



- 1 - Turn Right, Go Forward, Turn Left, Go Forward, Turn Left, Turn Left, Go Forward as well as use Timer.**
- 2 - Reverse using Timer , spin 180 and Go Forward using I/R sensor and Ultrasonic Sensor.**
- 3. Stop and Reverse using Timer , spin 180 and Go Forward using I/R sensor and Ultrasonic Sensor.**
- 4. random walk, levy flight by using IR sensor and Ultrasonic sensor**



