

CS 5/6110, Software Correctness Analysis, Spring 2021

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Least Fixpoint of Functions, Computational Rules
Monotonicity, Continuity
Y Combinators

Where
we
are

	NO ASG NOW ON...	AS WE HAVE 6 WKS	BUT QUIZZES YES!!
W 3/17	Wrap up fixed-point theory -- AND/OR show how fixed-points work in the context of CTL model checking		
M 3/22	Fixpoint Theory used to realize Computational Tree Logic (CTL) Model Checking		Quiz10
W 3/24	Office Hours		

f1, f2, and f3 are solutions for F below. We can arrive at f3 (the least fixpoint by iterating up from "Bottom")

Now consider the recursive definition:

$$F(x, y) = \text{if } x = y \text{ then } y + 1 \text{ else } F(x, F(x - 1, y + 1)).$$

$$f_1 = \lambda(x, y) . \text{if } x = y \text{ then } y + 1 \text{ else } x + 1$$

$$f_2 = \lambda(x, y) . \text{if } x \geq y \text{ then } x + 1 \text{ else } y - 1$$

$$f_3 = \lambda(x, y) . \text{if } x \geq y \text{ and } x - y \text{ is even then } x + 1 \text{ else } \perp$$

Here, the "bottom" in f3 is the bottom value

For LFP, we have to substitute the bottom function in place of "F" and iterate

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The same f3 would also be obtained if we solve for the recursion of "F" using the Y combinator

$$Y = (\text{lambda } x. (\text{lambda } h. x(h\ h)) (\text{lambda } h. x(h\ h)))$$

This demo of the use of Y will be presented in later slides
plus using the Jove demo's on the use of Y

Modeling Partial Functions

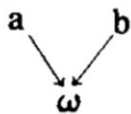
- Discussions from manna-fp-theory-2.pdf
- Manna uses “omega” instead of Bottom (for the undefined value) and Capital Omega for the undefined function
- Manna calls second-order functions by the term “functional”

Modeling Partial Functions

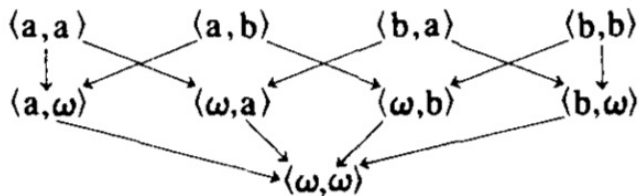
In developing a theory for handling partial functions it is convenient to introduce the special element ω to represent the value undefined. We let D^+ denote $D \cup \{\omega\}$, assuming $\omega \notin D$ by convention; when D is the Cartesian product $A_1 \times \cdots \times A_n$, we let D^+ be $A_1^+ \times \cdots \times A_n^+$. Any partial function f mapping $D_1 = A_1 \times \cdots \times A_n$ into D_2 may then be considered as a total function mapping D_1 into D_2^+ : if f is undefined for $\langle d_1, \dots, d_n \rangle \in D_1$, we let $f(d_1, \dots, d_n)$ be ω .

Lattice Ordering

- How values are ordered in the information order is shown
- How pairs of values are ordered is shown
- No reflexive and transitive edges shown for clarity



D^+



$(D \times D)^+ = D^+ \times D^+$

Monotonic functions act as per info order

- Monotonic functions “respect the information order ” of their arguments

Monotonic Functions

Any function f computed by a program has the property that whenever the input x is less defined than the input y , the output $f(x)$ is less defined than $f(y)$. We therefore require that the extended function f from D_1^+ into D_2^+ be *monotonic*, i.e.

$x \subseteq y$ implies $f(x) \subseteq f(y)$ for all $x, y \in D_1^+$.

We let $(D_1^+ \rightarrow D_2^+)$ denote the set of all monotonic functions from D_1^+ into D_2^+ .

Monotonic functions act as per info order

- For multiple arguments, there is a “natural extension” - useful for languages with the call-by-value semantics (“evaluate the arguments before applying the function body”)

Following we denote such a constant function just by c . If f has many arguments, i.e. $D_1 = A_1 \times \dots \times A_n$, it may have many different monotonic extensions. A particularly important extension of any function is called the *natural extension*, defined by letting $f(d_1, \dots, d_n)$ be ω whenever at least one of the d_i is ω . This corresponds intuitively to the functions computed by programs which must know all their inputs before beginning execution (i.e. ALGOL “call by value”).

Example where Call By Value makes a diff.

- The call by value evaluation rule computes less than the least fixpoint - can terminate even when another computation rule can discover the answer - example from paper manna-fp-theory-1.pdf is below
- Those other evaluation rules are
 - “normal order” evaluation rules: Example:
 - Leftmost Outermost
 - Popularly, these are known as [Lazy Evaluation Order](#)
- See next slide for details!

Example where Call By Value makes a diff.

Let us consider, for example, the following recursive program over the integers

$P_1 : F(x, y) \Leftarrow \text{if } x = 0 \text{ then } 1 \text{ else } F(x - 1, F(x, y)).$

The least fixpoint f_{P_1} can be shown to be

$f_{P_1}(x, y) : \text{if } x \geq 0 \text{ then } 1 \text{ else undefined.}$

However, the computed function C_{P_1} , where C is “call by value,” turns out to be

$C_{P_1}(x, y) : \text{if } x = 0 \text{ then } 1 \text{ else undefined.}$

Thus C_{P_1} is properly less defined than f_{P_1} —e.g. $C_{P_1}(1, 0)$ is *undefined* while $f_{P_1}(1, 0) = 1$.

We construct increasing chains of monotonic functions from the functional obtained from the body of a recursive definition. Such chains have unique least fixpoints

The Ordering \subseteq on Functions

Let f and g be two monotonic functions mapping D_1^+ into D_2^+ . We say that $f \subseteq g$, read “ f is less defined than or equal to g ,” if $f(x) \subseteq g(x)$ for any $x \in D_1^+$; this relation is indeed a partial ordering on $(D_1^+ \rightarrow D_2^+)$. We say that $f \equiv g$, read “ f is equal to g ,” if $f(x) \equiv g(x)$ for each $x \in D_1^+$ (that is, $f \equiv g$ iff $f \subseteq g$ and $g \subseteq f$). We denote by Ω the function which is always undefined: $\Omega(x)$ is ω for any $x \in D_1^+$. Note that $\Omega \subseteq f$ for any function f of $(D_1^+ \rightarrow D_2^+)$.

Infinite increasing sequences $f_0 \subseteq f_1 \subseteq f_2 \subseteq \dots$ of functions in $(D_1^+ \rightarrow D_2^+)$ are called *chains*. It can be shown that any chain has a *unique limit function* in $(D_1^+ \rightarrow D_2^+)$, denoted by $\lim_i \{f_i\}$, which has the characteristic properties that $f_i \subseteq \lim_i \{f_i\}$ for every i , and for any function g such that $f_i \subseteq g$ for every i , we have $\lim_i \{f_i\} \subseteq g$.

Example 4. Consider the sequence of monotonic functions f_0, f_1, f_2, \dots over the natural numbers defined by $f_i(x) \equiv (\text{if } x \leq i \text{ then } x! \text{ else } \omega)$.

This sequence is a chain, as $f_i \subseteq f_{i+1}$ for every i ; $\lim_i \{f_i\}$ is the factorial function. \square

Derivation of Least Fixpoint of Functionals

- We need monotonicity and continuity
- For finite lattices, monotonicity implies continuity
- For infinite lattices, it does not
- So let's first understand monotonicity and continuity thru more examples before we dive in!

Monotonicity ensures the absence of “composition surprises”

- Example:
 - Suppose the lattice ordering is reflective of the quality of an object
 - Example: a 5% tolerance resistor is better than a 10% tolerance resistor
- Does it then mean that a circuit where we clip out a 10% resistor and solder-in a 5% resistor also improves?
- Think of a circuit as a Lambda function and reason out ...

Example

- $\text{Parcomp}(R1, R2) = R1R2 / (R1+R2)$
- Now we can ask: if $R2' \sqsubseteq R2''$
 - Does this hold : $\text{Parcomp}(R, R') \sqsubseteq \text{Parcomp}(R, R'')$ for any R ?
- If so, Parcomp is a monotonic map
- With this property preserved, we can improve one resistor and the whole circuit as a result improves

Monotonicity is sometimes violated!

- Instead of Parcomp, what if it is a floating-point program where you optimize ONE expression?
 - The accuracy of the whole program can reduce, sometimes
 - Example: the introduction of the fused-multiply-add by a compiler may improve local accuracy, but can lead to the overall computation's accuracy reducing
- What if it is a real-time system where we make ONE component faster?
 - By one module's output arriving faster, the whole system may slow down
- Thus, “local improvements” may not be a global improvement
 - Monotonicity is what ensure this – and hence, highly preferred

Continuity: “no limit-surprise”

- Most functions (and functionals) are continuous
- Lack of continuity evidenced by the following:
 - One requires an “infinite amount of information” before emitting a finite (small) piece of information
 - If this behavior occurs, the function is not continuous
- Continuity is manifested by situations where “as you provide more input”, the “output grows more”
- The lack of continuity is also evident in situations where you “need to solve the halting problem” before you can answer something

Example from actual computations

- Think of stream-based computations
- A computer node can often be viewed as a stream function
- Let the node be a factorial node!
 - Initial input (at time t_0) = bottom \rightarrow output = bottom
 - Input at t_1 : 1, bottom \rightarrow 1, bottom
 - Input at t_2 : 1,2,bottom \rightarrow 1,2,bottom
 - Input at t_3 : 1,2,3, bottom \rightarrow 1,2,6,bottom
 - ...
 - I.e. you are progressively providing more input to the node, the node computes more
- Thus you have a stream-to-stream factorial function which is continuous
- But in mathematics, you don't need to do this: you can have a non-continuous and weird function
 - "I want all of Nat before I output anything"
- In this sense, continuity is deeply tied to computability on actual machines
- These are things I learned from Prof. Eugene Stark when I took his programming semantics course during my PhD. These things must be written down somewhere... but these days, not too many people talk about it.
- I also learned these ideas from Prof. Prateek Misra, also an instructor during my PhD

Example of a non-monotonic fn from Manna

(i) The natural extension (*weak equality*), denoted by $=$, yields the value ω whenever at least one of its arguments is ω . The weak equality predicate is of course monotonic.

(ii) Another extension (*strong equality*), denoted by \equiv , yields the value **true** when both arguments are ω and **false** when exactly one argument is ω ; in other words, $x \equiv y$ if and only if $x \subseteq y$ and $y \subseteq x$. The strong equality predicate is *not* a monotonic mapping from $D^+ \times D^+$ into $\{\mathbf{true}, \mathbf{false}\}^+$, since $\langle \omega, d \rangle \subseteq \langle d, d \rangle$ but $(\omega \equiv d) \not\subseteq (d \equiv d)$ (i.e. **false** $\not\subseteq$ **true**) for $d \in D$.

Continuous Functionals

We now consider a function τ mapping the set of functions $(D_1^+ \rightarrow D_2^+)$ into itself, called a *functional*; that is, τ takes any monotonic function f as its argument and yields a monotonic function $\tau[f]$ as its value. As in the case of functions, it is natural to restrict ourselves to *monotonic* functionals, i.e. τ such that $f \subseteq g$ implies $\tau[f] \subseteq \tau[g]$ for all f and g in $(D_1^+ \rightarrow D_2^+)$. For our purposes, however, we consider only functionals satisfying a stronger property, called *continuity*. A functional τ is said to be continuous if for any chain of functions $f_0 \subseteq f_1 \subseteq f_2 \subseteq \dots$

we have

$$\tau[f_0] \subseteq \tau[f_1] \subseteq \tau[f_2] \subseteq \dots$$

and

$$\tau[\lim_i \{f_i\}] \equiv \lim_i \{\tau[f_i]\}.$$

Every continuous functional is clearly monotonic.

Example of a non-continuous fn from Manna

(b) The functional over the natural numbers $(N^+ \rightarrow N^+)$ defined by

$$\tau[F](x) \equiv \text{if } \forall x[F(x) = x] \text{ then } F(x) \text{ else } \omega$$

is monotonic but not continuous; if we consider the chain $f_0 \subseteq f_1 \subseteq \dots$ where $f_i(x) \equiv \text{if } x < i \text{ then } x \text{ else } \omega$, $\tau[f_i] \equiv \Omega$ for any i so that $\lim_i \{\tau[f_i]\} \equiv \Omega$, whereas $\tau[\lim_i \{f_i\}]$ is the identity function. \square

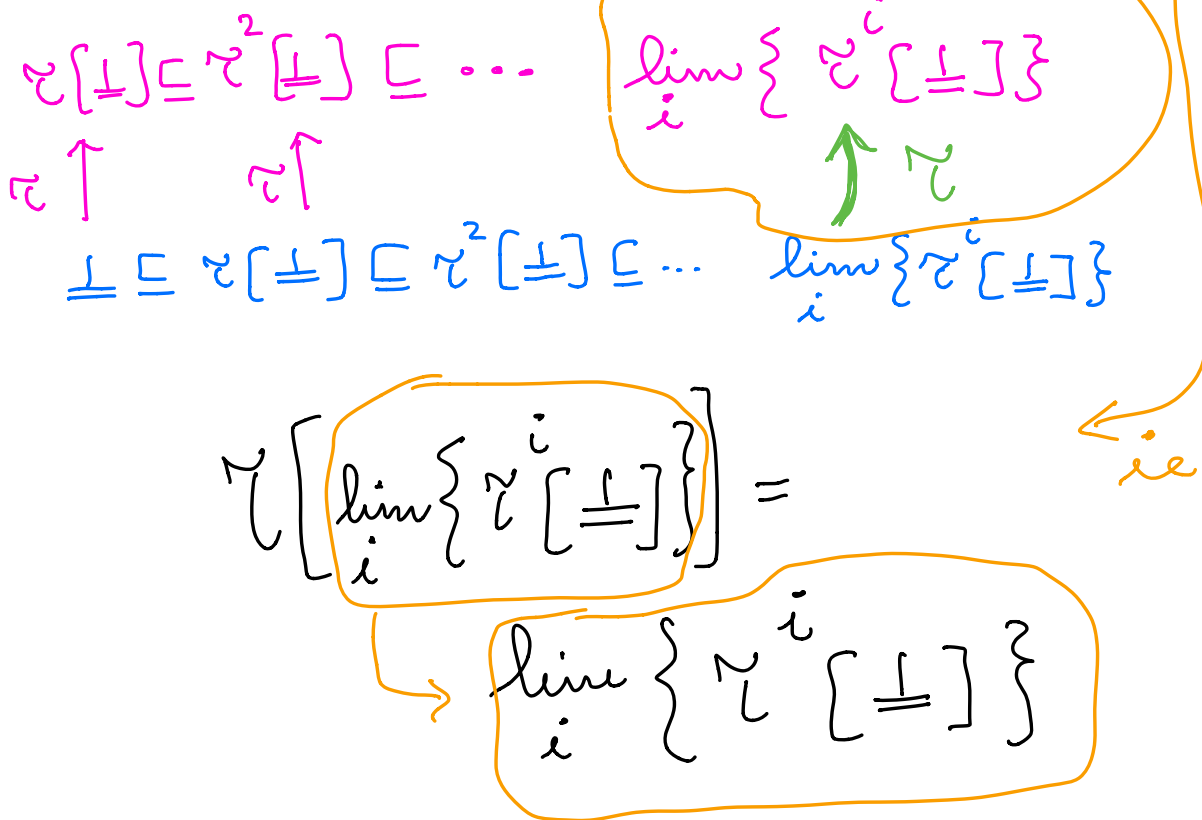
Theorem (Kleene, Others)

- Continuous functions “tau” on lattices (or other structures such as CPOs) have a unique least fixpoint given by $\text{tau}^i(\text{bottom})$

* Derivation in class

Let \perp or Ω be the undef fn
 $\perp(x) = \perp$ for all x
 \perp or ω is the undef value.

Suppose γ is a functional that
is monotonic and continuous
Then we have this figure



Thus

$\lim_i \gamma^i[\perp]$ is a fp of γ

Why is it a lfp?

Suppose $\exists g$ s.t. $\gamma[g] = g$

Then $\perp \sqsubseteq g$

$$\gamma[\perp] \sqsubseteq \gamma[g] = g$$

why?

Thus $\gamma^i[\perp] \sqsubseteq g$ for any i

$$\text{Thus } \lim_i \{ \gamma^i[\perp] \} \sqsubseteq g$$

↑
is lower than
or the same as
any other
fp called g

Relationship with Lambda Calculus

- One can compute least fixpoints also using “Y”
- One can see that “YF” and “least fixpoint iteration” both behave similarly
- Derivation in class

$$f(x) = x \leq 0 \rightarrow 1, x * f(x-1)$$

$$\text{fix}(f) = \bigvee \left[\lambda f. \lambda x. x \leq 0 \rightarrow 1, x * f(x-1) \right] = \bigvee G$$

$$\text{fix}(f) = \lim_{i \rightarrow \infty} \{ G^i(\perp) \}$$

$$\text{show } \bigvee G = \lim_{i \rightarrow \infty} \{ G^i(\perp) \}$$

$$\therefore G^i(\bigvee G) \text{ vs. } G^i(\perp)$$

$$G^n(\bigvee G) = G^n(\perp)$$

show

$$G^{n+1}(\bigvee G) = G^{n+1}(\perp)$$

Intuitively so!

Should be able to

show based on

$$\perp \sqsubseteq \bigvee G \text{ and}$$

fixpoint induction

Then show $\bigvee G$ also the

lfp.

Demo using Jupyter (Jove) notebooks

- See Chapter 18's material from <https://github.com/ganeshutah/Jove.git>

$$\tau(1) \subseteq \tau(f) \subseteq \tau^2(f). \quad \lim_i \tau^i(f)$$

$$\uparrow \quad \uparrow \quad \uparrow$$

$$1 \subseteq f \subseteq \tau[f] \dots \subseteq \lim_i \tau^i(f)$$

$$\lim_i \tau^i(f) = \tau \lim_i (\tau^i(f))$$

\uparrow
 cont

f is another f then

$$\begin{aligned} 1 &\subseteq g \\ \tau 1 &\subseteq \tau[g] \subseteq g \\ \vdots & \\ &\subseteq g. \end{aligned}$$
