

## CHAPTER ONE

### REALISTIC CONSTRAINTS

#### 1.1 DESIGN CONSTRAINTS

#### 1.2 ENGINEERING STANDARDS AND LIFELONG LEARNING

The successful deployment of an Automated Guided Vehicle (AGV) system relies heavily on adherence to established engineering standards. These standards provide a framework for the design, implementation, and operation of AGVs, ensuring they meet safety, reliability, and performance requirements.

Compliance with these guidelines is essential not only for regulatory approval but also for fostering a culture of continuous learning and improvement in AGV technology and its applications.

##### 1.2.1 Agv safety standards and their importance

Various international standards govern the safety of AGVs, ensuring their integration into industrial, healthcare, and logistics environments without compromising human safety.

Notable among these are **ISO 3691-4** [?], which outlines safety requirements for driverless industrial trucks, and **ANSI/ITSDF B56.5** [?], which provides American safety guidelines for automated guided industrial vehicles.

The **EN 3691-4** [?] standard mirrors the ISO regulations for European markets, emphasizing risk reduction and operational reliability. Meanwhile, **RIA R15.08** [?] is an evolving effort to create comprehensive safety guidelines for mobile robots in industrial settings.

These standards establish essential safety features for AGVs, including **emergency stop mechanisms, audible alarms, warning lights, and collision avoidance systems**.

They also define environmental considerations such as clear pathways, adequate lighting, and obstacle detection to enhance the safe operation of AGVs.

Additionally, operational protocols for **startup, shutdown, emergency response, and periodic maintenance** are emphasized to prevent malfunctions and ensure continuous performance.

### 1.2.2 Categorization of machinery safety standards

Engineering safety standards are categorized into three types to ensure a structured approach to risk mitigation:

- **Type-A Standards:** These provide general safety principles applicable to all machinery, focusing on fundamental design requirements.

- **Type-B Standards:** These cover protective devices and safety measures that apply to a wide range of machines, ensuring standardization across different industries.

- **Type-C Standards:** These are specific to particular types of machinery, including AGVs, and take precedence over Type-A and Type-B standards when addressing specific risks.

While these standards ensure a structured approach to AGV safety, they do not account for additional hazards such as **severe environmental conditions, nuclear operations, or public-road navigation**, necessitating customized engineering solutions for such applications.

### 1.2.3 Designing agvs for public interaction

Most AGVs are deployed in controlled industrial environments, operated by trained professionals.

However, in certain sectors, they may interact with **untrained personnel, visitors, or even the general public**.

For instance, in healthcare settings, robots used for hospital logistics must safely co-exist with **doctors, nurses, patients, and visitors** who may be unfamiliar with automated systems.

Similarly, in retail and hospitality sectors, AGVs designed for service roles must incorporate intuitive safety mechanisms and user-friendly interfaces to prevent accidents.

To ensure safe public interaction, they must be designed with **intelligent obstacle detection, adaptive navigation, and fail-safe mechanisms** that allow them to adjust their behavior in real time.

Features such as **voice alerts, digital displays, and intuitive stop/start functionalities** help bridge the gap between automation and human interaction.

### 1.2.4 Lifelong learning and continuous development in agv engineering

The field of AGV technology is rapidly evolving, necessitating **continuous education and lifelong learning** among engineers, operators, and industry stakeholders.

Given the advancements in **artificial intelligence, sensor technologies, and machine learning**, professionals must stay updated on emerging safety protocols, regulatory changes,

and new engineering methodologies.

Training programs, certifications, and industry workshops play a crucial role in ensuring that **engineers, technicians, and operators** remain proficient in the latest AGV technologies.

Furthermore, the increasing adoption of **Robot-as-a-Service (RaaS)** models means that companies must not only invest in AGV technology but also continuously train their workforce to adapt to evolving automation trends.

Engineering standards form the backbone of AGV safety, reliability, and efficiency, guiding their deployment across various industries.

The integration of **rigorous safety measures, structured categorization of standards, and adaptive public interaction mechanisms** ensures that AGVs can function seamlessly while maintaining workplace safety.

Additionally, the fast-paced evolution of AGV technology demands a culture of **lifelong learning and professional development**, enabling engineers and industry professionals to keep pace with advancements in automation and robotics.

Through adherence to standards and continuous education, businesses can maximize the benefits of AGVs while fostering a safer, more efficient work environment

### **1.3 ECONOMIC ANALYSIS OF INDUSTRIAL AUTOMATED GUIDED VEHICLES (AGVS)**

Developing Automated Guided Vehicles (AGVs) requires a substantial financial investment for engineers and companies aiming to automate material handling and logistics operations. While AGVs significantly enhance efficiency and productivity, a thorough economic analysis is essential to assess direct costs, such as equipment and installation, as well as indirect costs, including unforeseen expenses.

A well-planned budget and strategic approach ensure that the cost of building AGVs remains within the initial projected expenditure, preventing cost overruns and maximizing return on investment. Building Automated Guided Vehicles (AGVs) in the TRNC presents unique financial challenges due to the region's geographical location and limited local manufacturing capabilities. One of the most significant hurdles is the complexity of sourcing components, which often need to be imported from various countries such as China, Germany, and the United States. This reliance on international suppliers introduces several direct and indirect costs that can strain budgets and complicate project timelines.

### **1.3.1 Sourcing components across borders**

The construction of AGVs requires highly specialized parts, including advanced sensors, navigation systems, robotic arms, and durable materials for vehicle frames. Many of these components are not readily available locally and must be ordered from manufacturers abroad. For example, high-precision sensors may come from Germany, battery systems from the United States, and certain electronic modules from China.

The process of coordinating shipments from multiple countries adds layers of complexity, delays, and additional expenses. Furthermore, some parts are custom-made to meet the specific requirements of the Teknofest competition, leading to longer lead times and higher procurement costs.

### **1.3.2 Direct costs: purchasing parts and shipping**

The direct costs associated with building AGVs in the TRNC include the purchase price of components and shipping fees. Importing parts from distant countries like China or the U.S. involves significant freight charges, especially for bulky or heavy items such as motors and chassis materials.

Additionally, currency exchange rates can further inflate costs, as fluctuations may increase the price of goods purchased in foreign currencies. These factors make it difficult to accurately forecast expenditures and maintain budgetary control during the development phase.

### **1.3.3 Indirect costs: taxes, customs fees, and regulatory compliance**

Beyond the direct costs, there are substantial indirect costs tied to importing parts into the TRNC. Customs duties, value-added taxes (VAT), and other regulatory fees can add a considerable percentage to the overall cost of components. For instance, certain high-tech equipment may attract steep import tariffs, while VAT rates in the region can further escalate expenses.

These regulations requires expertise and administrative effort, which can divert resources away from core engineering tasks. Moreover, delays at customs due to paperwork issues or inspections can disrupt production schedules, causing additional financial strain.

### **1.3.4 Cost**

The following table provides a detailed breakdown of the estimated costs associated with building an AGV.

Table 1.1: List of Components and Their Costs

Components	Quantity	Price (per Unit)	Reference Image
Raspberry Pi 4 8GB RAM	1	3127.03 ₪	
ESP32-S3-DevKitC-1-N8R8 - ESP32-S3-WROOM-1	2	1220 ₪	
Closed Loop Stepper Driver V4.1 0-8.0A 24-48VDC CL57T	2	1186 ₪	
Motorbit Weight Sensor 120 kg	2	768.2 ₪	
Weight Sensor - Load Sensor 50Kg.	4	29.7 ₪	
Load Cell Amplifier - HX711	4	27.3 ₪	
BTS7960B 40 Amp Motor Driver Board	1	188.82 ₪	
Barcode Scanner Module 1D/2D Codes Reader	1	1261.83 ₪	
QTRXL-MD-01A Re- flectance Sensor Array	4	90.57 ₪	

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Table 1.1 – continued from previous page

Components	Quantity	Price (per Unit)	Reference Image
Gravity: HUSKYLENS	1	1723.14 ₮	
IMU Sensor / 9 Axis MPU9255 IMU and Barometric Sensor (Low Power)	1	1058.31 ₮	
RPLIDAR - 360 degree Laser Scanner Development Kit	1	5029.72 ₮	
TXS0108E 8 Channel Voltage Level Transducer	4	40 ₮	
The VL53L0X is a time-of-flight (ToF) distance sensor	10	101.76 ₮	
UV Solder Mask	3	180.78 ₮	
LM2596HV/LM2576 Voltage Regulator for Multiple power supply	4	36.09 ₮	
Aluminum heatsink	2	439 ₮	
5V 8 Channel Relay Card	1	154.68 ₮	

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Table 1.1 – continued from previous page

Components	Quantity	Price (per Unit)	Reference Image
P Series Nema 23 Closed Loop Stepper Motor 2Nm(283.28oz.in) with Electromagnetic Brake	2	2971.78 ₪	
EG Series Planetary Gear-box Gear Ratio 20:1 Backlash 20arc-min for 10mm Shaft Nema 23 Stepper Motor	2	1642 ₪	
Shaft Sleeve Adaptor 11mm to 8mm for NMRV30 Worm Gearbox	4	35 ₪	
Single Output Shaft for NMRV30 Worm Gearbox	4	121.37 ₪	
Double Output Shaft for NMRV30 Worm Gearbox	4	121.37 ₪	
NEMA 23 Stepper Motor Vibration Damper	4	243.74 ₪	
Nema 23 Bracket for Stepper Motor	4	243.74 ₪	
Nema 23 Flange for ISC And ISD Series Drivers	3	175.28 ₪	
AWG 20 High-flexible with Shield Layer Stepper Motor Cable	2	43.25 ₪	

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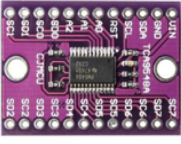


Table 1.1 – continued from previous page

Components	Quantity	Price (per Unit)	Reference Image
TP-Link TL-WR840N	1	569 ₪	
Raspberry Pi 4.3 Inch Capacitive Touch Screen DSI Interface 800x480	1	1750.28 ₪	
Nema 8R 5W 87dB 90x39mm Speaker	1	108.11 ₪	
Nema RS232 to Bluetooth Series Adapter	2	455 ₪	
12V 70 AH AGM BATTERY	1	5000 ₪	
Battery Chargers 6V/2A 12V/2A Full Automatic Smart Battery	1	642.99 ₪	
RS232 Adapter Cable to USB 2.0	2	453.65 ₪	
Motor and encoder extension cable kit	2	351 ₪	
DC 12V Electric Linear Actuator Force 6000N	1	2479 ₪	

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Table 1.1 – continued from previous page

Components	Quantity	Price (per Unit)	Reference Image
WM-045 DC-DC 150W Voltage Booster	1	521.04 ₪	
Motorbit DC-DC 1500W 30A Voltage Boost Module	1	881.76 ₪	
TCA9548A I2C Multiplexer Card	1	40.66 ₪	
3B Printer Limit Switch	2	37.07 ₪	
Drn956 16mm Emergency Stop Switch (Head 27mm)	1	145.08 ₪	
<b>Total Price</b>			<b>82945.29 ₪</b>

## 1.4 SUSTAINABILITY

The integration of Automated Guided Vehicles (AGVs) in material handling and logistics has ushered in a new era of sustainability, offering significant advantages over traditional methods such as forklifts.

As industries increasingly prioritize environmentally friendly solutions, these vehicles have emerged as a critical component in reducing environmental impact while simultaneously improving operational efficiency. Their ability to operate on electric power, optimize movement, and minimize waste positions them as a sustainable choice for modern warehouses and logistics operations.

One of the most notable contributions to sustainability is their energy efficiency. Unlike conventional forklifts, which rely on fossil fuels and emit harmful pollutants, these systems are electrically powered, producing zero direct emissions. Equipped with advanced route optimization and intelligent navigation, they ensure the most efficient paths, reducing unnecessary energy consumption.

Furthermore, many modern models utilize lithium-ion batteries, which offer longer operational cycles and shorter charging times compared to traditional lead-acid batteries. Some even incorporate regenerative braking technology, enabling them to recover and reuse energy that would otherwise be lost, further enhancing their efficiency.

Another key advantage lies in their ability to reduce waste. With precise movement capabilities and advanced sensor technology, these systems minimize product damage during transportation, significantly lowering material waste. Traditional equipment, such as forklifts, often leads to inventory losses due to human error or accidents.

In contrast, these automated systems are designed to handle goods with care and accuracy, preserving inventory integrity. By preventing unnecessary waste and reducing the need for product replacements, they contribute to a more sustainable and cost-effective supply chain. Beyond energy efficiency and waste reduction, these vehicles also support sustainability through optimized space utilization and reduced labor dependency. Their compact design and ability to operate in tight spaces allow warehouses to maximize storage capacity, reducing the need for expansive facilities.

Additionally, they can operate continuously without fatigue, minimizing reliance on human labor and lowering operational costs over time. Beyond energy efficiency and waste reduction, these vehicles also support sustainability through optimized space utilization and reduced labor dependency. Their compact design and ability to operate in tight spaces allow warehouses to maximize storage capacity, reducing the need for expansive facilities. Additionally, they can operate continuously without fatigue, minimizing reliance on human labor and lowering operational costs over time.

## **1.5 ETHICAL IMPLICATIONS OF AGVS IN LOGISTICS AND MATERIAL HANDLING**

Automated Guided Vehicles (AGVs) in logistics and material handling brings not only sustainability benefits but also significant ethical challenges. While AGVs enhance efficiency and reduce environmental impact, their adoption raises critical concerns related to job displacement, data privacy, workplace safety, and environmental responsibility. Addressing these issues is essential for businesses to ensure ethical and responsible implementation.

### **1.5.1 Job displacement and workforce transition**

The widespread adoption of AGVs and autonomous systems has the potential to disrupt not only individual workers but also entire communities and economies. As these technologies replace human labor in industries such as logistics, warehousing, and transportation, the ripple effects extend beyond job loss. Local economies that depend on these industries may

experience reduced consumer spending, declining tax revenues, and increased demand for social services, creating a cycle of economic stagnation.

Furthermore, the displacement of workers in lower-wage, manual labor roles can lead to broader societal challenges, such as increased income inequality and reduced social mobility. Communities heavily reliant on these jobs may face higher rates of poverty and unemployment, exacerbating existing social divides. On a macroeconomic level, the shift toward automation could alter labor market dynamics, potentially leading to a mismatch between available jobs and the skills of the workforce.

### **1.5.2 Data privacy and security**

Another ethical challenge is the handling of data collected by AGVs. These systems rely on advanced sensors, cameras, and AI-driven software to navigate and optimize operations. In the process, they gather vast amounts of data on operational efficiency, movement patterns, and even worker behavior. Without proper management, this data could be misused, leading to concerns about workplace surveillance and privacy violations.

### **1.5.3 Workplace safety**

Safety is a critical ethical consideration in AGV deployment. While AGVs are designed to reduce accidents and enhance workplace safety, their interaction with human workers requires careful oversight. Malfunctions, software errors, or unexpected obstacles could lead to accidents if safety protocols are not strictly followed. Employers must ensure that AGVs are equipped with reliable collision avoidance systems and that employees receive adequate training to work alongside automated systems. Regular maintenance and system updates are also essential to prevent operational failures that could endanger workers.

### **1.5.4 Environmental responsibility**

Beyond operational sustainability, the environmental impact of AGV production and disposal raises ethical concerns. While AGVs contribute to greener logistics during their operation, their manufacturing involves resource-intensive components such as lithium-ion batteries. Responsible sourcing of materials, fair labor practices in manufacturing, and proper recycling programs for outdated AGVs are essential to minimize their environmental footprint. Companies must prioritize ethical supply chain practices to ensure that AGVs align with broader sustainability goals.

### 1.5.5 Balancing technology and ethics

The ethical deployment of AGVs requires a careful balance between technological advancement and corporate responsibility. Businesses must proactively address concerns related to employment, data privacy, safety, and environmental impact to ensure that AGVs benefit both operations and society. By adopting ethical frameworks alongside technological innovations, companies can harness the advantages of AGVs while upholding fairness, transparency, and sustainability in their practices.

## 1.6 HEALTH AND SAFETY PROBLEMS

The integration of Automated Guided Vehicles (AGVs) in industrial and warehouse environments has revolutionized operational efficiency. However, safety remains a top priority. Modern AGVs are equipped with advanced sensor technologies that continuously scan their surroundings, dynamically adjusting detection ranges based on speed to minimize collision risks.

For instance, some of the latest automated forklifts incorporate dynamic sensors that monitor not only the vehicle's path but also its sides, ensuring swift responses to detected obstacles. If a person or object enters the AGV's field of view, the system can slow down within milliseconds or stop entirely if the obstruction is too close.

Beyond sensors, AGVs use visual and audio alerts to enhance workplace awareness. Before moving, they emit audible warnings to alert nearby personnel and then gradually accelerate. Their predictability—following fixed routes—further reduces the risk of unexpected encounters with workers or equipment.

### 1.6.1 Key safety measures for agv environments

To maintain a safe workplace, it is crucial to implement best practices for AGV operation:

- **Clear Travel Routes:** Obstructions reduce efficiency and create hazards. Workers should avoid stepping into AGV paths and always give them the right of way.
- **Restricted Areas:** Zones where AGVs handle heavy loads must remain off-limits to unauthorized personnel. These areas are clearly marked to indicate potential hazards.
- **Elevated Items:** AGVs may not always recognize objects raised high off the ground. To prevent accidents, elevated items must be kept out of AGV paths.
- **Blind Corners:** Facilities should implement safety measures such as mirrors and warning signals to alert personnel of approaching vehicles.

### 1.6.2 Regulatory standards and safety guidelines

AGVs operate under strict safety standards to ensure workplace protection:

- The ANSI/ITSDF B56.5-2019 [?] guidelines specify requirements such as maintaining a minimum clearance of 0.5 meters (19.7 inches) on either side of an AGV's guideway, except when a fixed structure is present.
- Restricted areas, where clearance is insufficient or escape routes are unavailable, enforce reduced AGV speeds to mitigate risks.
- The VDI 2510 [?] guideline emphasizes risk minimization by mandating robust safety designs, thorough manufacturer risk assessments, and compliance documentation to certify AGV systems.

### 1.6.3 Advanced safety technology and risk mitigation

AGVs rely on a combination of contact and non-contact safety systems to prevent accidents:

- **Contact Systems:** Traditional bumpers serve as secondary safeguards, ensuring that even if all other safety measures fail, impact forces are absorbed to protect workers and equipment.
- **Non-Contact Systems:** Laser scanners and infrared sensors continuously analyze the environment to detect potential obstacles, enabling AGVs to adjust their movement dynamically based on real-time conditions.
- **Emergency Stop Buttons:** Strategically placed along AGV routes, these provide an immediate override mechanism in critical situations.
- **Image Processing:** Some advanced models utilize image processing to differentiate between people and objects, enabling intelligent decision-making in busy areas.

### 1.6.4 Human factors and maintenance considerations

While AGVs are designed for autonomous operation, human awareness and behavior play a crucial role in safety:

- Employees must remain attentive in areas where AGVs are active, especially near corners or new aisles.
- Listening for alarms, avoiding distractions like mobile phones, and adhering to training protocols help prevent incidents.

- Regular maintenance is essential to ensure the continued reliability of AGVs. Facilities should strictly follow manufacturer guidelines for inspections and servicing while keeping detailed records of all maintenance activities.
- Unauthorized modifications can compromise safety, so any changes to AGV configurations must be approved by the system provider.

Clear documentation is necessary for operational efficiency and regulatory compliance. Manufacturers provide safety certifications and declarations to confirm that their AGVs meet industry standards, ensuring trust in their safe deployment.

## **1.7 SOCIAL AND POLITICAL ISSUES**

The development and widespread adoption of Autonomous Ground Vehicles (AGVs) raise several social and political challenges. These challenges touch on labor, safety, privacy, inequality, ethics, and regulation.

### **1.7.1 Job displacement and economic impact**

One of the most significant social concerns surrounding autonomous vehicles is the potential for job displacement. As these machines take over tasks traditionally performed by human workers, such as material handling in warehouses or transportation of goods, there is a risk that large numbers of jobs will be lost. This can impact industries like logistics, warehousing, and delivery services. Workers displaced by automation may struggle to find new employment, especially in sectors with fewer opportunities for reskilling.

Governments consider policies to support workers affected by automation, such as retraining programs, unemployment benefits, and a universal basic income (UBI) to address potential economic disparities. Society faces challenges in transitioning the workforce, especially those in lower-wage, manual labor positions, to new types of employment that are less vulnerable to automation.

### **1.7.2 Regulatory and safety concerns**

The safety of autonomous vehicles is a major concern. These machines must adhere to strict safety standards to prevent accidents, especially when operating in environments with humans or other vehicles. The lack of established safety regulations in many countries complicates the situation. For instance, in the event of a malfunction or collision, questions of liability arise—whether the manufacturer, the operator, or the software developer is responsible.

### **1.7.3 Privacy and surveillance**

Autonomous vehicles often rely on advanced sensor systems, cameras, and GPS technology to navigate. These systems can raise privacy concerns as they may collect data on individuals' movements, locations, and interactions with the vehicle. If used in public spaces or residential areas, the data they collect could be misused or exploited, leading to privacy violations.

### **1.7.4 Inequality in access and impact**

While these vehicles promise efficiency and productivity, their adoption may not be equally distributed. Large corporations and developed countries are more likely to afford and deploy this technology, leaving smaller businesses or less developed regions at a disadvantage. This could further widen the gap between economically privileged and disadvantaged groups.

### **1.7.5 Environmental impact**

These vehicles have the potential to reduce carbon footprints by optimizing logistics and transportation, especially when electric vehicles are used. However, concerns about the environmental impact of production, battery disposal, and resource extraction (e.g., lithium for batteries) persist. Long-term sustainability hinges on addressing these environmental challenges.

### **1.7.6 Public trust and acceptance**

For this technology to be widely accepted, society must trust that these machines are safe, efficient, and beneficial. Public perception is often shaped by media coverage, accidents, and personal experiences with the technology. Building trust will require transparency, rigorous testing, and communication from both the private and public sectors.

## **1.8 ENVIRONMENTAL IMPACT OF INDUSTRIAL ROBOTS AND AGVS**

The environmental footprint of industrial robots and Autonomous Ground Vehicles (AGVs) extends beyond their day-to-day operations. The production of these machines requires substantial amounts of raw materials, including metals, plastics, and electronics, which come with their own environmental costs. The mining and extraction of these materials can contribute to habitat destruction, air and water pollution, and increased carbon emissions.

Additionally, the batteries that power many AGVs and industrial robots raise concerns about their environmental impact. Lithium-ion batteries, commonly used in these systems,

require rare earth materials and pose challenges regarding disposal and recycling. Improper disposal can result in the release of toxic chemicals into the environment, while recycling programs for used batteries are still developing, leaving a gap in sustainable end-of-life management.

Despite these challenges, advancements in green technologies offer opportunities for mitigating the environmental impact. Companies are increasingly exploring ways to make these systems more energy-efficient, such as using renewable energy sources to power industrial robots and AGVs, and investing in more sustainable materials for production. Moreover, research into better battery recycling methods and longer-lasting batteries could help reduce the ecological footprint of these machines.

## **1.9 MANUFACTURABILITY**

Manufacturability of an Automated Guided Vehicle (AGV) refers to the ease and efficiency with which it can be produced while maintaining quality, intended performance, and cost-effectiveness. The design process must consider material selection, modularity, ease of assembly, and integration of standard and custom components for production. The use of off-the-shelf sensors, motors, and controllers reduces development complexity and ensures reliability. Additionally, adopting a modular design allows for easier maintenance, upgrades, and customization based on specific industry needs.

Manufacturing challenges include precise fabrication of mechanical components, good electrical wiring, and integrating software for navigation and automation.

## **1.10 RISK MANAGEMENT, AND CHANGE MANAGEMENT**

## **1.11 LEGAL CONSEQUENCES**

The deployment of Automated Guided Vehicles (AGVs) comes with several legal considerations, including safety regulations, liability, data privacy, and trade compliance. AGVs must adhere to international safety standards such as ISO 3691-4, ANSI/ITSDF B56.5 [?], and OSHA requirements [?] to ensure workplace safety and prevent accidents. In the event of malfunctions or collisions, liability can fall on manufacturers, integrators, or operators, depending on product liability laws and negligence claims. Additionally, AGVs using AI and wireless communication must comply with data privacy laws like GDPR [?] and CCPA [?] while addressing cybersecurity risks to prevent hacking or unauthorized control. Environmental regulations also apply, particularly regarding battery disposal and energy efficiency. Failure to comply with these legal aspects can lead to fines, lawsuits, or product bans, making



regulatory adherence essential for AGV manufacturers and users.