

In the beginning we want to work on improving and developing all the skills of the robot in terms of rigidity, strength and durability. In terms of the legs, we will work to develop all parts of the legs in terms of the operating system of the legs. First, we will put a thick piece over the infidels to maintain the smoothness and cohesion of the tires, and secondly, we put aids to reduce From the movement of the body during the movement of the legs and then we install it at the top of the infidelity with an orderly design, and then we come with a thick cover and iron inside it to arrange the infidelity under the infidelity.

