

Recap++

# Two Fundamental Questions in Sample Complexity

Sampling models: episodic, offline, gen models

**Generative model setting:** input:  $(s, a)$  output: a sample  $s' \sim P(\cdot | s, a)$  and  $r(s, a)$

## 1. The Model Size Question (Sublinear Learning)

- Q1: Can we find an  $\epsilon$ -optimal policy with **sublinear** sample complexity?

## 2. The Horizon Question (Error Amplification)

- Q2: What is the “**horizon amplification**”? i.e. the dependence on  $1/(1 - \gamma)$

# Attempt 1:

## the naive model based approach

# Matrix Expressions

- View  $P$  as a matrix of size  $SA \times S$  (rows are probability distributions)
- Define  $P^\pi$  to be the transition matrix on state-action pairs (for deterministic  $\pi$ ):

$$P^\pi_{(s,a),(s',a')} := \begin{cases} P(s' | s, a) & \text{if } a' = \pi(s') \\ 0 & \text{if } a' \neq \pi(s') \end{cases}$$

- With this notation,

$$Q^\pi = r + \gamma P V^\pi$$

$$Q^\pi = r + \gamma P^\pi Q^\pi$$

- Also,

$$Q^\pi = (I - \gamma P^\pi)^{-1} r$$

(where one can show the inverse exists)

# Model accuracy

**Proposition:**  $c$  is an absolute constant.  $\epsilon > 0$ . For  $N \geq \frac{c\gamma}{(1-\gamma)^4} \frac{S \log(cSA/\delta)}{\epsilon^2}$

and with probability greater than  $1 - \delta$ ,

- Model accuracy: The transition model is  $\epsilon$  has error bounded as:

$$\max_{s,a} \|P(\cdot | s, a) - \hat{P}(\cdot | s, a)\|_1 \leq (1 - \gamma)^2 \epsilon / 2.$$

- Uniform value accuracy: For all policies  $\pi$ ,

$$\|Q^\pi - \hat{Q}^\pi\|_\infty \leq \epsilon / 2$$

- Near optimal planning: Suppose that  $\hat{\pi}^\star$  is the optimal policy in  $\hat{M}$ .

$$\|Q^\star - Q^{\hat{\pi}^\star}\|_\infty \leq \epsilon$$

# Attempt 2:

obtaining sublinear sample complexity

idea: use concentration only on  $V^\star$

# Sample Size Corollaries

**Corollary:** for  $\epsilon < 1$ , provided  $N \geq \frac{c}{(1-\gamma)^4} \frac{\log(cSA/\delta)}{\epsilon^2}$  then

$$\|Q^\star - \widehat{Q}^\star\|_\infty \leq \epsilon \text{ (with prob. greater than } 1 - \delta)$$

What about the policy?

**Corollary:** for  $\epsilon < 1$ , provided  $N \geq \frac{c}{(1-\gamma)^6} \frac{\log(cSA/\delta)}{\epsilon^2}$  then

$$\|Q^\star - Q^{\widehat{\pi}^\star}\|_\infty \leq \epsilon \text{ (with prob. greater than } 1 - \delta)$$

# Component-wise Bounds Lemma

**Lemma:** we have that

$$Q^\star - \widehat{Q}^\star \leq \gamma(I - \gamma \widehat{P}^{\pi^\star})^{-1}(P - \widehat{P})V^\star$$

$$Q^\star - \widehat{Q}^\star \geq \gamma(I - \gamma \widehat{P}^{\hat{\pi}^\star})^{-1}(P - \widehat{P})V^\star$$

**Proof:**

For the first claim, the optimality of  $\pi^\star$  in  $M$  implies:

$$Q^\star - \widehat{Q}^\star = Q^{\pi^\star} - \widehat{Q}^{\hat{\pi}^\star} \leq Q^{\pi^\star} - \widehat{Q}^{\pi^\star} = \gamma(I - \gamma \widehat{P}^{\pi^\star})^{-1}(P - \widehat{P})V^\star,$$

using the simulation lemma in the final step.

See notes for the proof of second claim.



# Attempt 3:

minimax optimal sample complexity

idea: better variance control

## Revisiting proof attempt 2: where is there slop?

- Proof of the first claim:

- By comp. lemma:  $\|Q^\star - \widehat{Q}^\star\|_\infty \leq \frac{\gamma}{1-\gamma} \|(P - \widehat{P})V^\star\|_\infty$

- Recall  $\|V^\star\|_\infty \leq 1/(1-\gamma)$ .

- By Hoeffding's inequality and the union bound,

$$\begin{aligned} \|(P - \widehat{P})V^\star\|_\infty &= \max_{s,a} \left| E_{s' \sim P(\cdot|s,a)}[V^\star(s')] - E_{s' \sim \widehat{P}(\cdot|s,a)}[V^\star(s')] \right| \\ &\leq \frac{1}{1-\gamma} \sqrt{\frac{2 \log(2SA/\delta)}{N}} \end{aligned}$$

which holds with probability greater than  $1 - \delta$ .

- Proof of second claim is similar (see the book)

# Minimax Optimal Sample Complexity

**Corollary:** for  $\epsilon < 1$ , provided  $N \geq \frac{c}{(1 - \gamma)^3} \frac{\log(cSA/\delta)}{\epsilon^2}$  then

$$\|Q^\star - \widehat{Q}^\star\|_\infty \leq \epsilon \text{ (with prob. greater than } 1 - \delta)$$

What about the policy?

Naively, we need  $N/(1 - \gamma)^2$  more samples.

**A different thm gives:** With the same  $N$ ,

$$\|Q^\star - Q^{\widehat{\pi}^\star}\|_\infty \leq \epsilon \text{ (with prob. greater than } 1 - \delta)$$

**Lower Bound:** We can't do better.

# Proof sketch: part 1

- From Bernstein's ineq, with pr. greater than  $1 - \delta$ , we have (component-wise):

$$|(P - \widehat{P})V^*| \leq \sqrt{\frac{2 \log(2SA/\delta)}{N}} \sqrt{\text{Var}_P(V^*)} + \frac{1}{1 - \gamma} \frac{2 \log(2SA/\delta)}{3N} \vec{1}$$

- How to use this: again from “Component-wise Bounds” lemma,

$$Q^* - \widehat{Q}^* \leq \gamma \|(I - \gamma \widehat{P}^{\pi^*})^{-1} (P - \widehat{P})V^*\|_\infty \leq ??$$

- Therefore

$$Q^* - \widehat{Q}^* \leq \gamma \sqrt{\frac{2 \log(2SA/\delta)}{N}} \|(I - \gamma \widehat{P}^{\pi^*})^{-1} \sqrt{\text{Var}_P(V^*)}\|_\infty$$

+ "lower order term"

# Bellman Equation for the (total) Variance

- **Variance:**  $\text{Var}_P(V)(s, a) := \text{Var}_{P(\cdot|s,a)}(V)$

Component wise variance:  $\text{Var}_P(V) := P(V)^2 - (PV)^2$

- Let's keep around the MDP M subscripts.

Define  $\Sigma_M^\pi$  as the (total) variance of the discounted reward:

$$\Sigma_M^\pi(s, a) := E \left[ \left( \sum_{t=0}^{\infty} \gamma^t r(s_t, a_t) - Q_M^\pi(s, a) \right)^2 \middle| s_0 = s, a_0 = a \right]$$

- **Bellman equation for the total variance:**

$$\Sigma_M^\pi = \gamma^2 \text{Var}_P(V_M^\pi) + \gamma^2 P^\pi \Sigma_M^\pi$$