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## Problem 1

---

```
format rat;
A = [3 -8 22 -8 2;
     6 -8 -2 -8 44;
     -3 3 15 3 -27;
     -1 1 6 1 -9;
     0 5 -7 5 25;
     4 2 -3 2 66];
% Part a
rref(A)
disp("Basis of Col(A): {(3, 6, -3, -1, 0, 4), (-8, -8, 3, 1, 5, 2), "
disp("(22, -2, 15, 6, -7, -3)}")
disp("Basis of Ker(A): {(0, -1, 0, 1, 0), (-14, -5, 0, 0, 1)}")
% Part b
disp("There are infinite solutions, as the fourth column (x4) is a free")
disp("variable")
disp("Parametric Vector Form: x4(0, -1, 0, 1, 0) + (-14, -5, 0, 0, 1)")
```

ans =

1	0	0	0	14
0	1	0	1	5
0	0	1	0	0
0	0	0	0	0
0	0	0	0	0
0	0	0	0	0

Basis of Col(A): {(3, 6, -3, -1, 0, 4), (-8, -8, 3, 1, 5, 2),  
(22, -2, 15, 6, -7, -3)}

Basis of Ker(A): {(0, -1, 0, 1, 0), (-14, -5, 0, 0, 1)}

There are infinite solutions, as the fourth column (x4) is a free  
variable

Parametric Vector Form:  $x_4(0, -1, 0, 1, 0) + (-14, -5, 0, 0, 1)$

## Problem 2

---

```
format rat;

A = [5 -3 6 7,
     0 0 0 1,
     7 -5 3 -7,
     4 0 3 -7];
rref(A)
```

```

%part a
disp("Basis of Row Space: {[1 0 0 0], [0 1 0 0], [0 0 1 0], [0 0 0 1]}")
%part b
disp("Basis of col space: {(5, 0, 7, 4), (-3, 0, -5, 0), (6, 0, 3, 3), (7, 1, -7, -7)}")
%part c
disp("Yes dim(col(A)) = dim(row(A))")
%part d
disp("No row(A) does not equal col(A) as row(A) represents the standard")
disp("basis while col(A) is just the original matrix.")

```

ans =

1	0	0	0
0	1	0	0
0	0	1	0
0	0	0	1

Basis of Row Space: {[1 0 0 0], [0 1 0 0], [0 0 1 0], [0 0 0 1]}  
 Basis of col space: {(5, 0, 7, 4), (-3, 0, -5, 0), (6, 0, 3, 3), (7, 1, -7, -7)}

Yes dim(col(A)) = dim(row(A))

No row(A) does not equal col(A) as row(A) represents the standard basis while col(A) is just the original matrix.

### Problem 3

```

format rat;
% part a
B = [4 2 4 -8;
     1 6 3 6;
     -5 4 0 7;
     5 -7 1 7]
v = [2; -30; 13; -10];
disp("What I do here is just put the coefficents/values of vector v")
disp("and multiply them in order according to the matrix B, which")
disp("gets you the u below")
u = [80; -199; -200; 163]
%part b
BsolutionV = [4 2 4 -8 2;
              1 6 3 6 -30;
              -5 4 0 7 13;
              5 -7 1 7 -10]
rref(BsolutionV)
disp("I set up the matrix as an augmented matrix where v is the solution")
disp("which will allow us to get the answer for the coefficients of the")
disp("vectors in B that produce the vector v, our final answer is the W")
disp("below: ")
W = [-958/91; -1783/273; 1231/118; -305/158]

```

B =

4	2	4	-8
1	6	3	6

-5	4	0	7
5	-7	1	7

What I do here is just put the coefficients/values of vector v and multiply them in order according to the matrix B, which gets you the u below

u =

```

80
-199
-200
163

```

BsolutionV =

4	2	4	-8	2
1	6	3	6	-30
-5	4	0	7	13
5	-7	1	7	-10

ans =

1	0	0	0	-958/91
0	1	0	0	-1783/273
0	0	1	0	1231/118
0	0	0	1	-305/158

I set up the matrix as an augmented matrix where v is the solution which will allow us to get the answer for the coefficients of the vectors in B that produce the vector v, our final answer is the W below:

W =

```

-958/91
-1783/273
1231/118
-305/158

```

## Problem 4

```

format rat;
%part a
v1 = [7; -3; 1; 7; 2];
v2 = [9; -3; -9; -5; -6];
v3 = [1, -1, 3, 4, 3];
v4 = [5; -3; -1; 0; 1];
%part b
A = [7 9 1 5;
     -3 -3 -1 -3;
     1 -9 3 -1;
     7 -5 4 0;
     2 -6 3 1]

```

```
%part c
rref(A)
disp("Basis is {(1, x, x^2, -1 + x + 3x^2)}")
%part d
disp("It is linearly dependent because there are free variables.")
disp("v4 can be written as a linear combination of v1, v2, v3")
```

---

A =

7	9	1	5
-3	-3	-1	-3
1	-9	3	-1
7	-5	4	0
2	-6	3	1

ans =

1	0	0	-1
0	1	0	1
0	0	1	3
0	0	0	0
0	0	0	0

Basis is {(1, x, x^2, -1 + x + 3x^2)}

It is linearly dependent because there are free variables.

v4 can be written as a linear combination of v1, v2, v3

## Problem 5

---

```
format short;
%part a
A = [1 cos(0.1) (cos(0.1))^2 (cos(0.1))^3 (cos(0.1))^4;
     1 cos(0.2) (cos(0.2))^2 (cos(0.2))^3 (cos(0.2))^4;
     1 cos(0.3) (cos(0.3))^2 (cos(0.3))^3 (cos(0.3))^4;
     1 cos(0.4) (cos(0.4))^2 (cos(0.4))^3 (cos(0.4))^4;
     1 cos(0.5) (cos(0.5))^2 (cos(0.5))^3 (cos(0.5))^4];
%part b
rref(A)
disp("As we can see there is a pivot in every row and column")
disp("and there are no free variables. This means that one vector")
disp("cannot be written as a linear combination of another, thus")
disp("meaning that we only have a trivial solution.")
%part c
u1 = [1; 0; -1; 0; 1];
u2 = [0; 1; 0; -3; 0];
u3 = [0; 0; 2; 0; -8];
u4 = [0; 0; 0; 4; 0];
u5 = [0; 0; 0; 0; 8];
%part d
B = [1 0 0 0 0;
     0 1 0 0 0;
     -1 0 2 0 0;
     0 -3 0 4 0;
     1 0 -8 0 8]
```

```

rref(B)
disp("Yes, C is linearly independent because it has a pivot/row in")
disp("every column/no free variables and one vector is not a linear")
disp("combination of another.")
%part e
disp("C is a basis for D because the rref of C is the standard basis")
disp("with a pivot in every row/column, meaning it must be a basis, it")
disp("is also the same matrix in rref as B.")

```

---

ans =

```

1      0      0      0      0
0      1      0      0      0
0      0      1      0      0
0      0      0      1      0
0      0      0      0      1

```

As we can see there is a pivot in every row and column and there are no free variables. This means that one vector cannot be written as a linear combination of another, thus meaning that we only have a trivial solution.

B =

```

1      0      0      0      0
0      1      0      0      0
-1     0      2      0      0
0     -3      0      4      0
1      0     -8      0      8

```

ans =

```

1      0      0      0      0
0      1      0      0      0
0      0      1      0      0
0      0      0      1      0
0      0      0      0      1

```

Yes, C is linearly independent because it has a pivot/row in every column/no free variables and one vector is not a linear combination of another.

C is a basis for D because the rref of C is the standard basis with a pivot in every row/column, meaning it must be a basis, it is also the same matrix in rref as B.