# Digital Systems

**CE212** 

**HW 5** 

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#### **Question 1**

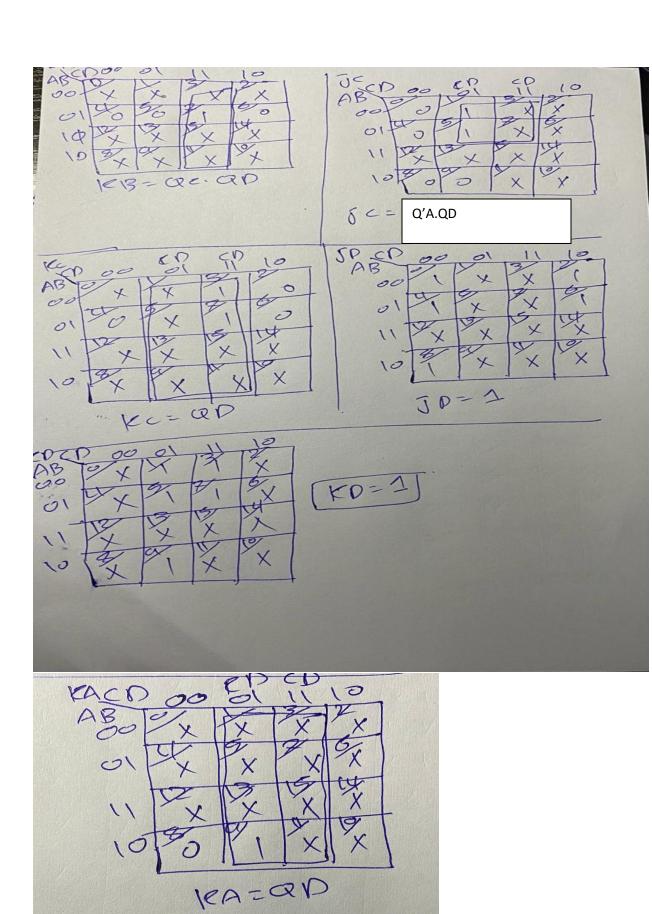
Step 1: the number of J-K F.Fs that are needed is 4

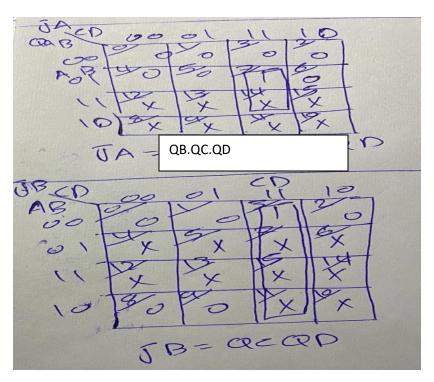
**Step 2 : State table** 

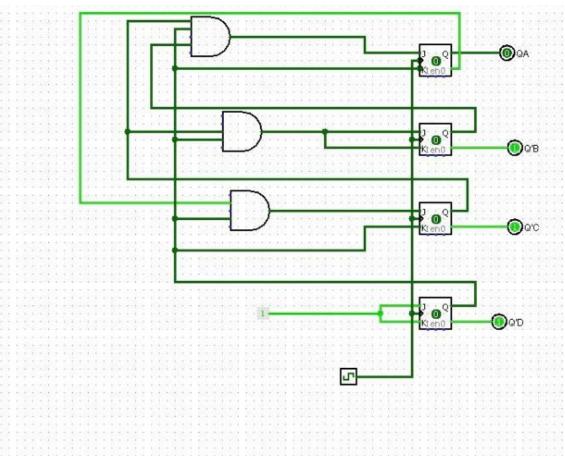
$\mathbf{Q}_{A}$	Q <sub>B</sub>	Q <sub>c</sub>	$\mathbf{Q}_{D}$	$\mathbf{Q}_{A}^{^{+}}$	$Q_B^+$	$\mathbf{Q_c}^{+}$	$Q_{D}^{+}$
0	0	0	0	0	0	0	1
0	0	0	1	0	0	1	0
0	0	1	0	0	0	1	1
0	0	1	1	0	1	0	0
0	1	0	0	0	1	0	1
0	1	0	1	0	1	1	0
0	1	1	0	0	1	1	1
0	1	1	1	1	0	0	0
1	0	0	0	1	0	0	1
1	0	0	1	0	0	0	0
1	0	1	0	X	X	X	X
1	0	1	1	X	X	X	X
1	1	0	0	X	X	X	X
1	1	0	1	X	X	X	X
1	1	1	0	X	X	X	X
1	1	1	1	X	X	X	X

**Step 3: transition table** 

$\mathbf{Q}_{A}$	$\mathbf{Q}_{B}$	$\mathbf{Q}_{C}$	$\mathbf{Q}_{D}$	$\mathbf{Q}_{A}^{+}$	$\mathbf{Q_B}^{+}$	$\mathbf{Q_c}^{+}$	$\mathbf{Q}_{D}^{+}$	J <sub>A</sub>	K <sub>A</sub>	J <sub>B</sub>	K <sub>B</sub>	J <sub>C</sub>	Kc	J <sub>D</sub>	K <sub>D</sub>
0	0	0	0	0	0	0	1	0	Х	0	Х	0	Х	1	Х
0	0	0	1	0	0	1	0	0	Х	0	Х	1	Х	Х	1
0	0	1	0	0	0	1	1	0	Х	0	Х	Х	0	1	Х
0	0	1	1	0	1	0	0	0	Х	1	Х	Х	1	Х	1
0	1	0	0	0	1	0	1	0	Х	Х	0	0	Х	1	Х
0	1	0	1	0	1	1	0	0	Х	Х	0	1	Х	Х	1
0	1	1	0	0	1	1	1	0	Х	Х	0	Х	0	1	Х
0	1	1	1	1	0	0	0	1	Х	Х	1	Х	1	Х	1
1	0	0	0	1	0	0	1	Х	0	0	Х	0	Х	1	Х
1	0	0	1	0	0	0	0	Х	1	0	Х	0	Х	Х	1
1	0	1	0	Х	X	X	X	Х	Х	Х	Х	Х	Х	Х	Х
1	0	1	1	Х	X	X	X	Х	Х	Х	Х	Х	Х	Х	Х
1	1	0	0	Х	X	X	X	Х	Х	Х	Х	Х	Х	Х	Х
1	1	0	1	Х	X	X	X	Х	Х	Х	Х	Х	Х	Х	Х
1	1	1	0	X	X	X	X	X	X	Х	Х	Х	Х	Х	Х
1	1	1	1	Х	X	X	X	X	X	Х	Х	Х	Х	Х	Х







a.

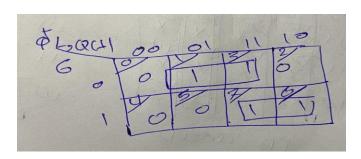
Step 1: truth table

G	L	Q(t)	Q(t+1)
0	0	Q(t-1)	Q'(t-1)
0	1	Q(t-1)	Q'(t-1)
1	0	0	1
1	1	1	0

Step 2 : Next state table

G	L	Q(t)	Q(t+1)
0	0	0	0
0	0	1	1
0	1	0	0
0	1	1	1
1	0	0	0
1	0	1	0
1	1	0	1
1	1	1	1

## **Deriving the characteristic equation using K-map**



$$Q(t+1) = G'Q(t) + G.L$$

## b.

Step 1: Build the next state table of the G-L f.f

G	L	Q(t)	Q(t+1)
0	0	0	0
0	0	1	1
0	1	0	0
0	1	1	1
1	0	0	0
1	0	1	0
1	1	0	1
1	1	1	1

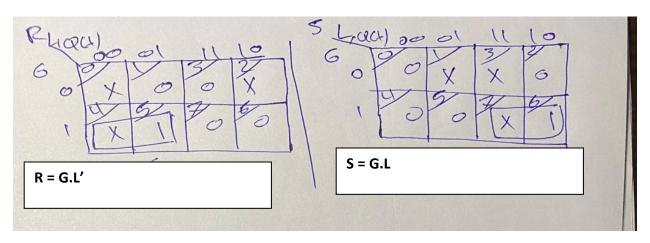
Step 2: Build the excitation table of the S-R f.f

Q(t)	Q(t+1)	S	R
0	0	0	X
0	1	1	0
1	0	0	1
1	1	Х	0

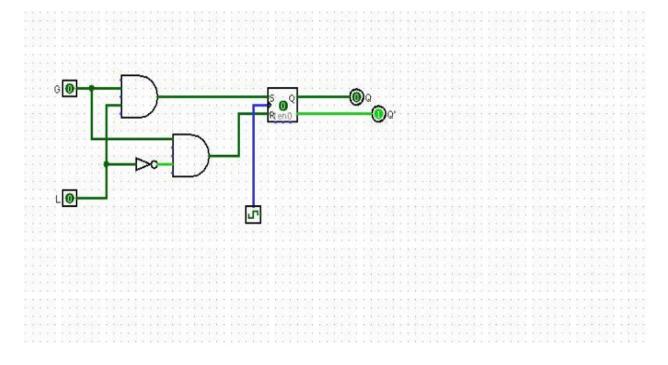
Step 3:

G	L	Q(t)	Q(t+1)	S	R
0	0	0	0	0	Х
0	0	1	1	Х	0
0	1	0	0	0	Х
0	1	1	1	Х	0
1	0	0	0	0	Х
1	0	1	0	0	1
1	1	0	1	1	0
1	1	1	1	X	0

Step 4: find the equation of the S-R



Step 5 : Build the circuit



Step1: # of f.fs that are needed is 3

**Step 2: State table** 

$\mathbf{Q}_{A}$	Q <sub>B</sub>	Q <sub>c</sub>	$\mathbf{Q_A}^{\dagger}$	Q <sub>B</sub> <sup>+</sup>	$Q_c^+$
0	0	0	0	0	1
0	0	1	0	1	0
0	1	0	1	0	0
0	1	1	0	0	0
1	0	0	1	1	1
1	0	1	0	0	0
1	1	0	0	0	0
1	1	1	0	0	0

**Step 3 : Transition table** 

Q <sub>A</sub>	Q <sub>B</sub>	Q <sub>c</sub>	$Q_A^{\dagger}$	$Q_B^+$	$Q_c^+$	J <sub>A</sub>	K <sub>A</sub>	J <sub>B</sub>	K <sub>B</sub>	J <sub>c</sub>	K <sub>C</sub>
0	0	0	0	0	1	0	X	0	X	1	X
0	0	1	0	1	0	0	X	1	X	X	1
0	1	0	1	0	0	1	X	X	1	0	X
0	1	1	0	0	0	0	X	X	1	X	1
1	0	0	1	1	1	X	0	1	X	1	X
1	0	1	0	0	0	X	1	0	X	X	1
1	1	0	0	0	0	X	1	X	1	0	X
1	1	1	0	0	0	X	1	X	1	X	1

$$JA = \sum_{m}(2) + \sum_{d} (4,5,6,7)$$

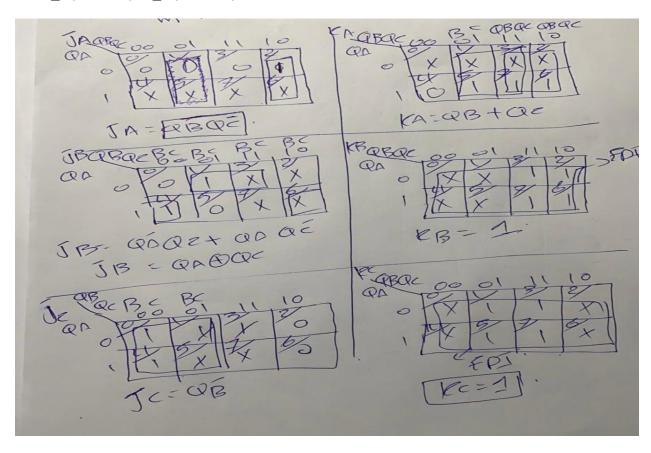
$$KA = \sum_{m}(5,6,7) + \sum_{d}(0,1,2,3)$$

$$JA = \sum_{m}(1,4) + \sum_{d}(2,3,6,7)$$

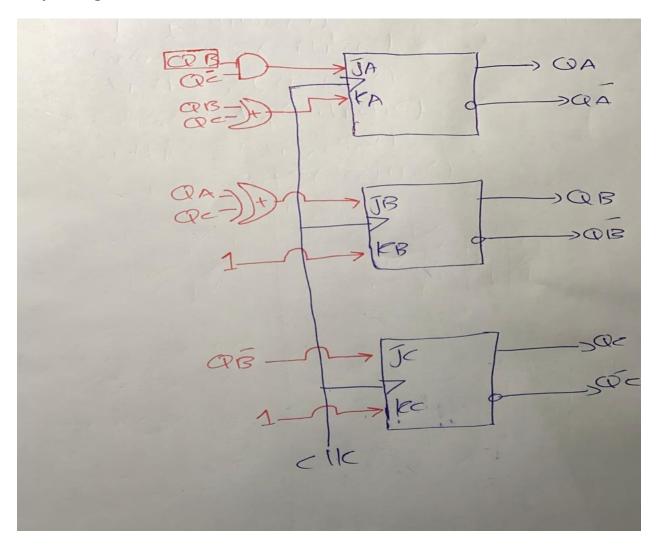
 $JA = \sum_{m}(2,3,6,7) + \sum_{d}(0,1,4,5)$ 

 $JA = \sum_{m}(0,4) + \sum_{d} (1,3,5,7)$ 

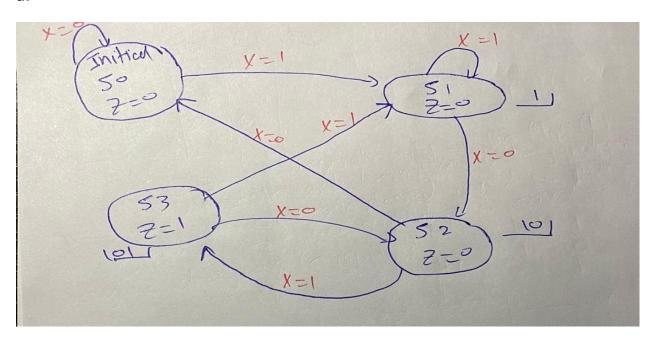
 $JA = \sum_{m} (1,3,5,7) + \sum_{d} (0,2,4,6)$ 



Step 5 : logic circuit



a.



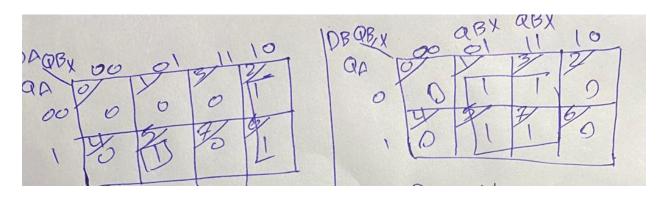
# b. The number of D-F.F that are needed is equal to:

#of F.Fs = 
$$Log_2$$
 (#of states) =  $Log_24$  = 2.

c.

$\mathbf{Q}_{A}$	Q <sub>B</sub>	X	Q <sub>A</sub> <sup>+</sup>	Q <sub>B</sub> <sup>+</sup>	Z	D <sub>A</sub>	D <sub>B</sub>
0	0	0	0	0	0	0	0
0	0	1	0	1	0	0	1
0	1	0	1	0	0	1	0
0	1	1	0	1	0	0	1
1	0	0	0	0	0	0	0
1	0	1	1	1	0	1	1
1	1	0	1	0	1	1	0
1	1	1	0	1	1	0	1

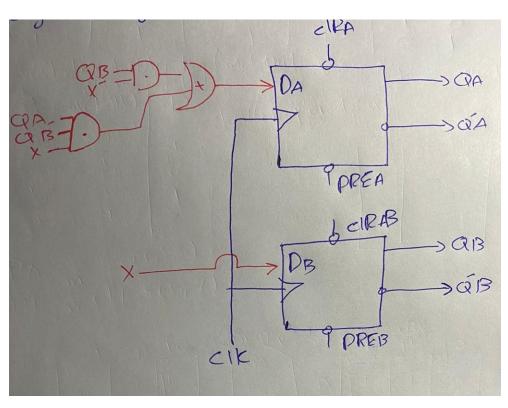
d.



 $D_A(QA,QB,X) = QB.X'+QA.Q'B.X$ 

 $D_B(QA,QB,X) = X$ 

e.



a.

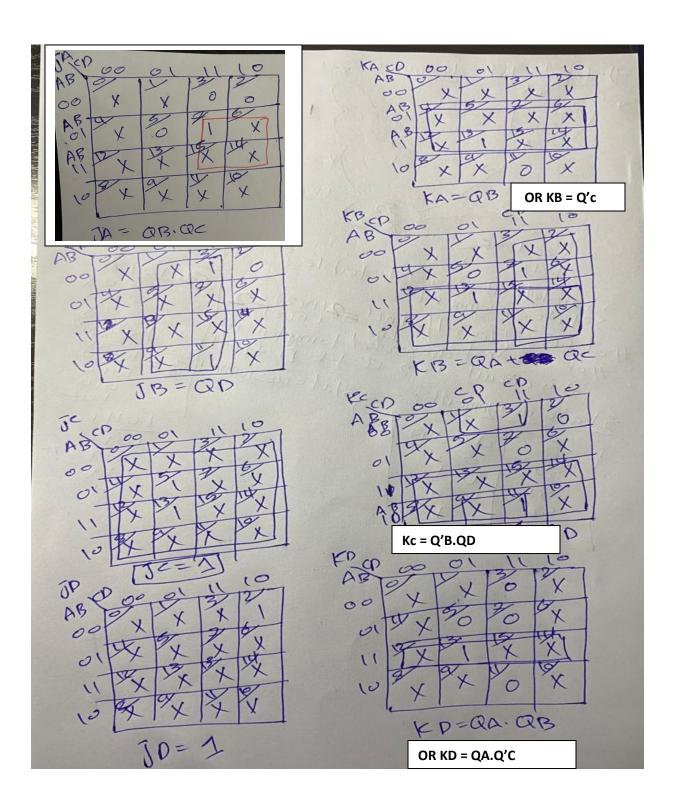
Q(t)	Q(t+1)	J	К
0	0	0	X
0	1	1	X
1	0	Х	1
1	1	Х	0

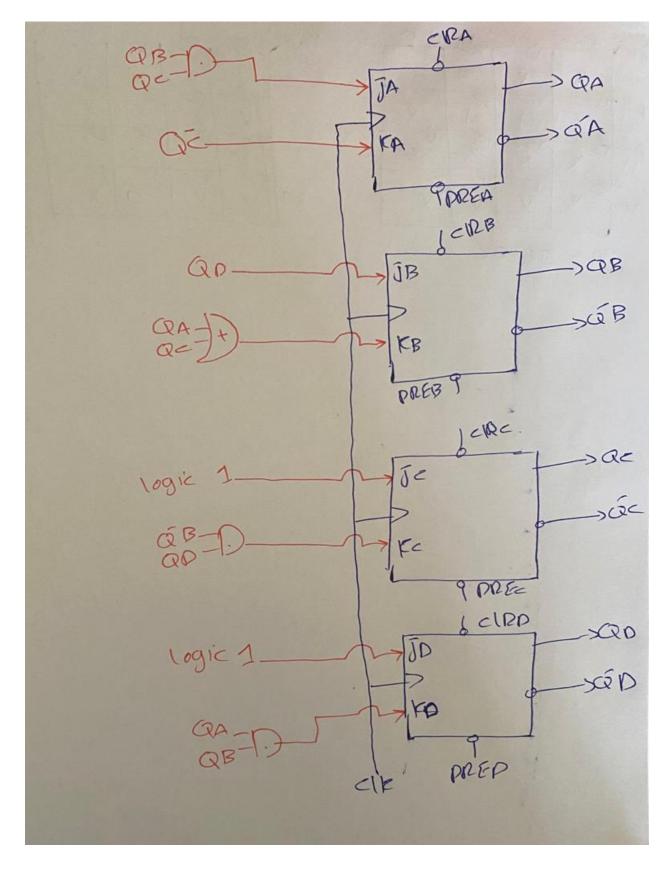
b.

c. The number of the F.Fs that are required to implement this circuit is 4 since we it is a 4-bit counter and each F.F represent one bit(each F.F has one stable output).

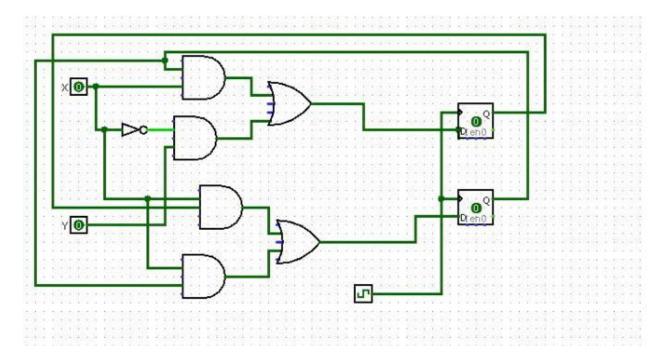
d.

$\mathbf{Q}_{A}$	$\mathbf{Q}_{B}$	$\mathbf{Q}_{c}$	$\mathbf{Q}_{D}$	$\mathbf{Q}_{A}^{+}$	$Q_B^{\dagger}$	$\mathbf{Q_c}^{\dagger}$	$\mathbf{Q}_{D}^{+}$	J <sub>A</sub>	K <sub>A</sub>	J <sub>B</sub>	K <sub>B</sub>	J <sub>C</sub>	K <sub>C</sub>	J <sub>D</sub>	K <sub>D</sub>
0	0	0	0	Х	X	X	X	Х	Х	Х	Х	Х	Х	Х	Х
0	0	0	1	Х	X	X	X	Х	Х	Х	Х	Х	Х	Х	Х
0	0	1	0	0	0	1	1	0	Х	0	Х	Х	0	1	Х
0	0	1	1	0	1	0	1	0	Х	1	Х	Х	1	Х	0
0	1	0	0	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х	Х
0	1	0	1	0	1	1	1	0	Х	Х	0	1	Х	Х	0
0	1	1	0	Х	X	X	X	Х	X	X	Х	Х	Х	Х	X
0	1	1	1	1	0	1	1	1	X	X	1	Х	0	Х	0
1	0	0	0	Х	Х	X	X	Х	Х	X	Х	Х	Х	Х	Х
1	0	0	1	Х	Х	X	X	Х	Х	X	Х	Х	Х	Х	Х
1	0	1	0	Х	Х	X	Х	Х	Х	X	Х	Х	Х	Х	Х
1	0	1	1	1	1	0	1	Х	0	1	Х	Х	1	Х	0
1	1	0	0	Х	Х	X	Х	Х	Х	X	Х	Х	Х	Х	Х
1	1	0	1	0	0	1	0	Х	1	Х	1	1	Х	Х	1
1	1	1	0	Х	Х	X	Х	Х	Х	Х	Х	Х	Х	Х	Х
1	1	1	1	Х	Х	Х	X	Х	Х	Х	Х	Х	Х	Х	Х





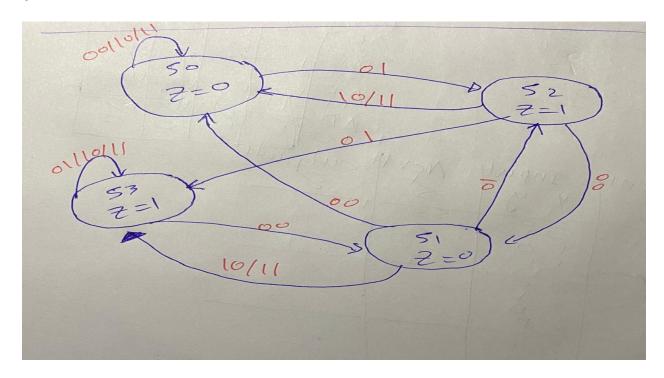
## Question 6 .a.



b.

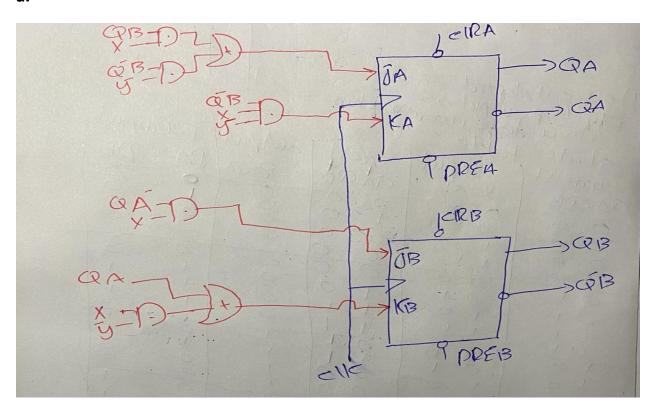
Q <sub>A</sub>	Q <sub>B</sub>	X	Υ	$\mathbf{Q}_{A}^{^{+}}$	$Q_B^+$	Z	D <sub>A</sub>	D <sub>B</sub>
0	0	0	0	0	0	0	0	0
0	0	0	1	1	0	0	1	0
0	0	1	0	0	0	0	0	0
0	0	1	1	0	0	0	0	0
0	1	0	0	0	0	0	0	0
0	1	0	1	1	0	0	1	0
0	1	1	0	1	1	0	1	1
0	1	1	1	1	1	0	1	1
1	0	0	0	0	1	1	0	1
1	0	0	1	1	1	1	1	1
1	0	1	0	0	0	1	0	0
1	0	1	1	0	0	1	0	0
1	1	0	0	0	1	1	0	1
1	1	0	1	1	1	1	1	1
1	1	1	0	1	1	1	1	1
1	1	1	1	1	1	1	1	1

c.



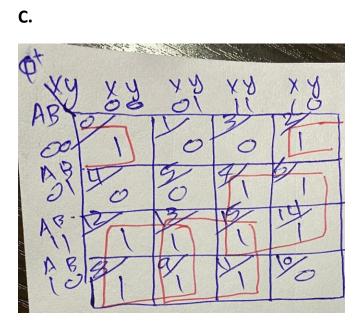
# Question 7

a.

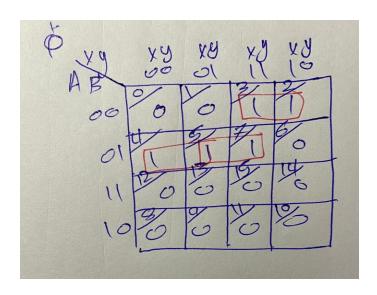


b.

$\mathbf{Q}_{A}$	Q <sub>B</sub>	Х	Υ	Q <sub>A</sub> <sup>+</sup>	Q <sub>B</sub> <sup>+</sup>	Z	J <sub>A</sub>	K <sub>A</sub>	J <sub>B</sub>	K <sub>B</sub>
0	0	0	0	1	0	0	1	X	0	X
0	0	0	1	0	0	0	0	Х	0	X
0	0	1	0	1	1	0	1	Х	1	X
0	0	1	1	0	1	0	0	Х	1	Х
0	1	0	0	0	1	1	0	Х	X	0
0	1	0	1	0	1	0	0	X	X	0
0	1	1	0	1	0	0	1	X	X	1
0	1	1	1	1	1	0	1	X	X	0
1	0	0	0	1	0	0	X	0	0	Х
1	0	0	1	1	0	0	X	0	0	Х
1	0	1	0	0	0	0	X	1	0	Х
1	0	1	1	1	0	0	X	0	0	Х
1	1	0	0	1	0	1	X	0	X	1
1	1	0	1	1	0	0	X	0	X	1
1	1	1	0	1	0	0	X	0	X	1
1	1	1	1	1	0	1	Х	0	X	1

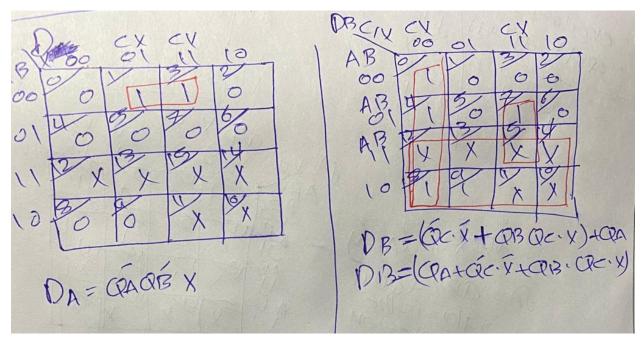


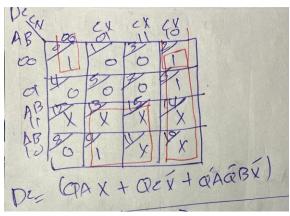
 $\mathbf{Q}_{\mathrm{A}}(\mathsf{t}\!+\!\mathsf{1}) = \mathbf{Q}_{\mathrm{A}}\mathsf{x}'\!+\!\mathbf{Q}_{\mathrm{A}}\mathsf{Y}\!+\!\mathbf{Q}_{\mathrm{B}}\mathsf{X}\!+\!\mathbf{Q'}_{\mathrm{A}}\mathsf{Q'}_{\mathrm{B}}\mathsf{Y'}$ 



 $\mathbf{Q_B(t+1)} = \mathbf{Q'_AQ_BX'+Q'_AQ_BY+Q'_AQ'_BX}$ 

$\mathbf{Q}_{A}$	Q <sub>B</sub>	Q <sub>c</sub>	X	$\mathbf{Q}_{A}^{}}$	$Q_B^{\dagger}$	$\mathbf{Q_c}^{+}$	Z	D <sub>A</sub>	D <sub>B</sub>	D <sub>c</sub>
0	0	0	0	0	1	1	0	0	1	1
0	0	0	1	1	0	0	1	1	0	0
0	0	1	0	0	0	1	0	0	0	1
0	0	1	1	1	0	0	1	1	0	0
0	1	0	0	0	1	0	0	0	1	0
0	1	0	1	0	0	0	1	0	0	0
0	1	1	0	0	0	1	0	0	0	1
0	1	1	1	0	1	0	1	0	1	0
1	0	0	0	0	1	0	0	0	1	0
1	0	0	1	0	1	1	0	0	1	1
1	0	1	0	Х	Х	Х	X	X	Х	Х
1	0	1	1	X	X	X	X	X	X	X
1	1	0	0	Х	Х	Х	X	X	Х	Х
1	1	0	1	Х	Х	Х	Х	Х	Х	Х
1	1	1	0	Х	Х	Х	Х	Х	Х	Х
1	1	1	1	Х	Х	Х	Х	X	Х	Х





#### **Unused States**

QA QB QC → Next

 $1 \quad 0 \quad 1 \rightarrow 0 \ 11$ 

 $D_A = 0$ ,  $D_B = 1$ ,  $D_C = 1$ .

QA QB QC → Next

1 1  $0 \rightarrow$ 

 $D_A = 0$ ,  $D_B = 1$ ,  $D_C = X$  (it is not a do not care condition ... it points to the input x .However, we have to values of x (i.e x = 0, x = 1).

For x = 1

QA QB QC → Next

 $1 \quad 1 \quad 0 \rightarrow 011$ 

For x = 0

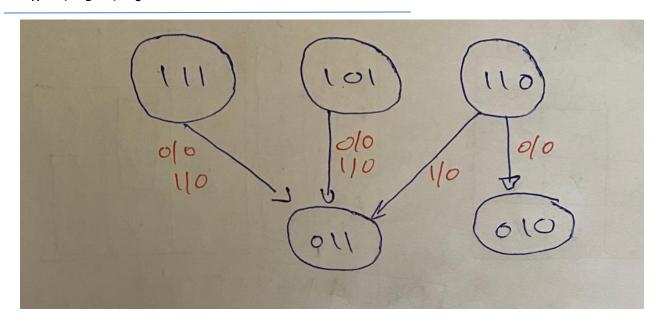
QA QB QC → Next

 $1 \quad 1 \quad 0 \rightarrow 010$ 

QA QB QC → Next

 $1 \quad 1 \quad 1 \rightarrow 011$ 

 $D_A = 0$ ,  $D_B = 1$ ,  $D_C = 1$ 



Using J-K-F-F

$\mathbf{Q}_{A}$	$\mathbf{Q}_{\mathrm{B}}$	$\mathbf{Q}_{C}$	X	$\mathbf{Q}_{A}^{}^{+}}$	$Q_B^{\dagger}$	$\mathbf{Q_c}^{+}$	Z	J <sub>A</sub>	K <sub>A</sub>	J <sub>B</sub>	K <sub>B</sub>	J <sub>C</sub>	K <sub>C</sub>
0	0	0	0	0	1	1	0	0	X	1	X	1	X
0	0	0	1	1	0	0	1	1	X	0	X	0	X
0	0	1	0	0	0	1	0	0	X	0	X	X	0
0	0	1	1	1	0	0	1	1	X	0	X	X	1
0	1	0	0	0	1	0	0	0	X	X	0	0	X
0	1	0	1	0	0	0	1	0	X	X	1	0	X
0	1	1	0	0	0	1	0	0	X	X	1	X	0
0	1	1	1	0	1	0	1	0	X	X	0	X	1
1	0	0	0	0	1	0	0	X	1	1	X	0	X
1	0	0	1	0	1	1	0	X	1	1	X	1	X
1	0	1	0	X	X	X	X	X	X	X	X	X	X
1	0	1	1	Х	X	Х	X	X	Х	X	X	Х	X
1	1	0	0	Х	X	Х	X	X	Х	X	X	Х	X
1	1	0	1	Х	X	X	X	X	Х	X	X	X	X
1	1	1	0	Х	X	X	X	X	Х	X	X	X	X
1	1	1	1	X	X	X	X	X	X	X	X	X	X

