CS1200: Intro. to Algorithms and their Limitations

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Problem Set 2

Harvard SEAS - Fall 2025

Due: Wed 2024-09-25 (11:59pm)

Please see the syllabus for the full collaboration and generative AI policy, as well as information on grading, late days, and revisions.

All sources of ideas, including (but not restricted to) any collaborators, AI tools, people outside of the course, websites, ARC tutors, and textbooks other than Hesterberg–Vadhan must be listed on your submitted homework along with a brief description of how they influenced your work. You need not cite core course resources, which are lectures, the Hesterberg–Vadhan textbook, sections, SREs, problem sets and solutions sets from earlier in the semester. If you use any concepts, terminology, or problem-solving approaches not covered in the course material by that point in the semester, you must describe the source of that idea. If you credit an AI tool for a particular idea, then you should also provide a primary source that corroborates it. Github Copilot and similar tools should be turned off when working on programming assignments.

If you did not have any collaborators or external resources, please write 'none.' Please remember to select pages when you submit on Gradescope. A problem set without selected pages is not eligible for an R+.

Your name:

Collaborators and External Resources:

No. of late days used on previous psets:

No. of late days used after including this pset:

1. (designing reductions) The purpose of this exercise is to give you practice designing reductions and proving their correctness and runtime.

Consider the following computational problem:

Input: Points $(x_0, y_0), \ldots, (x_{n-1}, y_{n-1})$ in the \mathbb{R}^2 plane that are the vertices of a convex polygon (in an arbitrary order) whose interior contains the origin

Output: The area of the polygon formed by the points

Computational Problem AreaOfConvexPolygon()

(a) Show that AreaOfConvexPolygon $\leq_{O(n),n}$ Sorting. Be sure to analyze both the correctness and runtime of your reduction.

In this part and the next one, you may assume that a point $(x, y) \in \mathbb{R}^2$ can be converted into polar coordinates (r, θ) in constant time.

You may find the following facts useful and you may use them (as well as other facts from geometry) without proof:

- The polar coordinates (r,θ) of a point (x,y) are the unique real numbers $r \geq 0$ and $\theta \in [0,2\pi)$ such that $x = r\cos\theta$ and $y = r\sin\theta$. Or, more geometrically, $r = \sqrt{x^2 + y^2}$ is the distance of the point from the origin, and θ is the angle between the positive x-axis and the ray from the origin to the point.
- The area of a triangle is $A = \sqrt{s(s-a)(s-b)(s-c)}$ where a,b,c are the side lengths of the triangle and $s = \frac{a+b+c}{2}$ (Heron's Formula).
- (b) Deduce that AreaOfConvexPolygon can be solved in time $O(n \log n)$.
- (c) (*challenge; extra credit; optional¹) Come up with a way to avoid conversion to polar coordinates and any other trigonometric functions in solving AreaOfConvexPolygon in time $O(n \log n)$. Specifically, design an O(n)-time reduction that makes O(1) calls to a Sorting oracle on arrays of length at most n, using only arithmetic operations $+, -, \times, \div$, and $\sqrt{}$, along with comparators like < and ==. (Hint: first partition the input points according to which quadrant they belong in, and consider the slope of the line from a vertex (x,y) to the origin.)

Similar techniques to what you are using in this problem are used in algorithms for other important geometric problems, like finding the Convex Hull of a set of points, which has applications in graphics and machine learning.

2. (composition of reductions) The purpose of this exercise is to give you practice in working with the abstract definition of reductions.

Let Π, Γ, Λ be computational problems, and suppose that $\Pi \leq_{T_1(n), q_1(n) \otimes h_1(n)} \Gamma$ and $\Gamma \leq_{T_2(n), q_2(n) \otimes h_2(n)} \Lambda$, for non-decreasing functions $T_1, T_2, q_1, q_2, h_1, h_2$. Determine functions T_3, q_3, h_3 in terms of $T_1, T_2, q_1, q_2, h_1, h_2$ such that

$$\Pi \leq_{O(T_3(n)),q_3(n)\otimes h_3(n)} \Lambda,$$

and justify your answers. You do not need to prove the correctness of the reduction from Π to Λ . Just justify the functions T_3 , q_3 and h. (Hint: you can take $h_3(n) = h_2(h_1(n))$.)

¹This problem is meant to be done based on your enjoyment/interest and only if you have time. It won't make a difference between N, L, R-, and R grades (meaning it will only impact whether an R gets increased to an R+), and course staff will deprioritize questions about this problem at office hours and on Ed.

3. (augmented binary search trees) The purpose of this problem is to give you experience reasoning about correctness and efficiency of dynamic data-structure operations, on variants of binary-search trees. You may assume that all keys are distinct.

Specifically, we will work with selection data structures. We have seen how binary search trees can support min queries in time O(h), where h is the height of the tree. A generalization is selection queries, where given a natural number q, we want to return the q'th smallest element of the set. So DS.select(0) should return the key-value pair with the minimum key among those stored by the data structure DS, DS.select(1) should return the one with the second-smallest key, DS.select(n-1) should return the one with the maximum key if the set is of size n, and DS.select((n-1)/2) should return the median element if n is odd.

It is known that if we *augment* binary search trees by adding to each node v the size of the subtree rooted at v, then select queries can be answered in time O(h).²

- (a) In the Github repository, we have given you a Python implementation of size-augmented BSTs supporting search, insertion, and selection, and with a stub for rotate. One of the implemented functions (search, insert, or select) has a correctness error, another one is too slow (running in time that's (at least) linear in the number of nodes of the tree rather than linear in the height of tree), and the third is correct. Identify and correct these errors. You should provide a text explanation of the errors and your corrections, as well as implement the corrections in Python.
- (b) Describe (in pseudocode or pictures) how to extend rotate to size-augmented BSTs, and argue that your extension maintains the runtime O(1). Prove that your new rotation operation preserves the invariant of correct size-augmentations. (That is, if every node's size attribute had the correct subtree size before the operation, then the same is true after the operation.)
- (c) Implement rotate in size-augmented BSTs in Python in the stub we have given you.

Food for thought (do read - it's an important take-away from this problem): This problem concerns size-augmented binary search trees. In lecture, we discussed AVL trees, which are balanced binary search trees where every vertex contains an additional height attribute containing the length of the longest path from the vertex to a leaf (height-augmented). Additionally, every pair of siblings in the tree have heights differing by at most 1, so the tree is height-balanced. Note that if we augment a binary search tree both by size (as in the above problem) and by height (and use it to maintain the AVL property), then we create a dynamic data structure able to perform search, insert, and select all in time $O(\log n)$.

4. (reflection) We aim for cs1200 to be a collaborative learning community. Describe two concrete ways in which you have supported, or will try to support, your classmates' learning in the course. Be specific, connecting your answer to the structure of cs1200.

Note: As with the previous psets, you may include your answer in your PDF submission, but the answer should ultimately go into a separate Gradescope submission form.

²Note that the Roughgarden text uses a different indexing than us for the inputs to select. For Roughgarden, the minimum key is selected by select(1), whereas for us it is selected by select(0).

