

Computer Architecture CSF342

Lab sheet 1

Topic: Introduction to MARS simulator and basic MIPS programming

Computer Architecture Lab: Introduction to MARS (MIPS Assembler and Runtime Simulator)

Lab 1: Basic MIPS Assembly Programming

1. Introduction to MARS

MARS is a lightweight simulator for the MIPS assembly language. It allows you to:

- Write, assemble, and run MIPS code.
- Debug programs step-by-step.
- Inspect registers, memory, and system resources.

Know more about MARS from here: <https://dpetersanderson.github.io/>

2. Starting MARS in Ubuntu

1. **Prerequisites:** Ensure Java is installed:



```
sudo apt install openjdk-17-jre
```

2. **Run MARS:** Open a terminal and execute:

```
java -jar Mars4_5.jar # Replace with your MARS .jar filename
```

The MARS GUI will launch.

3. Basic Operations

- **Create a New File:** Click **File** > **New** to open an editor.
- **Write Code:** Type MIPS assembly code (save as *.s).
- **Assemble:** Click  (or press **F3**).
- **Execute:** Click  (or press **F5**).

Key Settings:



- **"Assemble all":** Combines **.text** (code) and **.data** (variables) segments.
- **"Initialize Program Counter":** Sets starting execution point (default: **0x00400000**).

4. Memory Segments

- **Text Segment:** Stores your code (instructions).
- **Data Segment:** Stores global variables and strings.
 - Example:

```
.data  
msg: .asciiz "Hello World!"    # Declares a string in data segment
```

5. Execution Modes

- **Run All:** Executes the entire program at once (use ).
 - **Step-by-Step:** Debug line-by-line (use ).
 - Observe changes in registers after each instruction.
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6. Side Panels

- **Registers Panel:** Shows values of all 32 MIPS registers ($\$t0$, $\$s0$, etc.).
 - **Coprocessor 1 (FPU):** Handles floating-point operations.
 - **Memory Panel:** Displays content of **data** and **text** segments.
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7. I/O via Syscalls

Use **syscall** to interact with the console:

1. Load service code into $\$v0$.
2. Set arguments (e.g., $\$a0$ = address of string).
3. Execute **syscall**.

Service	$\$v0$ - control register	Arguments
Print integer	1	$\$a0$ = integer
Print string	4	$\$a0$ = address of string
Read integer	5	Input saved to $\$v0$
Exit	10	Terminates program

8. Example 1: Hello World

```
.data
msg: .asciiz "Hello World!"    # String declaration

.text
main:
    li $v0, 4                # Service 4: print string
    la $a0, msg              # Load address of 'msg'
    syscall                  # Execute
    li $v0, 10               # Service 10: exit
    syscall
```

To Run: Assemble → Execute. Output appears in the "Run I/O" console.

9. Example 2: Hardcoded Adder

```
.text
main:
    li $s0, 5                # Load 5 into $s0
    li $s1, 3                # Load 3 into $s1
    add $t0, $s0, $s1        # $t0 = $s0 + $s1

    # Print result
    li $v0, 1                # Service 1: print integer
    move $a0, $t0            # Copy $t0 to $a0
    syscall

    li $v0, 10               # Exit
    syscall
```

10. Lab Task: User-Input Adder

Modify the adder to:

1. Prompt the user for two integers.
2. Read the integers.
3. Compute and print their sum.

Hint: Use `syscall` services 4 (print string), 5 (read integer), and 1 (print integer).

```
.data
msg1: .asciiz "Enter first number : "
msg2: .asciiz "Enter second number : "
msg3: .asciiz "sum : "

.text
main:
    li $v0, 4
    la $a0, msg1
```

syscall

```
li $v0, 5
syscall
move $s0, $v0
```

```
li $v0, 4
la $a0, msg2
syscall
```

```
li $v0, 5
syscall
```

```
move $s1, $v0
```

```
add $t0, $s0, $s1
```

```
li $v0, 4
la $a0, msg3
syscall
```

```
li $v0, 1
move $a0, $t0
syscall
```

```
li $v0, 10
syscall
```

Example Workflow:

```
Enter first number: 5
Enter second number: 3
Sum = 8
```

Appendix: MARS Settings and Help Manual

A.1 Key MARS Settings (Bulleted Overview)

- **Assemble all:** Combines `.text` (code) and `.data` (variables) segments into one executable.
- **Initialize Program Counter to global 'main' if defined:** Sets start address to `main` label (else defaults to `0x00400000`).
- **Permit extended (pseudo) instructions:** Enables simplified instructions (e.g., `move`, `li`) that translate to core MIPS commands.

- **Delayed branching:** Simulates MIPS pipeline behavior (disable for simplicity in beginners' labs).
 - **Self-modifying code:** Allows code to alter itself during runtime (advanced; keep disabled).
 - **Highlight execution path:** Colors the next instruction to execute during step-by-step debugging.
 - **Popup dialog for input syscalls:** Opens a separate window for user input (disable to use the console).
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A.2 Help Manual (F1) Overview

The built-in help manual (`HeLp` → `HeLp` or `F1`) provides:

- **Basic Instructions:**
Core MIPS commands (e.g., `add`, `lw`, `beq`) with syntax and usage examples.
- **Pseudo-Instructions:**
Simplified commands translated to core instructions (e.g., `move $t0, $t1` → `add $t0, $t1, $zero`).
- **Directives:**
Assembly-time controls (e.g., `.data`, `.ascii`, `.word`) for data allocation and program structure.
- **Syscalls:**
Complete list of I/O services (e.g., `$v0=1` prints integer; `$v0=8` reads string) with argument requirements.
- **Troubleshooting:**
Common errors (e.g., alignment issues, undefined labels) and debugging tips.

Tip: Use `F1` as a quick reference during coding!

Early habits to Adopt (as suggested by deepseek) will be needed in future.

Pro Tips for MIPS Assembly Programming

Adopt these habits from Day 1 to write cleaner, more efficient, and debuggable code:

1. Comment Religiously

```
add $t0, $s1, $s2    # $t0 = current_score + bonus (avoid "adds s1 and s2")
```

- **Why:** Assembly is opaque. Explain the **purpose** (e.g., "calculating total score"), not just the operation.
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2. Use Labels, Not Magic Numbers

✗ `li $v0, 4`
✓ `li $v0, 4 # syscall: print_string`

- **Better:** Define constants:

```
.eqv PRINT_INT 1  
.eqv EXIT 10
```

Then use: `li $v0, PRINT_INT`

3. Stick to Register Conventions

Register	Purpose
<code>\$t0-\$t9</code>	Temporaries (caller-saved)
<code>\$s0-\$s7</code>	Saved values (callee-saved)
<code>\$a0-\$a3</code>	Arguments
<code>\$v0-\$v1</code>	Return values/syscalls

- **Why:** Prevents bugs in larger programs and nested calls.
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4. Always Exit Cleanly

```
end_program:  
  li $v0, 10   # syscall: exit  
  syscall
```

- **Why:** Prevents "falling off" into undefined memory.
-

5. Test Incrementally

After writing 3-5 lines:

1. **Assemble** (check for syntax errors).
 2. **Step-through** (verify register values).
- **Tip:** Set breakpoints early.
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6. Isolate Subroutines

Good structure:

```

.text
main:
    ...
    jal get_input    # Jump to subroutine
    ...

get_input:          # Subroutine
    ...
    jr $ra           # Return

```

7. Initialize Registers

✗ Assuming `$s0` is 0 at startup.

✓ Explicitly set:

```

start:
    li $s0, 0        # Initialize counter

```

- **Why:** Simulators may not zero registers.
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8. Use MARS Features

- **Auto-complete:** Press `Ctrl+Space` for directives/syscalls.
 - **Debugger:** Set breakpoints (click left margin) to pause at critical points.
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9. Avoid Pseudo-Instructions Early

✗ `move $t0, $t1` (pseudo-instruction)

✓ `add $t0, $t1, $zero` (core instruction)

- **Why:** Deepens understanding of MIPS internals.
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10. Sanitize User Input

After `syscall` reads:

```

# Example: Check if input is negative
blt $v0, $zero, invalid_input

```

- **Why:** Prevents overflow/logic errors.

Golden Rule: If it feels hacky, it probably is. Rewrite.

Adopting these habits early saves hours of debugging and builds foundational skills for advanced labs! 🚀

