simulink model and implement hardware for both FPGA and ASIC targets.
- Estimate the performance and cost of the hardware implementation for both FPGA and ASIC targets.
- Understand some of the architectural optimization options available in HDL Coder.

Procedure

You will review and synthesize a design using fixed-point data types. This tutorial consists of four tasks:

1. Design a fixed-point complex multiplier using HDL coder blocks.
2. Simulate the complex multiplier design.
3. Generate VHDL/Verilog wrapper and create a hardware resource estimate for an FPGA target.
4. Generate VHDL/Verilog wrapper and create a hardware resource estimate for an ASIC Target.

Task 1: Design and Simulate a fixed-point Complex Multiplier

In this task, you will complete a design implemented with fixed-point data types.

1-1. Type “simulink” in the MATLAB command line to invoke Simulink.

1-2. Open the provided design file Tutorial1_1.slx. The Simulink design is shown in Figure 1. This design implements a complex multiplier with standard Simulink blocks (SL_Complex_Multiplier). Thus, it is a software model.

The multiplier model has two inputs X and Y, which receive data from two sources `data1` and `data2`. The input sources provide a sequence of fixed-point complex numbers from the MATLAB workspace generated by the provided MATLAB script (`data_sample_fp.m`). If you double-click on the block `SL_Complex_Multiplier`, you will be able to see the implementation of the complex multiplier. The model has one output Z connected to two different types of sink. All `To Workspace` sinks save the outputs into a single workspace variable `out`. The Scope helps us to see the output sequence in a graph.

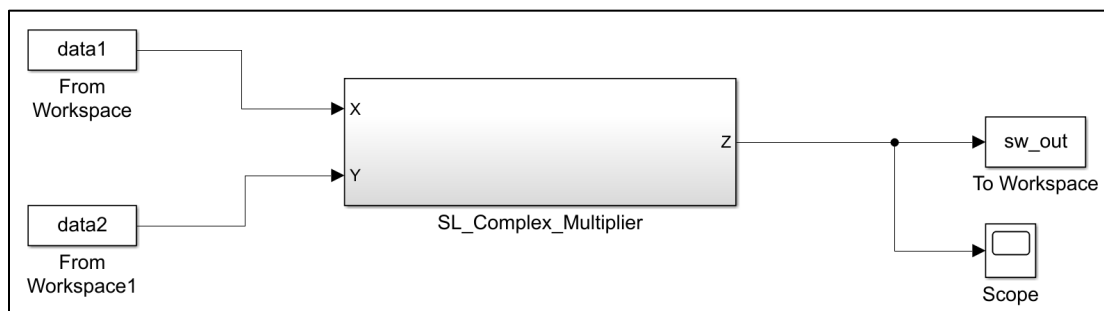


Figure 1: Multiplier model designed using standard Simulink blocks

1-3. Now, you will need to implement the same complex multiplier using HDL Coder blocks from the Simulink library. We will call this implementation `HDL_Complex_Multiplier`. Note that a Simulink model implemented using HDL Coder blocks is a hardware model, which can be later on mapped into hardware targets. The `SL_Complex_Multiplier` and `HDL_Complex_Multiplier` blocks model exactly the same function.

1-4. Open the Simulink library browser using the button shown in Figure 2.

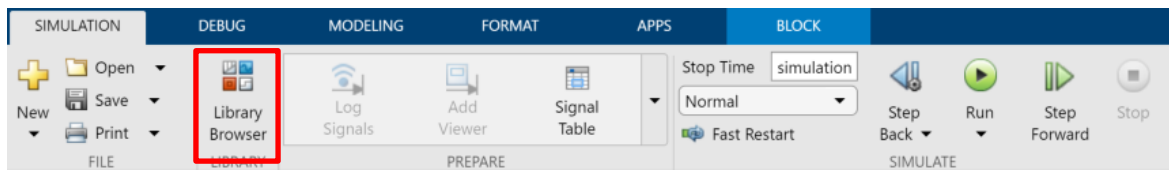


Figure 2: Simulink Library Browser Button

1-5. Expand the HDL Coder Blockset menu (Figure 3), select the Delay block from Commonly Used Blocks. A delay unit with n cycles of delay (Z^{-n}) in a dataflow model represents n stages of pipeline registers in hardware.

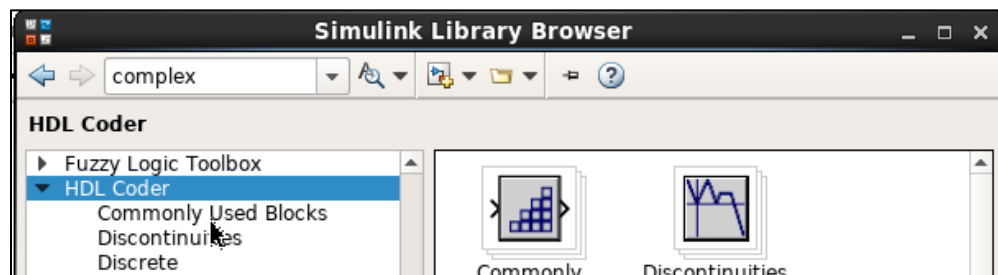


Figure 3: HDL Coder blocks in the Simulink Library Browser

1-6. Right-click the Delay block and select “Add block to model Tutorial1_1.slx”. If you need multiple instances of a block, you can use the Add block to model option from the library browser multiple times. Alternatively, you can go back to your design, right-click on a block, copy and paste. You can press Ctrl on the keyboard and drag a block using a mouse to make a copy as well.

1-7. Similarly, add the following blocks to your design:

Block Name	Library
Delay	HDL Coder -> Commonly Used Blocks
Complex to Real-Imag	HDL Coder -> Math Operations
Real-Imag to Complex	
Product	
Add	
Scope	Simulink -> Sinks
To workspace	

1-8. Figure 4 shows the completed design. Use this figure to make necessary copies of the blocks added from the library browser. Then connect the blocks according to Figure 4 by clicking on the ports.

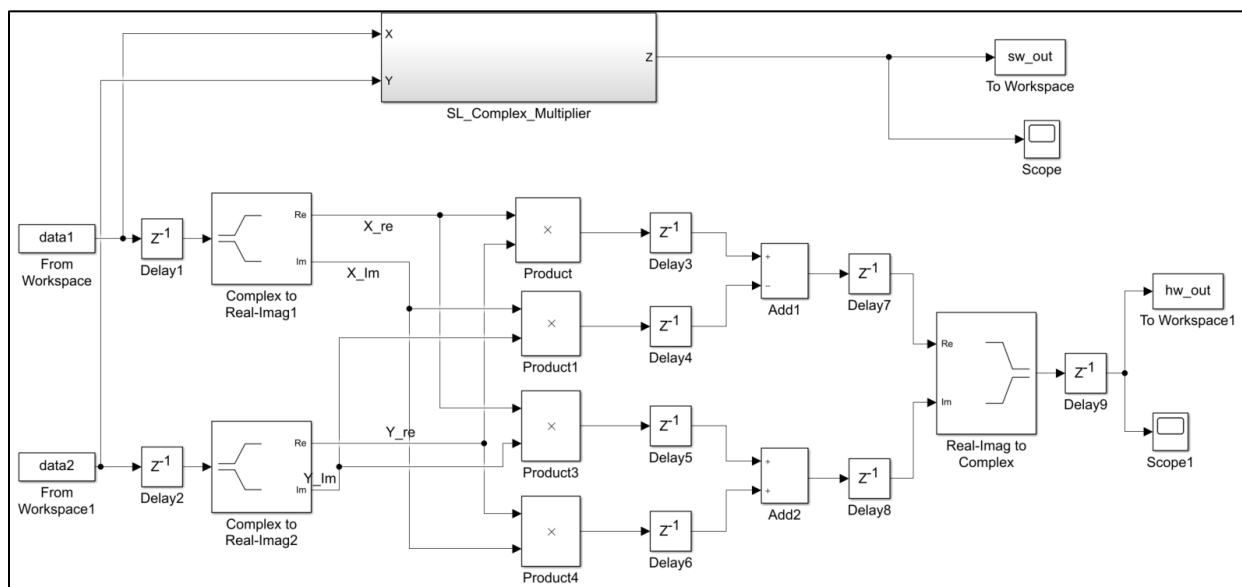


Figure 4: Complete Design

1-9. Double click on the To Workspace block added by you. Rename the block's variable name from simout to hw_out. Change the Save format option to Structure with Time (Figure 5).

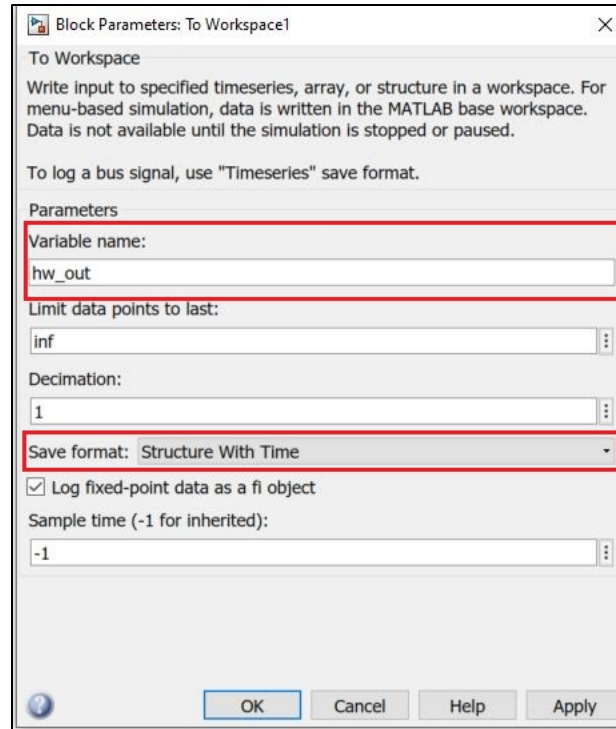


Figure 5: To Workspace Block Parameters

1-10. Define the design boundary that will be synthesized into HDL code. Click and drag using a mouse to select the HDL Coder blocks. Selected blocks will be marked with a blue boundary (Figure 5). Right-click on the selected block and select “Create Subsystem from Selection”.

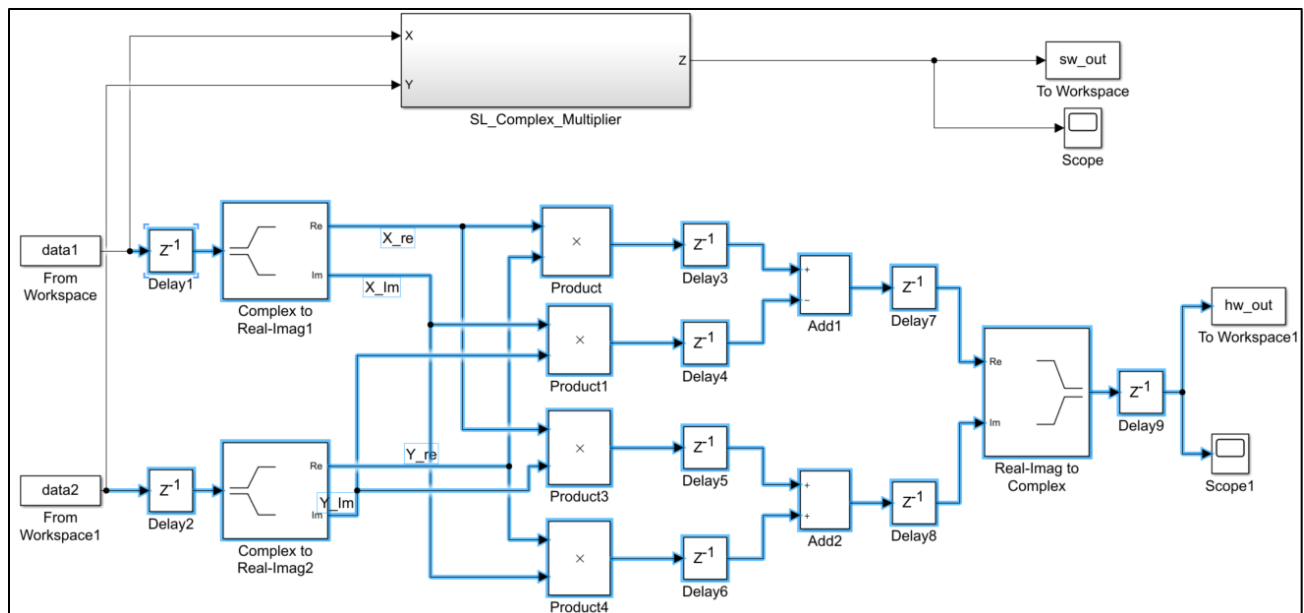


Figure 6: Select HDL Coder Blocks

1-11. Rename the subsystem created to HDL_Complex_Multiplier (Figure 6). Now, the design has both the

software and the hardware models of the complex multiplier. The HDL_Complex_Multiplier block is the hardware model to be synthesized, and the SL_Complex_Multiplier block is the software reference model for functional verification purposes. It is important to note that HDL_Complex_Multiplier is built entirely by HDL coder blocks, as only HDL coder blocks can be synthesized into HDL codes. Differently, the design blocks in SL_Complex_Multiplier are general Simulink blocks that are not synthesizable.

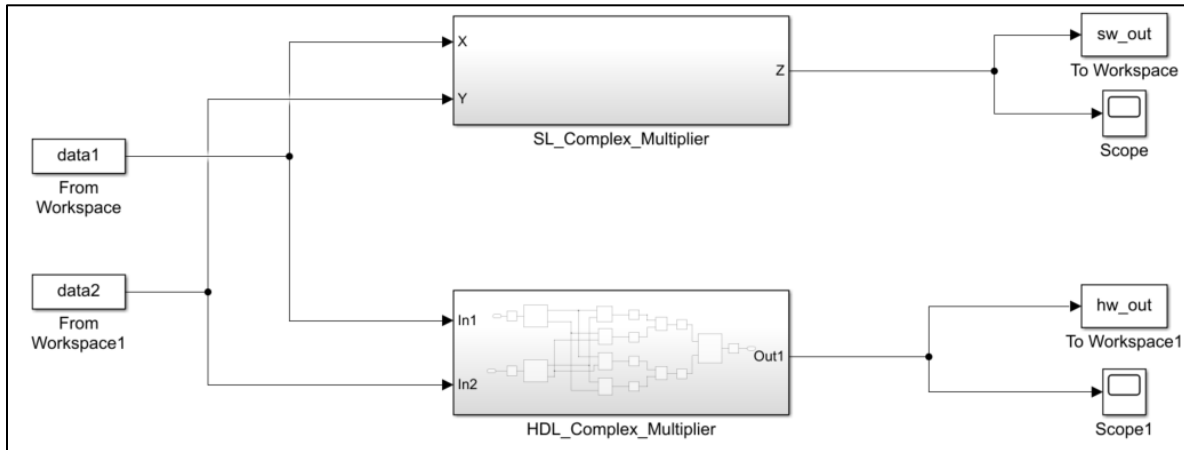


Figure 7: Subsystem HDL_Complex_Multiplier

For more HDL coder blocks, you can find them via Simulink Library Browser->HDL coder. For more guidelines about HDL coder, please refer to the [HDL Coder Evaluation Reference Guide](#).

Task 2: Simulate the Complex Multiplier Design

In this task, you will simulate the complex multiplier design from task 1.

2-1. From the MATLAB window, open the provided script `data_sample_fp.m`. This script is used to generate a sequence of fixed-point complex numbers and send them to the complex multiplier blocks from MATLAB workspace. The script provided to you generates 50 complex numbers. If you want to generate more input samples, you can modify the `num_sample` variable. You can also change the `WordLength` and `FractionLength` of the fixed-point numbers generated to specify a different fixed-point data format. Note that the input sources' variable names (`data1` and `data2`) must match the `From Workspace` block's variable names in the Simulink model.

2-2. Run the 1st section of the MATLAB script using the button shown in Figure 7 to generate random input samples.

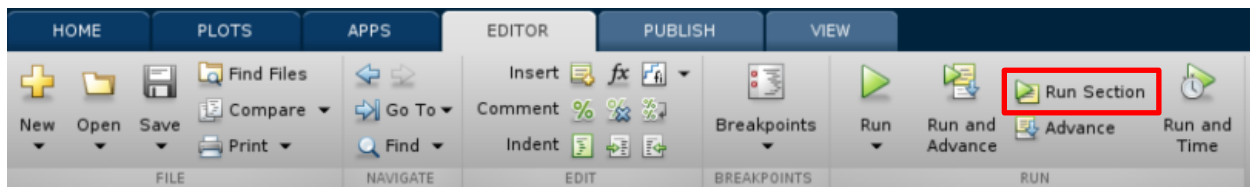


Figure 8: Run MATLAB Script

2-3. The `From Workspace` blocks will show an error "Unrecognized functions or variables" when there are no variables `data1` and `data2` defined in the MATLAB workspace. This error will be automatically fixed after the variables got defined by running the simulation or manually clicking the fix button (Figure 8).

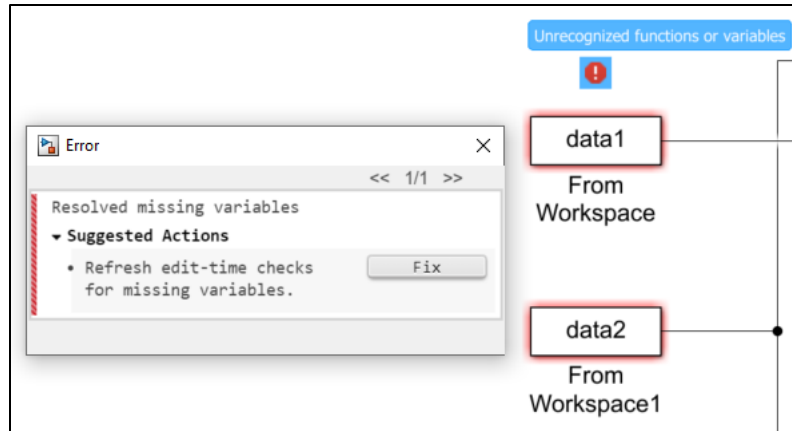


Figure 9: Unrecognized functions or variables error

- 2-4. From your Simulink project worksheet, select **Simulation > Run** or click the **Run** simulation button. Double click on the data source blocks (data1 or data2). See that the sample time we use to feed inputs into our design is specified by the `sample_time` variable, which is defined as $1\mu\text{s}$ (sampling frequency of 1MHz) by the MATLAB script. Also, see that the sample time of the input and output ports in HDL_Complex_Multiplier is specified as -1, which means to inherit the sample time from the previous block. Therefore, the system frequency of the HDL_Complex_Multiplier subsystem is equivalent to 1MHz. The end time of the simulation is specified by the `simulation_stop_time` variable, which is calculated to generate at least 50 samples at the outputs.

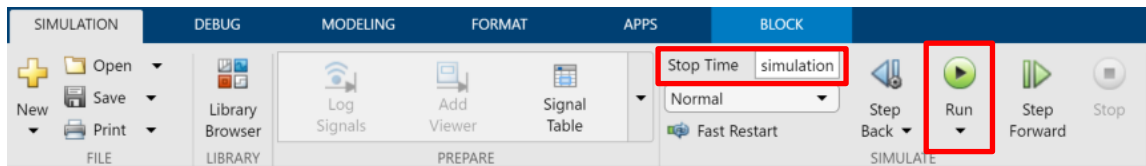


Figure 10: Simulation Run Button and end time

- 2-5. When the simulation completes, you can see that the color of the blocks turns into red, and the port data types are displayed. If you cannot see the data types on the connections, you can enable it by right click, then Other Display->Signals & Ports->Port Data Types. Since the input sources are fixed-point numbers and the rest of the design are inherited from them, the entire design now is running with a fixed-point number.

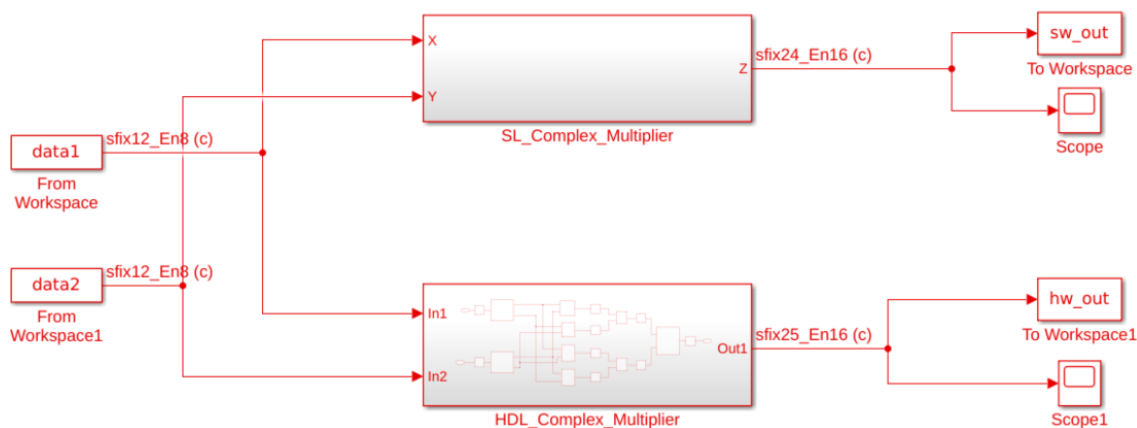


Figure 11: Model after Simulation

2-6. You can view the simulation result either from the workspace or using the Scope. The multiplication results are sent to the workspace by To Workspace blocks. You can check the results by checking the `out` variable in the workspace (Figure 12), which is a `SimulationOutput` object. The output from the `SL_Complex_Multiplier` block is at `out.sw_out.signals.values`, and the output from the `HDL_Complex_Multiplier` block is at `out.hw_out.signals.values`. Figure 12 shows some of the results from the `HDL_Complex_Multiplier` block.

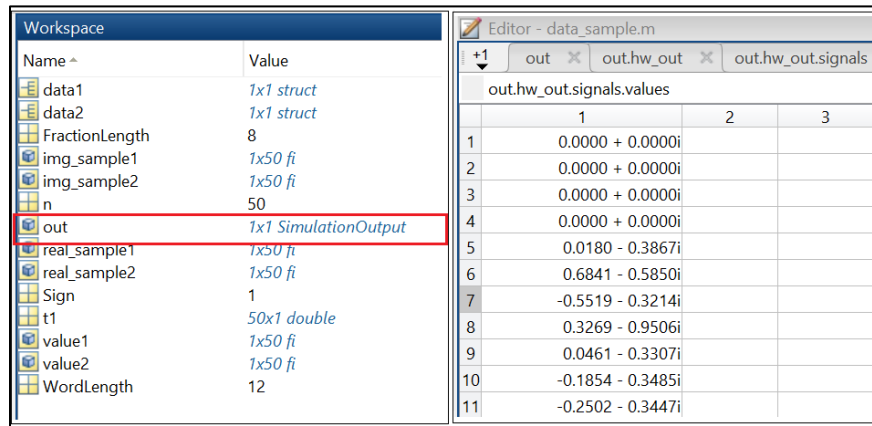


Figure 12: Check simulation results from workspace

It should be noted that the hardware multiplier model has four stages of delay in the design. That is why the output results show a system latency of four clock cycles—the first four output samples are zero (Figure 12).

2-7. Double click on the scopes to view the simulation results as a graph. The results are shown in Figure 13. The Scope on the left-hand side of Figure 13 shows the multiplication result from the software model, and the one on the right-hand side shows the multiplication result from the hardware model. Since there are four stages of delay blocks in the data path, the output graph of the hardware model also shows a system latency of four clock cycles—the first valid result is generated after four clock cycles.

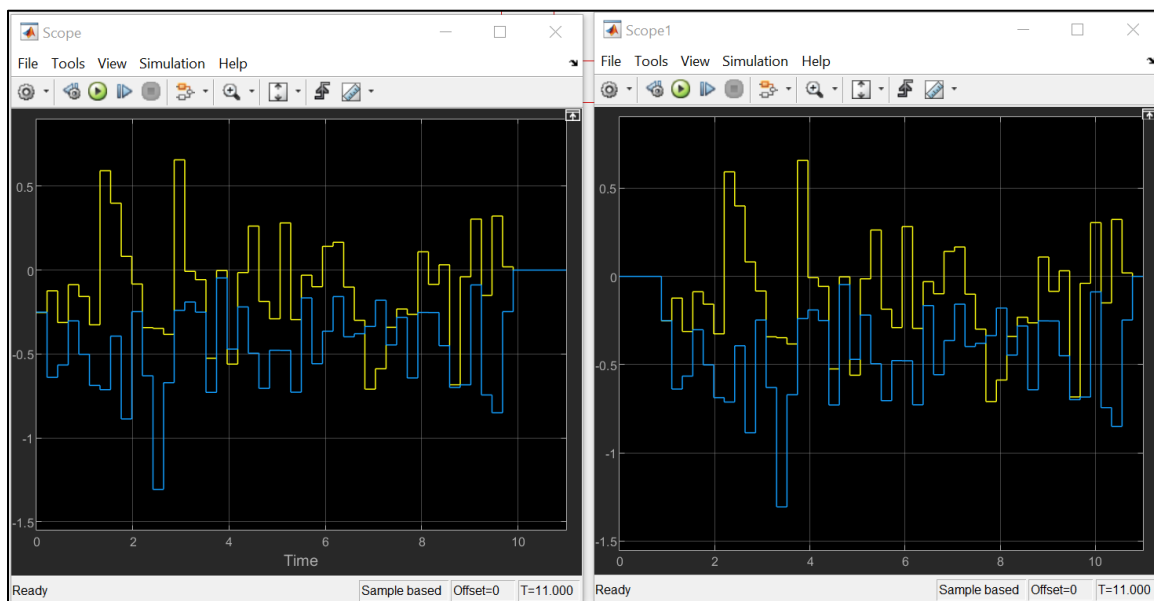


Figure 13: Simulation results as graphs

2-8. Next, we will perform functional verification by checking whether the multiplication results from software

and hardware flows are identical. Double click on the SL_Complex_Multiplier block and add one unit of delay at the input and three units of delay at the output to match the system latency of the hardware model. The modified design is shown in Figure 14.

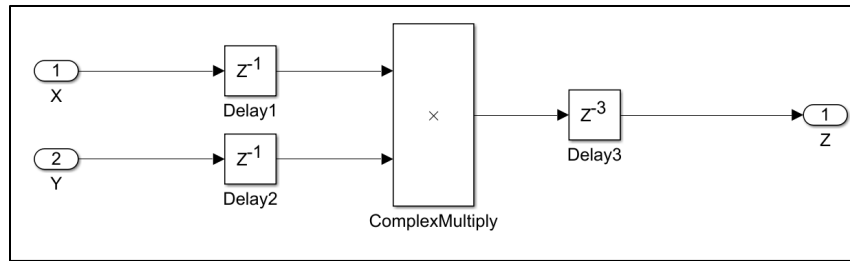


Figure 14: Modified SL_Complex_Multiplier

2-9. Run the 2nd section of the MATLAB script to compare the outputs of the hardware model against the software ones. If the outputs are identical, the functional verification is successful (Figure 15).

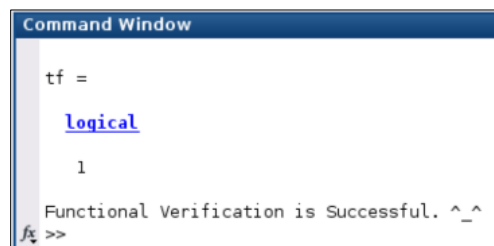


Figure 15: Compare results from SW and HW flows

The 3rd section of the MATLAB script provides another example code to compare the outputs of the hardware Simulink model against the outputs of a MATLAB reference model for the same functional verification purpose.

You can also check the scopes and observe that the graphs are identical now. Both graphs should have a 4 unit time delay before the first valid output.

Task 3: Generate VHDL/Verilog Wrapper and Create An Hardware Resource Estimate for an FPGA Target

The task is to implement this design in hardware. This process will synthesize the HDL_Complex_Multiplier subsystem into hardware description language (HDL) codes. The HDL codes can be in either Verilog or VHDL. This process is controlled by the **HDL Workflow Advisor**. With HDL Workflow Advisor, you can synthesize your design without launching the synthesis tool manually.

3-1. First, use `hdlsetuptoolpath` command to add the path for Xilinx Vivado to MATLAB. The command needs to be run once per MATLAB session. You can save it in a MATLAB script.

```
hdlsetuptoolpath('ToolName', 'Xilinx Vivado',  
'ToolPath', '/usr/local/Xilinx-2019.2/Vivado/2019.2/bin');
```

3-2. Right-click the HDL_Complex_Multiplier block, then select HDL Code->HDL Workflow Advisor.

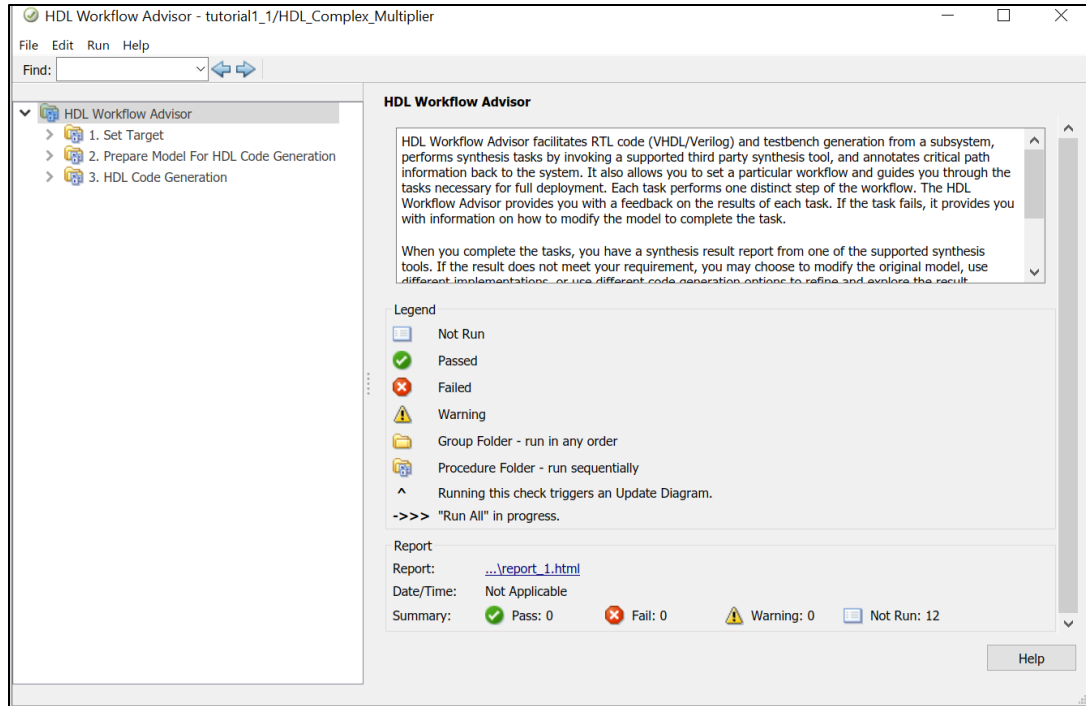


Figure 16: HDL Workflow Advisor

3-3. In 1.1 Set Target Device and Synthesis Tool, set your desired workflow, hardware target, and synthesis tool. For design iterations through synthesis, use the default Generic ASIC/FPGA in Target workflow.

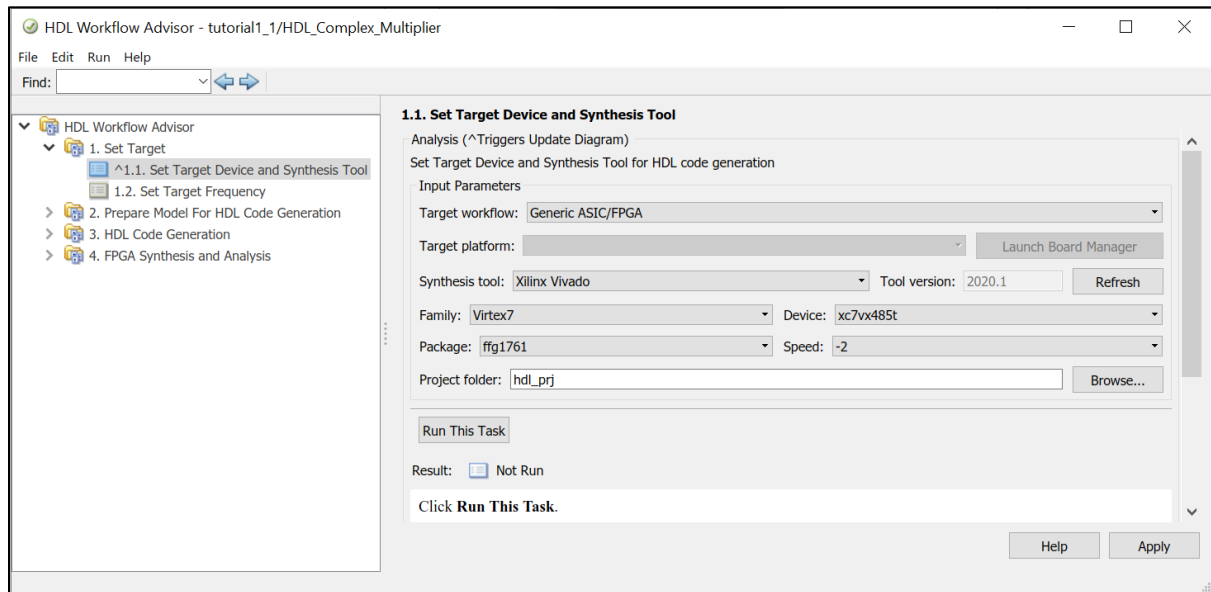


Figure 17: Set target device and tool

3-4. For FPGA targets: Specify FPGA Device details for which you want to do resource estimation. You can use the FPGA target in Figure 17 as an example.

3-5. After configuration, click “Run This Task”. This button will be clicked at the end of each workflow step.

3-6. Set Target Frequency. The target frequency here can be different from the sample time you use in

the Simulink block. This is the FPGA target frequency (HDL clock) that will be used in synthesis. Please use 100 MHz for this example.

In Simulink block, for a single-rate model, 1 sample time in Simulink maps to 1 clock cycle in HDL. You can use a relative mapping (e.g., 1 second in Simulink = one HDL clock cycle) or an absolute mapping (e.g., 10e-9 second in Simulink = one HDL clock cycle), depending on your preference and design requirement.

For more information, please refer to Section 2.1 of the [HDL Coder Evaluation Reference Guide](#).

- 3-7.** In step 2 of the workflow (Prepare Model for HDL Code Generation), select Run All. This step performs some basic checks on the design like checking algebraic loop, sample time, and compatibility of the blocks for HDL generation.
- 3-8.** In step 3.1.1, you can choose the desired HDL for your hardware description. Here, we choose Verilog.
- 3-9.** In step 3.1.2, you can choose to generate optional reports for the HDL code generation. Refer to Section 3.4.1 of the [HDL Coder Evaluation Reference Guide](#) for more details.
- 3-10.** In step 3.1.3, you can set advanced options on details of the HDL code generation, such as synchronous or asynchronous, active-low or active-high reset, clock settings, naming conventions, coding style, etc. Here, we use the default.
- 3-11.** In step 3.1.4, you can choose to apply several architectural optimizations, including pipelining and resource sharing, to optimize for performance or area cost. Here, we use the default. Refer to Section 3.3.4 of the [HDL Coder Evaluation Reference Guide](#) for more details about the pipelining options.
- 3-12.** In step 3.1.5, Set the Testbench Options, as shown in Figure 18. Then, select 3.1 and click Run All.

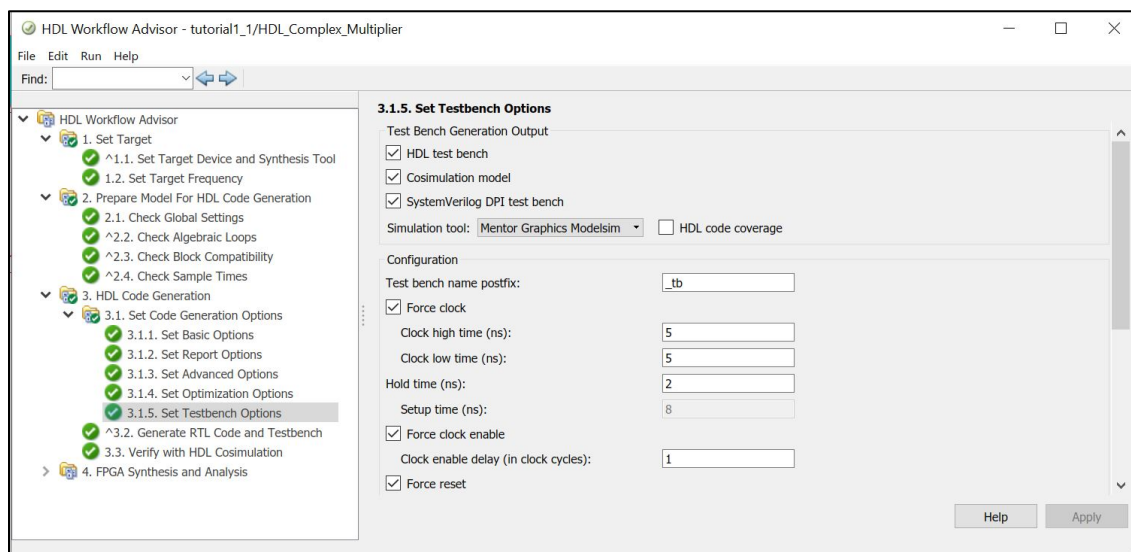


Figure 18: Set testbench option

- 3-13.** In step 3.2 Generate RTL code and Testbench, check the options related to testbench generation, as shown in Figure 19. Click Run this task. Note that a new Simulink model for HDL cosimulation is created and pops up upon the completion of this task.

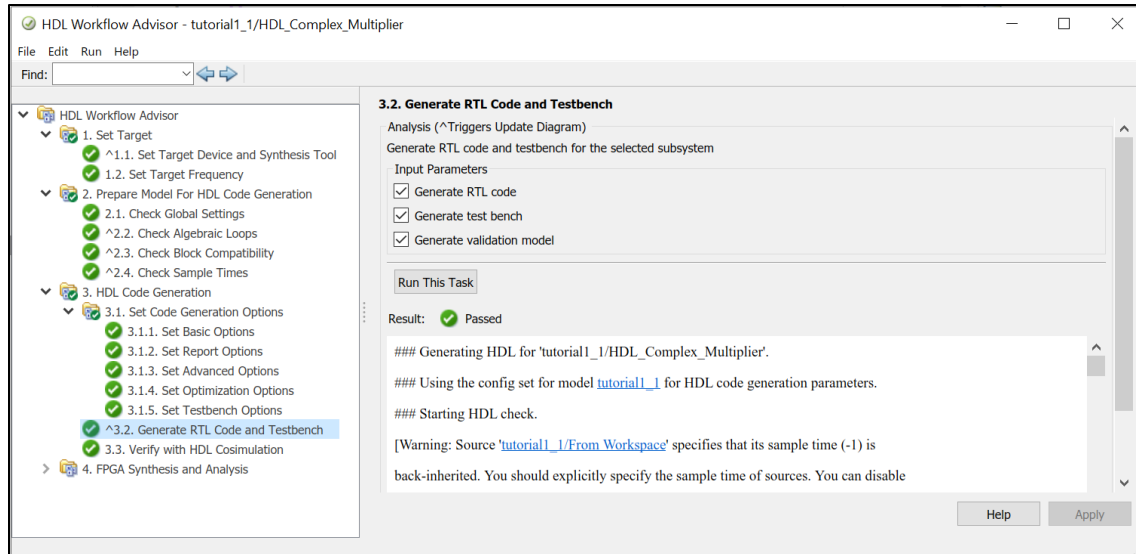


Figure 19: Generate RTL and Testbench options

3-14. Select step 3.3 and click on Run this task. This step uses the Simulink testbench generated in the previous step to perform HDL cosimulation using ModelSim to verify the functionality of the generated HDL codes. After the cosimulation is finished, a message Passed HDL Cosimulation is displayed (Figure 20). Two graphs also pop up, which show the comparison between the real and imaginary outputs from the Simulink and the HDL simulations, respectively. (Figure 21).

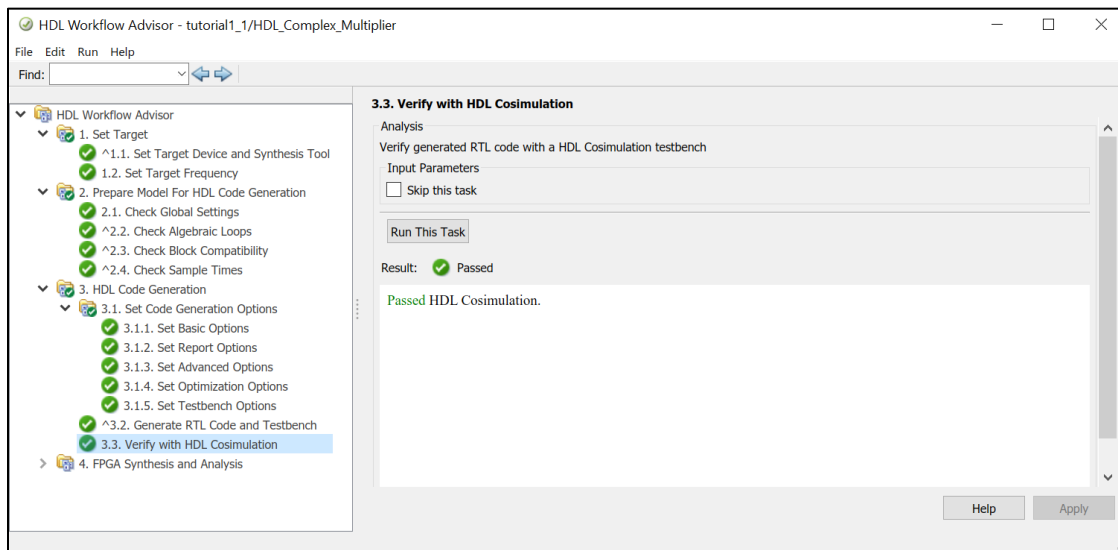


Figure 20: HDL Cosimulation

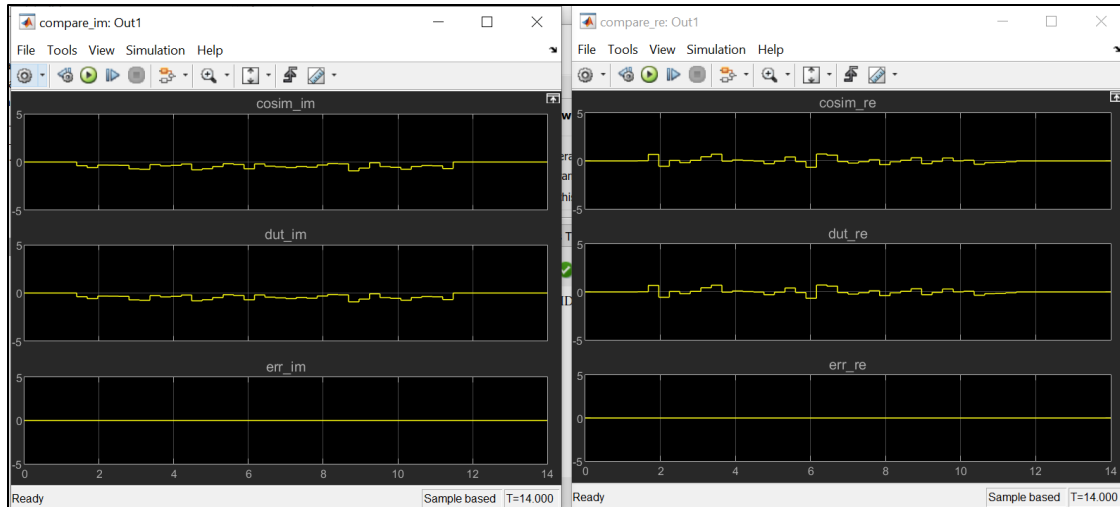


Figure 21: Comparison of cosimulation results

3-15. Click “run all” in step 4 FPGA Synthesis and Analysis. This step creates a Vivado project and performs the synthesis in the background. **Note that Vivado cannot work with a project folder that contains any space in its path.** So make sure you are running your HDL Workflow Advisor under a work folder with no space in its path. Otherwise, the project creation will fail and Vivado run will fail.

When the synthesis run is completed, you can check the post-synthesis resource utilization and timing summaries from the synthesis results (Figure 22). By default, the implementation stage (placement and routing) is skipped. If you want to run the implementation stage after synthesis, uncheck the “Skip this task” option in step 4.2.2.

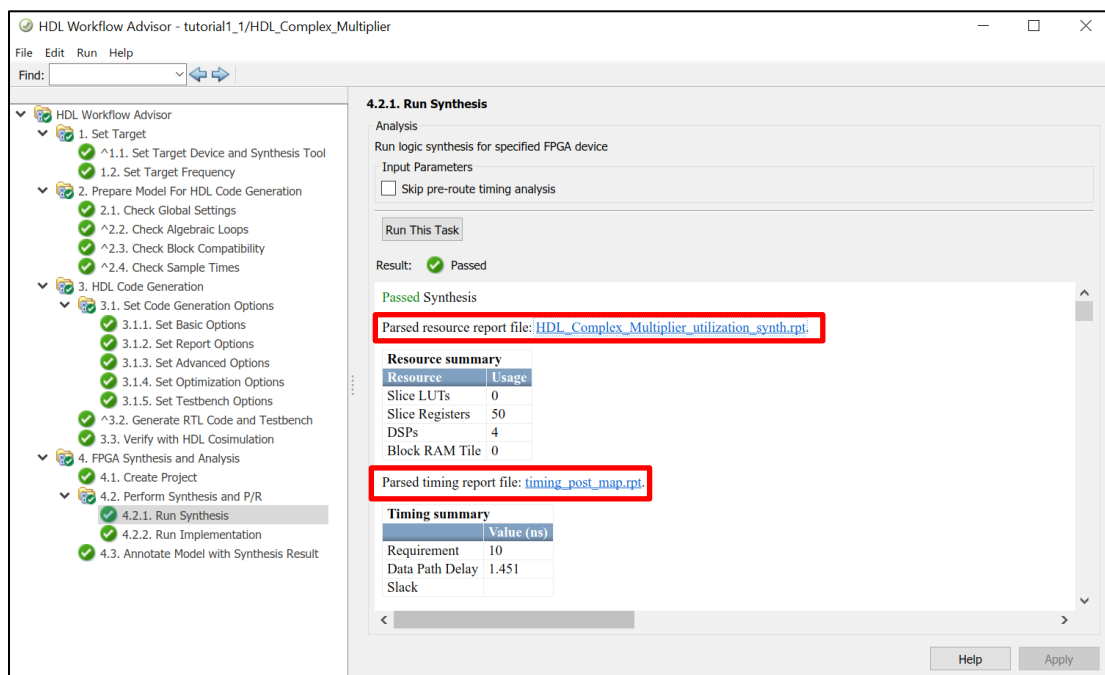


Figure 22: Result Summary

- 3-16.** You can click on the parsed resource and timing report files for detailed reports (Figure 22). In the resource report, you can see a list of used and available resources on the FPGA, as well as the percentage of resource utilization. In the timing report, you can check the worst-case setup and hold time slacks and details of the maximum and minimum delay paths. Under the Design Timing Summary section of the timing report, the WNS (ns) value is the worst-case setup time slack, and the WHS (ns) value is the worst-case hold time slack.
- 3-17.** If you need to run FPGA synthesis and implementation manually in Vivado and/or want to see other details of synthesized and/or implemented design and/or perform bit file generation with valid pin-mapping constraints, you can open the created Vivado Project inside the `hdl_prj` folder using the Xilinx Vivado tool to proceed further. You can also check the power report of the design after running the implementation in Vivado (Figure 23).

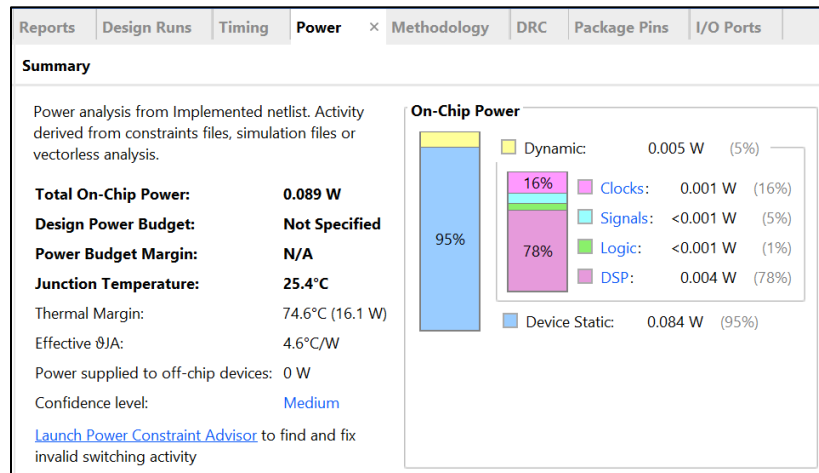


Figure 23: Power report from Vivado Project

Task 4: Generate VHDL/Verilog Wrapper and Create Hardware Resource Estimate for an ASIC Target

- 4-1. For ASIC targets:** Launch a new HDL Workflow Advisor. In 1.1 Set Target Device and Synthesis tool, apply the settings as shown in the figure below. Change the folder name to `hdl_prj_asic` so that you don't overwrite the FPGA synthesis results.

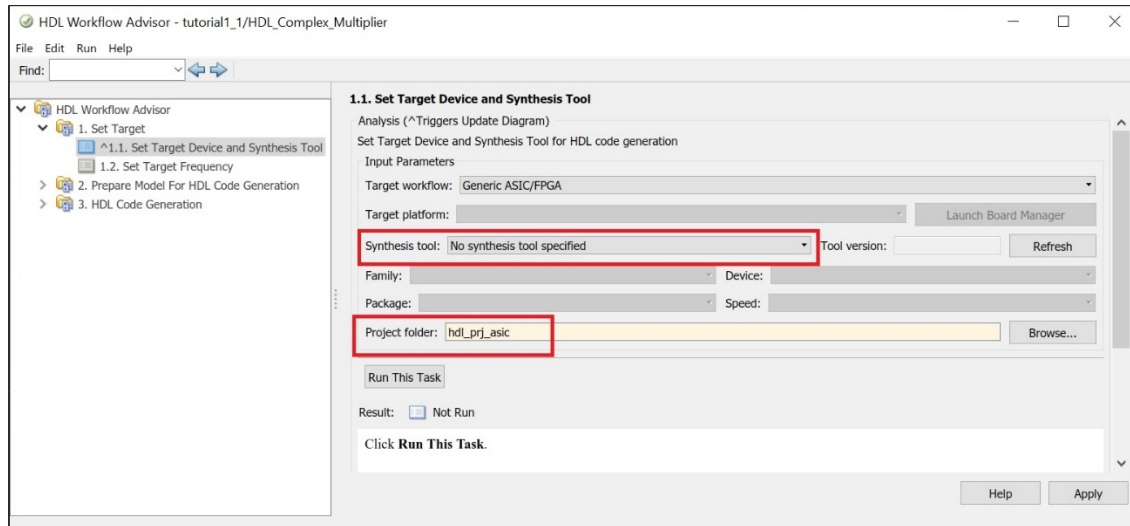


Figure 24: ASIC Target

4-2. In step 1.2, set the target frequency to zero. Follow the rest steps as in the FPGA target flow. The HDL cosimulation shall pass (Figure 25).

Unlike the FPGA target flow, there will be no synthesis step in the HDL workflow advisor since the ASIC synthesis will be performed using a separate tool—Synopsys Design Compiler. Since no synthesis tool is specified, the target frequency setting in this step is useless. We will specify the target frequency for synthesis later on using a Synopsys Design Compiler constraint file (.sdc) instead.

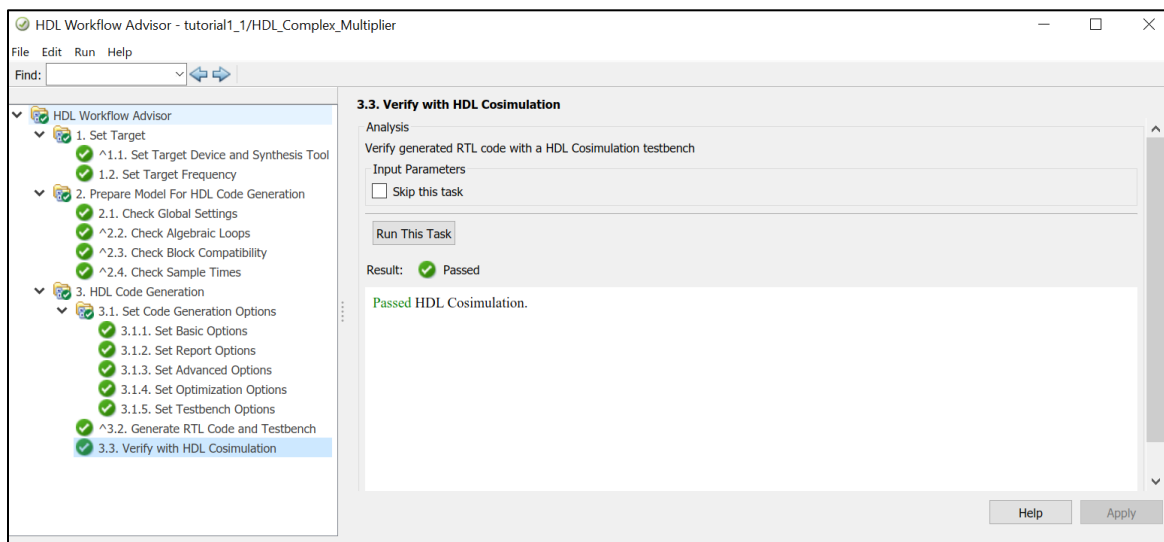


Figure 25: HDL Workflow Advisor for the ASIC flow

4-3. Download the provided template_dc.tcl and template_dc.sdc and place them under the same folder where the generated VHDL/Verilog files are (under hdl_prj_asic/hdlsrc/tutorial1_1_sol). And rename the two files with the name of the HDL Simulink model as <HDL_Name>_dc.tcl and <HDL_Name>_dc.sdc, where the <HDL_Name> is HDL_Complex_Multiplier in this Tutorial.

4-4. Modify following lines in the <HDL_Name>_dc.tcl.

```
set DESIGN_NAME top_level_module_name -> set DESIGN_NAME <HDL_Name>
```

```
source "/path/to/a_dc_setup_file.setup" -> source "<specify the full path to the chosen DC setup file>"
```

- 4-5.** The design compiler (DC) setup file defines the standard cell libraries for timing and power analysis and the process, voltage, and temperature (PVT) corner for setup and hold time analysis, respectively. To get you started with ASIC synthesis, we have provided three different DC setup files (DC_setup_28nm_1v.setup, DC_setup_28nm_0p85v.setup and DC_setup_28nm_0p75v.setup). These setup files are configured to load the Synopsys 28nm generic library that includes standard VT (SVT), low VT (LVT), and high VT (HVT) cells. This will allow you to run leakage optimization in DC, which first synthesizes your design using HVT cells only and then insert SVT/LVT cells into the critical paths to improve timing (all with sizing optimization). To allow you to explore voltage scaling on your design, the three setup file is configured for a supply voltage of 1V (typical voltage), 0.85V (middle voltage), and 0.75V (low voltage), respectively. So, the choice of the setup file depends on the supply voltage that you want to run your design under. For this tutorial, we choose the 1V setup file DC_setup_28nm_1v.setup. Specify the setup file in the last line of Step **4-4**.

You can change or modify the setup file to run synthesis again and observe the difference in results.

- 4-6.** The provided .sdc file defines a 800MHz clock as the system clock. To synthesize the design for a different clock frequency, you will need to modify the clock period defined in the .sdc file. Synthesize the design at 800MHz, 400 MHz, and 200MHz, respectively, and notice the difference in results due to circuit-level optimizations.

- 4-7.** Type following command in the terminal to do ASIC synthesis.

```
$ dc_shell -f <Project_Name>_dc.tcl
```

- 4-8.** The reports on Power, Area, and Timing can be found under the “Report” folder created in the project folder.

- 4-9.** Figure 26 shows an example power report (.mapped.power.rpt). You can observe the total dynamic power and cell leakage power from the report. The breakdown of dynamic power into cell internal power and switching power and their percentages are shown. The contribution of the sequential and combinational logic to the total power is shown in the table. The unit of dynamic and leakage power is in micro-watts (mW) and picowatts (pW), respectively.

The switching power of a driving cell is the power dissipated by the charging and discharging of the load capacitance at the output of the cell. The total load capacitance at the output of a driving cell is the sum of the net and gate capacitances on the driving output.

Internal power is any power dissipated within the boundary of a cell. During switching, a circuit dissipates internal power by the charging or discharging of any existing capacitances internal to the cell. Internal power also includes power dissipated by a momentary short circuit between the P and N transistors of a gate, called short-circuit power.

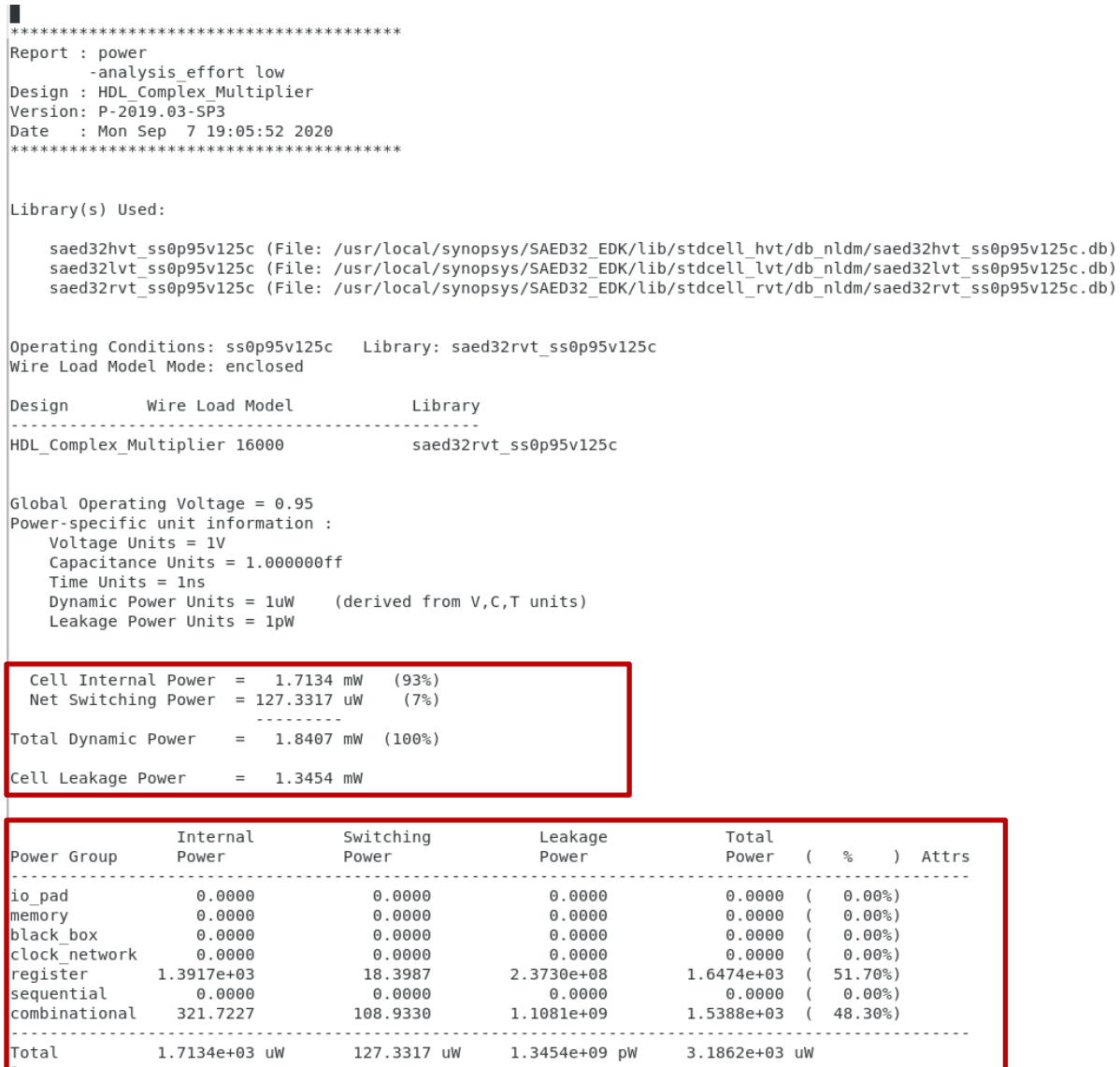


Figure 26: Example Power Report

4-10. Figure 27 shows an example area report (.mapped.area.rpt). From the area report, you can see the number of ports, nets, cells, and buffers in your design. You can also observe the total area and the breakdown of the area into different components of the circuits. The unit of area is square micrometer (μm^2).


```

*****
Report : area
Design : HDL_Complex_Multiplier
Version: P-2019.03-SP3
Date   : Mon Sep  7 19:05:52 2020
*****

Information: Updating design information... (UID-85)
Library(s) Used:

saed32hvt_ss0p95v125c (File: /usr/local/synopsys/SAED32_EDK/lib/stdcell_hvt/db_nldm/saed32hvt_ss0p95v125c.db)
saed32lvt_ss0p95v125c (File: /usr/local/synopsys/SAED32_EDK/lib/stdcell_lvt/db_nldm/saed32lvt_ss0p95v125c.db)
saed32rvt_ss0p95v125c (File: /usr/local/synopsys/SAED32_EDK/lib/stdcell_rvt/db_nldm/saed32rvt_ss0p95v125c.db)

Number of ports:                102
Number of nets:                 3688
Number of cells:                3259
Number of combinational cells:  2965
Number of sequential cells:     292
Number of macros/black boxes:   0
Number of buf/inv:              327
Number of references:           82

Combinational area:             7918.364590
Buf/Inv area:                   434.332098
Noncombinational area:         1939.627069
Macro/Black Box area:          0.000000
Net Interconnect area:         2234.398665

Total cell area:                 9857.991660
Total area:                     12092.390324

```

Figure 27: Example area report

4-11. Figure 28 shows an example timing report (.mapped.timing.rpt). You can observe the critical path of your design and whether the timing requirement of the critical path is satisfied with a positive or zero slack.

```

*****
Report : timing
        -path full
        -delay max
        -max_paths 1
Design : HDL_Complex_Multiplier
Version: P-2019.03-SP3
Date   : Mon Sep  7 19:05:52 2020
*****

Operating Conditions: ss0p95v125c  Library: saed32rvt_ss0p95v125c
Wire Load Model Mode: enclosed

Startpoint: X_Im_reg[6]
            (rising edge-triggered flip-flop clocked by clk)
Endpoint: Product4_out1_1_reg[20]
            (rising edge-triggered flip-flop clocked by clk)
Path Group: clk
Path Type: max

Des/Clust/Port      Wire Load Model      Library
-----
HDL_Complex_Multiplier
16000                                saed32rvt_ss0p95v125c

Point                                     Incr      Path
-----
clock clk (rise edge)                    0.00      0.00
clock network delay (ideal)              0.00      0.00
X_Im_reg[6]/CLK (DFFX1_LVT)              0.00      0.00 r
X_Im_reg[6]/QN (DFFX1_LVT)              0.13      0.13 r
U1380/Y (NOR2X0_RVT)                    0.10      0.24 f
U2167/Y (XNOR2X2_RVT)                   0.09      0.33 r
U476/S (FADDX1_RVT)                     0.15      0.49 f
U384/Y (XOR3X1_LVT)                     0.14      0.63 f
U364/Y (XOR3X1_LVT)                     0.13      0.76 f
U2238/Y (AND2X1_LVT)                     0.05      0.81 f
U490/Y (INVX1_RVT)                       0.03      0.84 r
U2236/Y (NAND4X0_LVT)                   0.04      0.88 f
U2233/Y (NAND4X0_LVT)                   0.04      0.92 r
U503/Y (INVX1_LVT)                       0.03      0.95 f
U511/Y (INVX2_LVT)                       0.03      0.98 r
U2357/Y (NAND3X0_LVT)                   0.03      1.01 f
U2356/Y (NAND3X0_LVT)                   0.04      1.05 r
U502/Y (XNOR2X2_LVT)                   0.07      1.12 r
U2355/Y (A022X1_LVT)                   0.04      1.16 r
Product4_out1_1_reg[20]/D (DFFX1_HVT)   0.00      1.16 r
data arrival time                        1.16

clock clk (rise edge)                    1.25      1.25
clock network delay (ideal)              0.00      1.25
Product4_out1_1_reg[20]/CLK (DFFX1_HVT) 0.00      1.25 r
library setup time                       -0.08      1.17
data required time                       1.17

data required time                       1.17
data arrival time                       -1.16

slack (MET)                             0.00

```

Figure 28: Example Timing Report

4-12. Figure 29 shows an example threshold voltage group report (.mapped.vth.rpt), which shows the percentage breakdown of the logic gates (standard cells) in each threshold flavor used in the synthesized design.

```
*****
Threshold Voltage Group Report
*****
```

Vth Group Name	All cells	Blackbox cells	Non-blackbox cells
hvt	997 (31.74%)	0 (0.00%)	997 (31.74%)
lvt	929 (29.58%)	0 (0.00%)	929 (29.58%)
nvt	1215 (38.68%)	0 (0.00%)	1215 (38.68%)
Total	3141 (100.00%)	0 (0.00%)	3141 (100.00%)

```
*****
Vth Group Name
```

Vth Group Name	All cell area	Blackbox cell area	Non-blackbox cell area
hvt	2929.01 (31.43%)	0.00 (0.00%)	2929.01 (31.43%)
lvt	3165.11 (33.96%)	0.00 (0.00%)	3165.11 (33.96%)
nvt	3225.34 (34.61%)	0.00 (0.00%)	3225.34 (34.61%)
Total	9319.46 (100.00%)	0.00 (0.00%)	9319.46 (100.00%)

```
*****
```

Figure 29: Example Timing Report

Grading Rubrics

Criteria	Inspection Item	Point
Design Correctness	Completed model of complex multiplier using HDL Coder blocks.	20
	Successful verification of HW model against the SW or MATLAB model.	20
FPGA Synthesis	HDL code generation for FPGA is successful.	10
	FPGA design synthesis is successful.	20
ASIC Synthesis	HDL code generation for ASIC is successful.	10
	Correct timing, power and area reports are generated.	20
Total		100

Due Date

Refer to Canvas.

Instructions on Submission

- A submission should include the MATLAB project folder containing the following items:
 - The completed Simulink model containing the HDL_Complex_Multiplier design.
 - The MATLAB script `data_sample_fp.m`.
 - The folder (`hdl_prj`) containing the Vivado Project and the HDL codes generated for FPGA synthesis and FPGA synthesis results.
 - The folder (`hdl_prj_asic`) containing the Design Compiler run files and the HDL codes generated for the ASIC Synthesis and all ASIC synthesis reports.
- Compress the files and folders into a single zip archive file named **cen571-firstname_lastname-tut1.zip**. Note that any other codes or any temporary build files should not be included in the submission.
- Submit the zip archive to Canvas by the due date and time.
- Failure to follow these instructions may cause the TA or instructor to deduct points while grading your assignment.