

# Elementary Differential Geometry

Hassium

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## 1 Calculus on Euclidean Space

**Definition 1.1.** The *Euclidean 3-space*, denoted  $\mathbb{R}^3$ , is the set of ordered triples of the form  $p = (p_1, p_2, p_3)$ , where  $p_i \in \mathbb{R}$ . An element of  $\mathbb{R}^3$  is called a *point*.

Let  $p = (p_1, p_2, p_3), q = (q_1, q_2, q_3) \in \mathbb{R}^3$  and let  $a \in \mathbb{R}$ . Define the addition to be  $p + q = (p_i + q_i)$  and define the scalar multiplication to be  $ap = (ap_i)$ . The additive identity  $0 = (0, 0, 0)$  is called the *origin* of  $\mathbb{R}^3$ . It is trivial that  $\mathbb{R}^3$  is a vector space over  $\mathbb{R}$ .

**Definition 1.2.** Let  $x, y$ , and  $z$  be real-valued functions on  $\mathbb{R}^3$  such that for all  $p = (p_1, p_2, p_3) \in \mathbb{R}^3$ ,  $x(p) = p_1$ ,  $y(p) = p_2$ , and  $z(p) = p_3$ . We call  $x, y$ , and  $z$  the *natural coordinate functions* of  $\mathbb{R}^3$ .

Let  $x, y$ , and  $z$  be the natural coordinate functions, rewrite  $x = x_1$ ,  $y = x_2$ , and  $z = x_3$ . Then we have  $p = (p_i) = (x_i(p))$ .

**Definition 1.3.** A real-valued function  $f$  on  $\mathbb{R}^3$  is *differetiable* if all partial derivatives exist and continuous.

**Definition 1.4.** A subset  $O \subset \mathbb{R}^3$  is *open* if for all  $p \in O$ , there exists  $\varepsilon > 0$  such that  $\{x \in \mathbb{R}^3 \mid \|x - p\| < \varepsilon\} \subset O$ .

Let  $f : O \rightarrow \mathbb{R}$  be a function defined on an open set. The differetiability of  $f$  at  $p$  can be determined entirely from values of  $f$  on  $O$ . This means that differetiation is a local operation. We will give a proof of this later.

**Definition 1.5.** A *tangent vector*  $v_p$  is an ordered pair  $v_p = (v, p)$ , where  $v, p \in \mathbb{R}^3$ . Here  $v$  is called the *vector part* and  $p$  is called its *point of application*. Two tangent vectors are said to be *parallel* if they have the same vector part and different points of application.

**Definition 1.6.** Let  $p \in \mathbb{R}^3$ . The *tangent space* at  $p$ , denoted  $T_p(\mathbb{R}^3)$ , is the set of all tangent vectors that have  $p$  as point of application.

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## Exercises and Proofs

**Exercise 1.1.1.** Let  $f = x^2y$  and  $g = y \sin z$  be functions on  $\mathbb{R}^3$ . Express the following functions in terms of  $x$ ,  $y$ , and  $z$ .

1.  $fg^2$ ;
2.  $\frac{\partial f}{\partial x}g + \frac{\partial g}{\partial y}f$ ;
3.  $\frac{\partial^2(fg)}{\partial y \partial z}$ ;
4.  $\frac{\partial}{\partial y}(\sin f)$ .

*Proof.* (i) We have  $fg^2 = x^2yy^2\sin^2z = x^2y^3\sin^2z$ . (ii) We have  $\frac{\partial f}{\partial x} = 2xy$  and  $\frac{\partial g}{\partial y} = \sin z$ , then  $\frac{\partial f}{\partial x}g + \frac{\partial g}{\partial y}f = 2xy^2\sin z + x^2y\sin z$ . (iii) We have  $fg = x^2y^2\sin z$ , then  $\frac{\partial^2(fg)}{\partial y \partial z} = 2x^2y\cos z$ . (iv) We have  $\sin f = \sin(x^2y)$ , then  $\frac{\partial}{\partial y}(\sin f) = x^2\cos(x^2y)$ .  $\square$

**Exercise 1.1.3.** Express  $\frac{\partial f}{\partial x}$  in terms of  $x$ ,  $y$ , and  $z$  for the following functions.

1.  $f = x \sin(xy) + y \cos(xz)$ ;
2.  $f = \sin g$ ,  $g = e^h$ , and  $h = x^2 + y^2 + z^2$ .

*Proof.* (i) We have  $\frac{\partial f}{\partial x} = \frac{x \sin(xy)}{\partial x} + \frac{\partial y \cos(xz)}{\partial x} = \sin(xy) + xy \cos(xy) - yz \sin(xz)$ . (ii) We have  $f = \sin(e^{x^2+y^2+z^2})$ , then  $\frac{\partial f}{\partial x} = 2x \cos(e^{x^2+y^2+z^2})e^{x^2+y^2+z^2}$ .  $\square$

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