Non-Relational Numerical Abstract Domains

MPRI 2–6: Abstract Interpretation, application to verification and static analysis

Antoine Miné

year 2015-2016

course 04 14 October 2015

Outline

- Some applications of numerical domains
- Generalities, notations
- Presentation of a few numerical abstract domains (non-relational)
 - sign domains
 - constant domain
 - interval domain
 - simple congruence domain
- Reduced products of domains
- Bibliography

Selected applications of numerical domains

Invariant discovery

Goal: find intermittent numerical invariants

(at each program point, properties of numerical variables true for all executions)

```
X := [0, 10]; Y := 100;
while X>=0 do
     // loop invariant?
  X := X-1;
  Y := Y + 10
done
// value of X and Y?
```

Invariant discovery

Goal: find intermittent numerical invariants

(at each program point, properties of numerical variables true for all executions)

```
Example
 X := [0, 10]; Y := 100;
   // X \in [0, 10], Y = 100
 while X >= 0 do
      // X \in [0, 10], Y \in [100, 200]
   X := X - 1 :
      // X \in [-1, 9], Y \in [100, 200]
   Y \cdot = Y + 10
      // X \in [-1, 9], Y \in [110, 210]
 done
 //X = -1, Y \in [110, 210]
```

Variable bounds

Invariant discovery

Hope: find the strongest intermittent numerical invariants

(at each program point, the strongest properties of numerical variables true for all executions)

```
Example
 X := [0,10]; Y := 100;
    // X \in [0, 10], Y = 100
 while X >= 0 do
       // X \in [0, 10], 10X + Y \in [100, 200] \cap 10\mathbb{Z}
    X := X - 1 :
       // X \in [-1, 9], 10X + Y \in [90, 190] \cap 10\mathbb{Z}
    Y := Y + 10
       // X \in [-1, 9], 10X + Y \in [100, 200] \cap 10\mathbb{Z}
 done
 //X = -1, Y \in [110, 210] \cap 10\mathbb{Z}
```

Variable bounds, linear relations and congruences

Application: proof of absence of run-time error

```
delay line, in C
 int delay[10], i;
 for (i=10; i>0; i=i-1)
     delay[i-1] = 0;
 while (1) {
     int y = delay[i];
     delay[i] = input();
     i = i+1;
     if (i>=10) i = 0;
     /* use y */
```

Some operations are undefined or dangerous:

- arithmetic operations can overflow
- arrays can be accessed out of bounds

Application: proof of absence of run-time error

```
delay line, in C
 int delay[10], i;
 for (i=10; i>0; \langle i-1 \in [-2^{31}, 2^{31}-1] \rangle i=i-1)
       (i-1 \in [0,9]) delay[i-1] = 0;
 while (1) {
       int y = \langle i \in [0, 9] \rangle delay[i];
       \langle i \in [0,9] \rangle delay[i] = input();
       \langle i+1 \in [-2^{31}, 2^{31}-1] \rangle i = i+1;
       if (i>=10) i = 0;
       /* use y */
```

To prove the absence of run-time error:

• insert verification conditions $\langle \cdot \rangle$ ensuring error-freedom

Application: proof of absence of run-time error

```
delay line, in C
 int delay[10], i;
 for (i=10; i>0; (i \in [1,10]) \langle i-1 \in [-2^{31}, 2^{31}-1] \rangle i=i-1)
       (i \in [1, 10]) \ (i - 1 \in [0, 9]) \ delay[i-1] = 0;
 (i = 0) while (1) {
       int y = (i \in [0, 9]) (i \in [0, 9]) delay[i];
       (i \in [0,9]) \langle i \in [0,9] \rangle delay[i] = input();
       (i \in [0, 9]) \langle i + 1 \in [-2^{31}, 2^{31} - 1] \rangle i = i+1;
       (i \in [1, 10]) if (i \ge 10) i = 0 (i \in [0, 9]);
       /* use y */
```

To prove the absence of run-time error:

- insert verification conditions ⟨·⟩ ensuring error-freedom
- infer invariants (·)
- check in the abstract that the invariants imply the conditions (e.g., reduces to interval inclusion in the interval domain)

Forward-backward analysis

sign function

```
X:=[-100,100];
if X=0 then Z:=0 else
   Y:=X;
   if Y < 0 then Y:=-Y;
   Z:=X/Y</pre>
```

Forward-backward analysis

sign function

```
 \begin{split} & \text{X:=} [-100,100] \; ; \; (\text{X} \in [-100,100]) \\ & \text{if X=0 then Z:=0 else} \; (\text{X} \in [-100,100]) \\ & \text{Y:=X;} \; (\text{X},\text{Y} \in [-100,100]) \\ & \text{if Y} < \text{0 then Y:=-Y;} \; (\text{X} \in [-100,100], \text{Y} \in [0,100]) \\ & \text{Z:=X/Y} \; (\text{X} \in [-100,100], \text{Y} \in [0,100]) \\ & \text{fi} \\ \end{split}
```

Forward interval analysis (possible division by 0)

Forward-backward analysis

sign function

```
X:=[-100,100]; (\bot)

if X=0 then Z:=0 else (X = 0)

Y:=X; (Y = 0)

if Y < 0 then Y:=-Y; (Y = 0)

Z:=X/Y (Y = 0)

fi
```

Backward interval analysis

- infer (tight) necessary conditions on inputs to reach a given point in a given state (Y = 0 at the end of the program)
- refine and focus the result of a forward analysis (prove the absence of division by zero) [Bour93b]

Relation analysis

store the maximum of X,Y,0 into Z

Relation analysis

```
store the maximum of X,Y,O into Z'

max(X,Y,Z)
   X':=X; Y':=Y; Z':=Z;
   Z':=X';
   if Y' > Z' then Z':=Y';
   if Z' < O then Z':=O;</pre>
```

• add and rename variables: keep a copy of input values

Relation analysis

```
store the maximum of X,Y,0 into Z'
\frac{\max}{(X,Y,Z)}
X':=X; Y':=Y; Z':=Z;
Z':=X';
if Y' > Z' then Z':=Y';
if Z' < 0 then Z':=0;
(Z' \geq X \wedge Z' \geq Y \wedge Z' \geq 0 \wedge X' = X \wedge Y' = Y)
```

- add and rename variables: keep a copy of input values
- infer a relation between input values (X,Y,Z) and current values (X',Y',Z')

Applications: procedure summaries, modular analyses. [Anco10]

Academic implementation: Apron and Interproc

Apron: library of numerical abstractions [Jean09]

Interproc: on-line analyzer for a toy language, based on Apron



http://pop-art.inrialpes.fr/interproc/interprocweb.cgi

Applications to non-numerical analyses

Pointer offset analysis

pointer arithmetic

```
float* p = q;
for (i=0; i<10; i++)
  if (...) p++;</pre>
```

offset arithmetic

```
unsigned off<sub>p</sub> = off<sub>q</sub>;
for (i=0; i<10; i++)
if (...) off<sub>p</sub> += 4;
(off_q \le off_p \le off_q + 4 \times i + 4)
```

In C, pointers can be viewed as symbolic integers with:

- a symbolic base
- an integer offset (off_p, off_q)

[Mine06]

String analysis for C

pointers and buffers char buf[20]; char* p; strcpy(buf, "Hello"); p = buf+5; strcpy(p, " world!");

In C, strings are pointers to arrays of char, terminated by 0:

- no explicit information on available space (buffer length)
- no explicit length information (position of 0)
- aliasing is possible
- ⇒ source of many programming errors

String analysis for C

pointers and buffers

```
char buf [20]; (alloc_{buf} = 20)

char* p;

(alloc_{buf} \ge 6)

strcpy(buf, "Hello"); (len_{buf} = 5)

p = buf+5; (stride_{p-buf} = 5, len_p = len_{buf} - 5, alloc_p = alloc_{buf} - 5)

(alloc_p \ge 8)

strcpy(p, " world!"); (len_p = 7, len_{buf} = len_p + stride_{p-buf})
```

Analysis of correctness: [Dor01]

- instrument the program with integer variables $(alloc_p, len_p, stride_{p-q})$
- add code to update the variables (·)
- add safety assertions ⟨·⟩
- infer invariants and prove that the assertions hold

Memory shape analysis

```
list creation and copy into an array

cell *x, *head = NULL;
for (i=0; i<n; i++) {
    x = alloc();
    x->next = head; head = x;
}

(k \in [0, n-1] \land head(->next)^k -> data = 0)
for (i=0, x=head; x; x=x->next, i++)
    a[i] = x->data;
(k \in [0, n-1] \land a[k] = head(->next)^k -> data)
```

Numerical analysis on:

- program variables: i, n, and
- instrumentation variables: k, $head(->next)^k -> data$, a[k]

[Vene02]

Cost analysis

```
selection sort

cost = 0;
for i=0 to n-2 do
   for j=i+1 to n-1 do
     if tab[i] > tab[j] then swap(tab[i],tab[j]);
   cost = cost+1
   done
done
```

To count the maximum number of instructions:

• instrument the program with a counter

Cost analysis

```
selection sort  \begin{aligned} & \text{cost} = 0; \\ & \text{for } i\text{=0 to } n\text{-2 do } \left( cost = i \times n - i \times (i+1)/2 \right) \\ & \text{for } j\text{=}i\text{+1 to } n\text{-1 do } \left( cost = i \times n - i \times (i+1)/2 + j - i - 1 \right) \\ & \text{if } tab[i] > tab[j] \text{ then } swap(tab[i], tab[j]); \\ & \text{cost} = cost\text{+1} \\ & \text{done} \\ & \text{done} \\ & \text{(}cost = (n+1) \times (n-2)/2 \text{)} \end{aligned}
```

To count the maximum number of instructions:

- instrument the program with a counter
- infer loop and exit invariants (·)

Dependency analysis for array indices

multiplication of polynomials

```
for i=1 to n do
  for j=1 to n do
    v := r[i+j] •;
         r[i+j] := v + a[i] * b[j];
         t := t+1
         done
done
```

Can a read at • depend on a previous write from ♠?

- add a global counter t (allows expressing temporal properties)
- infer an invariant set $X \in \mathbb{Z}^3$ for t, i, j
- check $\exists ((t, i, j), (t', i', j')) \in X \times X, t > t', i + j = i' + j'$

Information used by compilers to enable loop transformations [Girb06].

Generalities and notations

Syntax

Expression syntax

Toy language:

- fixed, finite set of variables V,
- one datatype: scalars in \mathbb{I} , with $\mathbb{I} \in \{ \mathbb{Z}, \mathbb{Q}, \mathbb{R} \}$ (and later, floating-point numbers \mathbb{F})
- no procedure

arithmetic expressions:

```
\begin{array}{lll} \texttt{exp} & ::= & \texttt{V} & \texttt{variable V} \in \mathbb{V} \\ & | & -\texttt{exp} & \texttt{negation} \\ & | & \texttt{exp} \diamond \texttt{exp} & \texttt{binary operation:} \; \diamond \in \{+,-,\times,/\} \\ & | & [c,c'] & \texttt{constant range,} \; c,c' \in \mathbb{I} \cup \{\pm \infty\} \\ & c \; \texttt{is a shorthand for} \; [c,c] \end{array}
```

Programs (structured syntax)

```
\begin{array}{lll} & \text{programs:} & \text{as syntax trees} \\ & \text{prog::=} & & & & & & \\ & & \text{V} := \exp & & & & & \text{assignment} \\ & & \text{if } \exp \bowtie 0 \text{ then prog else prog fi test} \\ & & & \text{while } \exp \bowtie 0 \text{ do prog done} & & & \text{loop} \\ & & & & & \text{prog; prog} & & & \text{sequence} \\ & & & & & & & \text{no-op} \\ \end{array}
```

comparison operators: $\bowtie \in \{=,<,>,<=,>=,<>\}$.

Programs (as control-flow graphs)

commands:

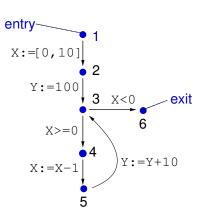
$$\begin{array}{lll} \text{com} & ::= & \mathtt{V} & := & \exp & \text{assignment into } \mathtt{V} \in \mathbb{V} \\ & | & \exp \bowtie 0 & \text{test, } \bowtie \in \{\,=,<,>,<=,>=,<>\,\} \end{array}$$

programs: as control-flow graphs

```
P \stackrel{\text{def}}{=} (L, e, x, A) \begin{vmatrix} L & \text{program points (labels)} \\ e & \text{entry point: } e \in L \\ x & \text{exit point: } x \in L \\ A & \text{arcs: } A \subseteq L \times \text{com} \times L \end{vmatrix}
```

Example

structured program



control flow graph

Concrete semantics

Forward concrete semantics

Semantics of expressions: $\mathbb{E}[\![e]\!]: (\mathbb{V} \to \mathbb{I}) \to \mathcal{P}(\mathbb{I})$

The evaluation of e in ρ gives a set of values:

```
def
                                                     \{x \in \mathbb{I} \mid c \le x \le c'\}
\mathbb{E}[[c,c']]\rho
                                       \stackrel{\text{def}}{=}
\mathbb{E}[\![V]\!]\rho
                                                   \{ \rho(V) \}
                                       \stackrel{\text{def}}{=} \{-v \mid v \in \mathsf{E} \llbracket e \rrbracket \rho \}
\mathbb{E} \llbracket -e \rrbracket \rho
                                        def
=
\mathbb{E} \llbracket e_1 + e_2 \rrbracket \rho
                                                \{v_1 + v_2 \mid v_1 \in E[[e_1]] \rho, v_2 \in E[[e_2]] \rho\}
                                       def
=
                                                   \{ v_1 - v_2 \mid v_1 \in \mathsf{E} \llbracket e_1 \rrbracket \rho, v_2 \in \mathsf{E} \llbracket e_2 \rrbracket \rho \}
\mathbb{E}\llbracket e_1 - e_2 \rrbracket \rho
                                      def
=
\mathbb{E}\llbracket e_1 \times e_2 \rrbracket \rho
                                                   \{v_1 \times v_2 \mid v_1 \in \mathbb{E}[e_1] \mid \rho, v_2 \in \mathbb{E}[e_2] \mid \rho\}
                                        def
\mathbb{E}[\![e_1/e_2]\!]\rho
                                                  \{v_1/v_2 \mid v_1 \in \mathbb{E}[\![e_1]\!] \rho, v_2 \in \mathbb{E}[\![e_2]\!] \rho, v_2 \neq 0\}
```

Forward concrete semantics (cont.)

A transfer function for c defines a relation on environments:

$$\begin{split} \mathbb{C} \big[\![\, \mathbb{V} := & e \, \big]\!] \, \mathcal{X} & \stackrel{\mathrm{def}}{=} & \big\{ \, \rho \big[\, \mathbb{V} \mapsto v \, \big] \, \big| \, \rho \in \mathcal{X}, \ v \in \mathbb{E} \big[\![\, e \, \big]\!] \, \rho \, \big\} \\ \mathbb{C} \big[\![\, e \bowtie 0 \, \big]\!] \, \mathcal{X} & \stackrel{\mathrm{def}}{=} & \big\{ \, \rho \, \big| \, \rho \in \mathcal{X}, \ \exists v \in \mathbb{E} \big[\![\, e \, \big]\!] \, \rho, \ v \bowtie 0 \, \big\} \end{split}$$

It relates the environments after the execution of a command to the environments before.

Complete join morphism: $C[\![c]\!]\mathcal{X} = \bigcup_{\rho \in \mathcal{X}} C[\![c]\!]\{\rho\}.$

Forward concrete semantics (cont.)

Semantics of programs: $P[(L, e, x, A)]: L \to \mathcal{P}(V \to I)$

$$P[(L, e, x, A)] \ell$$
 is the most precise invariant at $\ell \in L$.

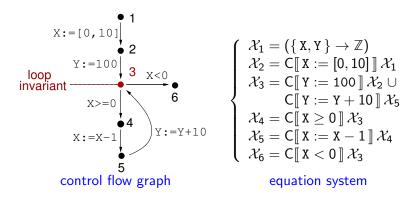
It is the smallest solution of a recursive equation system $(\mathcal{X}_{\ell})_{\ell \in L}$:

Semantic equation system
$$\mathcal{X}_e \qquad \qquad \qquad \text{(given initial state)} \\ \mathcal{X}_{\ell \neq e} \ = \ \bigcup_{(\ell',c,\ell) \in A} \mathsf{C} \llbracket \, c \, \rrbracket \, \mathcal{X}_{\ell'} \quad \text{(transfer function)}$$

Tarski's Theorem: this smallest solution exists and is unique.

- $\mathcal{D} \stackrel{\text{def}}{=} (\mathcal{P}(\mathbb{V} \to \mathbb{I}), \subset, \cup, \cap, \emptyset, (\mathbb{V} \to \mathbb{I}))$ is a complete lattice,
- each $M_{\ell}: \mathcal{X}_{\ell} \mapsto \bigcup C \llbracket c \rrbracket \mathcal{X}_{\ell'}$ is monotonic in \mathcal{D} . $(\ell',c,\ell)\in A$
 - \Rightarrow the solution is the least fixpoint of $(M_{\ell})_{\ell \in L}$.

Forward concrete semantics (example)



Loop invariant:

$$\mathcal{X}_3 = \{ \rho \mid \rho(X) \in [0, 10], \ 10\rho(X) + \rho(Y) \in [100, 200] \cap 10\mathbb{Z} \}$$

Resolution

Resolution by increasing iterations:

$$\left\{ \begin{array}{ccc} \mathcal{X}_{e}^{0} & \stackrel{\mathrm{def}}{=} & \mathcal{X}_{e} \\ \mathcal{X}_{\ell \neq e}^{0} & \stackrel{\mathrm{def}}{=} & \emptyset \end{array} \right. \quad \left\{ \begin{array}{ccc} \mathcal{X}_{e}^{n+1} & \stackrel{\mathrm{def}}{=} & \mathcal{X}_{e} \\ \mathcal{X}_{\ell \neq e}^{n+1} & \stackrel{\mathrm{def}}{=} & \bigcup_{(\ell', c, \ell) \in A} \mathsf{C} \llbracket \, c \, \rrbracket \, \mathcal{X}_{\ell'}^{n} \right.$$

Converges in ω iterations to a least solution, because each $\mathbb{C}[\![c]\!]$ is continuous in the CPO \mathcal{D} .

(Kleene fixpoint theorem)

iteration 0

$$\left\{ \begin{array}{ll} \mathcal{X}_1 = \mathbb{Z}^2 & \mathbb{Z}^2 \\ \mathcal{X}_2 = \mathbb{C} \llbracket \, \mathbf{X} := [0,10] \, \rrbracket \, \mathcal{X}_1 & \emptyset \\ \mathcal{X}_3 = & \mathbb{C} \llbracket \, \mathbf{Y} := 100 \, \rrbracket \, \mathcal{X}_2 \cup \\ \mathbb{C} \llbracket \, \mathbf{Y} := \mathbf{Y} + 10 \, \rrbracket \, \mathcal{X}_5 & \emptyset \\ \mathcal{X}_4 = & \mathbb{C} \llbracket \, \mathbf{X} \ge 0 \, \rrbracket \, \mathcal{X}_3 & \emptyset \\ \mathcal{X}_5 = & \mathbb{C} \llbracket \, \mathbf{X} := \mathbf{X} - 1 \, \rrbracket \, \mathcal{X}_4 & \emptyset \\ \mathcal{X}_6 = & \mathbb{C} \llbracket \, \mathbf{X} < 0 \, \rrbracket \, \mathcal{X}_3 & \emptyset \end{array} \right.$$

iteration 1

$$\mathcal{X}_1 = \mathbb{Z}^2$$

$$\mathcal{X}_2 = \texttt{C}[\![\, \texttt{X} := [0,10]\,]\!]\,\mathcal{X}_1$$

$$\begin{cases} \mathcal{X}_1 = \mathbb{Z}^2 & \mathbb{Z}^2 \\ \mathcal{X}_2 = \mathbb{C} \llbracket \, \mathtt{X} := [0,10] \, \rrbracket \, \mathcal{X}_1 & [0,10] \times \mathbb{Z} \\ \mathcal{X}_3 = & \mathbb{C} \llbracket \, \mathtt{Y} := 100 \, \rrbracket \, \mathcal{X}_2 \cup & \emptyset \\ \mathbb{C} \llbracket \, \mathtt{Y} := \, \mathtt{Y} + 10 \, \rrbracket \, \mathcal{X}_5 & \emptyset \\ \mathcal{X}_4 = & \mathbb{C} \llbracket \, \mathtt{X} \ge 0 \, \rrbracket \, \mathcal{X}_3 & \emptyset \\ \mathcal{X}_5 = & \mathbb{C} \llbracket \, \mathtt{X} := \, \mathtt{X} - 1 \, \rrbracket \, \mathcal{X}_4 & \emptyset \\ \mathcal{X}_6 = & \mathbb{C} \llbracket \, \mathtt{X} < 0 \, \rrbracket \, \mathcal{X}_3 & \emptyset \end{cases}$$

$$\mathcal{X}_4 = \mathsf{C}[\![\mathtt{X} \geq \mathsf{0} \,]\!] \, \mathcal{X}_3$$

$$\mathcal{X}_5 = \mathsf{C} \llbracket \mathtt{X} := \mathtt{X} - 1 \rrbracket \mathcal{X}_4 \qquad \emptyset$$

$$\mathcal{X}_6 = \mathsf{C}[\![\mathsf{X} < \mathsf{0}]\!] \, \mathcal{X}_3 \tag{9}$$

$$\begin{cases} \mathcal{X}_1 = \mathbb{Z}^2 & \text{iteration 2} \\ \mathcal{X}_2 = \mathsf{C} \llbracket \, \mathtt{X} := [0,10] \, \rrbracket \, \mathcal{X}_1 & [0,10] \times \mathbb{Z} \\ \mathcal{X}_3 = & \mathsf{C} \llbracket \, \mathtt{Y} := 100 \, \rrbracket \, \mathcal{X}_2 \cup \\ \mathsf{C} \llbracket \, \mathtt{Y} := \mathtt{Y} + 10 \, \rrbracket \, \mathcal{X}_5 & \{ \, (0,100), \ldots, (10,100) \, \} \\ \mathcal{X}_4 = & \mathsf{C} \llbracket \, \mathtt{X} \geq 0 \, \rrbracket \, \mathcal{X}_3 & \emptyset \\ \\ \mathcal{X}_5 = & \mathsf{C} \llbracket \, \mathtt{X} := \mathtt{X} - 1 \, \rrbracket \, \mathcal{X}_4 & \emptyset \\ \\ \mathcal{X}_6 = & \mathsf{C} \llbracket \, \mathtt{X} < 0 \, \rrbracket \, \mathcal{X}_3 & \emptyset \end{cases}$$

$$\begin{cases} \mathcal{X}_1 = \mathbb{Z}^2 & \text{iteration 3} \\ \mathcal{X}_2 = \mathsf{C}[\![\, \mathbb{X} := [0,10]\,]\!]\,\mathcal{X}_1 & [0,10] \times \mathbb{Z} \\ \mathcal{X}_3 = & \mathsf{C}[\![\, \mathbb{Y} := 100\,]\!]\,\mathcal{X}_2 \cup \\ & \mathsf{C}[\![\, \mathbb{Y} := \mathbb{Y} + 10\,]\!]\,\mathcal{X}_5 & \{\,(0,100),\ldots,(10,100)\,\} \\ \mathcal{X}_4 = & \mathsf{C}[\![\, \mathbb{X} \ge 0\,]\!]\,\mathcal{X}_3 & \{\,(0,100),\ldots,(10,100)\,\} \\ \mathcal{X}_5 = & \mathsf{C}[\![\, \mathbb{X} := \mathbb{X} - 1\,]\!]\,\mathcal{X}_4 & \emptyset \\ \mathcal{X}_6 = & \mathsf{C}[\![\, \mathbb{X} < 0\,]\!]\,\mathcal{X}_3 & \emptyset \end{cases}$$

$$\begin{cases} \mathcal{X}_1 = \mathbb{Z}^2 & \text{iteration 4} \\ \mathcal{X}_2 = \mathbb{C}[\![\, \mathbb{X} := [0,10] \,]\!] \, \mathcal{X}_1 & [0,10] \times \mathbb{Z} \\ \mathcal{X}_3 = & \mathbb{C}[\![\, \mathbb{Y} := 100 \,]\!] \, \mathcal{X}_2 \cup \\ & \mathbb{C}[\![\, \mathbb{Y} := \mathbb{Y} + 10 \,]\!] \, \mathcal{X}_5 \end{cases} & \left\{ (0,100), \dots, (10,100) \right\} \\ \mathcal{X}_4 = & \mathbb{C}[\![\, \mathbb{X} \ge 0 \,]\!] \, \mathcal{X}_3 & \left\{ (0,100), \dots, (10,100) \right\} \\ \mathcal{X}_5 = & \mathbb{C}[\![\, \mathbb{X} := \mathbb{X} - 1 \,]\!] \, \mathcal{X}_4 & \left\{ (-1,100), \dots, (9,100) \right\} \\ \mathcal{X}_6 = & \mathbb{C}[\![\, \mathbb{X} < 0 \,]\!] \, \mathcal{X}_3 & \emptyset \end{cases}$$

$$\begin{cases} \mathcal{X}_1 = \mathbb{Z}^2 & \text{iteration 5} \\ \mathcal{X}_2 = \mathbb{C}[\![\, \mathbf{X} := [0,10] \,]\!] \, \mathcal{X}_1 & [0,10] \times \mathbb{Z} \\ \mathcal{X}_3 = & \mathbb{C}[\![\, \mathbf{Y} := 100 \,]\!] \, \mathcal{X}_2 \cup \\ & \mathbb{C}[\![\, \mathbf{Y} := \, \mathbf{Y} + 10 \,]\!] \, \mathcal{X}_5 & (-1,110), \dots, (9,110) \,\} \\ \mathcal{X}_4 = & \mathbb{C}[\![\, \mathbf{X} \ge 0 \,]\!] \, \mathcal{X}_3 & \{ \, (0,100), \dots, (10,100) \,\} \\ \mathcal{X}_5 = & \mathbb{C}[\![\, \mathbf{X} := \, \mathbf{X} - 1 \,]\!] \, \mathcal{X}_4 & \{ \, (-1,100), \dots, (9,100) \,\} \\ \mathcal{X}_6 = & \mathbb{C}[\![\, \mathbf{X} < 0 \,]\!] \, \mathcal{X}_3 & \emptyset \end{cases}$$

$$\begin{cases} \mathcal{X}_1 = \mathbb{Z}^2 & \text{iteration 6} \\ \mathcal{X}_2 = \mathbb{C}[\![\, \mathbb{X} := [0,10] \,]\!] \, \mathcal{X}_1 & [0,10] \times \mathbb{Z} \\ \mathcal{X}_3 = & \mathbb{C}[\![\, \mathbb{Y} := 100 \,]\!] \, \mathcal{X}_2 \cup \\ & \mathbb{C}[\![\, \mathbb{Y} := \mathbb{Y} + 10 \,]\!] \, \mathcal{X}_5 & (-1,110), \dots, (9,110) \,\} \\ \mathcal{X}_4 = & \mathbb{C}[\![\, \mathbb{X} \ge 0 \,]\!] \, \mathcal{X}_3 & \{ (0,100), \dots, (10,100), \\ & (0,110), \dots, (9,110) \,\} \\ \mathcal{X}_5 = & \mathbb{C}[\![\, \mathbb{X} := \mathbb{X} - 1 \,]\!] \, \mathcal{X}_4 & \{ (-1,100), \dots, (9,100) \,\} \\ \mathcal{X}_6 = & \mathbb{C}[\![\, \mathbb{X} < 0 \,]\!] \, \mathcal{X}_3 & \{ (-1,110) \,\} \end{cases}$$

$$\begin{cases} \mathcal{X}_1 = \mathbb{Z}^2 & \text{iteration 7} \\ \mathcal{X}_2 = C[X := [0, 10]] \mathcal{X}_1 & [0, 10] \times \mathbb{Z} \\ \mathcal{X}_3 = & C[Y := 100] \mathcal{X}_2 \cup \\ & C[Y := Y + 10] \mathcal{X}_5 & \{(0, 100), \dots, (10, 100), \\ & (-1, 110), \dots, (9, 110)\} \end{cases}$$

$$\mathcal{X}_4 = & C[X \ge 0] \mathcal{X}_3 & \{(0, 100), \dots, (10, 100), \\ & (0, 110), \dots, (9, 110)\} \end{cases}$$

$$\mathcal{X}_5 = & C[X := X - 1] \mathcal{X}_4 & \{(-1, 100), \dots, (9, 100), \\ & (-1, 110), \dots, (8, 110)\} \end{cases}$$

$$\mathcal{X}_6 = & C[X < 0] \mathcal{X}_3 & \{(-1, 110)\}$$

$$\begin{cases} \mathcal{X}_1 = \mathbb{Z}^2 & \text{iteration 8} \\ \mathcal{X}_2 = \mathsf{C}[\![\, \mathtt{X} := [0,10]\,]\!]\,\mathcal{X}_1 & [0,10] \times \mathbb{Z} \\ \mathcal{X}_3 = & \mathsf{C}[\![\, \mathtt{Y} := 100\,]\!]\,\mathcal{X}_2 \cup \\ & \mathsf{C}[\![\, \mathtt{Y} := \mathtt{Y} + 10\,]\!]\,\mathcal{X}_5 & (-1,110),\ldots,(9,110),\\ \mathcal{X}_4 = & \mathsf{C}[\![\, \mathtt{X} \ge 0\,]\!]\,\mathcal{X}_3 & \{(0,100),\ldots,(10,100),\\ & (0,110),\ldots,(9,110)\,\} \end{cases}$$

$$\mathcal{X}_5 = & \mathsf{C}[\![\, \mathtt{X} := \mathtt{X} - 1\,]\!]\,\mathcal{X}_4 & \{(-1,100),\ldots,(9,100),\\ & (-1,110),\ldots,(8,110)\,\} \end{cases}$$

$$\mathcal{X}_6 = & \mathsf{C}[\![\, \mathtt{X} < 0\,]\!]\,\mathcal{X}_3 & \{(-1,110)\}$$

$$\begin{cases} \mathcal{X}_1 = \mathbb{Z}^2 & \mathbb{Z}^2 \\ \mathcal{X}_2 = \mathsf{C} \llbracket \, \mathsf{X} := [0,10] \, \rrbracket \, \mathcal{X}_1 & [0,10] \times \mathbb{Z} \\ \mathcal{X}_3 = & \mathsf{C} \llbracket \, \mathsf{Y} := 100 \, \rrbracket \, \mathcal{X}_2 \cup \\ \mathsf{C} \llbracket \, \mathsf{Y} := \, \mathsf{Y} + 10 \, \rrbracket \, \mathcal{X}_5 & (0,100), \dots, (10,100), \\ \mathcal{X}_4 = & \mathsf{C} \llbracket \, \mathsf{X} \ge 0 \, \rrbracket \, \mathcal{X}_3 & \{ (0,100), \dots, (9,110), \\ (-1,120), \dots, (8,120) \, \} \\ \mathcal{X}_5 = & \mathsf{C} \llbracket \, \mathsf{X} := \, \mathsf{X} - 1 \, \rrbracket \, \mathcal{X}_4 & \{ (0,100), \dots, (9,100), \\ (0,120), \dots, (8,120) \, \} \\ \mathcal{X}_6 = & \mathsf{C} \llbracket \, \mathsf{X} < 0 \, \rrbracket \, \mathcal{X}_3 & \{ (-1,110), (-1,120) \} \end{cases}$$

$$\begin{cases} \mathcal{X}_1 = \mathbb{Z}^2 & \mathbb{Z}^2 \\ \mathcal{X}_2 = \mathsf{C} \llbracket \, \mathsf{X} := [0,10] \, \rrbracket \, \mathcal{X}_1 & [0,10] \times \mathbb{Z} \\ \mathcal{X}_3 = & \mathsf{C} \llbracket \, \mathsf{Y} := 100 \, \rrbracket \, \mathcal{X}_2 \cup \\ \mathsf{C} \llbracket \, \mathsf{Y} := \, \mathsf{Y} + 10 \, \rrbracket \, \mathcal{X}_5 & (-1,110), \ldots, (9,110), \\ \mathcal{X}_4 = & \mathsf{C} \llbracket \, \mathsf{X} \ge 0 \, \rrbracket \, \mathcal{X}_3 & \{ (0,100), \ldots, (10,100), \\ (-1,120), \ldots, (8,120) \, \} \\ \mathcal{X}_5 = & \mathsf{C} \llbracket \, \mathsf{X} := \, \mathsf{X} - 1 \, \rrbracket \, \mathcal{X}_4 & \{ (-1,100), \ldots, (9,110), \\ (0,120), \ldots, (8,120) \, \} \\ \mathcal{X}_6 = & \mathsf{C} \llbracket \, \mathsf{X} < 0 \, \rrbracket \, \mathcal{X}_3 & \{ (-1,110), \ldots, (9,100), \\ (-1,120), \ldots, (7,120) \, \} \end{cases}$$

```
 \begin{cases} \mathcal{X}_1 = \mathbb{Z}^2 & \text{iteration } \dots \\ \mathcal{X}_2 = \mathbb{C}[\![ \, \mathbb{X} := [0,10] \,]\!] \, \mathcal{X}_1 & [0,10] \times \mathbb{Z} \\ \mathcal{X}_3 = & \mathbb{C}[\![ \, \mathbb{Y} := 100 \,]\!] \, \mathcal{X}_2 \cup \\ & \mathbb{C}[\![ \, \mathbb{Y} := \mathbb{Y} + 10 \,]\!] \, \mathcal{X}_5 & (-1,110),\dots,(9,110),\\ \mathcal{X}_4 = & \mathbb{C}[\![ \, \mathbb{X} \ge 0 \,]\!] \, \mathcal{X}_3 & \{(0,100),\dots,(10,100),\\ & (0,120),\dots,(8,120),\dots\\ \mathcal{X}_5 = & \mathbb{C}[\![ \, \mathbb{X} := \mathbb{X} - 1 \,]\!] \, \mathcal{X}_4 & \{(-1,100),\dots,(9,100),\\ & & (-1,120),\dots,(9,100),\\ & & & (-1,120),\dots,(7,120),\dots\\ \mathcal{X}_6 = & \mathbb{C}[\![ \, \mathbb{X} < 0 \,]\!] \, \mathcal{X}_3 & \{(-1,110),(-1,120),\dots \end{cases} 
                                                                                                                                                                                                                 iteration ...
                                                                                                                                                                                               (-1, 120), \ldots, (8, 120), \ldots \}
                                                                                                                                                                                                (0, 120), \ldots, (8, 120), \ldots \}
                                                                                                                                                                                                (-1, 120), \ldots, (7, 120), \ldots
                                                                                                                                                                                         \{(-1,110),(-1,120),\ldots\}
```

Backward concrete semantics

(necessary conditions on ρ to have a successor in \mathcal{X} by c)

Refinement decreasing iterations: given:

- a solution $(\mathcal{X}_{\ell})_{\ell \in L}$ of the forward system
- ullet an output criterion $\mathcal{Y}_{\!\scriptscriptstyle X}$

compute a least fixpoint by decreasing iterations [Bour93b]

$$\begin{cases} \mathcal{Y}_{x}^{0} & \stackrel{\text{def}}{=} \quad \mathcal{X}_{x} \cap \mathcal{Y}_{x} \\ \mathcal{Y}_{\ell \neq x}^{0} & \stackrel{\text{def}}{=} \quad \mathcal{X}_{\ell} \end{cases}$$

$$\begin{cases} \mathcal{Y}_{x}^{n+1} & \stackrel{\text{def}}{=} \quad \mathcal{X}_{x} \cap \mathcal{Y}_{x} \\ \mathcal{Y}_{\ell \neq x}^{n+1} & \stackrel{\text{def}}{=} \quad \mathcal{X}_{\ell} \cap (\bigcup_{(\ell, c, \ell') \in A} \overleftarrow{C} \llbracket c \rrbracket \mathcal{Y}_{\ell'}^{n}) \end{cases}$$

Limit to automation

We wish to perform automatic numerical invariant discovery.

Theoretical problems

- ullet elements of $\mathcal{P}(\mathbb{V} o \mathbb{I})$ are not computer representable
- transfer functions $C[\![c]\!]$, $\overleftarrow{C}[\![c]\!]$ are not computable
- ullet lattice iterations in $\mathcal{P}(\mathbb{V} \to \mathbb{I})$ are transfinite

Finding the best invariant is an undecidable problem

Note:

Even when I is finite, a concrete analysis is not tractable:

- ullet representing elements in $\mathcal{P}(\mathbb{V} o \mathbb{I})$ in extension is expensive
- computing $C[\![c]\!]$, $\overleftarrow{C}[\![c]\!]$ explicitly is expensive
- ullet the lattice $\mathcal{P}(\mathbb{V} o \mathbb{I})$ has a large height $(\Rightarrow$ many iterations)

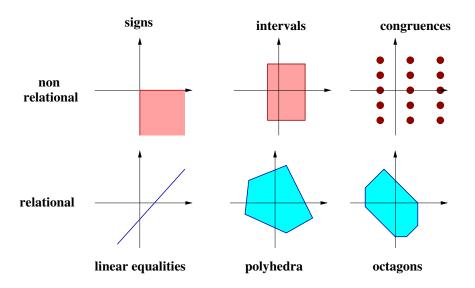
Abstraction

Numerical abstract domains

A numerical abstract domain is given by:

- a subset of P(V → I)
 (a set of environment sets)
 together with a machine encoding,
- effective and sound abstract operators,
- an iteration strategy ensuring convergence in finite time.

Numerical abstract domain examples



Numerical abstract domains (cont.)

Representation: given by

- a set D[#] of machine-representable abstract values,
- a partial order (D[♯], □, ⊥[♯], ⊤[♯])
 relating the amount of information given by abstract values,
- a concretization function $\gamma \colon \mathcal{D}^{\sharp} \to \mathcal{P}(\mathbb{V} \to \mathbb{I})$ giving a concrete meaning to each abstract element.

Required algebraic properties:

- γ should be monotonic for \sqsubseteq : $\mathcal{X}^{\sharp} \sqsubseteq \mathcal{Y}^{\sharp} \Longrightarrow \gamma(\mathcal{X}^{\sharp}) \subseteq \gamma(\mathcal{Y}^{\sharp})$,
- $\gamma(\perp^{\sharp}) = \emptyset$,
- $\gamma(\top^{\sharp}) = \mathbb{V} \to \mathbb{I}$.

Note: γ need not be one-to-one.

Numerical abstract domains (cont.)

Abstract operators: we require:

- sound, effective, abstract transfer functions C[‡] [c], C[‡] [c] for all commands c,
- sound, effective, abstract set operators ∪[‡], ∩[‡],
- an algorithm to decide the ordering ⊆.

Soundness criterion:

 F^{\sharp} is a sound abstraction of a n-ary operator F if:

$$\forall \mathcal{X}_1^{\sharp}, \dots, \mathcal{X}_n^{\sharp} \in D^{\sharp}, \ F(\gamma(\mathcal{X}_1^{\sharp}), \dots, \gamma(\mathcal{X}_n^{\sharp})) \ \subseteq \ \gamma(F^{\sharp}(\mathcal{X}_1^{\sharp}, \dots, \mathcal{X}_n^{\sharp}))$$

Both semantic and algorithmic aspects.

Abstract semantics

Abstract semantic equation system

Soundness Theorem

Any solution $(\mathcal{X}_{\ell}^{\sharp})_{\ell \in L}$ is a **sound over-approximation** of the concrete collecting semantics:

$$\forall \ell \in \textit{L}, \ \gamma(\mathcal{X}_{\ell}^{\sharp}) \supseteq \mathcal{X}_{\ell} \qquad \left\{ \begin{array}{l} \text{where } \mathcal{X}_{\ell} \text{ is the smallest solution of given} \\ \mathcal{X}_{\ell} = \bigcup\limits_{(\ell',c,\ell) \in \textit{A}} \mathsf{C} \llbracket \, c \, \rrbracket \, \mathcal{X}_{\ell'} \quad \text{if } \ell \neq \mathsf{e} \end{array} \right.$$

Iteration strategy

Resolution by iterations in \mathcal{D}^{\sharp} :

To effectively solve the abstract system, we require:

- an iteration ordering on abstract equations (which equation(s) are applied at a given iteration)
- a widening operator

 to speed-up the convergence,

 if there are infinite strictly increasing chains in D[♯].
 - $\nabla: (\mathcal{D}^{\sharp} \times \mathcal{D}^{\sharp}) \to \mathcal{D}^{\sharp}$ is a widening if:
 - it is sound: $\gamma(\mathcal{X}^{\sharp}) \cup \gamma(\mathcal{Y}^{\sharp}) \subseteq \gamma(\mathcal{X}^{\sharp} \vee \mathcal{Y}^{\sharp})$
 - it enforces termination: $\forall \text{ sequence } (\mathcal{Y}_i^{\sharp})_{i \in \mathbb{N}}$ the sequence $\mathcal{X}_0^{\sharp} = \mathcal{Y}_0^{\sharp}, \ \mathcal{X}_{i+1}^{\sharp} = \mathcal{X}_i^{\sharp} \ \nabla \ \mathcal{Y}_{i+1}^{\sharp}$ stabilizes in finite time: $\exists n < \omega, \ \mathcal{X}_{n+1}^{\sharp} = \mathcal{X}_n^{\sharp}$ (note: $\exists n, \forall m \geq n, \ \mathcal{X}_{n+1}^{\sharp} = \mathcal{X}_m^{\sharp}$ is not required)

Abstract analysis

 $\mathcal{W} \subseteq L$ is a set of widening points if every CFG cycle has a point in \mathcal{W} .

Forward analysis:

$$\mathcal{X}_{\ell \neq e}^{\sharp 0} \overset{\text{def}}{=} \mathcal{X}_{e}^{\sharp} \quad \text{given, such that } \mathcal{X}_{e} \subseteq \gamma(\mathcal{X}_{e}^{\sharp})$$

$$\mathcal{X}_{\ell \neq e}^{\sharp 0} \overset{\text{def}}{=} \perp^{\sharp} \quad \text{if } \ell = e$$

$$\mathcal{X}_{\ell}^{\sharp n+1} \overset{\text{def}}{=} \left\{ \begin{array}{ccc} \mathcal{X}_{e}^{\sharp} & \text{if } \ell = e \\ & \bigcup_{(\ell',c,\ell) \in A}^{\sharp} C^{\sharp} \llbracket c \rrbracket \mathcal{X}_{\ell'}^{\sharp n} & \text{if } \ell \notin \mathcal{W}, \, \ell \neq e \\ & \mathcal{X}_{\ell}^{\sharp n} \vee \bigcup_{(\ell',c,\ell) \in A}^{\sharp} C^{\sharp} \llbracket c \rrbracket \mathcal{X}_{\ell'}^{\sharp n} & \text{if } \ell \in \mathcal{W}, \, \ell \neq e \end{array} \right.$$

- ullet termination: for some δ , $orall \ell$, $\mathcal{X}_\ell^{\sharp \delta+1} = \mathcal{X}_\ell^{\sharp \delta}$
- soundness: $\forall \ell \in L, \ \mathcal{X}_{\ell} \subseteq \gamma(\mathcal{X}_{\ell}^{\sharp \delta})$
- can be refined by decreasing iterations with narrowing △ (presented later)
- here, apply every equation at each step, but other iteration scheme are possible (worklist, chaotic iterations, see [Bour93a])

Abstract analysis (proof)

Proof of soundness:

Suppose that
$$\forall \ell, \, \mathcal{X}_{\ell}^{\sharp \delta+1} = \mathcal{X}_{\ell}^{\sharp \delta}.$$

If
$$\ell = e$$
, by definition: $\mathcal{X}_e^{\sharp \delta} = \mathcal{X}_e^{\sharp}$ and $\mathcal{X}_e \subseteq \gamma(\mathcal{X}_e^{\sharp \delta})$.

$$\text{If } \ell \neq e, \, \ell \notin \mathcal{W} \text{, then } \mathcal{X}_{\ell}^{\sharp \delta} = \mathcal{X}_{\ell}^{\sharp \delta+1} = \cup_{(\ell',c,\ell) \in A}^{\sharp} \, \mathsf{C}^{\sharp} \llbracket \, c \, \rrbracket \, \mathcal{X}_{\ell'}^{\sharp \, \delta}.$$

By soundness of
$$\cup^{\sharp}$$
 and $C^{\sharp}[\![c]\!]$, $\gamma(\mathcal{X}_{\ell}^{\sharp\delta}) \supseteq \cup_{(\ell',c,\ell)\in A} C[\![c]\!] \gamma(\mathcal{X}_{\ell'}^{\sharp\delta})$.

$$\text{If } \ell \neq e, \, \ell \in \mathcal{W}, \, \text{then } \mathcal{X}^{\sharp \delta}_{\ell} = \mathcal{X}^{\sharp \delta+1}_{\ell} = \mathcal{X}^{\sharp \delta}_{\ell} \, \triangledown \cup_{(\ell',c,\ell) \in A}^{\sharp} C^{\sharp} \llbracket \, c \, \rrbracket \, \mathcal{X}^{\sharp \, \delta}_{\ell'}.$$

By soundness of
$$\nabla$$
, $\gamma(\mathcal{X}_{\ell}^{\sharp \delta}) \supseteq \gamma(\cup_{(\ell',c,\ell)\in A}^{\sharp} \mathsf{C}^{\sharp} \llbracket c \rrbracket \mathcal{X}_{\ell'}^{\sharp \delta})$,

and so we also have
$$\gamma(\mathcal{X}_{\ell}^{\sharp \delta}) \supseteq \cup_{(\ell',c,\ell) \in \mathcal{A}} \mathsf{C}[\![\,c\,]\!] \gamma(\mathcal{X}_{\ell'}^{\sharp \,\delta}).$$

We have proved that $\lambda\ell.\gamma(\chi_\ell^{\sharp\delta})$ is a postfixpoint of the concrete equation system. Hence, it is greater than its least solution.

Abstract analysis (proof)

Proof of termination:

Suppose that the iteration does not terminate in finite time.

Given a label $\ell \in L$, we denote by $i_\ell^1, \ldots, i_\ell^k, \ldots$ the increasing sequence of unstable indices, i.e., such that $\forall k, \ \mathcal{X}^{\sharp_\ell^{i_\ell^k}+1} \neq \mathcal{X}^{\sharp_\ell^{i_\ell^k}}_{\ell}$.

As the iteration is not stable, $\forall n, \exists \ell, \, \mathcal{X}_{\ell}^{\sharp n} \neq \mathcal{X}_{\ell}^{\sharp n+1}$.

Hence, the sequence $(i_{\ell}^k)_k$ is infinite for at least one $\ell \in L$.

We argue that $\exists \ell \in \mathcal{W}$ such that $(i_{\ell}^k)_k$ is infinite as, otherwise,

 $N=\max\{\,i_\ell^k\,|\,\ell\in\mathcal{W}\,\}+|L|$ is finite and satisfies: $\forall n\geq N, \forall \ell\in L,\, \mathcal{X}_\ell^{\sharp\,n}=\mathcal{X}_\ell^{\sharp\,n+1},$ contradicting our assumption.

For such a $\ell \in \mathcal{W}$, consider the subsequence $\mathcal{Y}_k^\sharp = \mathcal{X}_\ell^{\sharp i_\ell^k}$ comprised of the unstable iterates of \mathcal{X}_ℓ^\sharp .

Then $\mathcal{Y}^{\sharp k+1} = \mathcal{Y}^{\sharp k} \triangledown \mathcal{Z}^{\sharp k}$ for some sequence $\mathcal{Z}^{\sharp k}$.

The subsequence is infinite and $\forall k, \mathcal{Y}^{\sharp k+1} \neq \mathcal{Y}^{\sharp k}$, which contradicts the definition of ∇ .

Hence, the iteration must terminate in finite time.

Abstract analysis (cont.)

Backward refinement:

Given a forward analysis result \mathcal{X}^{\sharp} and an abstract output \mathcal{Y}_{x}^{\sharp} .

△ overapproximates ∩ while enforcing the convergence of decreasing iterations (the definition will be given later, on intervals)

Forward-backward analyses can be iterated [Bour93b].

Exact and best abstractions: Reminders

Galois connection:
$$(\mathcal{D},\subseteq) \stackrel{\gamma}{\underset{\alpha}{\longleftarrow}} (\mathcal{D}^{\sharp},\sqsubseteq)$$

- α , γ monotonic and $\forall \mathcal{X}, \mathcal{Y}^{\sharp}$, $\alpha(\mathcal{X}) \sqsubseteq \mathcal{Y}^{\sharp} \iff \mathcal{X} \subseteq \gamma(\mathcal{Y}^{\sharp})$
- \Rightarrow elements $\mathcal X$ have a best abstraction: $\alpha(\mathcal X)$
- \Rightarrow operators F have a best abstraction: $F^{\sharp} = \alpha \circ F \circ \gamma$

Sometimes, no α exists:

- $\{\gamma(\mathcal{Y}^{\sharp}) | \mathcal{X} \subseteq \gamma(\mathcal{Y}^{\sharp})\}$ has no greatest lower bound
- ullet abstract elements with the same γ have no best representation

 $\alpha \circ F \circ \gamma$ may still be defined for some F (partial α)

Concretization-based optimality:

- sound abstraction: $\gamma \circ F^{\sharp} \supseteq F \circ \gamma$
- exact abstraction: $\gamma \circ F^{\sharp} = F \circ \gamma$
- optimal abstraction: $\gamma(\mathcal{X}^{\sharp})$ minimal in $\{\gamma(\mathcal{Y}^{\sharp}) \mid \mathcal{X} \subseteq \gamma(\mathcal{Y}^{\sharp})\}$

Non-relational domains

Value abstract domain

<u>Idea:</u> start from an abstraction of values $\mathcal{P}(\mathbb{I})$

Numerical value abstract domain:

$$\mathcal{B}^{\sharp}$$
 abstract values, machine-representable $\gamma_b\colon \mathcal{B}^{\sharp} o \mathcal{P}(\mathbb{I})$ concretization \sqsubseteq_b partial order $\bot_b^{\sharp}, \top_b^{\sharp}$ represent \emptyset and \mathbb{I} $\cup_b^{\sharp}, \cap_b^{\sharp}$ abstractions of \cup and \cap extrapolation operator $\alpha_b\colon \mathcal{P}(\mathbb{I}) o \mathcal{B}^{\sharp}$ abstraction (optional)

Derived abstract domain

$$\mathcal{D}^{\sharp} \stackrel{\mathrm{def}}{=} (\mathbb{V} \to (\mathcal{B}^{\sharp} \setminus \{\perp_b^{\sharp}\})) \cup \{\perp^{\sharp}\}$$

- point-wise extension: $\mathcal{X}^{\sharp} \in \mathcal{D}^{\sharp}$ is a vector of elements in \mathcal{B}^{\sharp} (e.g. using arrays of size $|\mathbb{V}|$)
- ullet smashed $oldsymbol{\perp}^{\sharp}$ (avoids redundant representations of \emptyset)

Definitions on \mathcal{D}^{\sharp} derived from \mathcal{B}^{\sharp} :

$$\begin{split} & \gamma(\mathcal{X}^{\sharp}) \stackrel{\mathrm{def}}{=} \left\{ \begin{array}{l} \emptyset & \text{if } \mathcal{X}^{\sharp} = \bot^{\sharp} \\ \left\{ \left. \rho \, | \, \forall \mathtt{V}, \, \rho(\mathtt{V}) \in \gamma_{b}(\mathcal{X}^{\sharp}(\mathtt{V})) \right. \right\} & \text{otherwise} \end{array} \right. \\ & \alpha(\mathcal{X}) \stackrel{\mathrm{def}}{=} \left\{ \begin{array}{l} \bot^{\sharp} & \text{if } \mathcal{X} = \emptyset \\ \lambda \mathtt{V}.\alpha_{b}(\left\{ \left. \rho(\mathtt{V}) \, | \, \rho \in \mathcal{X} \right. \right\}) & \text{otherwise} \end{array} \right. \\ & \mathsf{T}^{\sharp} \stackrel{\mathrm{def}}{=} \lambda \mathtt{V}.\mathsf{T}^{\sharp}_{b} \end{split}$$

Derived abstract domain (cont.)

$$\mathcal{X}^{\sharp} \sqsubseteq \mathcal{Y}^{\sharp} \overset{\text{def}}{\Longrightarrow} \mathcal{X}^{\sharp} = \bot^{\sharp} \lor (\mathcal{X}^{\sharp}, \mathcal{Y}^{\sharp} \neq \bot^{\sharp} \land \forall V, \mathcal{X}^{\sharp}(V) \sqsubseteq_{b} \mathcal{Y}^{\sharp}(V))$$

$$\mathcal{X}^{\sharp} \cup^{\sharp} \mathcal{Y}^{\sharp} \overset{\text{def}}{\Longrightarrow} \begin{cases} \mathcal{Y}^{\sharp} & \text{if } \mathcal{X}^{\sharp} = \bot^{\sharp} \\ \lambda V. \mathcal{X}^{\sharp}(V) \cup_{b}^{\sharp} \mathcal{Y}^{\sharp}(V) & \text{otherwise} \end{cases}$$

$$\mathcal{X}^{\sharp} \vee \mathcal{Y}^{\sharp} \overset{\text{def}}{\Longrightarrow} \begin{cases} \mathcal{Y}^{\sharp} & \text{if } \mathcal{X}^{\sharp} = \bot^{\sharp} \\ \lambda V. \mathcal{X}^{\sharp}(V) \vee_{b} \mathcal{Y}^{\sharp}(V) & \text{otherwise} \end{cases}$$

$$\mathcal{X}^{\sharp} \wedge^{\sharp} \mathcal{Y}^{\sharp} \overset{\text{def}}{\Longrightarrow} \begin{cases} \bot^{\sharp} & \text{if } \mathcal{X}^{\sharp} = \bot^{\sharp} \text{ or } \mathcal{Y}^{\sharp} = \bot^{\sharp} \\ \bot^{\sharp} & \text{if } \exists V, \mathcal{X}^{\sharp}(V) \cap_{b}^{\sharp} \mathcal{Y}^{\sharp}(V) = \bot_{b}^{\sharp} \end{cases}$$

$$\mathcal{X}^{\sharp} \wedge^{\sharp} \mathcal{Y}^{\sharp} \overset{\text{def}}{\Longrightarrow} \begin{cases} \bot^{\sharp} & \text{if } \exists V, \mathcal{X}^{\sharp}(V) \cap_{b}^{\sharp} \mathcal{Y}^{\sharp}(V) = \bot_{b}^{\sharp} \\ \lambda V. \mathcal{X}^{\sharp}(V) \cap_{b}^{\sharp} \mathcal{Y}^{\sharp}(V) & \text{otherwise} \end{cases}$$

We will see later how to derive $C^{\sharp}[c]$, $C^{\sharp}[c]$ using:

- abstract operators $+^{\sharp}_{b}$, ... for $C^{\sharp} \llbracket V := e \rrbracket$
- backward abstract operators $\stackrel{+}{\leftarrow}_b^{\sharp}$, ... for $\stackrel{\leftarrow}{C}^{\sharp} \llbracket V := e \rrbracket$ and $C^{\sharp} \llbracket e \bowtie 0 \rrbracket^{\sharp}$

Cartesian abstraction

Non-relational domains "forget" all relationships between variables.

Cartesian abstraction:

Upper closure operator
$$\rho_c: \mathcal{P}(\mathbb{V} \to \mathbb{I}) \to \mathcal{P}(\mathbb{V} \to \mathbb{I})$$

 $\rho_c(\mathcal{X}) \stackrel{\text{def}}{=} \{ \rho \in \mathbb{V} \to \mathbb{I} \mid \forall \mathbb{V} \in \mathbb{V}, \ \exists \rho' \in \mathcal{X}, \ \rho(\mathbb{V}) = \rho'(\mathbb{V}) \}$

A domain is non relational if $\rho \circ \gamma = \gamma$, i.e. it cannot distinguish between \mathcal{X} and \mathcal{X}' if $\rho_c(\mathcal{X}) = \rho_c(\mathcal{X}')$.

Example: $\rho_c(\{(X,Y) \mid X \in \{0,2\}, Y \in \{0,2\}, X + Y \le 2\}) = \{0,2\} \times \{0,2\}.$



Data-structures for non-relational domains

Arrays

- $\mathcal{O}(1)$ to read or modify a variable
- $\mathcal{O}(|V|)$ for a copy or a binary operator $(\cup^{\sharp}, \cap^{\sharp}, \text{ etc.})$

Functional arrays e.g.: balanced binary trees

- $\mathcal{O}(\log |V|)$ to read or modify a variable
- $\mathcal{O}(1)$ to copy
- $\mathcal{O}(|\mathcal{X}^{\sharp} \Delta \mathcal{Y}^{\sharp}| \times \log |\mathbb{V}|)$ for a binary operator $\mathcal{X}^{\sharp} \cup^{\sharp} \mathcal{Y}^{\sharp}$, etc. (Δ is the symmetric difference)

In practice, $|\mathcal{X}^{\sharp} \Delta \mathcal{Y}^{\sharp}| \ll |V|$.

Generic non-relational abstract assignments

Given: sound abstract versions in \mathcal{B}^{\sharp} of all arithmetic operators:

```
 \begin{bmatrix} \mathbf{c}, \mathbf{c}' \end{bmatrix}_b^{\sharp} : & \{ x \mid \mathbf{c} \leq \mathbf{x} \leq \mathbf{c}' \} & \subseteq & \gamma_b ([\mathbf{c}, \mathbf{c}']_b^{\sharp}) \\ -\frac{\beta}{b} : & \{ -\mathbf{x} \mid \mathbf{x} \in \gamma_b (\mathcal{X}_b^{\sharp}) \} & \subseteq & \gamma_b (-\frac{\beta}{b} \mathcal{X}_b^{\sharp}) \\ +\frac{\beta}{b} : & \{ \mathbf{x} + \mathbf{y} \mid \mathbf{x} \in \gamma_b (\mathcal{X}_b^{\sharp}), \mathbf{y} \in \gamma_b (\mathcal{Y}_b^{\sharp}) \} & \subseteq & \gamma_b (\mathcal{X}_b^{\sharp} + \frac{\beta}{b} \mathcal{Y}_b^{\sharp}) \\ \vdots & \vdots & \vdots & \vdots \\ \end{aligned}
```

We can define:

Generic non-relational abstract assignments (cont.)

We can then define:

an abstract assignment:

$$\begin{split} \mathbf{C}^{\sharp} \llbracket \mathbf{V} := & \mathbf{e} \rrbracket \, \mathcal{X}^{\sharp} \, \stackrel{\mathrm{def}}{=} \, \left\{ \begin{array}{ll} \bot^{\sharp} & \text{if } \mathcal{V}_{b}^{\sharp} = \bot_{b}^{\sharp} \\ \mathcal{X}^{\sharp} \llbracket \mathbf{V} \mapsto \mathcal{V}_{b}^{\sharp} \rrbracket & \text{otherwise} \end{array} \right. \\ \text{where } \mathcal{V}_{b}^{\sharp} = \mathbf{E}^{\sharp} \llbracket \, e \, \rrbracket \, \mathcal{X}^{\sharp}. \end{split}$$

Using a Galois connection (α_b, γ_b) :

We can define best abstract arithmetic operators:

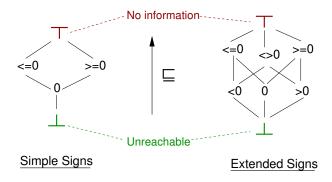
$$\begin{aligned} & [c,c']_b^{\sharp} & \stackrel{\mathrm{def}}{=} & \alpha_b(\{x \mid c \leq x \leq c'\}) \\ & -_b^{\sharp} \mathcal{X}_b^{\sharp} & \stackrel{\mathrm{def}}{=} & \alpha_b(\{-x \mid x \in \gamma(\mathcal{X}_b^{\sharp})\}) \\ & \mathcal{X}_b^{\sharp} +_b^{\sharp} \mathcal{Y}_b^{\sharp} & \stackrel{\mathrm{def}}{=} & \alpha_b(\{x + y \mid x \in \gamma(\mathcal{X}_b^{\sharp}), y \in \gamma(\mathcal{Y}_b^{\sharp})\}) \\ & \vdots & \end{aligned}$$

Note: in general, $\mathsf{E}^{\sharp} \llbracket \, e \, \rrbracket$ is less precise than $\alpha_b \circ \mathsf{E} \llbracket \, e \, \rrbracket \circ \gamma$ e.g. $e = \mathsf{V} - \mathsf{V}$ and $\gamma_b(\mathcal{X}^{\sharp}(\mathsf{V})) = [0,1]$

The sign domain

The sign lattices

<u>Hasse diagram:</u> for the lattice $(\mathcal{B}^{\sharp}, \sqsubseteq_b, \perp_b^{\sharp}, \top_b^{\sharp})$



The extended sign domain is a refinement of the simple sign domain.

The diagram implicitly defines \cup^{\sharp} and \cap^{\sharp} as the least upper bound and greatest lower bound for \Box .

Operations on simple signs

<u>Abstraction α:</u> there is a Galois connection between \mathcal{B}^{\sharp} and $\mathcal{P}(\mathbb{I})$:

$$\alpha_b(S) \stackrel{\mathrm{def}}{=} \left\{ \begin{array}{ll} \bot_b^{\sharp} & \text{if } S = \emptyset \\ 0 & \text{if } S = \{0\} \\ \geq 0 & \text{else if } \forall s \in S, \ s \geq 0 \\ \leq 0 & \text{else if } \forall s \in S, \ s \leq 0 \\ \top_b^{\sharp} & \text{otherwise} \end{array} \right.$$

Derived abstract arithmetic operators:

$$c_b^{\sharp} \stackrel{\text{def}}{=} \alpha_b(\{c\}) = \begin{cases} 0 & \text{if } c = 0 \\ \leq 0 & \text{if } c < 0 \\ \geq 0 & \text{if } c > 0 \end{cases}$$

$$X^{\sharp} + \begin{matrix} \sharp \\ b \end{matrix} Y^{\sharp} \stackrel{\text{def}}{=} \alpha_b(\{x + y \mid x \in \gamma_b(X^{\sharp}), \ y \in \gamma_b(Y^{\sharp}) \})$$

$$= \begin{cases} \bot_b^{\sharp} & \text{if } X \text{ or } Y^{\sharp} = \bot_b^{\sharp} \\ 0 & \text{if } X^{\sharp} = Y^{\sharp} = 0 \\ \leq 0 & \text{else if } X^{\sharp} \text{ and } Y^{\sharp} \in \{0, \leq 0\} \\ \ge 0 & \text{else if } X^{\sharp} \text{ and } Y^{\sharp} \in \{0, \geq 0\} \end{cases}$$

$$\top_b^{\sharp} & \text{otherwise}$$

Operations on simple signs (cont.)

Abstract test examples:

$$\begin{split} \mathsf{C}^{\sharp} \llbracket \, \mathbf{X} &\leq \mathbf{0} \, \rrbracket \, \mathcal{X}^{\sharp} \overset{\mathrm{def}}{=} \, \left(\left\{ \begin{array}{l} \mathcal{X}^{\sharp} [\mathbf{X} \mapsto \mathbf{0}] & \text{if } \mathcal{X}^{\sharp} (\mathbf{X}) \in \{0, \geq 0\} \\ \mathcal{X}^{\sharp} [\mathbf{X} \mapsto \leq \mathbf{0}] & \text{if } \mathcal{X}^{\sharp} (\mathbf{X}) \in \{\top_b^{\sharp}, \leq \mathbf{0}\} \\ \mathcal{L}^{\sharp} & \text{otherwise} \\ \end{array} \right) \\ \mathsf{C}^{\sharp} \llbracket \, \mathbf{X} - \mathbf{c} &\leq \mathbf{0} \, \rrbracket \, \mathcal{X}^{\sharp} \overset{\mathrm{def}}{=} \, \left(\left\{ \begin{array}{l} \mathsf{C}^{\sharp} \llbracket \, \mathbf{X} \leq \mathbf{0} \, \rrbracket \, \mathcal{X}^{\sharp} & \text{if } \mathbf{c} \leq \mathbf{0} \\ \mathcal{X}^{\sharp} & \text{otherwise} \\ \end{array} \right. \right) \\ \mathsf{C}^{\sharp} \llbracket \, \mathbf{X} - \mathbf{Y} &\leq \mathbf{0} \, \rrbracket \, \mathcal{X}^{\sharp} \overset{\mathrm{def}}{=} \\ \left\{ \begin{array}{l} \mathsf{C}^{\sharp} \llbracket \, \mathbf{X} \leq \mathbf{0} \, \rrbracket \, \mathcal{X}^{\sharp} & \text{if } \mathcal{X}^{\sharp} (\mathbf{Y}) \in \{\mathbf{0}, \leq \mathbf{0}\} \\ \mathcal{X}^{\sharp} & \text{otherwise} \\ \end{array} \right. \\ \left\{ \begin{array}{l} \mathsf{C}^{\sharp} \llbracket \, \mathbf{Y} \geq \mathbf{0} \, \rrbracket \, \mathcal{X}^{\sharp} & \text{if } \mathcal{X}^{\sharp} (\mathbf{X}) \in \{\mathbf{0}, \geq \mathbf{0}\} \\ \mathcal{X}^{\sharp} & \text{otherwise} \\ \end{array} \right. \end{split}$$

Other cases: $C^{\sharp} \llbracket expr \bowtie 0 \rrbracket \mathcal{X}^{\sharp} \stackrel{\text{def}}{=} \mathcal{X}^{\sharp}$ is always a sound abstraction.

Simple sign analysis example

Example analysis using the simple sign domain:

$$\left\{ \begin{array}{ll} \mathcal{X}_{2}^{\sharp i+1} &=& \mathsf{C}^{\sharp} \llbracket \, \mathtt{X} := 0 \, \rrbracket \, \mathcal{X}_{1}^{\sharp i} \, \cup \\ && \mathsf{C}^{\sharp} \llbracket \, \mathtt{X} := \mathtt{X} + 1 \, \rrbracket \, \mathcal{X}_{3}^{\sharp i} \\ \mathcal{X}_{3}^{\sharp i+1} &=& \mathsf{C}^{\sharp} \llbracket \, \mathtt{X} < 40 \, \rrbracket \, \mathcal{X}_{2}^{\sharp i} \\ \mathcal{X}_{4}^{\sharp i+1} &=& \mathsf{C}^{\sharp} \llbracket \, \mathtt{X} \geq 40 \, \rrbracket \, \mathcal{X}_{2}^{\sharp i} \end{array} \right.$$

$$\left. \begin{array}{ll} \mathsf{Iteration \ system} \end{array} \right.$$

Program

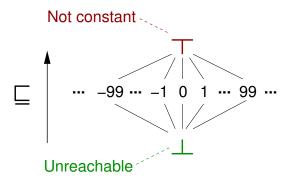
CFG

Iterations

The constant domain

The constant lattice

Hasse diagram:



$$\mathcal{B}^{\sharp} = \mathbb{I} \cup \{ \top_{b}^{\sharp}; \bot_{b}^{\sharp} \}$$

The lattice is flat but infinite.

Operations on constants

Abstraction α : there is a Galois connection:

$$\alpha_b(S) \stackrel{\text{def}}{=} \left\{ egin{array}{ll} \bot_b^\sharp & \text{if } S = \emptyset \\ c & \text{if } S = \{c\} \\ \top_b^\sharp & \text{otherwise} \end{array} \right.$$

Derived abstract arithmetic operators:

$$c_b^{\sharp} \qquad \stackrel{\mathrm{def}}{=} \qquad c \\ (X^{\sharp}) +_b^{\sharp} (Y^{\sharp}) \qquad \stackrel{\mathrm{def}}{=} \qquad \left\{ \begin{array}{l} \bot_b^{\sharp} & \text{if } X^{\sharp} \text{ or } Y^{\sharp} = \bot_b^{\sharp} \\ \top_b^{\sharp} & \text{else if } X^{\sharp} \text{ or } Y^{\sharp} = \top_b^{\sharp} \\ X^{\sharp} + Y^{\sharp} & \text{otherwise} \end{array} \right.$$

$$(X^{\sharp}) \times_b^{\sharp} (Y^{\sharp}) \qquad \stackrel{\mathrm{def}}{=} \qquad \left\{ \begin{array}{l} \bot_b^{\sharp} & \text{if } X^{\sharp} \text{ or } Y^{\sharp} = \bot_b^{\sharp} \\ 0 & \text{else if } X^{\sharp} \text{ or } Y^{\sharp} = 0 \\ \top_b^{\sharp} & \text{else if } X^{\sharp} \text{ or } Y^{\sharp} = \top_b^{\sharp} \\ X^{\sharp} \times Y^{\sharp} & \text{otherwise} \end{array} \right.$$

Operations on constants (cont.)

Abstract test examples:

$$C^{\sharp} \llbracket \mathbf{X} - \mathbf{c} = \mathbf{0} \rrbracket \, \mathcal{X}^{\sharp} \stackrel{\mathrm{def}}{=} \left\{ \begin{array}{l} \bot^{\sharp} & \text{if } \mathcal{X}^{\sharp}(\mathbf{X}) \notin \{\mathbf{c}, \top^{\sharp}_{b}\} \\ \mathcal{X}^{\sharp} \llbracket \mathbf{X} \mapsto \mathbf{c} \end{bmatrix} \text{ otherwise} \end{array} \right.$$

$$C^{\sharp} \llbracket \mathbf{X} - \mathbf{Y} - \mathbf{c} = \mathbf{0} \rrbracket \, \mathcal{X}^{\sharp} \stackrel{\mathrm{def}}{=} \left(\left\{ \begin{array}{l} C^{\sharp} \llbracket \mathbf{X} - (\mathcal{X}^{\sharp}(\mathbf{Y}) + \mathbf{c}) = \mathbf{0} \rrbracket \, \mathcal{X}^{\sharp} & \text{if } \mathcal{X}^{\sharp}(\mathbf{Y}) \notin \{\bot^{\sharp}_{b}, \top^{\sharp}_{b}\} \\ \mathcal{X}^{\sharp} & \text{otherwise} \end{array} \right) \cap^{\sharp} \left. \left\{ \begin{array}{l} C^{\sharp} \llbracket \mathbf{Y} - (\mathcal{X}^{\sharp}(\mathbf{X}) - \mathbf{c}) = \mathbf{0} \rrbracket \, \mathcal{X}^{\sharp} & \text{if } \mathcal{X}^{\sharp}(\mathbf{X}) \notin \{\bot^{\sharp}_{b}, \top^{\sharp}_{b}\} \\ \mathcal{X}^{\sharp} & \text{otherwise} \end{array} \right. \right\}$$

Constant analysis example

```
\mathcal{B}^{\sharp} has finite height, the (\mathcal{X}_{\ell}^{\sharp i}) converge in finite time. (even though \mathcal{B}^{\sharp} is infinite...)
```

Analysis example:

The constant analysis finds, at \bullet , the invariant: $\begin{cases} X = \top_b^{\sharp} \\ Y = 7 \end{cases}$

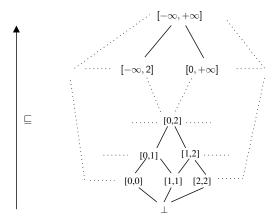
<u>Note:</u> the analysis can find constants that do not appear syntactically in the program.

The interval domain

The interval lattice

Introduced by [Cous76].

$$\mathcal{B}^{\sharp} \stackrel{\mathrm{def}}{=} \{ [a,b] \, | \, a \in \mathbb{I} \cup \{-\infty\}, \ b \in \mathbb{I} \cup \{+\infty\}, \ a \leq b \, \} \ \cup \ \{\perp_b^{\sharp}\}$$



Note: intervals are open at infinite bounds $+\infty$, $-\infty$.

The interval lattice (cont.)

Galois connection (α_b, γ_b) :

$$\begin{array}{ll} \gamma_b([a,b]) & \stackrel{\mathrm{def}}{=} & \{\, x \in \mathbb{I} \,|\, a \leq x \leq b \,\} \\ \\ \alpha_b(\mathcal{X}) & \stackrel{\mathrm{def}}{=} & \left\{ \begin{array}{ll} \bot_b^\sharp & \text{if } \mathcal{X} = \emptyset \\ [\min \mathcal{X}, \max \mathcal{X}] & \text{otherwise} \end{array} \right. \end{array}$$

If $\mathbb{I} = \mathbb{Q}$, α_b is not always defined...

If $\mathbb{I} \neq \mathbb{Q}$, it is a complete lattice.

Partial order:

Interval abstract arithmetic operators

Operators are strict: $-\sharp_b \perp_b^{\sharp} = \perp_b^{\sharp}$, $[a, b] + \sharp_b \perp_b^{\sharp} = \perp_b^{\sharp}$, etc.

Non-Relational Numerical Abstract Domains

p. 63 / 100

Exactness and optimality: Example proofs

```
Proof: exactness of +^{\sharp}_{6}
        \{x + y \mid x \in \gamma_b([a, b]), y \in \gamma_b([c, d])\}
 = \{x + y \mid a < x < b \land c < y < d\}
 = \{z \mid a+c \le z \le b+d\}
 = \gamma_b([a+c,b+d])
 = \gamma_b([a,b] + \sharp [c,d])
Proof optimality of \cup_{b}^{\sharp}
       \alpha_b(\gamma_b([a,b]) \cup \gamma_b([c,d]))
 = \alpha_b(\{x \mid a < x < b\} \cup \{x \mid c < x < d\})
 = \alpha_b(\{x \mid a < x < b \lor c < x < d\})
 = [\min \{x \mid a < x < b \lor c < x < d\}, \max \{x \mid a < x < b \lor c < x < d\}]
 = [\min(a, c), \max(b, d)]
 = [a,b] \cup_b^{\sharp} [c,d]
but ∪<sup>‡</sup> is not exact
```

Interval abstract tests (non-generic)

```
If \mathcal{X}^{\sharp}(\mathtt{X}) = [a,b] and \mathcal{X}^{\sharp}(\mathtt{Y}) = [c,d], we can define:  \mathsf{C}^{\sharp}[\mathtt{X}-c \leq 0] \, \mathcal{X}^{\sharp} \quad \stackrel{\mathrm{def}}{=} \quad \left\{ \begin{array}{c} \bot^{\sharp} & \text{if } a > c \\ \mathcal{X}^{\sharp}[\mathtt{X} \mapsto [a, \min(b,c)] \,] \end{array} \right. \text{ otherwise}   \mathsf{C}^{\sharp}[\mathtt{X}-\mathtt{Y} \leq 0] \, \mathcal{X}^{\sharp} \quad \stackrel{\mathrm{def}}{=} \quad \left\{ \begin{array}{c} \bot^{\sharp} & \text{if } a > d \\ \mathcal{X}^{\sharp}[\mathtt{X} \mapsto [a, \min(b,d)], & \text{otherwise} \end{array} \right.   \mathsf{C}^{\sharp}[e \bowtie 0] \, \mathcal{X}^{\sharp} \quad \stackrel{\mathrm{def}}{=} \quad \mathcal{X}^{\sharp} \quad \text{otherwise}
```

Note: fall-back operators

- $C^{\sharp} \llbracket e \bowtie 0 \rrbracket \mathcal{X}^{\sharp} = \mathcal{X}^{\sharp}$ is always sound.
- $C^{\sharp}[X := e] \mathcal{X}^{\sharp} = \mathcal{X}^{\sharp}[X \mapsto T_{h}^{\sharp}]$ is always sound.

Backward arithmetic and comparison operators

<u>Given:</u> sound backward arithmetic and comparison operators that refine their argument given a result. i.e.

$$\mathcal{X}_{b}^{\sharp\prime} = \stackrel{\checkmark}{\leq} 0_{b}^{\sharp}(\mathcal{X}_{b}^{\sharp}) \Longrightarrow \\
\{x \in \gamma_{b}(\mathcal{X}_{b}^{\sharp}) \mid x \leq \mathbf{0}\} \subseteq \gamma_{b}(\mathcal{X}_{b}^{\sharp\prime}) \subseteq \gamma_{b}(\mathcal{X}_{b}^{\sharp}) \\
\mathcal{X}_{b}^{\sharp\prime} = \stackrel{\leftarrow}{-}_{b}^{\sharp}(\mathcal{X}_{b}^{\sharp}, \mathcal{R}_{b}^{\sharp}) \Longrightarrow \\
\{x \mid x \in \gamma_{b}(\mathcal{X}_{b}^{\sharp}), -x \in \gamma_{b}(\mathcal{R}_{b}^{\sharp})\} \subseteq \gamma_{b}(\mathcal{X}_{b}^{\sharp\prime}) \subseteq \gamma_{b}(\mathcal{X}_{b}^{\sharp}) \\
(\mathcal{X}_{b}^{\sharp\prime}, \mathcal{Y}_{b}^{\sharp\prime}) = \stackrel{\leftarrow}{+}_{b}^{\sharp}(\mathcal{X}_{b}^{\sharp}, \mathcal{Y}_{b}^{\sharp}, \mathcal{R}_{b}^{\sharp}) \Longrightarrow \\
\{x \in \gamma_{b}(\mathcal{X}_{b}^{\sharp}) \mid \exists y \in \gamma_{b}(\mathcal{Y}_{b}^{\sharp}), x + y \in \gamma_{b}(\mathcal{R}_{b}^{\sharp})\} \subseteq \gamma_{b}(\mathcal{X}_{b}^{\sharp\prime}) \subseteq \gamma_{b}(\mathcal{X}_{b}^{\sharp}) \\
\{y \in \gamma_{b}(\mathcal{Y}_{b}^{\sharp}) \mid \exists x \in \gamma_{b}(\mathcal{X}_{b}^{\sharp}), x + y \in \gamma_{b}(\mathcal{R}_{b}^{\sharp})\} \subseteq \gamma_{b}(\mathcal{Y}_{b}^{\sharp\prime}) \subseteq \gamma_{b}(\mathcal{Y}_{b}^{\sharp}) \\
\vdots$$

Note: best backward operators can be designed with α_b :

e.g. for
$$\stackrel{\leftarrow}{+}_b$$
: $\mathcal{X}_b^{\sharp\prime} = \alpha_b(\{x \in \gamma_b(\mathcal{X}_b^{\sharp}) \mid \exists y \in \gamma_b(\mathcal{Y}_b^{\sharp}), x + y \in \gamma_b(\mathcal{R}_b^{\sharp})\})$

Generic backward operator construction

Synthesizing (non optimal) backward arithmetic operators from forward arithmetic operators.

$$\stackrel{\stackrel{\leftarrow}{=}}{\circ} 0_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}) \stackrel{\text{def}}{=} \mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp}] - \infty, 0]_{b}^{\sharp}$$

$$\stackrel{\leftarrow}{-}_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{R}_{b}^{\sharp}) \stackrel{\text{def}}{=} \mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (-\frac{1}{b} \mathcal{R}_{b}^{\sharp})$$

$$\stackrel{\leftarrow}{+}_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{Y}_{b}^{\sharp}, \mathcal{R}_{b}^{\sharp}) \stackrel{\text{def}}{=} (\mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{R}_{b}^{\sharp} - \frac{1}{b} \mathcal{Y}_{b}^{\sharp}), \mathcal{Y}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{R}_{b}^{\sharp} - \frac{1}{b} \mathcal{X}_{b}^{\sharp}))$$

$$\stackrel{\leftarrow}{-}_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{Y}_{b}^{\sharp}, \mathcal{R}_{b}^{\sharp}) \stackrel{\text{def}}{=} (\mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{R}_{b}^{\sharp} + \frac{1}{b} \mathcal{Y}_{b}^{\sharp}), \mathcal{Y}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp} - \frac{1}{b} \mathcal{R}_{b}^{\sharp}))$$

$$\stackrel{\leftarrow}{\leftarrow}_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{Y}_{b}^{\sharp}, \mathcal{R}_{b}^{\sharp}) \stackrel{\text{def}}{=} (\mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{R}_{b}^{\sharp} / \mathcal{Y}_{b}^{\sharp}), \mathcal{Y}_{b}^{\sharp} \cap_{b}^{\sharp} ((\mathcal{X}_{b}^{\sharp} / \mathcal{J}_{b}^{\sharp} \mathcal{X}_{b}^{\sharp}))$$

$$\stackrel{\leftarrow}{\leftarrow}_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{Y}_{b}^{\sharp}, \mathcal{R}_{b}^{\sharp}) \stackrel{\text{def}}{=} (\mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{S}_{b}^{\sharp} \times \mathcal{Y}_{b}^{\sharp}), \mathcal{Y}_{b}^{\sharp} \cap_{b}^{\sharp} ((\mathcal{X}_{b}^{\sharp} / \mathcal{J}_{b}^{\sharp} \mathcal{S}_{b}^{\sharp}) \cup_{b}^{\sharp} [0, 0]_{b}^{\sharp}))$$

$$\stackrel{\leftarrow}{\leftarrow}_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{Y}_{b}^{\sharp}, \mathcal{R}_{b}^{\sharp}) \stackrel{\text{def}}{=} (\mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{S}_{b}^{\sharp} \times \mathcal{Y}_{b}^{\sharp}), \mathcal{Y}_{b}^{\sharp} \cap_{b}^{\sharp} ((\mathcal{X}_{b}^{\sharp} / \mathcal{J}_{b}^{\sharp}) \cup_{b}^{\sharp} [0, 0]_{b}^{\sharp}))$$

$$\stackrel{\leftarrow}{\leftarrow}_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{Y}_{b}^{\sharp}, \mathcal{X}_{b}^{\sharp}) \stackrel{\text{def}}{=} (\mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{Y}_{b}^{\sharp}), \mathcal{Y}_{b}^{\sharp} \cap_{b}^{\sharp} ((\mathcal{X}_{b}^{\sharp} / \mathcal{X}_{b}^{\sharp}) \cup_{b}^{\sharp} [0, 0]_{b}^{\sharp}))$$

$$\stackrel{\leftarrow}{\leftarrow}_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{X}_{b}^{\sharp}) \stackrel{\text{def}}{=} (\mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{X}_{b}^{\sharp}), \mathcal{Y}_{b}^{\sharp} \cap_{b}^{\sharp} ((\mathcal{X}_{b}^{\sharp} / \mathcal{X}_{b}^{\sharp}) \cup_{b}^{\sharp} [0, 0]_{b}^{\sharp})$$

$$\stackrel{\leftarrow}{\leftarrow}_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{X}_{b}^{\sharp}) \stackrel{\text{def}}{=} (\mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{X}_{b}^{\sharp}) \stackrel{\text{def}}{=} (\mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{X}_{b}^{\sharp}), \mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{X}_{b}^{\sharp}))$$

$$\stackrel{\leftarrow}{\leftarrow}_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp}, \mathcal{X}_{b}^{\sharp}) \stackrel{\text{def}}{=} (\mathcal{X}_{b}^{\sharp} \cap_{b}^{\sharp} (\mathcal{X}_{b}^{\sharp})$$

Note: $\stackrel{\leftarrow}{\diamond}_{b}^{\sharp}(\mathcal{X}_{b}^{\sharp}, \mathcal{Y}_{b}^{\sharp}, \mathcal{R}_{b}^{\sharp}) = (\mathcal{X}_{b}^{\sharp}, \mathcal{Y}_{b}^{\sharp})$ is always sound (no refinement).

Interval backward operators

Applying the generic construction to the interval domain:

Generic non-relational abstract test

Abstract test algorithm: $C^{\sharp} \llbracket e \bowtie 0 \rrbracket \mathcal{X}^{\sharp}$

Associate to each expression node an abstract value in \mathcal{B}^{\sharp} using two traversals of the expression tree:

- first, a bottom-up evaluation using forward operators \diamond_b^{\sharp} ,
- apply $\bowtie 0_b^{\sharp}$ to the root,
- then, a top-down refinement using backward operators $\overleftarrow{\diamond}_b^{\sharp}$.

For each expression leaf, we get an abstract value \mathcal{V}_b^{\sharp} :

- for a variable V, replace $\mathcal{X}^{\sharp}(V)$ with $\mathcal{X}^{\sharp}(V) \cap_{b}^{\sharp} \mathcal{V}_{b}^{\sharp}$,
- ullet for a constant [c,c'], check that $[c,c']_b^\sharp \cap_b^\sharp \mathcal{V}_b^\sharp
 eq \bot_b^\sharp$,
- ullet return \bot^{\sharp} if some $\cap_b^{\sharp} \mathcal{V}_b^{\sharp}$ returns \bot_b^{\sharp} .

Improvement: local iterations [Gran92].

Interval test example

$C^{\sharp} \llbracket X + Y - Z \leq 0 \rrbracket \mathcal{X}^{\sharp}$ Example: with $\mathcal{X}^{\sharp} = \{ X \mapsto [0, 10], Y \mapsto [2, 10], Z \mapsto [3, 5] \}$ [-3, 17]Z [3, 5][2, 20][3, 5][0, 10][2, 10][0, 10][2, 10][-3, 0][-3, 0][2, 20][3, 5][2, 5][3, 5][0, 10][2, 10][0, 3]

Generic non-relational backward assignment

Abstract function: $C^{\sharp} \llbracket V := e \rrbracket (\mathcal{X}^{\sharp}, \mathcal{R}^{\sharp})$ over-approximates $\gamma(\mathcal{X}^{\sharp}) \cap C \llbracket V := e \rrbracket \gamma(\mathcal{R}^{\sharp})$ given:

- ullet an abstract pre-condition \mathcal{X}^{\sharp} to refine,
- ullet according to a given abstract post-condition $\mathcal{R}^{\sharp}.$

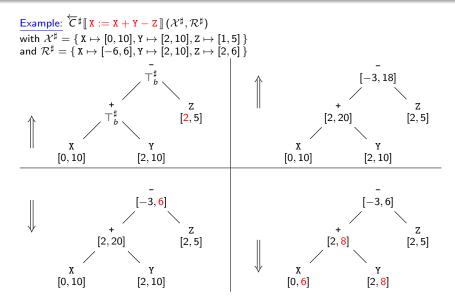
Algorithm: similar to the abstract test

- annotate variable leaves based on $\mathcal{X}^{\sharp} \cap^{\sharp} (\mathcal{R}^{\sharp}[V \mapsto \top_{h}^{\sharp}]);$
- evaluate bottom-up using forward operators \diamond_b^{\sharp} ;
- intersect the root with R[‡](V);
- refine top-down using backward operators $\overleftarrow{b}_b^{\sharp}$;
- return \mathcal{X}^{\sharp} intersected with values at variable leaves.

Note:

- local iterations can also be used
- fallback: $C^{\sharp} \llbracket V := e \rrbracket (\mathcal{X}^{\sharp}, \mathcal{R}^{\sharp}) = \mathcal{X}^{\sharp} \cap^{\sharp} (\mathcal{R}^{\sharp} \llbracket V \mapsto \top_{h}^{\sharp} \rrbracket)$

Interval backward assignment example



Interval widening

Widening on non-relational domains:

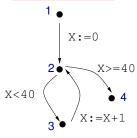
Given a value widening $\nabla_b \colon \mathcal{B}^{\sharp} \times \mathcal{B}^{\sharp} \to \mathcal{B}^{\sharp}$, we extend it point-wisely into a widening $\nabla \colon \mathcal{D}^{\sharp} \times \mathcal{D}^{\sharp} \to \mathcal{D}^{\sharp} \colon \mathcal{X}^{\sharp} \nabla \mathcal{Y}^{\sharp} \stackrel{\text{def}}{=} \lambda V \cdot (\mathcal{X}^{\sharp}(V) \nabla_b \mathcal{Y}^{\sharp}(V))$

Interval widening example:

Unstable bounds are set to $\pm \infty$.

Analysis with widening example

Analysis example with $W = \{2\}$



ℓ	$\mid \mathcal{X}_{\ell}^{\sharp 0} \mid$	$\mathcal{X}_{\ell}^{\sharp 1}$	$\mathcal{X}_{\ell}^{\sharp 2}$	$\mathcal{X}_{\ell}^{\sharp 3}$	$\mathcal{X}_{\ell}^{\sharp 4}$	$\mathcal{X}_{\ell}^{\sharp 5}$
1	_#	⊤♯	#	\ \ #	⊤♯	⊤♯
2 ▽	⊥#	= 0	= 0	≥ 0	≥ 0	≥ 0
3	#	#	= 0	= 0	∈ [0, 39]	∈ [0, 39]
4	♯	#	⊥#	#	⊤ [♯] ≥ 0 ∈ [0, 39] ≥ 40	≥ 40
					'	'

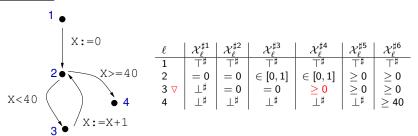
More precisely, at the widening point:

Note that the most precise interval abstraction would be $X \in [0, 40]$ at 2, and X = 40 at 4.

Influence of the widening point and iteration strategy

Changing ${\mathcal W}$ changes the analysis result

Example: The analysis is less precise for $W = \{3\}$.



Intuition: extrapolation to $+\infty$ is no longer contained by the tests.

Chaotic iterations

Changing the iteration order changes the analysis result in the presence of a widening.

Narrowing

Using a widening makes the analysis less precise.

Some precision can be retrieved by using a narrowing \triangle .

Definition: narrowing △

Binary operator $\mathcal{D}^{\sharp} \times \mathcal{D}^{\sharp} \to \mathcal{D}^{\sharp}$ such that:

$$\bullet \ (\mathcal{X}^{\sharp} \cap^{\sharp} \mathcal{Y}^{\sharp}) \ \sqsubseteq \ (\mathcal{X}^{\sharp} \vartriangle \mathcal{Y}^{\sharp}) \ \sqsubseteq \ \mathcal{X}^{\sharp},$$

• for all sequences $(\mathcal{X}_{i}^{\sharp})$, the decreasing sequence $(\mathcal{Y}_{i}^{\sharp})$ defined by $\begin{cases} \mathcal{Y}_{0}^{\sharp} & \stackrel{\text{def}}{=} & \mathcal{X}_{0}^{\sharp} \\ \mathcal{Y}_{i+1}^{\sharp} & \stackrel{\text{def}}{=} & \mathcal{Y}_{i}^{\sharp} \wedge \mathcal{X}_{i+1}^{\sharp} \end{cases}$ is stationary.

This is not the dual of a widening!

Narrowing examples

Trivial narrowing:

 $\mathcal{X}^{\sharp} \wedge \mathcal{Y}^{\sharp} \stackrel{\text{def}}{=} \mathcal{X}^{\sharp}$ is a correct narrowing.

Finite-time intersection narrowing:

$$\mathcal{X}^{\sharp i} \triangle \mathcal{Y}^{\sharp} \stackrel{\text{def}}{=} \left\{ \begin{array}{ll} \mathcal{X}^{\sharp i} \cap^{\sharp} \mathcal{Y}^{\sharp} & \text{if } i \leq N \\ \mathcal{X}^{\sharp i} & \text{if } i > N \end{array} \right.$$

Interval narrowing:

$$[a,b] \triangle_b [c,d] \stackrel{\text{def}}{=} \begin{bmatrix} c & \text{if } a = -\infty \\ a & \text{otherwise} \end{bmatrix}, \begin{cases} d & \text{if } b = +\infty \\ b & \text{otherwise} \end{bmatrix}$$
 (refine only infinite bounds)

Point-wise extension to \mathcal{D}^{\sharp} : $\mathcal{X}^{\sharp} \triangle \mathcal{Y}^{\sharp} \stackrel{\text{def}}{=} \lambda V.(\mathcal{X}^{\sharp}(V) \triangle_b \mathcal{Y}^{\sharp}(V))$

Iterations with narrowing

Let $\mathcal{X}_{\ell}^{\sharp \delta}$ be the result after widening stabilisation, *i.e.*:

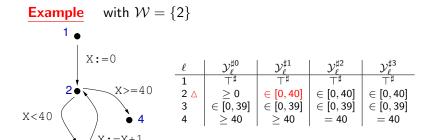
$$\mathcal{X}_{\ell}^{\sharp\delta} \supseteq \left\{ egin{array}{ll} oldsymbol{\top}^{\sharp} & ext{if } \ell = e \ igcup_{(\ell',c,\ell)\in A}^{\sharp} oldsymbol{C}^{\sharp} \llbracket \, c \, \rrbracket \, \mathcal{X}_{\ell'}^{\sharp\delta} & ext{if } \ell
eq e \end{array}
ight.$$

The following sequence is computed:

$$\mathcal{Y}_{\ell}^{\sharp 0} \stackrel{\mathrm{def}}{=} \mathcal{X}_{\ell}^{\sharp \delta} \qquad \mathcal{Y}_{\ell}^{\sharp i+1} \stackrel{\mathrm{def}}{=} \left\{ \begin{array}{ll} \top^{\sharp} & \text{if } \ell = e \\ \bigcup_{\ell',c,\ell) \in A}^{\sharp} \mathsf{C}^{\sharp} \llbracket \, c \rrbracket \, \mathcal{Y}_{\ell'}^{\sharp i} & \text{if } \ell \notin \mathcal{W} \\ \mathcal{Y}_{\ell}^{\sharp i} & \triangle & \bigcup_{\ell',c,\ell) \in A}^{\sharp} \mathsf{C}^{\sharp} \llbracket \, c \rrbracket \, \mathcal{Y}_{\ell'}^{\sharp i} & \text{if } \ell \in \mathcal{W} \end{array} \right.$$

- the sequence $(\mathcal{Y}_{\ell}^{\sharp i})$ is decreasing and converges in finite time,
- all $(\mathcal{Y}_{\ell}^{\sharp i})$ are solutions of the abstract semantic system.

Analysis with narrowing example



Narrowing at 2 gives:

$$\mathcal{Y}_{2}^{\sharp 1} = [0, +\infty[\Delta_{b}([0, 0] \cup_{b}^{\sharp}[1, 40]) = [0, +\infty[\Delta_{b}[0, 40] = [0, 40]])$$

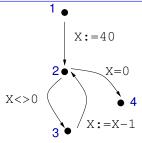
 $\mathcal{Y}_{2}^{\sharp 2} = [0, 40] \Delta_{b}([0, 0] \cup_{b}^{\sharp}[1, 40]) = [0, 40] \Delta_{b}[0, 40] = [0, 40]$

Then
$$\mathcal{Y}_2^{\sharp 2}: \mathtt{X} \in [0,40]$$
 gives $\mathcal{Y}_4^{\sharp 3}: \mathtt{X} = 40.$

We found the most precise invariants!

Improving the widening

Example of imprecise analysis



ℓ	intervals with ∇_b	extended signs	intervals with ∇' ₆
1	T#	#	#
2 ▽	$x \le 40$	$x \ge 0$	$X \in [0, 40]$
3	x ≤ 40	X > 0	$X \in [0, 40]$
4	X = 0	X = 0	X = 0

The interval domain cannot prove that $X \ge 0$ at 2, while the (less powerful) sign domain can!

Solution: improve the interval widening

$$[a,b] \; \triangledown_b' \; [c,d] \; \stackrel{\mathrm{def}}{=} \; \left[\left\{ \begin{array}{ll} a & \text{if } a \leq c \\ \mathbf{0} & \text{if } 0 \leq c < a \\ -\infty & \text{otherwise} \end{array} \right. \; , \; \left\{ \begin{array}{ll} b & \text{if } b \geq d \\ \mathbf{0} & \text{if } 0 \geq b > d \\ +\infty & \text{otherwise} \end{array} \right]$$

 $(\nabla'_b$ checks the stability of 0)

Widening with thresholds

Analysis problem:

```
X:=0;
while • 1=1 do
   if [0,1]=0 then
    X:=X+1;
    if X>40 then X:=0 fi
   fi
   done
```

We wish to prove that $X \in [0, 40]$ at \bullet .

- Widening at finds the loop invariant $X \in [0, +\infty[$. $\mathcal{X}_{\bullet}^{\sharp} = [0, 0] \nabla_b ([0, 0] \cup^{\sharp} [0, 1]) = [0, 0] \nabla_b [0, 1] = [0, +\infty[$
- Narrowing is unable to refine the invariant:

$$\mathcal{Y}_{\bullet}^{\sharp} = [0, +\infty[\triangle_{b}([0, 0] \cup^{\sharp} [0, +\infty[) = [0, +\infty[$$

(the code that limits X is not executed at every loop iteration)

Widening with thresholds (cont.)

Solution:

Choose a finite set T of thresholds containing $+\infty$ and $-\infty$.

Definition: widening with thresholds ∇_b^T

$$[a,b] \nabla_b^T [c,d] \stackrel{\text{def}}{=} \left[\left\{ \begin{array}{ll} a & \text{if } a \leq c \\ \max \left\{ x \in T \mid x \leq c \right\} \end{array} \right. \text{ otherwise} \right.,$$

$$\left\{ \begin{array}{ll} b & \text{if } b \geq d \\ \min \left\{ x \in T \mid x \geq d \right\} \end{array} \right. \text{ otherwise} \right.$$

The widening tests and stops at the first stable bound in T.

Widening with thresholds (cont.)

Applications:

- On the previous example, we find: $X \in [0, \min \{x \in T \mid x \ge 40\}].$
- Useful when it is easy to find a 'good' set T.
 Example: array bound-checking
- Useful if an over-approximation of the bound is sufficient.
 Example: arithmetic overflow checking

<u>Limitations:</u> only works if some non- ∞ bound in T is stable.

Example: with $T = \{5, 15\}$

r = (3, 13)						
while 1=1 do	while 1=1 do					
X:=X+1;	X:=X+1;					
if X>10 then X=0 fi	if X<>10 then X=0 fi					
done	done					

15 is stable

no stable bound

The congruence domain

The congruence lattice

$$\mathcal{B}^{\sharp} \stackrel{\text{def}}{=} \left\{ \left(a\mathbb{Z} + b \right) \mid a \in \mathbb{N}, \ b \in \mathbb{Z} \right\} \cup \left\{ \perp_{b}^{\sharp} \right\}$$

$$1\mathbb{Z} + 0$$

$$2\mathbb{Z} \qquad 2\mathbb{Z} + 1 \qquad 3\mathbb{Z} \qquad \dots$$

$$6\mathbb{Z} \qquad 6\mathbb{Z} + 3 \qquad \dots$$

$$\dots \qquad 0\mathbb{Z} + 6 \qquad 0\mathbb{Z} + 3 \qquad \dots$$

Introduced by Granger [Gran89]. We take $\mathbb{I} = \mathbb{Z}$.

The congruence lattice (cont.)

Concretization:

$$\gamma_b(\mathcal{X}_b^{\sharp}) \stackrel{\text{def}}{=} \begin{cases}
\{ak+b \mid k \in \mathbb{Z}\} & \text{if } \mathcal{X}_b^{\sharp} = (a\mathbb{Z}+b) \\
\emptyset & \text{if } \mathcal{X}_b^{\sharp} = \perp_b^{\sharp}
\end{cases}$$

Note that $\gamma(0\mathbb{Z} + b) = \{b\}.$

 γ_b is not injective: $\gamma_b(2\mathbb{Z}+1)=\gamma_b(2\mathbb{Z}+3)$.

Definitions:

Given $x, x' \in \mathbb{Z}, \ y, y' \in \mathbb{N}$, we define:

- $y/y' \iff y \text{ divides } y' (\exists k \in \mathbb{N}, \ y' = ky) \pmod{\text{that } \forall y : y/0}$
- $x \equiv x' [y] \iff y/|x-x'|$ (in particular, $x \equiv x' [0] \iff x = x'$)
- \vee is the LCM, extended with $y \vee 0 \stackrel{\text{def}}{=} 0 \vee y \stackrel{\text{def}}{=} 0$
- \wedge is the GCD, extended with $y \wedge 0 \stackrel{\text{def}}{=} 0 \wedge y \stackrel{\text{def}}{=} y$

 $(\mathbb{N},/,\vee,\wedge,1,0)$ is a complete distributive lattice.

Abstract congruence operators

Complete lattice structure on \mathcal{B}^{\sharp} :

- $(a\mathbb{Z} + b) \sqsubseteq_b (a'\mathbb{Z} + b') \stackrel{\text{def}}{\iff} a'/a \text{ and } b \equiv b' [a']$
- $\bullet \ \top_b^{\sharp} \stackrel{\mathrm{def}}{=} (1\mathbb{Z} + 0)$
- $(a\mathbb{Z}+b) \cup_{b}^{\sharp} (a'\mathbb{Z}+b') \stackrel{\text{def}}{=} (a \wedge a' \wedge |b-b'|)\mathbb{Z}+b$
- $(a\mathbb{Z}+b)\cap_b^\sharp (a'\mathbb{Z}+b')\stackrel{\mathrm{def}}{=} \left\{ \begin{array}{ll} (a\vee a')\mathbb{Z}+b'' & \mathrm{if}\ b\equiv b'\ [a\wedge a'] \\ \bot_b^\sharp & \mathrm{otherwise} \end{array} \right.$ b'' such that $b''\equiv b\ [a\vee a']\equiv b'\ [a\vee a']$ is given by Bezout's Theorem.

Galois connection:
$$\alpha_b(\mathcal{X}) = \bigcup_{c \in \mathcal{X}}^{\sharp} (0\mathbb{Z} + c)$$

(up to equivalence $a\mathbb{Z} + b \equiv a'\mathbb{Z} + b' \iff a = a' \land b \equiv b'$ [a])

Abstract congruence operators (cont.)

Arithmetic operators:

Abstract congruence operators (cont.)

Test operators:

$$\stackrel{\longleftarrow}{\leq} 0^{\sharp}_{b} (a\mathbb{Z} + b) \qquad \stackrel{\mathrm{def}}{=} \qquad \left\{ \begin{array}{ll} \bot^{\sharp}_{b} & \text{if } a = 0, \ b > 0 \\ a\mathbb{Z} + b & \text{otherwise} \end{array} \right.$$

<u>Note:</u> better than the generic $\stackrel{\longleftarrow}{\leq} 0^\sharp_b \, (\mathcal{X}^\sharp_b) \stackrel{\mathrm{def}}{=} \mathcal{X}^\sharp_b \cap^\sharp_b \,] - \infty, 0]^\sharp_b = \mathcal{X}^\sharp_b$

Extrapolation operators:

- lacktriangle no infinite increasing chain \Longrightarrow no need for \triangledown
- infinite decreasing chains $\Longrightarrow \triangle$ needed $(a\mathbb{Z}+b) \ \triangle_b \ (a'\mathbb{Z}+b') \ \stackrel{\mathrm{def}}{=} \ \left\{ \begin{array}{ll} a'\mathbb{Z}+b' & \text{if } a=1 \\ a\mathbb{Z}+b & \text{otherwise} \end{array} \right.$

Note: $\mathcal{X}^{\sharp} \triangle \mathcal{Y}^{\sharp} \stackrel{\text{def}}{=} \mathcal{X}^{\sharp}$ is always a narrowing.

Congruence analysis example

```
X:=0; Y:=2;
while • X<40 do
    X:=X+2;
    if X<5 then Y:=Y+18 fi;
    if X>8 then Y:=Y-30 fi
done
```

We find, at •, the loop invariant

$$\left\{ \begin{array}{l} X \in 2\mathbb{Z} \\ Y \in 6\mathbb{Z} + 2 \end{array} \right.$$

Reduced products of domains

Non-reduced product of domains

Product representation:

Cartesian product $\mathcal{D}_{1\times2}^{\sharp}$ of \mathcal{D}_{1}^{\sharp} and \mathcal{D}_{2}^{\sharp} :

- $\bullet \ \mathcal{D}_{1\times 2}^\sharp \stackrel{\mathrm{def}}{=} \ \mathcal{D}_1^\sharp \times \mathcal{D}_2^\sharp$
- $\bullet \ \gamma_{1\times 2}(\mathcal{X}_1^{\sharp},\mathcal{X}_2^{\sharp}) \stackrel{\text{def}}{=} \gamma_1(\mathcal{X}_1^{\sharp}) \cap \gamma_2(\mathcal{X}_2^{\sharp})$
- $\alpha_{1\times 2}(\mathcal{X}) \stackrel{\text{def}}{=} (\alpha_1(\mathcal{X}), \alpha_2(\mathcal{X}))$
- $\bullet \ (\mathcal{X}_1^{\sharp},\mathcal{X}_2^{\sharp}) \sqsubseteq_{1\times 2} (\mathcal{Y}_1^{\sharp},\mathcal{Y}_2^{\sharp}) \ \stackrel{\scriptscriptstyle \mathrm{def}}{\Longleftrightarrow} \ \ X_1^{\sharp} \sqsubseteq_{1} \mathcal{Y}_1^{\sharp} \quad \text{and} \quad X_2^{\sharp} \sqsubseteq_{2} \mathcal{Y}_2^{\sharp}$

Abstract operators: performed in parallel on both components:

- $(\mathcal{X}_{1}^{\sharp}, \mathcal{X}_{2}^{\sharp}) \cup_{1 \times 2}^{\sharp} (\mathcal{Y}_{1}^{\sharp}, \mathcal{Y}_{2}^{\sharp}) \stackrel{\text{def}}{=} (\mathcal{X}_{1}^{\sharp} \cup_{1}^{\sharp} \mathcal{Y}_{1}^{\sharp}, \mathcal{X}_{2}^{\sharp} \cup_{2}^{\sharp} \mathcal{Y}_{2}^{\sharp})$ and the same for $\nabla_{1 \times 2}^{\sharp}$ and $\Delta_{1 \times 2}^{\sharp}$
- $\bullet \ \mathsf{C}^{\sharp} \llbracket \ c \rrbracket_{1 \times 2} (\mathcal{X}_{1}^{\sharp}, \mathcal{X}_{2}^{\sharp}) \stackrel{\mathrm{def}}{=} (\mathsf{C}^{\sharp} \llbracket \ c \rrbracket_{1} (\mathcal{X}_{1}^{\sharp}), \mathsf{C}^{\sharp} \llbracket \ c \rrbracket_{2} (\mathcal{X}_{2}^{\sharp}))$

Non-reduced product example

The product analysis is no more precise than two separate analyses.

Example: interval–congruence product:

	interval	congruence	product γ
•	$\mathtt{X} \in [11, 12]$	$X \equiv 1$ [2]	X = 11
•	X = 12	${\tt X}\equiv {\tt 1}$ [2]	Ø
*	X = 0	X = 0	X = 0

We cannot prove that the if branch is never taken!

Fully-reduced product

Definition:

Given the Galois connections (α_1, γ_1) and (α_2, γ_2) on \mathcal{D}_1^{\sharp} and \mathcal{D}_2^{\sharp} we define the reduction operator ρ as:

$$\rho: \mathcal{D}_{1\times 2}^{\sharp} \to \mathcal{D}_{1\times 2}^{\sharp}$$

$$\rho(\mathcal{X}_{1}^{\sharp}, \mathcal{X}_{2}^{\sharp}) \stackrel{\text{def}}{=} (\alpha_{1}(\gamma_{1}(\mathcal{X}_{1}^{\sharp}) \cap \gamma_{2}(\mathcal{X}_{2}^{\sharp})), \alpha_{2}(\gamma_{1}(\mathcal{X}_{1}^{\sharp}) \cap \gamma_{2}(\mathcal{X}_{2}^{\sharp})))$$

ho propagates information between domains.

Application:

We can reduce the result of each abstract operator, except ∇ :

$$\bullet \ (\mathcal{X}_1^{\sharp}, \mathcal{X}_2^{\sharp}) \cup_{1 \times 2}^{\sharp} (\mathcal{Y}_1^{\sharp}, \mathcal{Y}_2^{\sharp}) \stackrel{\text{def}}{=} \rho (\mathcal{X}_1^{\sharp} \cup_{1}^{\sharp} \mathcal{Y}_1^{\sharp}, \mathcal{X}_2^{\sharp} \cup_{2}^{\sharp} \mathcal{Y}_2^{\sharp}),$$

$$\bullet \ \mathsf{C}^{\sharp} \llbracket \, c \, \rrbracket_{1 \times 2} (\mathcal{X}_{1}^{\sharp}, \mathcal{X}_{2}^{\sharp}) \stackrel{\mathrm{def}}{=} \rho (\mathsf{C}^{\sharp} \llbracket \, c \, \rrbracket_{1} (\mathcal{X}_{1}^{\sharp}), \mathsf{C}^{\sharp} \llbracket \, c \, \rrbracket_{2} (\mathcal{X}_{2}^{\sharp})).$$

We refrain from reducing after a widening ∇ , this may jeopardize the convergence (octagon domain example).

Fully-reduced product example

Reduction example: between the interval and congruence domains:

Noting:
$$a' \stackrel{\text{def}}{=} \min \{ x \ge a | x \equiv d [c] \}$$

 $b' \stackrel{\text{def}}{=} \max \{ x \le b | x \equiv d [c] \}$

We get:

$$\rho_b([a,b], c\mathbb{Z} + d) \stackrel{\text{def}}{=} \left\{ \begin{array}{ll} \left(\bot_b^{\mathbb{L}}, \bot_b^{\mathbb{L}}\right) & \text{if } a' > b' \\ \left([a',a'], 0\mathbb{Z} + a'\right) & \text{if } a' = b' \\ \left([a',b'], c\mathbb{Z} + d\right) & \text{if } a' < b' \end{array} \right.$$

extended point-wisely to ρ on \mathcal{D}^{\sharp} .

Application:

- $\rho_b([10,11], 2\mathbb{Z}+1) = ([11,11], 0\mathbb{Z}+11)$ (proves that the branch is never taken on our example)
- $\rho_b([1,3], 4\mathbb{Z}) = (\perp_b^{\sharp}, \perp_b^{\sharp})$

Partially-reduced product

Definition: of a partial reduction:

any function $\rho: \mathcal{D}_{1\times 2}^\sharp \to \mathcal{D}_{1\times 2}^\sharp$ such that:

$$(\mathcal{Y}_{1}^{\sharp}, \mathcal{Y}_{2}^{\sharp}) = \rho(\mathcal{X}_{1}^{\sharp}, \mathcal{X}_{2}^{\sharp}) \Longrightarrow \begin{cases} \gamma_{1 \times 2}(\mathcal{Y}_{1}^{\sharp}, \mathcal{Y}_{2}^{\sharp}) = \gamma_{1 \times 2}(\mathcal{X}_{1}^{\sharp}, \mathcal{X}_{2}^{\sharp}) \\ \gamma_{1}(\mathcal{Y}_{1}^{\sharp}) \subseteq \gamma_{1}(\mathcal{X}_{1}^{\sharp}) \\ \gamma_{2}(\mathcal{Y}_{2}^{\sharp}) \subseteq \gamma_{2}(\mathcal{X}_{2}^{\sharp}) \end{cases}$$

Useful when:

- there is no Galois connection, or
- a full reduction exists but is expensive to compute.

Partial reduction example:

$$\rho(\mathcal{X}_1^{\sharp}, \mathcal{X}_2^{\sharp}) \stackrel{\text{def}}{=} \left\{ \begin{array}{ll} (\bot^{\sharp}, \bot^{\sharp}) & \text{if } \mathcal{X}_1^{\sharp} = \bot^{\sharp} \text{ or } \mathcal{X}_2^{\sharp} = \bot^{\sharp} \\ (\mathcal{X}_1^{\sharp}, \mathcal{X}_2^{\sharp}) & \text{otherwise} \end{array} \right.$$

(works on all domains)

For more complex examples, see [Blan03].

Bibliography

Bibliography

- [Anco10] **C. Ancourt, F. Coelho & F. Irigoin**. *A modular static analysis approach to affine loop invariants detection*. In Proc. NSAD'10, ENTCS, Elsevier, 2010.
- [Berd07] J. Berdine, A. Chawdhary, B. Cook, D. Distefano & P. O'Hearn. Variance analyses from invariances analyses. In Proc. POPL'07 211–224, ACM, 2007.
- [Blan03] B. Blanchet, P. Cousot, R. Cousot, J. Feret, L. Mauborgne, A. Miné, D. Monniaux & X. Rival. *A static analyzer for large safety-critical software.* In Proc. PLDI'03, 196–207, ACM, 2003.
- [Bour93a] **F. Bourdoncle**. *Efficient chaotic iteration strategies with widenings*. In Proc. FMPA'93, LNCS 735, 128–141, Springer, 1993.
- [Bour93b] **F. Bourdoncle**. Assertion-based debugging of imperative programs by abstract interpretation. In Proc. ESEC'93, 501–516, Springer, 1993.

Bibliography (cont.)

- [Cous76] **P. Cousot & R. Cousot**. Static determination of dynamic properties of programs. In Proc. ISP'76, Dunod, 1976.
- [Dor01] **N. Dor, M. Rodeh & M. Sagiv**. Cleanness checking of string manipulations in C programs via integer analysis. In Proc. SAS'01, LNCS 2126, 194–212, Springer, 2001.
- [Girb06] S. Girbal, N. Vasilache, C. Bastoul, A. Cohen, D. Parello, M. Sigler & O. Temam. Semi-automatic composition of loop transformations for deep parallelism and memory hierarchies. In J. of Parallel Prog., 34(3):261–317, 2006.
- [Gran89] **P. Granger**. *Static analysis of arithmetical congruences*. In JCM, 3(4–5):165–190, 1989.
- [Gran92] **P. Granger**. *Improving the results of static analyses of programs by local decreasing iterations*. In Proc. FSTTCSC'92, LNCS 652, 68–79, Springer, 1992.

Bibliography (cont.)

[Gran97] **P. Granger**. Static analyses of congruence properties on rational numbers. In Proc. SAS'97, LNCS 1302, 278–292, Springer, 1997.

[Jean09] **B. Jeannet & A. Miné**. Apron: A library of numerical abstract domains for static analysis. In Proc. CAV'09, LNCS 5643, 661–667, Springer, 2009, http://apron.cri.ensmp.fr/library.

[Mine06] **A. Miné**. Field-sensitive value analysis of embedded *C* programs with union types and pointer arithmetics. In Proc. LCTES'06, 54–63, ACM, 2006.

[Vene02] **A. Venet**. *Nonuniform alias analysis of recursive data structures and arrays.* In Proc. SAS'02, LNCS 2477, 36–51, Springer, 2002.