

18/01/2021

Experiment - 1Second Order SystemTheoretical Calculations:For underdamped systems:

~~$$\frac{C(s)}{R(s)} = \frac{0.25}{s^2 + 0.25s + 0.625}$$~~

$$\frac{C(s)}{R(s)} = \frac{1225}{s^2 + 35s + 1225}$$

$$\omega_n^2 = 1225, \quad 2\zeta\omega_n = 35$$

$$\omega_n = 35$$

$$\zeta = 0.5$$

For step input.  $R(s) = \frac{1}{s}$ 

$$c(t) = 1 - \frac{e^{-1.25t}}{\sqrt{1-\zeta^2}} \sin\left[\omega_d t + \tan^{-1}\left(\frac{\sqrt{1-\zeta^2}}{\zeta}\right)\right]$$

$$\omega_d = \omega_n \sqrt{1-\zeta^2}$$

$$\text{delay time} = \frac{1 + 0.7\zeta}{\omega_n} = \frac{1 + (0.7)(0.5)}{35} = 0.038 \text{ sec}$$

$$\text{Peak time} = \frac{\pi}{\omega_d} = \frac{\pi}{35\sqrt{1-(0.5)^2}} = 0.1036 \text{ sec}$$

$$\text{Max peak overshoot } M_p = e^{\frac{-\pi\zeta}{\sqrt{1-\zeta^2}}} = 0.163$$

$$\text{Settling time } T_s = \frac{4}{\zeta\omega_n} = 0.228 \text{ sec}$$

rise time  $T_r = \frac{\pi - 0}{\omega_d} = \frac{\pi - \left( \cos^{-1} \left( \xi \times \frac{\pi}{180} \right) \right)}{\omega_n \sqrt{1 - \xi^2}}$

$= 0.0878 \text{ sec}$

For Critically damped:

$\xi = 1, \omega_n = 35$

for step input  $R(s) = \frac{1}{s}$

$C(t) = 1 - (1 + \omega_n t) e^{-\omega_n t}$

delay time  $t_d = \frac{1 + 0.7\xi}{\omega_n} = 0.0485 \text{ sec}$

Settling time  $t_s = \frac{4}{\xi \omega_n} = 0.114 \text{ sec}$

For over damped:

$\xi = 1.79, \omega_n = 35$

for step input  $R(s) = \frac{1}{s}$

$C(t) = A + B e^{-k_1 t} + C e^{-k_2 t}$

delay time  $t_d = \frac{1 + 0.7\xi}{\omega_n} = 0.0635 \text{ sec}$

Settling time  $t_s = \frac{4}{\xi \omega_n} = 0.0653 \text{ sec}$

For undamped system:

$$\xi = 0, \omega_n = 3.5$$

for step input  $R(s) = \frac{1}{s}$

$$c(t) = 1 - \cos \omega_n t$$