

# Scoliosis Screening using Self Contained Ultrasound and Neural Networks

Hastings Greer, Stephen Aylward, Sam Gerber, Matt McCormick, Deepak Chittajallu, and Neal Siekierski

Kitware Inc, Carrboro NC 27510, USA

**Abstract.** We aim to diagnose scoliosis using a self contained ultrasound device that will not require expert operation. The device will detect the angle between the device and the spine using a neural network, and measure the angle between the device and vertical using an off the shelf IMU. The difference between these values will produce a plot of the spine deviation from vertical during the scan, and the extrema of this plot will yield the Cobb angle.

## 1 Motivation

Currently scoliosis diagnosis and tracking requires either X-Ray imaging, which, while very accurate, involves radiation and is impractical for in school screening, or visual inspection, which requires training, is subjective, and requires an X-ray for confirmation. We hope to replace both of these using a hand-held ultrasound wand.

## 2 Training Data

Our initial study was conducted on

## Acknowledgments

This work was funded, in part, by the following grants.

- NIH/NIBIB: In-field FAST procedure support and automation (R43EB016621)
- NIH/NIGMS/NIBIB: Slicer+PLUS: Collaborative, open-source software for ultrasound analysis (R01EB021396)

## References

1. Stephen R Aylward, Matthew McCormick, HJ Kang, Sharif Razzaque, Roland Kwitt, and Marc Niethammer. Ultrasound spectroscopy. In *Biomedical Imaging (ISBI), 2016 IEEE 13th International Symposium on*, pages 1013–1016. IEEE, 2016.

2. Samuel Gerber, Maeliss Jallais, Hastings Greer, Matt McCormick, Sean Montgomery, Bradley Freeman, Deborah Kane, Deepak Chittajallu, Neal Siekierski, and Stephen Aylward. Automatic estimation of the optic nerve sheath diameter from ultrasound images. In *MICCAI Workshop*, 2017.
3. Christoph Mertz, Sanjeev J Koppal, Solomon Sia, and Srinivasa Narasimhan. A low-power structured light sensor for outdoor scene reconstruction and dominant material identification. In *Computer Vision and Pattern Recognition Workshops (CVPRW), 2012 IEEE Computer Society Conference on*, pages 15–22. IEEE, 2012.
4. Daniel Moreno and Gabriel Taubin. Simple, accurate, and robust projector-camera calibration. In *3D Imaging, Modeling, Processing, Visualization and Transmission (3DIMPVT), 2012 Second International Conference on*, pages 464–471. IEEE, 2012.