

OAK-D S2 PoE

1 Features

- Movidius Myriad X VPU
- 256/512/1024Mbit QSPI NOR Flash (128Mbit is used on some batches)
- 32Kb I2C EEPROM
- Gigabit Ethernet + PoE power
- 2x 2-lane MIPI connects OV9282 1MP global shutter cameras with no IR filter
- 1x center 4-lane MIPI connects IMX378 12 MP color rolling shutter camera
- ¼ -20 tripod mount on the bottom of the unit
- VESA-spec (7.5cm, M4) set of mounting holes on the back of the unit
- IP67 rated

2 Applications

- Industrial automation
- Robotics
- Surveillance IP camera
- Security systems
- Remote intelligence

3 Description

The Luxonis OAK-D S2 PoE is an AI Edge vision system driven by Movidius Myriad X VPU. The system is powered with Power over Ethernet (PoE). OAK-D S2 PoE has three on-board cameras which implement stereo and RGB vision, piped directly into the DepthAI Myriad X VPU for depth and AI processing. The data is then output to a host via Gigabit Ethernet connection using an M12 X-coded connector.

The OAK-D S2 PoE also features auxiliary M8 connector that provides USB and GPIO capability to control external devices.

Device Information

PART NUMBER	SIZE (WxHxD)
OAK-D-S2-PoE	111 mm x 47 mm x 31.1 mm



Figure 1 – OAK-D S2 PoE

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4 Electrical Characteristics

4.1 Absolute Maximum Ratings¹

SYMBOL	RATINGS	MIN	MAX	UNIT
V_{POE}	802.3af, Class3 input supply voltage range. ⁽²⁾	37	57	V
V_{BUSIN}	USB input supply voltage range. ⁽³⁾	3.5	5.5	V
I_{VBUS}	Maximum input current requirement		2	A
T_{stq}	Ambient temperature	0	60	C

4.2 Recommended Operating Conditions

SYMBOL	RATINGS	MIN	TYP	MAX	UNIT
V_{POE}	PoE input voltage range ⁽²⁾	37		57	V
V_{BUSIN}	VBUS input supply voltage		5V	5.25	V
$V_{io-imax}$	Maximum input voltage for GPIO pins			5.5	V
$V_{io-omax}$	Maximum output voltage for GPIO pins			3.3	V
P	Power consumption requirement	4	6	7.5	W
P_{IDLE}	VBUS idle power draw (Myriad X booted)		2.5		W
T_A	Ambient operating temperature			50	°C

- 1) Stresses beyond those listed under *Absolute Maximum Ratings* may cause permanent damage to the device. These are stress ratings only, which do not imply functional operation of the device at these or any other conditions beyond those indicated under *Recommended Operating Conditions*. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- 2) Power supply designed according to 802.3af (802.3at Type 1) standard.
- 3) According to industry standard Universal Serial Bus (USB) specifications.

5 Camera sensors characteristics

5.1 Center Color Camera

The color sensor on the stereo depth module in addition to color image provides texture information. Usages for the texture information include overlay on a depth image to create a color point cloud and overlay on a 3D model for reconstruction.

Parameter	Value
Image sensor	Sony IMX378
Active pixels	4056x3040@60fps
Output video format	RAW12/10/8
Focus type	Auto Focus 8cm - ∞ / Fixed Focus 50cm- ∞
FOV	78°
Shutter Type	Rolling shutter
IR sensitive	No

5.2 Stereo vision gray scale camera

Stereo cameras compare the features and based on the disparity determines the distance/depth of the object tracked on by the product. It also provides the depth map in color and raw depth map in gray scale.

Parameter	Value
Image sensor	OmniVision OV9282
Active pixels	1280x800@120FPS
Output video format	8/10-bit RAW
Focus type	Fixed Focus 19.6cm - ∞
FOV	89.5°
Shutter Type	Global shutter
IR sensitive	Yes

6 Inertial Measurement Unit (IMU)

OAK-D S2 PoE integrates a 9-Axis (Acceleration, Gyroscope and magnetometer) BNO086 inertial measurement unit. MotionEngine 9-Axis and 6-Axis Sensor Fusion provides raw, calibrated sensor orientation data for more accurate heading and orientation.

7 Auxiliary interface

1) USB:

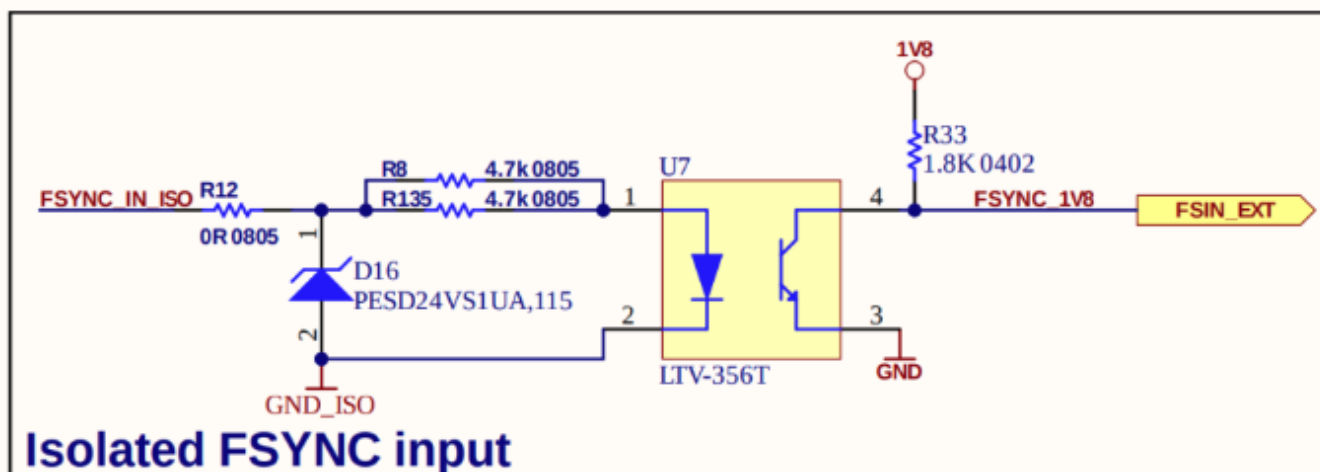
Device supports USB 2.0 interface used as a host to control external devices. Optionally this interface is used to reprogram the OAK-D-S2-POE device (AUX GPIO 3V3 needs to be pulled high during boot up in this case)

2) GPIO:

AUX GPIO 3V3 – General purpose input output pin. This pin is used to put the device in to USB boot by pulling this pin high with a 10k resistor during startup. Also this pin is multiplexed with the Strobe functionality.

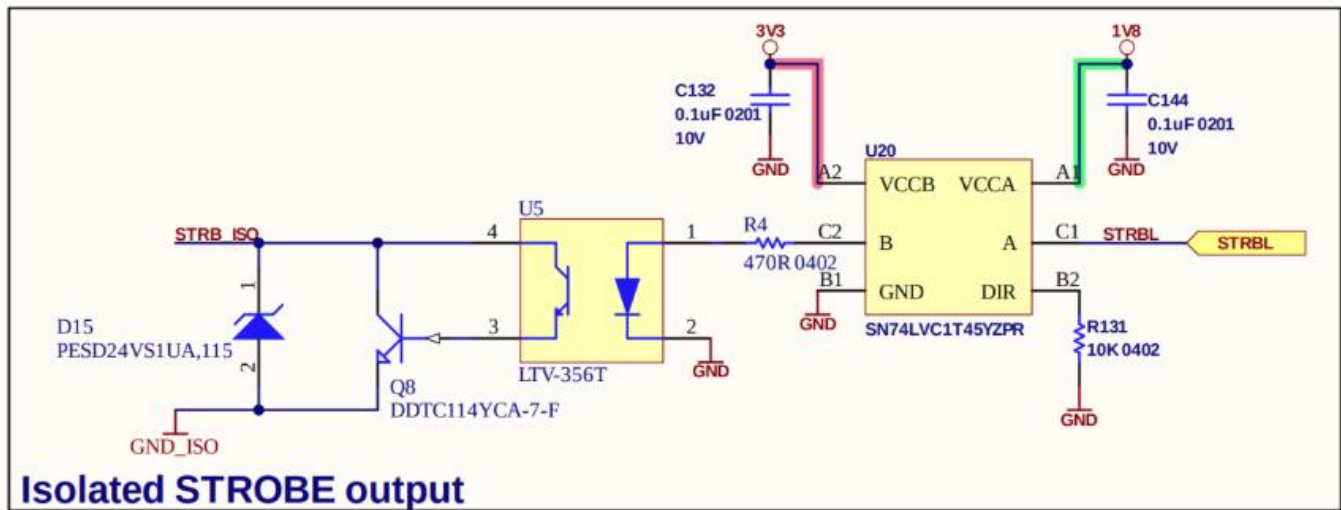
3) FSYNC:

Frame synchronization signal for cameras. This pin is optically isolated (refer to the implementation bellow).



4) STROBE:

Strobe signal for controlling external lights. This pin is optically isolated (refer to the implementation bellow)

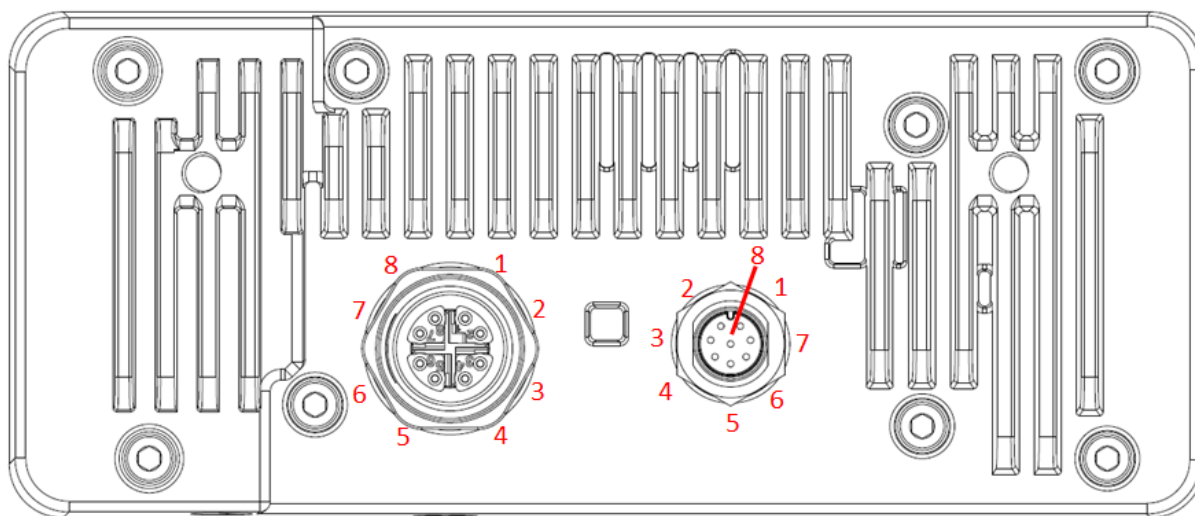


5) 5V:

This pin is used for sourcing 5V power to accessory devices connected to the M8 connector. If trying to boot the device in USB boot mode, this pin can also sink current.

8 Connectors

OAK-D S2 PoE features an M12 connector for connecting to host via Ethernet and providing power, and M8 auxiliary connector.



Ethernet M12 connector, X-Coded, Female

1	Ethernet MX0+
2	Ethernet MX0-
3	Ethernet MX1+
4	Ethernet MX1-
5	Ethernet MX3+
6	Ethernet MX3-
7	Ethernet MX2+
8	Ethernet MX2-

Auxiliary M8 connector, A-Coded, Male

1	AUX GPIO 3V3
2	FSYNC ISO
3	USB+
4	USB-
5	5V
6	Strobe ISO
7	Isolated GND
8	GND

9 Mechanical Information

The following information is the most current data available for the designated device. This data is subject to change without notice and without revision of this document.

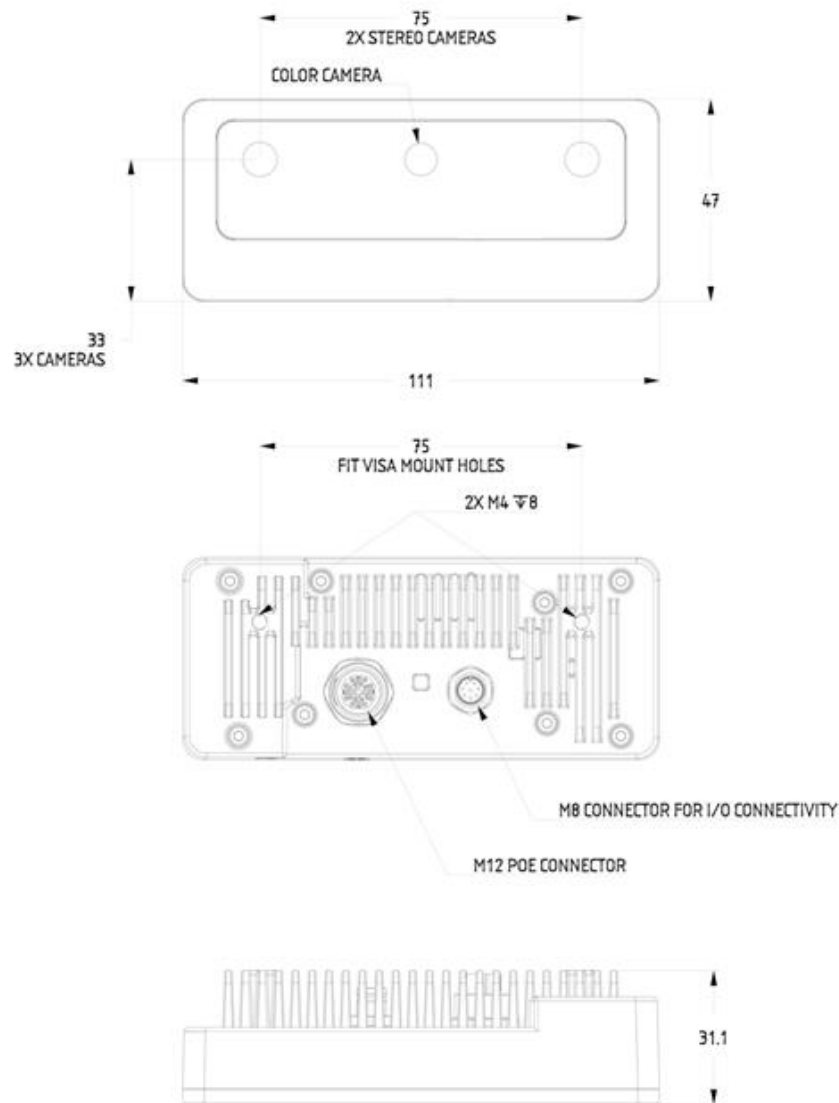


Figure 2 – OAK-D S2 PoE Mechanical measurements

10 Support

If having any issue with the device or using SW cloned from Github, please contact support@luxonis.com or reach out to Discord public server.