

**ALMA MATER STUDIORUM
UNIVERSITÀ DI BOLOGNA**

**DEPARTMENT OF COMPUTER SCIENCE
AND ENGINEERING**

ARTIFICIAL INTELLIGENCE

MASTER THESIS

in

Cognitive modeling for robotics in manufacturing

**TOWARDS SEQUENTIAL PROBLEM
SOLVING IN ACT-R: A CASE STUDY OF
TANGRAM**

CANDIDATE

Giacomo Zamprogno

SUPERVISOR

Prof. Giuseppe Di Pellegrino

CO-SUPERVISOR

co-supervisor

Academic year 2021-2022

Session 1st

+retrieval>

ISA dedication

NAME tbd

REASON tbd

Contents

1	Introduction	1
2	Related Works	2
2.0.1	ACT-R	2
2.0.2	Cognitive modelling of puzzles	2
2.0.3	The Tangram	2
3	Experimental scenario	3
4	Data Analysis and Hypothesis	4
5	Model description	5
6	Results and discussion	6
	Bibliography	7
	Acknowledgements	8

List of Figures

List of Tables

Chapter 1

Introduction

Where I describe cognitive modelling and its applications, and the specific case study of the tangram in the context manufacturing and tutoring

Cognitive architectures and AI [1]

Chapter 2

Related Works

Where I quickly go through the available Literature, describe ACT-R and its functioning and analyze the various approaches for tangram solving

2.0.1 ACT-R

2.0.2 Cognitive modelling of puzzles

Despite their nature and potential as an abstraction for more sophisticated sequential problem solving tasks, the applications of cognitive modelling to puzzles are still at an early stage.

Rosenberg et al. [3] coupled cognitive architectures and the tangram puzzle in order to model the curiosity aspect of a social robot, but the actual solution of the puzzle was implemented with a connectionist approach and the cognitive aspect was focused on the social interaction and artificial curiosity modelling. Gentile and Lieto [2] instead used ACT-R in order to model the role of mental rotation applied at the task of the TetrisTM video-game, based on the previous work of Shepard and Metzler[4], providing introductory results and a functioning model for the mental rotation process.

2.0.3 The Tangram

Chapter 3

Experimental scenario

Where I describe the performed experiments

Chapter 4

Data Analysis and Hypothesis

Where I qualitatively and quantitatively analyze the available data, provide figures and introduce the leading Hypothesis that the model will try to explain

Chapter 5

Model description

Where I provide a detailed description of the model and the modelling choices

Chapter 6

Results and discussion

Where I compare the model to the expected data and try to discuss whether the hypothesis are funded and whether there are possible applications

Bibliography

- [1] L. A., B. M., O. A., and V. D. The role of cognitive architectures in general artificial intelligence. *Cognitive Systems Research*, 48:1–3, 2018. DOI: 10 . 1016 / j . cogsys . 2017 . 08 . 003. URL: <https://www.scopus.com/inward/record.uri?eid=2-s2.0-85028355583&doi=10.1016%2fj.cogsys.2017.08.003&partnerID=40&md5=86d65b9707a233d2bde94e786841e92a>. Cited by: 46; All Open Access, Green Open Access.
- [2] M. Gentile and A. Lieto. The role of mental rotation in tetrism gameplay: an act-r computational cognitive model. *Cognitive Systems Research*, 73:1–11, 2022. ISSN: 1389-0417. DOI: <https://doi.org/10.1016/j.cogsys.2021.12.005>. URL: <https://www.sciencedirect.com/science/article/pii/S1389041721000991>.
- [3] M. Rosenberg, H. W. Park, R. Rosenberg-Kima, S. Ali, A. K. Ostrowski, C. Breazeal, and G. Gordon. Expressive cognitive architecture for a curious social robot. *ACM Trans. Interact. Intell. Syst.*, 11(2), 2021. ISSN: 2160-6455. DOI: 10 . 1145 / 3451531. URL: <https://doi.org/10.1145/3451531>.
- [4] R. N. Shepard and J. Metzler. Mental rotation of three-dimensional objects. *Science*, 171(3972):701–703, 1971.

Acknowledgements