

Introduction to CMOS VLSI Design

Lecture 17: Design for Testability

Outline

- ❑ Testing
 - Logic Verification
 - Silicon Debug
 - Manufacturing Test
- ❑ Fault Models
- ❑ Observability and Controllability
- ❑ Design for Test
 - Scan
 - BIST
- ❑ Boundary Scan

Testing

- ❑ Testing is one of the most expensive parts of chips
 - Logic verification accounts for $> 50\%$ of design effort for many chips
 - Debug time after fabrication has enormous opportunity cost
 - Shipping defective parts can sink a company

- ❑ Example: Intel FDIV bug
 - Logic error not caught until $> 1\text{M}$ units shipped
 - Recall cost \$450M (!!!)

Logic Verification

- ❑ Does the chip simulate correctly?
 - Usually done at HDL level
 - Verification engineers write test bench for HDL
 - Can't test all cases
 - Look for corner cases
 - Try to break logic design
- ❑ Ex: 32-bit adder
 - Test all combinations of corner cases as inputs:
 - 0, 1, 2, $2^{31}-1$, -1, -2^{31} , a few random numbers
- ❑ Good tests require ingenuity

Silicon Debug

- ❑ Test the first chips back from fabrication
 - If you are lucky, they work the first time
 - If not...
- ❑ Logic bugs vs. electrical failures
 - Most chip failures are logic bugs from inadequate simulation
 - Some are electrical failures
 - Crosstalk
 - Dynamic nodes: leakage, charge sharing
 - Ratio failures
 - A few are tool or methodology failures (e.g. DRC)
- ❑ Fix the bugs and fabricate a corrected chip

Shmoo Plots

❑ How to diagnose failures?

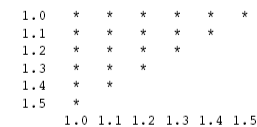
- Hard to access chips
 - Picoprobe
 - Electron beam
 - Laser voltage probing
 - Built-in self-test

❑ Shmoo plots

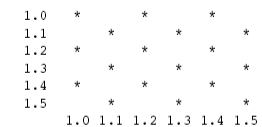
- Vary voltage, frequency
- Look for cause of electrical failures

*Clock period in ns on the left, frequency increases going up
Voltage on the bottom, increase left to right*

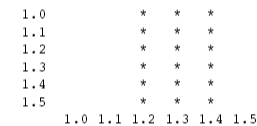
** indicates a failure*



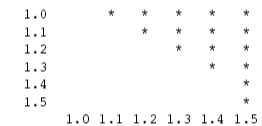
Normal
Well-behaved shmoo
Typical Speedpath



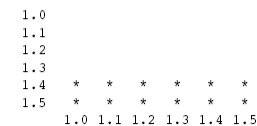
"Brick Wall"



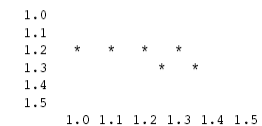
"Wall"
Fails at a certain voltage



"Reverse speedpath"
Increase in voltage reduces frequency



"Floor"
Works at high but not low frequency



"Finger"
Fails at a specific point in the shmoo

Shmoo Plots

❑ How to diagnose failures?

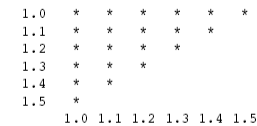
- Hard to access chips
 - Picoprobe
 - Electron beam
 - Laser voltage probing
 - Built-in self-test

❑ Shmoo plots

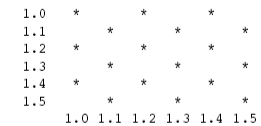
- Vary voltage, frequency
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*Clock period in ns on the left, frequency increases going up
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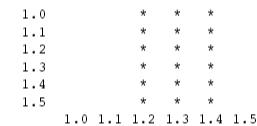
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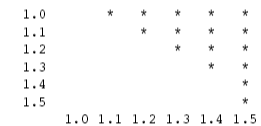
Normal
Well-behaved shmoo
Typical Speedpath



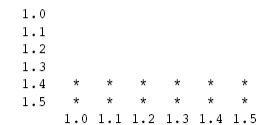
"Brick Wall"
Bistable
Initialization



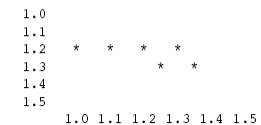
"Wall"
Fails at a certain voltage
Coupling, charge share, races



"Reverse speedpath"
Increase in voltage reduces frequency
Speedpath, leakage



"Floor"
Works at high but not low frequency
Leakage



"Finger"
Fails at a specific point in the shmoo
Coupling

Manufacturing Test

- ❑ A speck of dust on a wafer is sufficient to kill chip
- ❑ *Yield* of any chip is $< 100\%$
 - Must test chips after manufacturing before delivery to customers to only ship good parts
- ❑ Manufacturing testers are very expensive
 - Minimize time on tester
 - Careful selection of *test vectors*

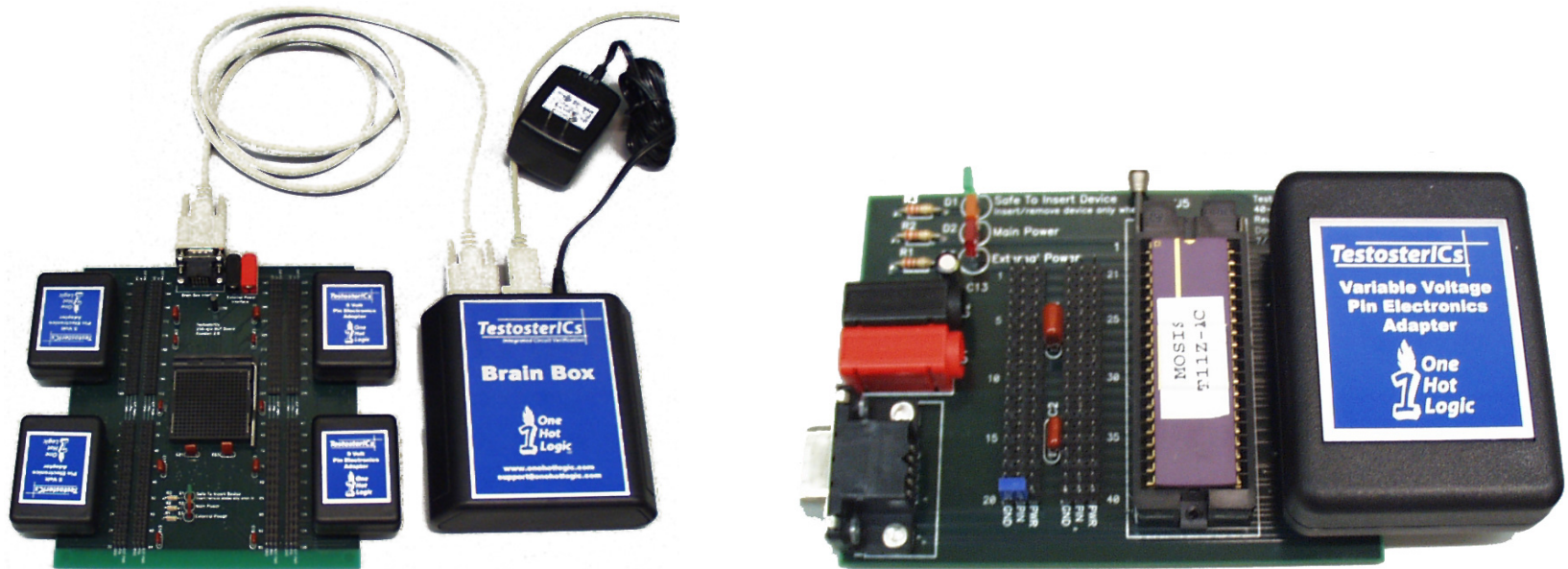


Testing Your Chips

- ❑ If you don't have a multimillion dollar tester:
 - Build a breadboard with LED's and switches
 - Hook up a logic analyzer and pattern generator
 - Or use a low-cost functional chip tester

TestosterICs

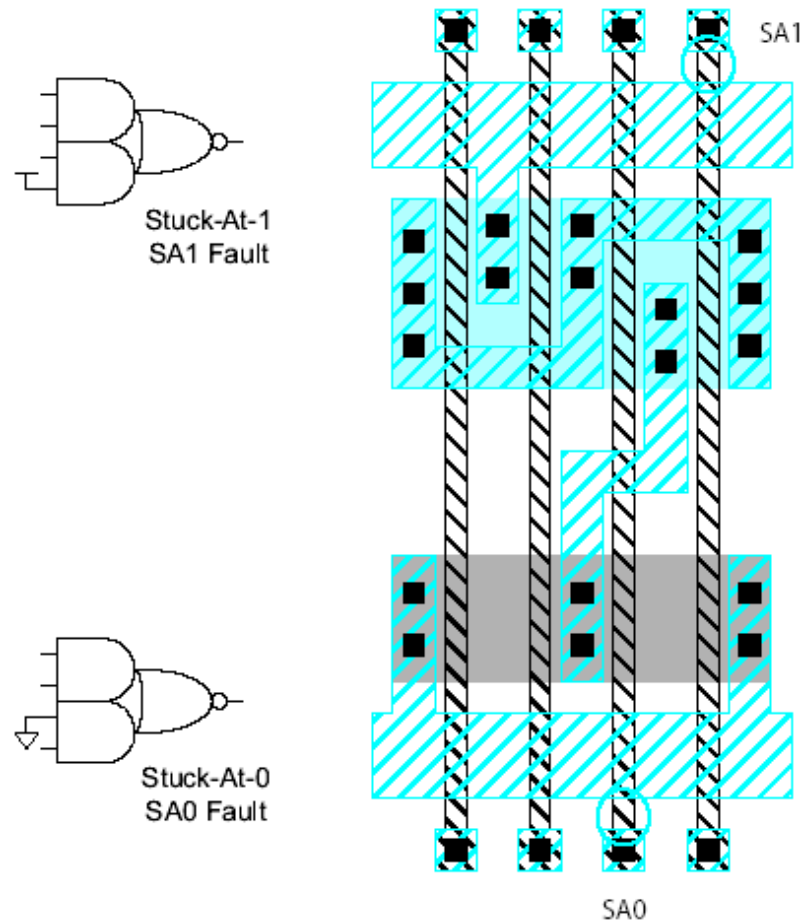
- ❑ Ex: TestosterICs functional chip tester
 - Designed by clinic teams and David Diaz at HMC
 - Reads your IRSIM test vectors, applies them to your chip, and reports assertion failures



Stuck-At Faults

- ❑ How does a chip fail?
 - Usually failures are shorts between two conductors or opens in a conductor
 - This can cause very complicated behavior
- ❑ A simpler model: *Stuck-At*
 - Assume all failures cause nodes to be “stuck-at” 0 or 1, i.e. shorted to GND or V_{DD}
 - Not quite true, but works well in practice

Examples



Observability & Controllability

- ❑ *Observability*: ease of observing a node by watching external output pins of the chip
- ❑ *Controllability*: ease of forcing a node to 0 or 1 by driving input pins of the chip
- ❑ Combinational logic is usually easy to observe and control
- ❑ Finite state machines can be very difficult, requiring many cycles to enter desired state
 - Especially if state transition diagram is not known to the test engineer

Test Pattern Generation

- ❑ Manufacturing test ideally would check every node in the circuit to prove it is not stuck.
- ❑ Apply the smallest sequence of test vectors necessary to prove each node is not stuck.
- ❑ Good observability and controllability reduces number of test vectors required for manufacturing test.
 - Reduces the cost of testing
 - Motivates design-for-test

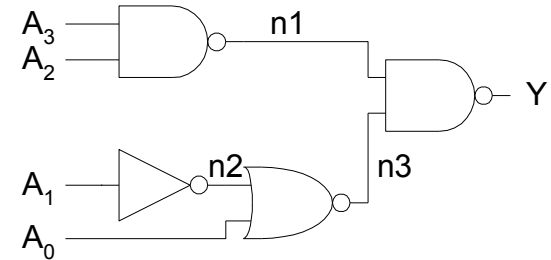
Test Example

SA1

SA0

- ☐ A_3
- ☐ A_2
- ☐ A_1
- ☐ A_0
- ☐ $n1$
- ☐ $n2$
- ☐ $n3$
- ☐ Y

☐ Minimum set:



Test Example

☐ A_3

☐ A_2

☐ A_1

☐ A_0

☐ $n1$

☐ $n2$

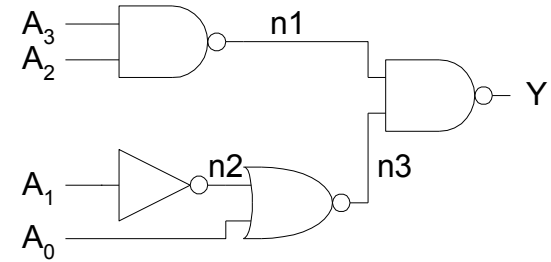
☐ $n3$

☐ Y

☐ Minimum set:

SA1
{0110}

SA0
{1110}



Test Example

☐ A_3

☐ A_2

☐ A_1

☐ A_0

☐ $n1$

☐ $n2$

☐ $n3$

☐ Y

☐ Minimum set:

SA1

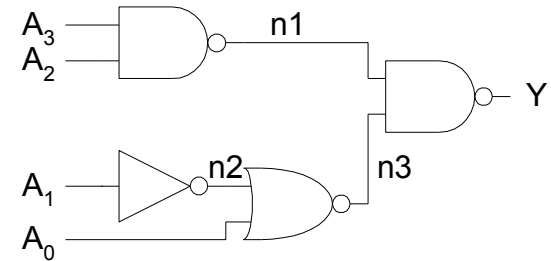
{0110}

{1010}

SA0

{1110}

{1110}



Test Example

☐ A_3

☐ A_2

☐ A_1

☐ A_0

☐ $n1$

☐ $n2$

☐ $n3$

☐ Y

SA1

{0110}

{1010}

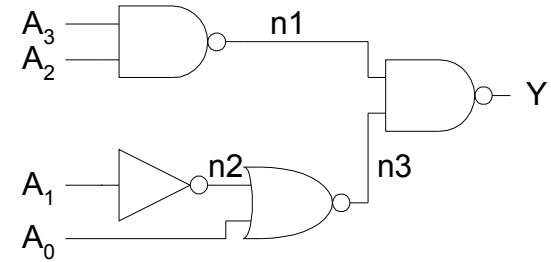
{0100}

SA0

{1110}

{1110}

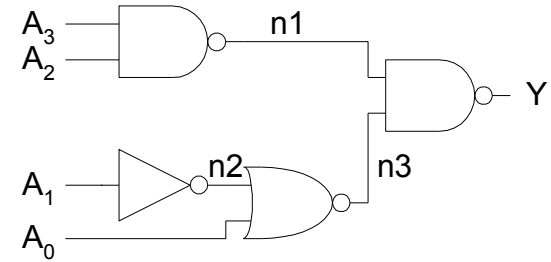
{0110}



☐ Minimum set:

Test Example

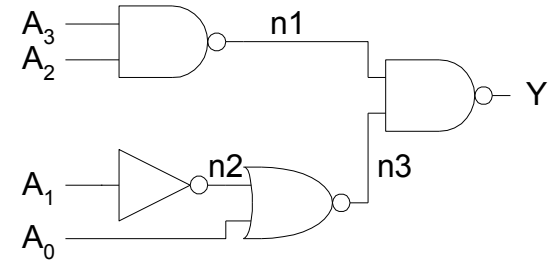
	SA1	SA0
<input type="checkbox"/> A_3	{0110}	{1110}
<input type="checkbox"/> A_2	{1010}	{1110}
<input type="checkbox"/> A_1	{0100}	{0110}
<input type="checkbox"/> A_0	{0110}	{0111}
<input type="checkbox"/> n1		
<input type="checkbox"/> n2		
<input type="checkbox"/> n3		
<input type="checkbox"/> Y		



☐ Minimum set:

Test Example

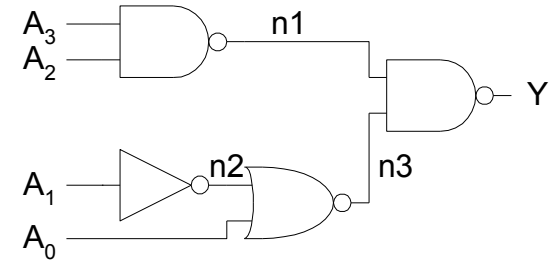
	SA1	SA0
<input type="checkbox"/> A_3	{0110}	{1110}
<input type="checkbox"/> A_2	{1010}	{1110}
<input type="checkbox"/> A_1	{0100}	{0110}
<input type="checkbox"/> A_0	{0110}	{0111}
<input type="checkbox"/> n1	{1110}	{0110}
<input type="checkbox"/> n2		
<input type="checkbox"/> n3		
<input type="checkbox"/> Y		



☐ Minimum set:

Test Example

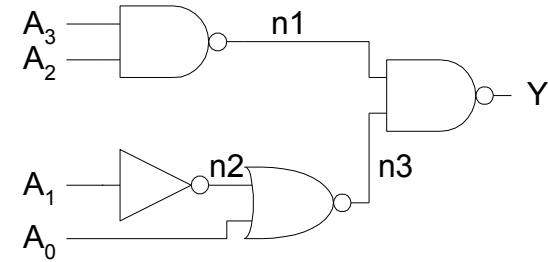
	SA1	SA0
<input type="checkbox"/> A_3	{0110}	{1110}
<input type="checkbox"/> A_2	{1010}	{1110}
<input type="checkbox"/> A_1	{0100}	{0110}
<input type="checkbox"/> A_0	{0110}	{0111}
<input type="checkbox"/> n1	{1110}	{0110}
<input type="checkbox"/> n2	{0110}	{0100}
<input type="checkbox"/> n3		
<input type="checkbox"/> Y		



☐ Minimum set:

Test Example

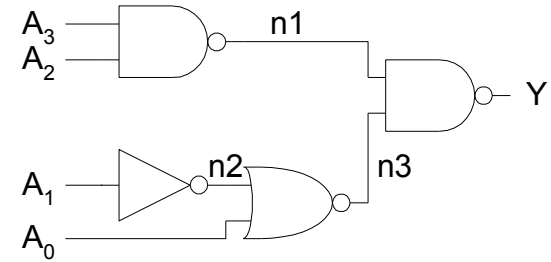
	SA1	SA0
<input type="checkbox"/> A_3	{0110}	{1110}
<input type="checkbox"/> A_2	{1010}	{1110}
<input type="checkbox"/> A_1	{0100}	{0110}
<input type="checkbox"/> A_0	{0110}	{0111}
<input type="checkbox"/> n1	{1110}	{0110}
<input type="checkbox"/> n2	{0110}	{0100}
<input type="checkbox"/> n3	{0101}	{0110}
<input type="checkbox"/> Y		



☐ Minimum set:

Test Example

	SA1	SA0
<input type="checkbox"/> A_3	{0110}	{1110}
<input type="checkbox"/> A_2	{1010}	{1110}
<input type="checkbox"/> A_1	{0100}	{0110}
<input type="checkbox"/> A_0	{0110}	{0111}
<input type="checkbox"/> n1	{1110}	{0110}
<input type="checkbox"/> n2	{0110}	{0100}
<input type="checkbox"/> n3	{0101}	{0110}
<input type="checkbox"/> Y	{0110}	{1110}



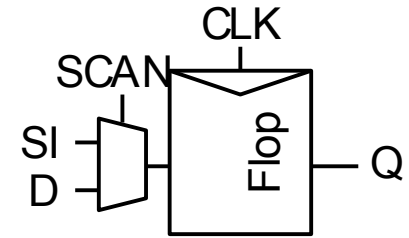
☐ Minimum set: {0100, 0101, 0110, 0111, 1010, 1110}

Design for Test

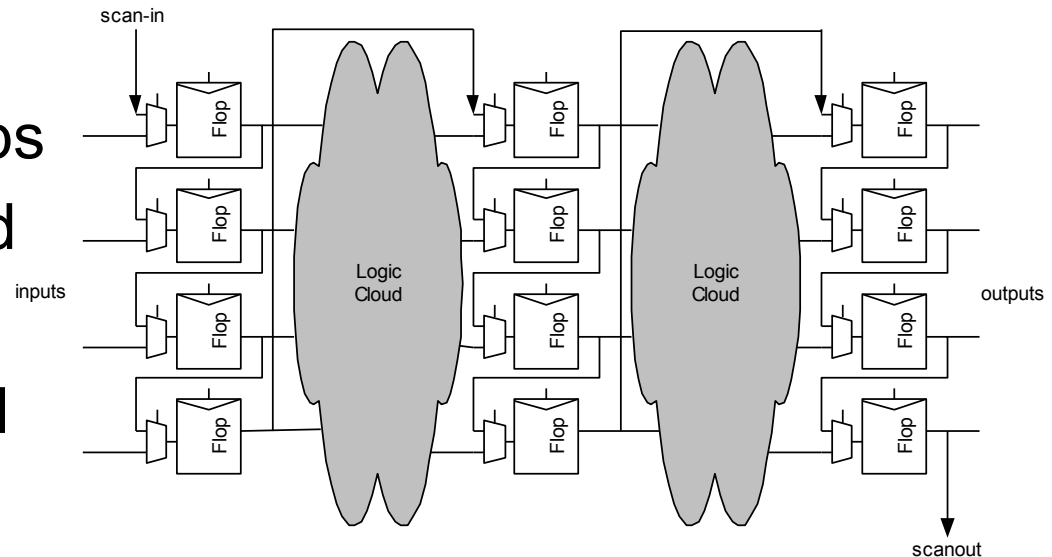
- ❑ Design the chip to increase observability and controllability
- ❑ If each register could be observed and controlled, test problem reduces to testing combinational logic between registers.
- ❑ Better yet, logic blocks could enter test mode where they generate test patterns and report the results automatically.

Scan

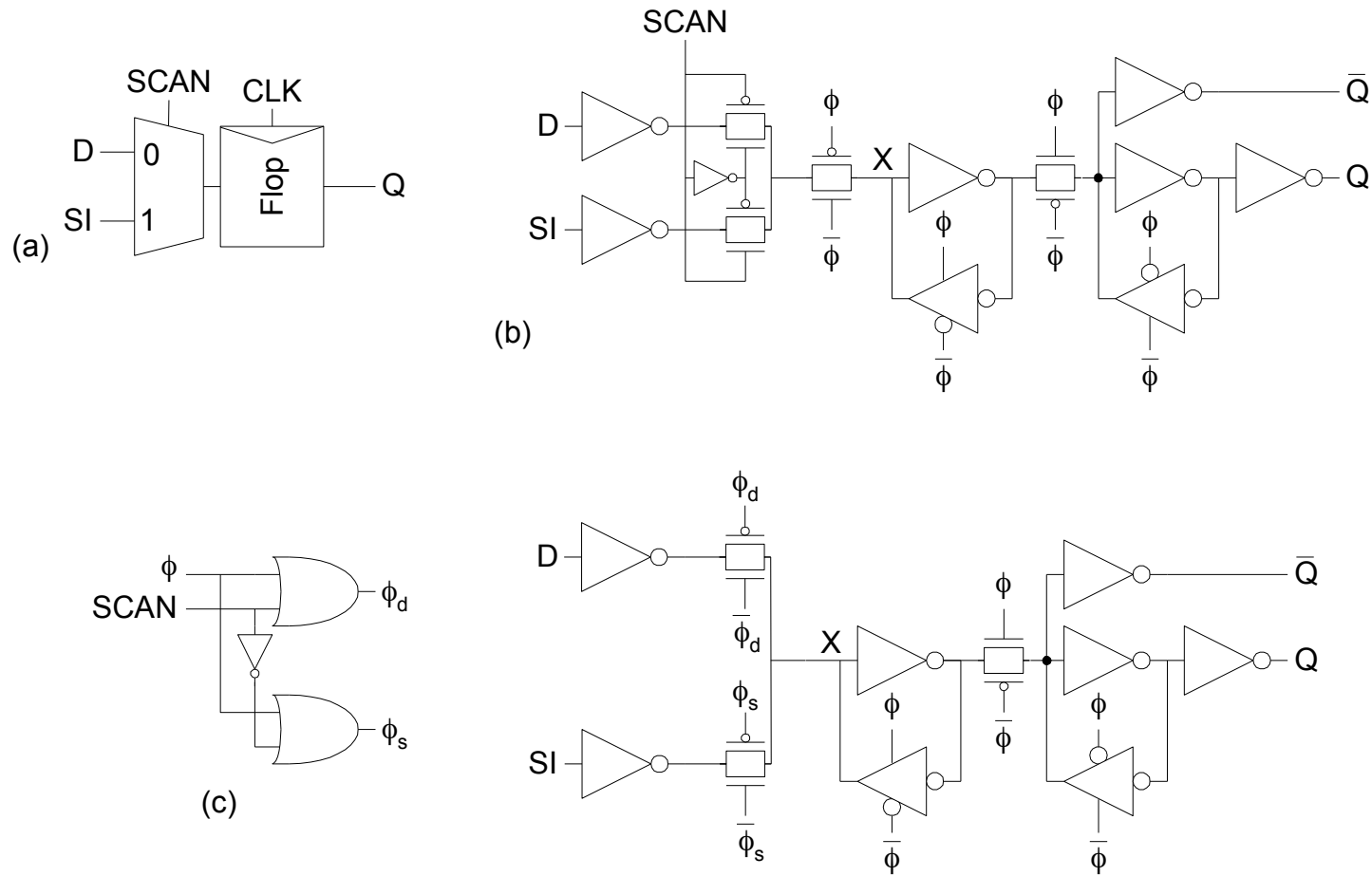
- ❑ Convert each flip-flop to a scan register
 - Only costs one extra multiplexer
- ❑ Normal mode: flip-flops behave as usual
- ❑ Scan mode: flip-flops behave as shift register



- ❑ Contents of flops can be scanned out and new values scanned in



Scannable Flip-flops



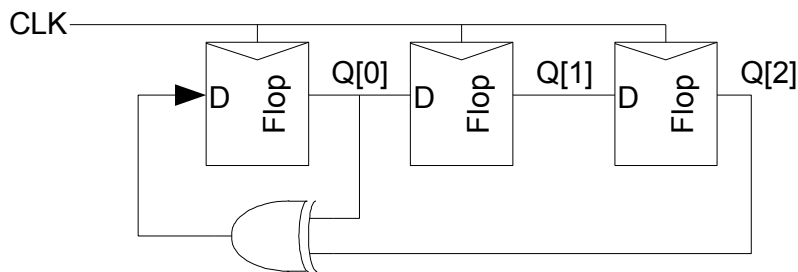
Built-in Self-test

- ❑ Built-in self-test lets blocks test themselves
 - Generate pseudo-random inputs to comb. logic
 - Combine outputs into a *syndrome*
 - With high probability, block is fault-free if it produces the expected syndrome

PRSG

❑ *Linear Feedback Shift Register*

- Shift register with input taken from XOR of state
- *Pseudo-Random Sequence Generator*

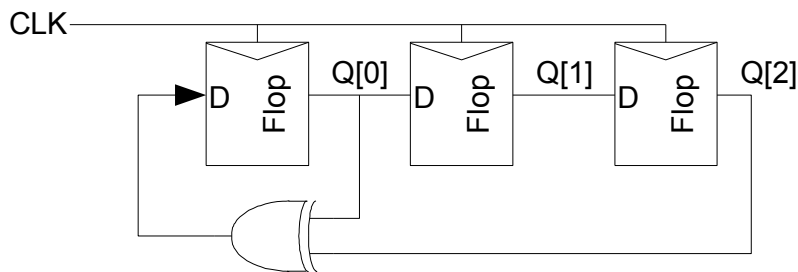


Step	Q
0	111
1	
2	
3	
4	
5	
6	
7	

PRSG

❑ *Linear Feedback Shift Register*

- Shift register with input taken from XOR of state
- *Pseudo-Random Sequence Generator*

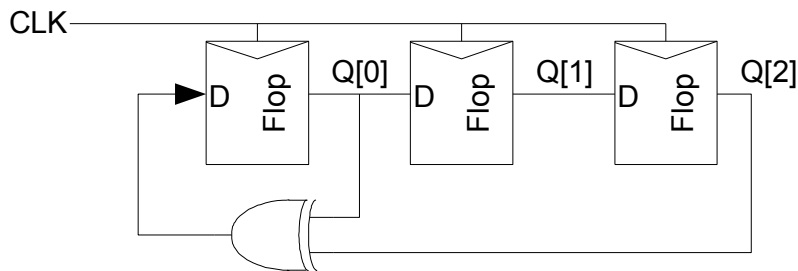


Step	Q
0	111
1	110
2	
3	
4	
5	
6	
7	

PRSG

❑ *Linear Feedback Shift Register*

- Shift register with input taken from XOR of state
- *Pseudo-Random Sequence Generator*

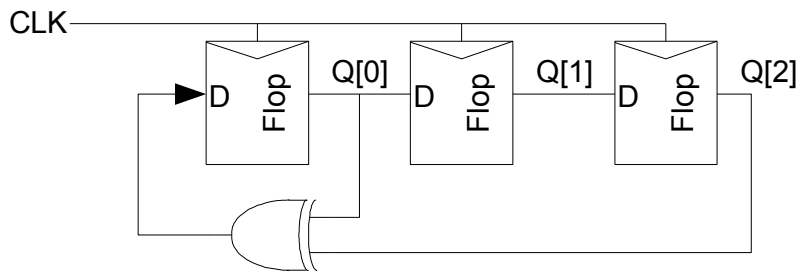


Step	Q
0	111
1	110
2	101
3	
4	
5	
6	
7	

PRSG

❑ *Linear Feedback Shift Register*

- Shift register with input taken from XOR of state
- *Pseudo-Random Sequence Generator*

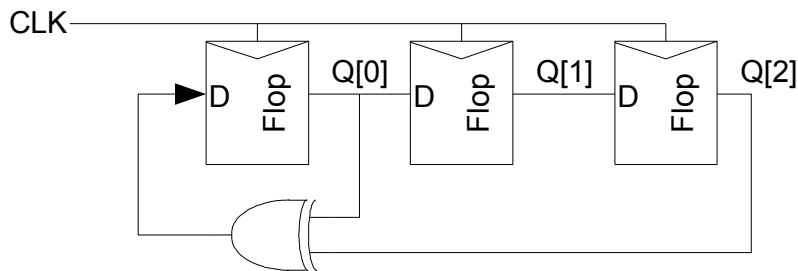


Step	Q
0	111
1	110
2	101
3	010
4	
5	
6	
7	

PRSG

❑ *Linear Feedback Shift Register*

- Shift register with input taken from XOR of state
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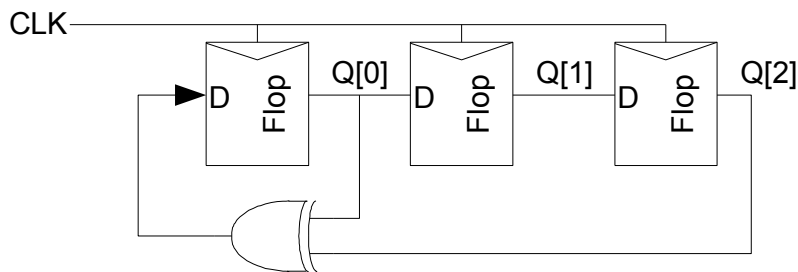


Step	Q
0	111
1	110
2	101
3	010
4	100
5	
6	
7	

PRSG

❑ *Linear Feedback Shift Register*

- Shift register with input taken from XOR of state
- *Pseudo-Random Sequence Generator*

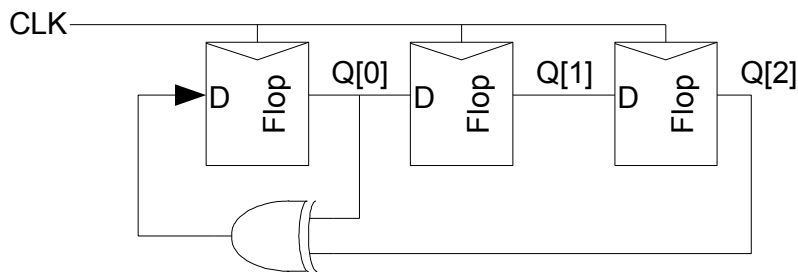


Step	Q
0	111
1	110
2	101
3	010
4	100
5	001
6	
7	

PRSG

❑ *Linear Feedback Shift Register*

- Shift register with input taken from XOR of state
- *Pseudo-Random Sequence Generator*

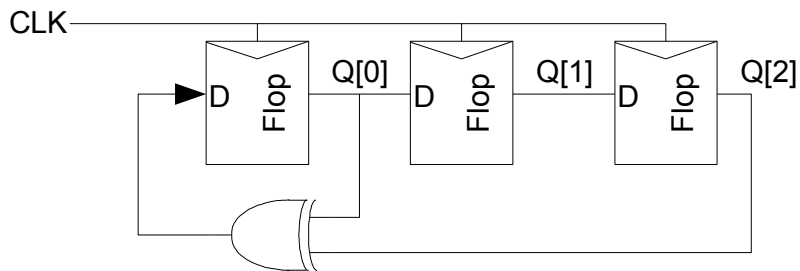


Step	Q
0	111
1	110
2	101
3	010
4	100
5	001
6	011
7	

PRSG

❑ *Linear Feedback Shift Register*

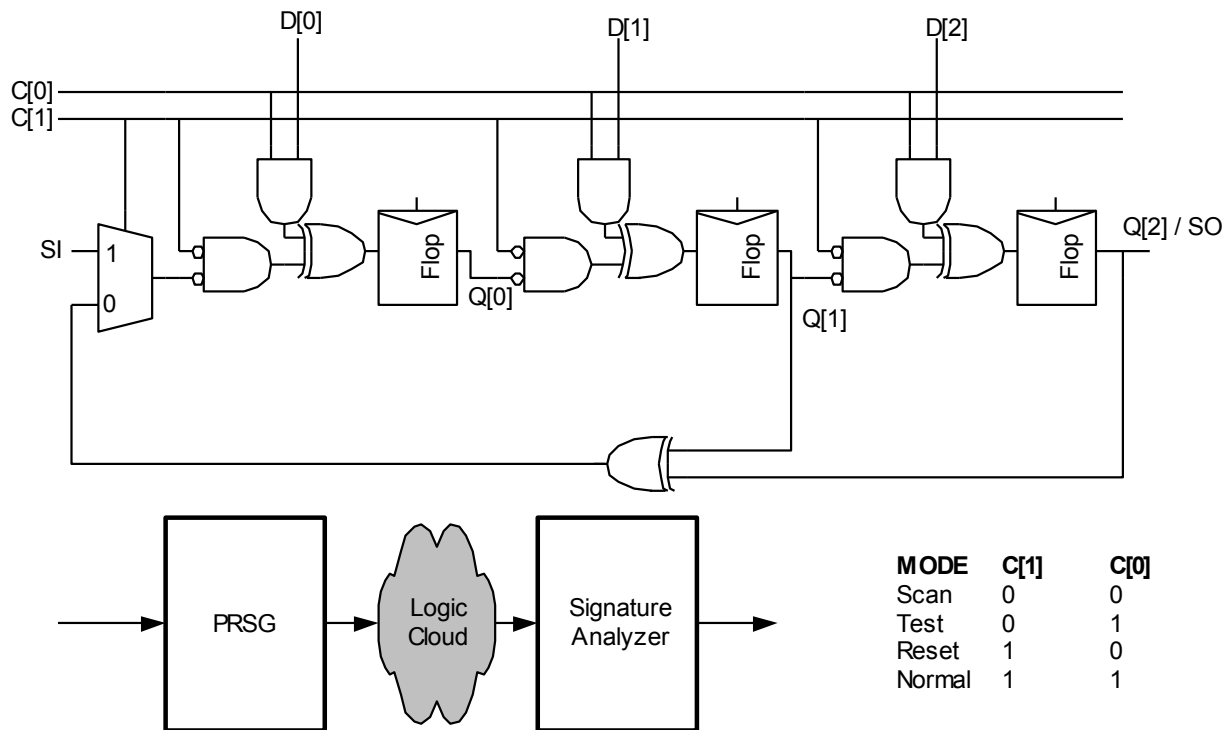
- Shift register with input taken from XOR of state
- *Pseudo-Random Sequence Generator*



Step	Q
0	111
1	110
2	101
3	010
4	100
5	001
6	011
7	111 (repeats)

BILBO

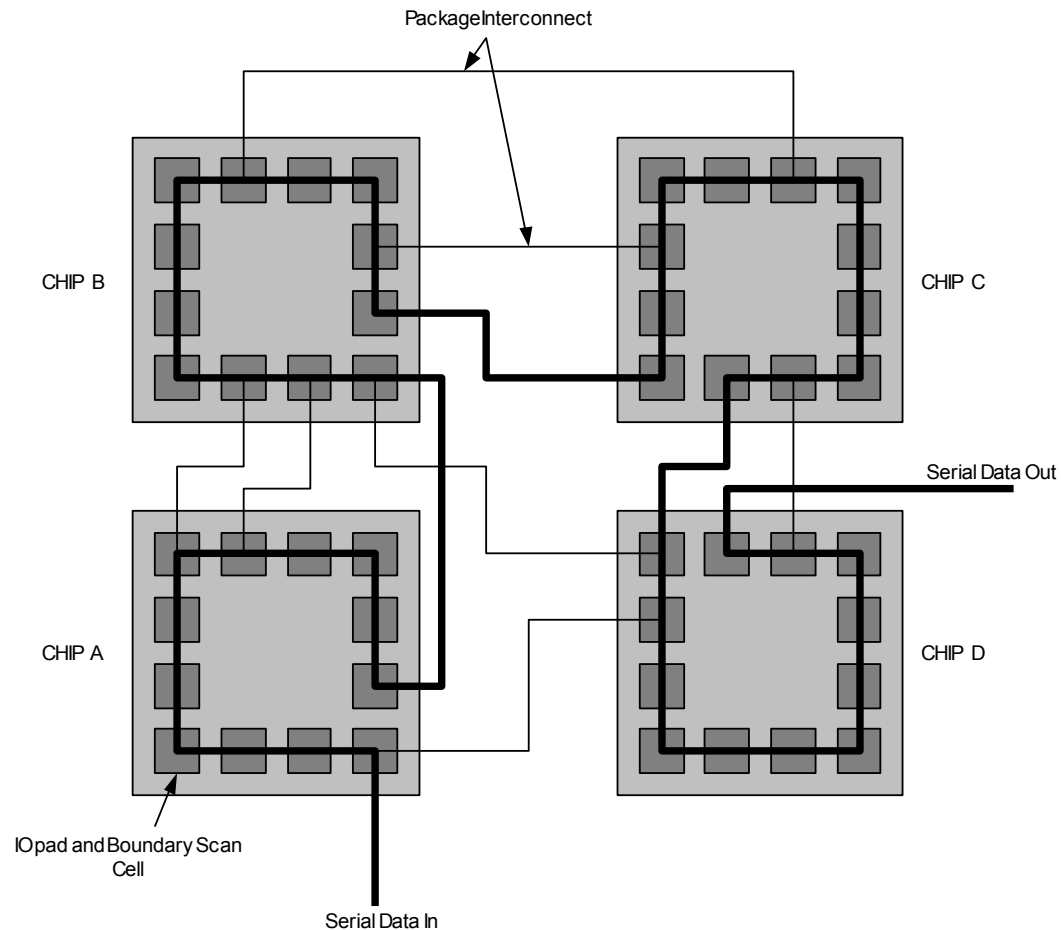
- ❑ Built-in Logic Block Observer
 - Combine scan with PRSG & signature analysis



Boundary Scan

- ❑ Testing boards is also difficult
 - Need to verify solder joints are good
 - Drive a pin to 0, then to 1
 - Check that all connected pins get the values
- ❑ Through-hole boards used “bed of nails”
- ❑ SMT and BGA boards cannot easily contact pins
- ❑ Build capability of observing and controlling pins into each chip to make board test easier

Boundary Scan Example



Boundary Scan Interface

- ❑ Boundary scan is accessed through five pins
 - TCK: test clock
 - TMS: test mode select
 - TDI: test data in
 - TDO: test data out
 - TRST*: test reset (optional)

- ❑ Chips with internal scan chains can access the chains through boundary scan for unified test strategy.

Summary

- ❑ Think about testing from the beginning
 - Simulate as you go
 - Plan for test after fabrication

- ❑ “If you don’ t test it, it won’ t work! (Guaranteed)”