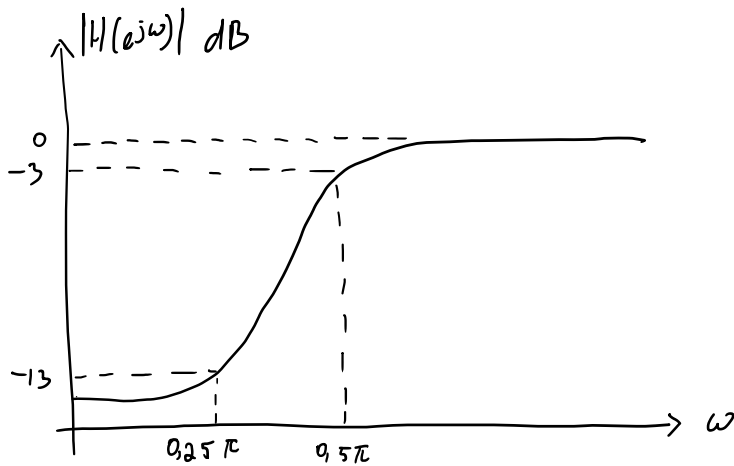


1. $f_p = 2000 \text{ Hz}$ $F_s = 8 \text{ kHz} = 8000 \text{ Hz}$
 $f_s = 1000 \text{ Hz}$ $R_p = -3 \text{ dB}$
 $f_o = 4000 \text{ Hz}$ $R_s = -13 \text{ dB}$

a. $\omega_p = \frac{2\pi f_p}{F_s} = \frac{2\pi \cdot 2000}{8000} = 0,5\pi \text{ rad/sampel}$

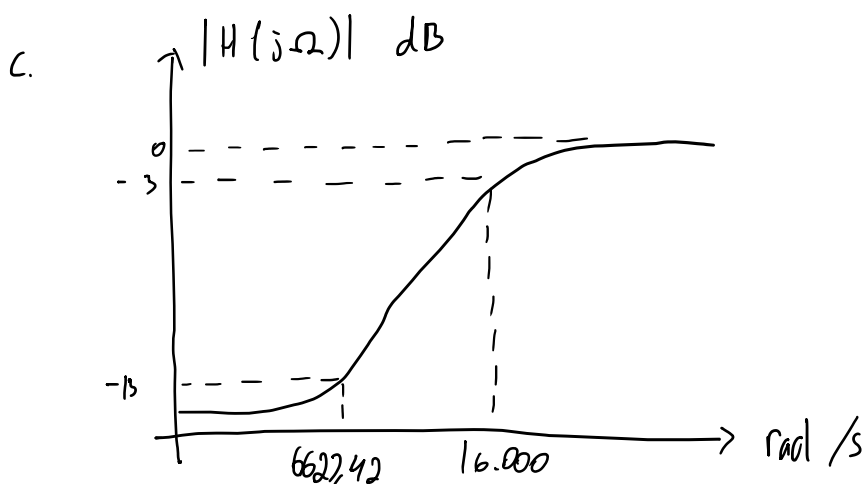
$\omega_s = \frac{2\pi f_s}{F_s} = \frac{2\pi \cdot 1000}{8000} = 0,25\pi \text{ rad/sampel}$



b. $T = \frac{1}{F_s} = \frac{1}{8000}$

$\Omega_p = \frac{2}{T} \tan\left(\frac{\omega_p}{2}\right) = \frac{2}{1/8000} \tan\left(\frac{0,5\pi}{2}\right) = 16.000 \text{ rad/s}$

$\Omega_s = \frac{2}{T} \tan\left(\frac{\omega_s}{2}\right) = \frac{2}{1/8000} \tan\left(\frac{0,25\pi}{2}\right) = 6627,42 \text{ rad/s}$



d.

$$\Omega_c = \frac{\Omega_p}{\Omega_s} = \frac{16.000}{6627,42} = 2,41$$

$$n = \left\lceil \frac{\log \left[\frac{\omega^{-\frac{R_p}{10}} - 1}{\omega^{-\frac{R_s}{10}} - 1} \right]}{2 \log \left(\frac{1}{\Omega_c} \right)} \right\rceil = \left\lceil \frac{\log \left[\frac{\omega^{\frac{3}{10}} - 1}{\omega^{\frac{13}{10}} - 1} \right]}{2 \log \left(\frac{1}{2,41} \right)} \right\rceil = \lceil 1,67 \rceil = 2$$

$$H(s) = \frac{1}{s^2 + \sqrt{2}s + 1}$$

e. $H(s)$ filter Butterworth karena tidak ada ripple

f. HPF: $s \rightarrow \frac{\Omega_p}{s} \rightarrow \frac{16.000}{s}$

$$H(s) \Big|_{s \rightarrow \frac{16.000}{s}} = \frac{1}{\left(\frac{16.000}{s} \right)^2 + \sqrt{2} \left(\frac{16.000}{s} \right) + 1}$$

$$= \frac{s^2}{s^2 + 16.000\sqrt{2}s + 16.000^2}$$

$$H(z) = H(s) \Big|_{s \rightarrow 2F_s \frac{(1-z^{-1})}{(1+z^{-1})}} = \frac{\left(16.000 \left(\frac{1-z^{-1}}{1+z^{-1}} \right) \right)^2}{\left(2.000 \cdot \frac{(1-z^{-1})}{(1+z^{-1})} \right)^2 + 16.000\sqrt{2} \left(2.000 \cdot \frac{(1-z^{-1})}{(1+z^{-1})} \right) + 16.000^2}$$

$$= \frac{(1-z^{-1})^2}{(1-z^{-1})^2 + \sqrt{2}(1-z^{-1})(1+z^{-1}) + (1+z^{-1})^2}$$

$$= \frac{1 - 2z^{-1} + z^{-2}}{1 - 2z^{-1} + z^{-2} + \sqrt{2}(1 - z^{-2}) + 1 + 2z^{-1} + z^{-2}}$$

$$H(z) = \frac{1 - 2z^{-1} + z^{-2}}{3,414 + 0,586 z^{-2}}$$

g. $n = \underline{2}$

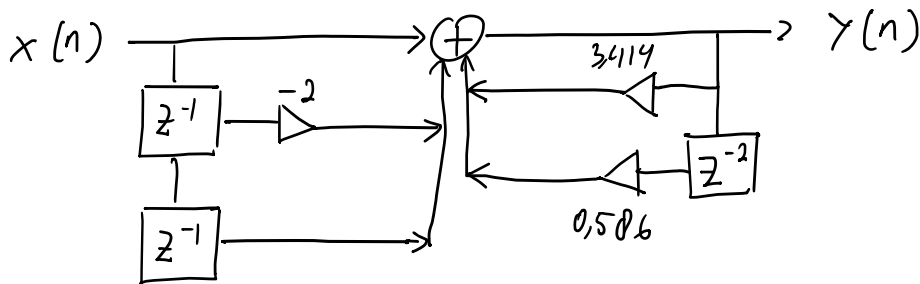
h.

$$H(z) = \frac{Y(z)}{X(z)} = \frac{1 - 2z^{-1} + z^{-2}}{3,414 + 0,586 z^{-2}}$$

$$Y(z)(3,414 + 0,586 z^{-2}) = X(z)(1 - 2z^{-1} + z^{-2})$$

$$3,414 Y(z) + 0,586 z^{-2} Y(z) = X(z) - 2z^{-1} X(z) + z^{-2} X(z)$$

$$3,414 Y(n) + 0,586 Y(n-2) = X(n) - 2X(n-1) + X(n-2)$$



i. $x(t) = 2 \cos(2000\pi t)$

$$X(n) = 2 \cos\left(\frac{2000\pi}{1000} n\right) = 2 \cos(0,25\pi n)$$

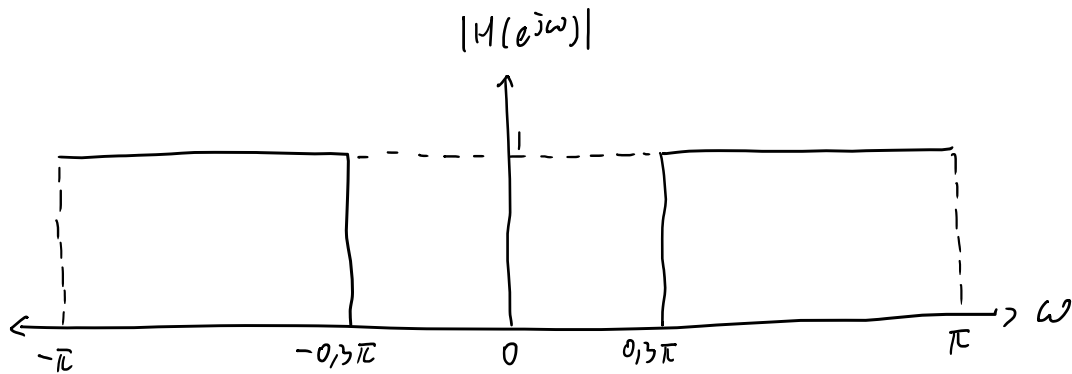
2.

$$H(e^{j\omega}) = \begin{cases} e^{-j2\omega}, & -\pi \leq \omega \leq -0,3\pi \\ 0, & -0,3\pi < \omega < 0,3\pi \\ e^{-j2\omega}, & 0,3\pi \leq \omega \leq \pi \end{cases}$$

$$w[n] = 0,54 - 0,46 \cos\left(\frac{2\pi n}{M-1}\right), \quad 0 \leq n \leq M-1$$

$$\bar{F}_s = 8 \text{ kHz}$$

a.

b. $\alpha = 2$

$$\text{Jumlah koef. filter: } M = 2\alpha + 1 = 2 \cdot 2 + 1 = 5$$

$$\text{Orde filter: } N = M - 1 = 4$$

c. $\omega_c = 0,3\pi$

$$h_d[n] = \frac{\sin[\pi(n-\alpha)] - \sin[\omega_c(n-\alpha)]}{\pi(n-\alpha)}, \quad 0 \leq n \leq N$$

$$h_d[n] = \frac{\sin[\pi(n-2)] - \sin[0,3\pi(n-2)]}{\pi(n-2)}, \quad 0 \leq n \leq 4$$

$$h_d[n] = [h_d(0) \quad h_d(1) \quad h_d(2) \quad h_d(3) \quad h_d(4)]$$

$$h_d[n] = [-0,151 \quad -0,258 \quad 0,7 \quad -0,258 \quad -0,151]$$

d. $w[n] = [w(0) \quad w(1) \quad w(2) \quad w(3) \quad w(4)]$
 $w[n] = [0,08 \quad 0,54 \quad 1 \quad 0,54 \quad 0,08]$

e. $h[n] = h_d[n] \cdot w[n]$
 $= [-0,012 \quad -0,139 \quad 0,7 \quad -0,139 \quad -0,012]$

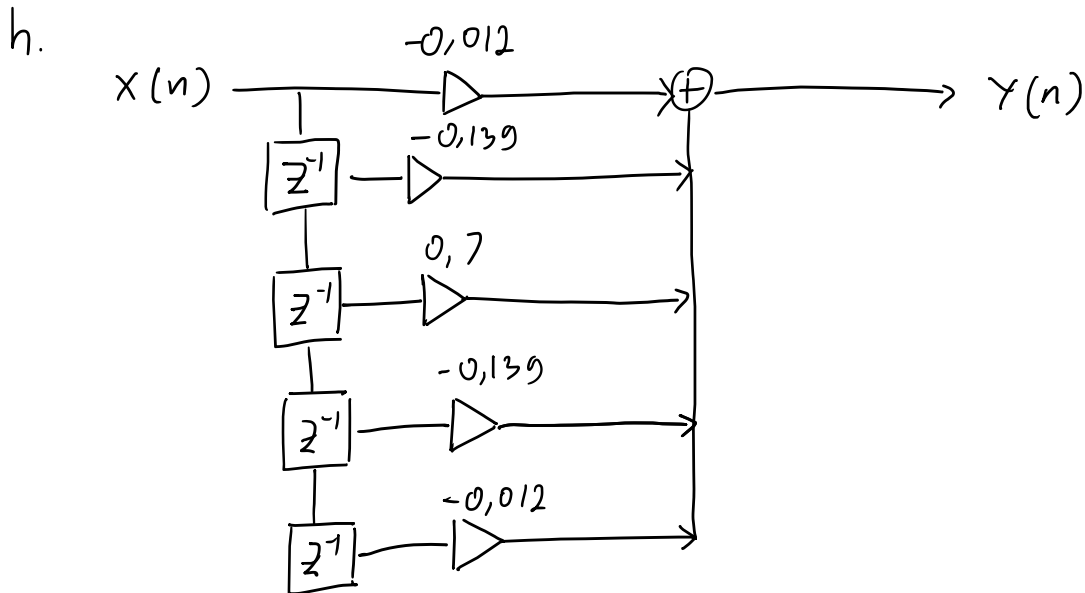
f. Filter stabil dan kausal karena jenis filter FIR yang non-rekursif dan BIBO

g. $\omega_c = \frac{2\pi f_c}{F_s}$

$0,3\pi = \frac{2\pi f_c}{8000}$

$f_c = 1200 \text{ Hz}$

Rentan frekuensi yang dilewatkan : $f \geq f_c$
 $f \geq 1200 \text{ Hz}$



i. $h[n] = [-0,012 \quad -0,139 \quad 0,7 \quad -0,139 \quad -0,012], \quad 0 \leq n \leq 4$

$h[n] = [-0,012 \quad -0,139 \quad 0,7 \quad -0,139 \quad -0,012 \quad 0 \quad 0 \quad 0], \quad 0 \leq n \leq 7$

$$f[n] = h[2n] = \{h[0], h[2], h[4], h[6]\}$$

$$= \begin{bmatrix} -0,012 & 0,7 & -0,012 & 0 \end{bmatrix}$$

$$g[n] = g[2n+1] = \{h[1], h[3], h[5], h[7]\}$$

$$= \begin{bmatrix} -0,139 & -0,139 & 0 & 0 \end{bmatrix}$$

$$W_4 = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix}$$

$$F_4 = W_4 \cdot f[n]$$

$$\begin{bmatrix} F[0] \\ F[1] \\ F[2] \\ F[3] \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} -0,012 \\ 0,7 \\ -0,012 \\ 0 \end{bmatrix} = \begin{bmatrix} 0,676 \\ -0,7j \\ -0,724 \\ 0,7j \end{bmatrix}$$

$$G_4 = W_4 \cdot g[n]$$

$$\begin{bmatrix} G[0] \\ G[1] \\ G[2] \\ G[3] \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & -j & -1 & j \\ 1 & -1 & 1 & -1 \\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} -0,139 \\ -0,139 \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} -0,278 \\ -0,139 + 0,139j \\ 0 \\ -0,139 - 0,139j \end{bmatrix}$$

$$H[0] = F[0] + W_8^0 \cdot G[0] = 0,676 + 1 \cdot (-0,278) = 0,398$$

$$H[1] = F[1] + W_8^1 \cdot G[1] = -0,7j + \left(\frac{1}{\sqrt{2}} - \frac{j}{\sqrt{2}}\right)(-0,139 + 0,139j)$$

$$= -0,504j$$

$$H[2] = F[2] + W_8^2 \cdot G[2] = -0,724 + (-j) \cdot 0 = -0,724$$

$$H[3] = F[3] + W_P^3 G[3] = 0,7j + \left(-\frac{1}{\sqrt{2}} - \frac{1}{\sqrt{2}}j\right)(-0,139 - 0,139j) \\ = 0,896j$$

$$H[4] = F[0] - W_P^0 G[0] = 0,676 - (1) \cdot (-0,278) = 0,954$$

$$H[5] = F[1] - W_P^1 G[1] = -0,7j - \left(\frac{1}{\sqrt{2}} - \frac{1}{\sqrt{2}}j\right)(-0,139 + 0,139j) \\ = -0,896j$$

$$H[6] = F[2] - W_P^2 G[2] = -0,724 - (j) \cdot 0 = -0,724$$

$$H[7] = F[3] - W_P^3 G[3] = 0,7j - \left(-\frac{1}{\sqrt{2}} - \frac{1}{\sqrt{2}}j\right)(-0,139 - 0,139j) \\ = 0,504j$$

j. $|H[0]| = 0,398 \quad |H[1]| = 0,504 \quad |H[2]| = 0,724 \quad |H[3]| = 0,896$
 $|H[4]| = 0,954 \quad |H[5]| = 0,896 \quad |H[6]| = 0,724 \quad |H[7]| = 0,504$

