resnet-small

March 18, 2024

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[]: # This Python 3 environment comes with many helpful analytics libraries_
     \hookrightarrow installed
     # It is defined by the kaggle/python Docker image: https://github.com/kaggle/
      \hookrightarrow docker-python
     # For example, here's several helpful packages to load
     import numpy as np # linear algebra
     import pandas as pd # data processing, CSV file I/O (e.g. pd.read_csv)
     # Input data files are available in the read-only "../input/" directory
     # For example, running this (by clicking run or pressing Shift+Enter) will list⊔
      ⇔all files under the input directory
     import os
     for dirname, _, filenames in os.walk('/kaggle/input'):
         for filename in filenames:
             print(os.path.join(dirname, filename))
     # You can write up to 20GB to the current directory (/kaggle/working/) that ⊔
      →gets preserved as output when you create a version using "Save & Run All"
     # You can also write temporary files to /kaqqle/temp/, but they won't be saved
      ⇔outside of the current session
[1]: import h5py
     electron_dataset = h5py.File('/kaggle/input/electron-photon-dataset/
      ⇒SingleElectronPt50_IMGCROPS_n249k_RHv1.hdf5', 'r')
     photon_dataset = h5py.File('/kaggle/input/electron-photon-dataset/
      →SinglePhotonPt50_IMGCROPS_n249k_RHv1.hdf5', 'r')
     electron_dataset.keys()
[1]: <KeysViewHDF5 ['X', 'y']>
[2]: from torch.utils.data import DataLoader, random_split
     from torch.utils.data import Dataset, ConcatDataset
     import torch
     from torchvision.transforms import ToTensor, Compose, Resize, Lambda
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from torch.utils.data import Subset
import numpy as np
import torch.nn as nn
import torch.nn.functional as F
class FullDataset(Dataset):
   def __init__(self, data, transform):
       self.data = data
       self.transform = transform
   def __len__(self):
       return self.data['y'].shape[0]
   def __getitem__(self, idx):
        return self.transform(self.data['X'][idx]), self.data['y'][idx]
transform = Compose([
   ToTensor(),
     Resize((128,128)),
     Lambda(lambd=lambda x: torch.cat([x, torch.zeros([1, 128, 128])], dim=0))
])
electron = FullDataset(electron_dataset, transform=transform)
photon = FullDataset(photon_dataset, transform=transform)
full = ConcatDataset([electron, photon])
random_indices = np.random.choice(len(full), size=10000, replace=False)
small_dataset = Subset(full, random_indices)
train_data, test_data = random_split(small_dataset, [0.8, 0.2])
batch_size = 64
train_dataloader = DataLoader(train_data, batch_size=batch_size, shuffle=True,)
test_dataloader = DataLoader(test_data, batch_size=batch_size, shuffle=True)
device = 'cuda'
from tqdm import tqdm
class ResidualBlock(nn.Module):
   def __init__(self, in_channels, out_channels, stride=1):
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super(ResidualBlock, self).__init__()
        self.conv1 = nn.Conv2d(in_channels, out_channels, kernel_size=3,__
 →stride=stride, padding=1, bias=False)
        self.bn1 = nn.BatchNorm2d(out channels)
        self.conv2 = nn.Conv2d(out_channels, out_channels, kernel_size=3,_
 ⇒stride=1, padding=1, bias=False)
        self.bn2 = nn.BatchNorm2d(out_channels)
        self.relu = nn.ReLU(inplace=True)
        self.downsample = None
        if stride != 1 or in_channels != out_channels:
            self.downsample = nn.Sequential(
                nn.Conv2d(in channels, out channels, kernel size=1,...
 ⇔stride=stride, bias=False),
                nn.BatchNorm2d(out_channels)
   def forward(self, x):
       identity = x
        out = self.conv1(x)
       out = self.bn1(out)
       out = self.relu(out)
       out = self.conv2(out)
       out = self.bn2(out)
       if self.downsample is not None:
            identity = self.downsample(x)
       out += identity
        out = self.relu(out)
       return out
class Model(nn.Module):
   def __init__(self, in_channels, out_channels, stride=1):
        super(Model, self).__init__()
        self.conv = nn.Conv2d(in_channels, out_channels, kernel_size=3,__
 →stride=stride, padding=1)
        self.residual block = ResidualBlock(out channels, out channels)
        self.fc = nn.Linear(320, 2) # Linear layer after the ResNet block
   def forward(self, x):
       out = self.conv(x)
       out = self.residual_block(out)
       out = F.avg_pool2d(out, 4) # Example downsampling operation
        out = out.view(out.size(0), -1)
        out = self.fc(out)
       return out
model = Model(2, 5).float().to(device)
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```
from torch.utils.data import Subset
import numpy as np
def evaluate(loader, model):
    model.eval()
    total loss = 0.0
    correct = 0
    total samples = 0
    all_preds = []
    all_labels = []
    with torch.no_grad():
        for batch in tqdm(loader):
            pred = model(batch[0].to(device))
            pred_labels = torch.sigmoid(pred).argmax(dim=-1)
            correct += (pred_labels == batch[1].to(device)).sum().item()
            total_samples += len(batch[1].to(device))
    return correct/total_samples
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[3]: num_epochs = 15
     best_acc = 0
     criterion = nn.CrossEntropyLoss()
     optimiser = torch.optim.AdamW(model.parameters(), lr=3e-4)
     for epoch in range(1, num_epochs+1):
         epoch loss = 0
         model.train()
         for batch in tqdm(train_dataloader, desc=f'Epoch {epoch}:'):
             # print(f'{i}/{len(train_dataloader)}')
             # print(batch[1],batch[1].shape)
             pred = model(batch[0].to(device))
             # print(pred, pred.shape)
             loss = criterion(pred, batch[1].long().to(device))
             optimiser.zero_grad()
             loss.backward()
             optimiser.step()
             epoch_loss += loss.item()
         acc = evaluate(test_dataloader, model)
         print(f'Loss after f{epoch} epochs = {epoch loss}, Val acc = {100*acc}%')
         if acc > best_acc:
             best_acc = acc
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```
Epoch 1:: 100%
                    | 125/125 [20:47<00:00, 9.98s/it]
100%|
         | 32/32 [05:11<00:00, 9.73s/it]
Loss after f1 epochs = 86.44747442007065, Val acc = 56.599999999999994%
Epoch 2:: 100%|
                 | 125/125 [20:48<00:00, 9.99s/it]
100%|
         | 32/32 [05:11<00:00, 9.73s/it]
Loss after f2 epochs = 85.28908115625381, Val acc = 57.550000000000004%
                  | 125/125 [20:54<00:00, 10.04s/it]
Epoch 3:: 100%|
100%|
         | 32/32 [05:14<00:00, 9.82s/it]
Loss after f3 epochs = 84.45879954099655, Val acc = 57.49999999999999%
Epoch 4:: 100% | 125/125 [20:48<00:00, 9.98s/it]
         | 32/32 [05:11<00:00, 9.72s/it]
100%|
Loss after f4 epochs = 83.70755857229233, Val acc = 58.75%
Epoch 5:: 100% | 125/125 [20:51<00:00, 10.01s/it]
         | 32/32 [05:14<00:00, 9.82s/it]
Loss after f5 epochs = 83.34814894199371, Val acc = 59.4%
Epoch 6:: 100%|
                 | 125/125 [20:47<00:00, 9.98s/it]
       | 32/32 [05:12<00:00, 9.77s/it]
100%|
Loss after f6 epochs = 82.91225200891495, Val acc = 58.8%
Epoch 7:: 100% | 125/125 [20:46<00:00, 9.97s/it]
         | 32/32 [05:10<00:00, 9.72s/it]
Loss after f7 epochs = 82.87983494997025, Val acc = 59.8%
Epoch 8:: 100%
                   | 125/125 [20:42<00:00, 9.94s/it]
         | 32/32 [05:09<00:00, 9.68s/it]
100%|
Loss after f8 epochs = 82.60226565599442, Val acc = 59.35%
Epoch 9:: 100% | 125/125 [20:45<00:00, 9.97s/it]
         | 32/32 [05:14<00:00, 9.83s/it]
Loss after f9 epochs = 82.43799072504044, Val acc = 59.6500000000000006%
Epoch 10:: 100%
                    | 125/125 [20:45<00:00, 9.96s/it]
        | 32/32 [05:11<00:00, 9.73s/it]
100%|
Loss after f10 epochs = 82.24004679918289, Val acc = 59.25%
Epoch 11:: 100% | 125/125 [20:41<00:00, 9.93s/it]
        | 32/32 [05:10<00:00, 9.70s/it]
Loss after f11 epochs = 82.43570989370346, Val acc = 60.25%
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torch.save(model.state_dict(), f'/kaggle/working/{epoch}.pth')

best_epoch = epoch

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Epoch 12:: 100%|
                         | 125/125 [20:39<00:00, 9.92s/it]
              | 32/32 [05:09<00:00, 9.67s/it]
    100%|
    Loss after f12 epochs = 82.04974013566971, Val acc = 59.95%
    Epoch 13:: 100%|
                         | 125/125 [20:50<00:00, 10.01s/it]
              | 32/32 [05:13<00:00, 9.79s/it]
    Loss after f13 epochs = 81.91537237167358, Val acc = 59.95%
    Epoch 14:: 100%
                         | 125/125 [20:47<00:00, 9.98s/it]
             | 32/32 [05:12<00:00, 9.75s/it]
    100%|
    Loss after f14 epochs = 81.78760993480682, Val acc = 59.6500000000000006%
    Epoch 15:: 100% | 125/125 [20:46<00:00, 9.97s/it]
              | 32/32 [05:12<00:00, 9.78s/it]
    Loss after f15 epochs = 81.78811627626419, Val acc = 60.35%
[]: for epoch in range(1, num epochs+1):
        epoch_loss = 0
        model.train()
        for batch in tqdm(train_dataloader, desc=f'Epoch {num_epochs+epoch}:'):
             # print(f'{i}/{len(train_dataloader)}')
             # print(batch[1],batch[1].shape)
            pred = model(batch[0].to(device))
             # print(pred, pred.shape)
            loss = criterion(pred, batch[1].long().to(device))
            optimiser.zero_grad()
            loss.backward()
            optimiser.step()
            epoch_loss += loss.item()
        acc = evaluate(test dataloader, model)
        print(f'Loss after {num_epochs+epoch} epochs = {epoch_loss}, Val acc = __
      →{100*acc}%')
        if acc > best acc:
            best_acc = acc
            best_epoch = epoch
            torch.save(model.state_dict(), f'/kaggle/working/{num_epochs+epoch}.
      →pth')
    Epoch 16:: 100%|
                         | 125/125 [20:46<00:00, 9.97s/it]
             | 32/32 [05:10<00:00, 9.71s/it]
    Loss after 16 epochs = 81.50043708086014, Val acc = 60.050000000000004%
                        | 125/125 [20:44<00:00, 9.96s/it]
    Epoch 17:: 100%|
    100%|
           | 32/32 [05:11<00:00, 9.74s/it]
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Loss after 17 epochs = 81.71386760473251, Val acc = 59.4\%
    Epoch 18:: 100%|
                       | 125/125 [20:47<00:00, 9.98s/it]
            | 32/32 [05:11<00:00, 9.73s/it]
    Loss after 18 epochs = 81.30803221464157, Val acc = 60.35%
    Epoch 19:: 100%|
                         | 125/125 [20:51<00:00, 10.01s/it]
             | 32/32 [05:14<00:00, 9.84s/it]
    Loss after 19 epochs = 81.26681661605835, Val acc = 60.25\%
                         | 125/125 [20:59<00:00, 10.08s/it]
    Epoch 20:: 100%
    100%|
             | 32/32 [05:14<00:00, 9.83s/it]
    Loss after 20 epochs = 81.20397907495499, Val acc = 60.55000000000000004%
    Epoch 21:: 100%|
                       | 125/125 [20:56<00:00, 10.05s/it]
             | 32/32 [05:12<00:00, 9.77s/it]
    Loss after 21 epochs = 81.19562822580338, Val acc = 60.19999999999999%
    Epoch 22:: 100%
                         | 125/125 [20:53<00:00, 10.03s/it]
            | 32/32 [05:13<00:00, 9.81s/it]
    100%|
    Loss after 22 epochs = 80.97035294771194, Val acc = 59.6500000000000006%
    Epoch 23:: 100% | 125/125 [21:02<00:00, 10.10s/it]
            | 32/32 [05:15<00:00, 9.85s/it]
    100%|
    Loss after 23 epochs = 80.81147682666779, Val acc = 60.3\%
    Epoch 24:: 100% | 125/125 [20:59<00:00, 10.07s/it]
            | 32/32 [05:14<00:00, 9.83s/it]
    Loss after 24 epochs = 80.93522256612778, Val acc = 60.35%
                       | 125/125 [21:00<00:00, 10.09s/it]
    Epoch 25:: 100%|
    100%|
           | 32/32 [05:14<00:00, 9.82s/it]
    Loss after 25 epochs = 80.62047773599625, Val acc = 60.5500000000000004%
    Epoch 26:: 100%|
                         | 125/125 [20:58<00:00, 10.07s/it]
            | 32/32 [05:15<00:00, 9.85s/it]
    Loss after 26 epochs = 80.64774167537689, Val acc = 60.35%
                         | 125/125 [21:01<00:00, 10.09s/it]
    Epoch 27:: 100%
              | 32/32 [05:15<00:00, 9.86s/it]
    Loss after 27 epochs = 80.67484217882156, Val acc = 60.0%
                          | 61/125 [10:16<10:44, 10.08s/it]
    Epoch 28:: 49%|
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