AOloopControl

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1 Overview

1.1 Scope

AO loop control package

1.2 Usage

Scripts to run the software are located within the source code directory:

./src/AOloopControl/scripts/

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The scripts can be linked to your working directory by executing the following command:

ln -s \$PWD/syncscripts /myworkdirectory/syncscripts

Then, execute in your work directory:

./syncscripts

This will install all required scripts in work directory and install any packages required.

The main script is

./aolconf

1.3 Supporting scripts, aoleonfscripts directory

Scripts in the aolconfscripts directory are part of the high-level ASCII control GUI

Script	Description	
aolconf_DMfuncs	DM functions	
${ m aolconf_DMturb}$	DM turbulence functions	
aolconf_funcs	Misc functions	
${ m aolconf_logfuncs}$	data and command logging	
aolconf_menuconfiguredonpgure loop menu		
aolconf_menucontrolloopntrol loop menu		
aolconf_menucontrolmatnixol matrix menu		
aolconf_menu_mkFModese modes		
aolconf_menurecord		
aolconf_menutestmodeTest mode menu		
$aolconf_menutop$	Top level menu	
${f aolconf_menuview}$	Data view menu	
aolconf_readconf	Configuration read functions	
aolconf_template	Template (not used)	

1.4 Supporting scripts, auxscripts directory

Scripts in the auxscripts directory are called by a olconf to perform various tasks.

Script	Description
acquRespM	Acquire response matrix

1.5 Hardware simulation scripts

SCripts in the aohardsim directory are called to simulate hardware for testing / simulations

Script	Description
aosimDMstart aosimDMrun aosimmkWF	Start simulation DM shared mem Simulates physical deformable mirror (DM) creates properly sized wavefronts from pre-computed wavefronts
aosimWPyrFS	Simulates WFS

2 Hardware Simulation

2.1 Overview

The AOsim simulation architecture relies on individual processes that simulate subsystems. Each process is launched by a bash script. ASCII configuration files are read by each process. Data I/O can be done with low latency using shared memory and semaphores: a process operation (for example, the wavefront sensor process computing WFS signals) is typically triggered by a semaphore contained in the shared memory wavefront stream. A low-speed file system based alternative to shared memory and semaphores is also provided.

2.2 Processes and scripts: main WF control loop

2.2.1 Process assimmkWF

aosimmkWF reads precomputed wavefronts and formats them for the simulations (pixel scale, temporal sampling).

Parameters for aosimmkWF are stored in configuration file:

File aosimmkWF.conf.default:

! INCLUDE "../scripts/aohardsim/aosimmkWF.conf.default"

2.2.2 Process assimDMrun

File aosimDMrun.conf.default:

!INCLUDE "../scripts/aohardsim/aosimDMrun.conf.default"

2.2.3 Process assimPyrWFS

File aosimPyrWFS.conf.default:

! INCLUDE "../scripts/aohardsim/aosimPyrWFS.conf.default"

2.3 AO loop control

The aolconf script is used to configure and launch the AO control loop. It can be configured with input/output from real hardware or a simulation of real hardware.

2.3.1 Shared memory streams

Script	Description
wf0opd	Wavefront OPD prior to wavefront correction

Script	Description
wf1opd	Wavefront OPD after correction (=wf0opd-2xdm05dispmap)
$ m dm05disp \ dm05dispmap$	DM actuators positions DM OPD map
WFSinst pWFSint	Instantaneous WFS intensity WFS intensity frame, time averaged to WFS frame rate and sampled to WFS camera pixels

2.3.2 Hardware simulation architecture

Close-loop simulation requires the following scripts to be launched to simulate the hardware, in the following order:

- aosimDMstart: This script creates DM channels (uses dm index 5 for simulation). Shared memory arrays dm05disp00 to dm05disp11 are created, along with the total displacement dm05disp. Also creates the wf1opd shared memory stream which is needed by aosimDMrun and will be updated by runWF. wf1opd is the master clock for the whole simulation, as it triggers DM shape computation and WFS image computation.
- aosimDMrun: Simulates physical deformable mirror (DM)
- aosimmkWF: Creates atmospheric wavefronts
- aosimWFS: Simulates WFS

Some key script variables need to coordinated between scripts. The following WF array size should match :

- WFsize in script aosimDMstart
- ARRAYSIZE in aosimmkWF.conf
- ARRAYSIZE in aosimDMrun.conf

The main hardware loop is between assimmkWF and assimWFS: computation of a wavefront by assimmkWF is *triggered* by completion of a WFS instantaneous image computation by assimWFS. The configuration files are configured for this link.

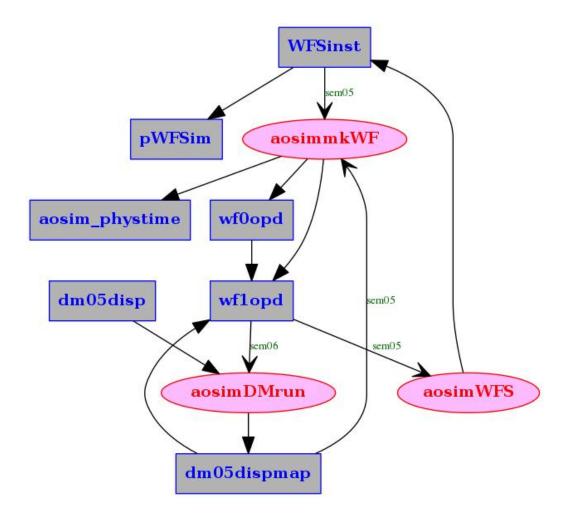


Figure 1: data flow

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2.3.3 DM temporal response

The DM temporal response is assumed to be such that the distance between the current position p and desired displacement c values is multiplied by coefficient a < 1 at each time step dt. The corresponding step response is :

$$c - p((k+1)dt) = (c - p(kdt))a$$
$$c - p(kdt) = (c - p0)a^{k}$$
$$p(kdt) = 1 - a^{k}$$

The corresponding time constant is

$$a^{\frac{t0}{dt}} = 0.5$$

 $\frac{t0}{dt}ln(a) = ln(0.5)$
 $ln(a) = ln(0.5)dt/t0$
 $a = 0.5^{\frac{dt}{t0}}$

2.4 Processes and scripts: system ouput

The output (corrected) wavefront is processed to compute output focal plane images, and optionally LOWFS image.

2.4.1 Process assimcoroLOWFS

Computes coronagraphic image output and LOWFS image

File aosimcoroLOWFS.conf.default:

!INCLUDE "../scripts/aohardsim/aosimcoroLOWFS.conf.default"

2.4.2 Ouput simulation architecture

3 AOloopControl setup

3.1 Files

SM = shared memory

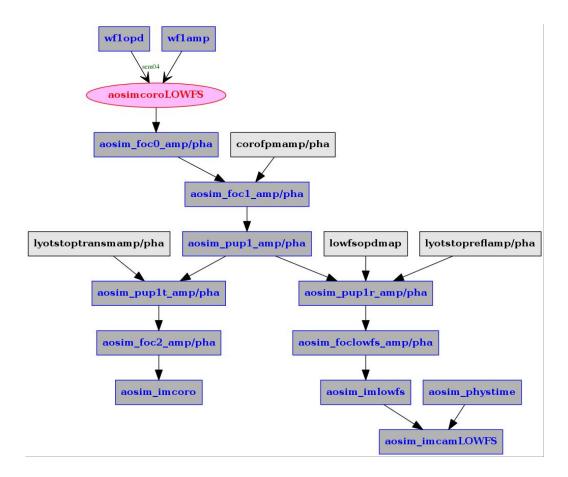


Figure 2: coroLOWFS data flow

File	stream	Description
./conf/HRM_	_DMmask.fits	DM mask to construct Hadamard RM pokes, created by auxscripts/mkHpoke if not present

3.2 GUI description

The script aolconf starts the main GUI, from which all setup and control can be done. The GUI consists of several main screens, as shown below.

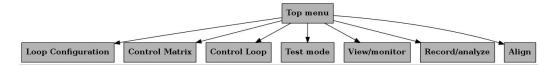


Figure 3: aolconf GUI screens

3.3 Setting up the hardware interfaces

• start allconf with loop number and loop name (you can ommit these arguments when launching the script again):

aolconf -L 3 -N testsim

- Set DM number (S command in Top Menu screen). If the DM stream exists, you should see its x and y size in the two lines below. If not, you will need to enter the desired DM size and create the DM stream with the initDM command in the Top Menu.
- autoconfigure streams (nolink in Top Menu screen). This command automactically sets up the following symbolic links:
 - dm##disp03 is linked to aol#_dmC (loop dm control channel)
 - dm##disp00 is linked to aol#_dmO (flat offset channel)

- dm##disp04 is linked to aol#_dmZP0 (zero point offset 0 actuation channel)
- dm##disp05 is linked to aol#_dmZP1 (zero point offset 1 actuation channel)
- dm##disp06 is linked to aol#_dmZP2 (zero point offset 2 actuation channel)
- dm##disp07 is linked to aol#_dmZP3 (zero point offset 3 actuation channel)
- dm##disp08 is linked to aol#_dmZP4 (zero point offset 4 actuation channel)
- dm##disp is linked to aol#_dmdisp (total dm displacement channel)
- dm##disp02 is linked to aol#_dmRM (response matrix actuation channel)
- load Memory (M in Top Menu screen). The dm performs the symbolic links to the DM channels.
- link to WFS camera (wfs to Loop Configuration screen). Select the WFS shared memory stream.

3.4 Acquiring a zonal response matrix

- set response matrix parameters in Loop Configure screen: amplitude, time delay, frame averaging, excluded frames
- set normalization and Hadmard modes in Loop Configure screen. Normalization should probably be set to 1.
- start zonal response matrix acquisition (zrespon in Loop Configure screen). The process runs in tmux session aol#zrepM.
- stop zonal response matrix acquistion (zrespoff in Loop Configure screen).

The following files are then created:

File	Archived location Description
zrespmat.fits	zrespM/zrespM_\${dat zstn }lfitsponse matrix
wfsref0.fits	$wfsref0/wfsref0_\$\{date \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \$
	image)
wfsmap.fits	wfsmap/wfsmap_\${datestp}ofiteVFS elements
	sensitivity
dmmap.fits	dmmap/dmmap_\${datestp}offiteM elements sensitivity
wfsmask.fits	wfsmask/wfsmask_\${dMtESn}ifielsmask, derived from
	wfsmap
dmmaskRM.fits	dmmaskRM/dmmaskRIDM_\$\footbatestr}m\hatsk, derived
	from dmmap by selecting
	actuators with strong response
dmslaved.fits	dmslaved/dmslaved_\$ {deatestE}Mitsctuators: actuators
	near active actuators in
	dmmaskRM
dmmask.fits	dmmask/dmmask_\${dDtVestm}askts all actuators
	controlled (union of dmmaskRM
	and dmslaved)

Note that at this point, the files are NOT loaded in shared memory, but the archieved file names are stored in "conf/conf_.txt" for future loading.

• Load zrespm files into shared memory (SMloadzrm in Loop Configure screen)

3.5 Acquiring a modal response matrix (optional)

In addition to the zonal response matrix, a modal response matrix can be acquired to improve sensitivity to low-oder modes.

To do so:

- \bullet activate RMMon to toggle the modal RM on.
- select RM amplitude and maximum cycles per aperture (CPA)

- start the acquisiton (LOresp_on)
- stop the acquisiton (LOresp_off)

The following files are then created:

File	Archived location Description
LOrespmat.fits	LOrespM/LOrespM_\$\dades\tr\sptense matrix
$respM_LOmode$	e LOD Mmlooks <u>or</u> Stedatesdes.fits
LOwfsref0.fits	LOwfsref0/LOwfsref0_\MEStesferefits measured during
	LO RM acquisition
LOwfsmap.fits	LOwfsmap/LOwfsmapM&plofeWiFSfielements
	sensitivity
LOdmmap.fits	LOdmmap/LOdmmap Maple of Edward Sensitivity
LOwfsmask.fits	LOwfsmask/LOwfsmask/FS datesturality derived from
	wfsmap
LOdmmask.fits	LOdmmask/LOdmmask Adatestor Intest, derived
	from dmmap by selecting
	actuators with strong response

Note that at this point, the files are NOT loaded in shared memory, but the archieved file names are stored in "conf/conf_.txt" for future loading.

• Load LOrespm files into shared memory (SMloadmrm in Loop Configure screen)

3.6 Building control matrix

- set SVDlimit (SVDla in Control Matrix screen). Set value is 0.1 as a starting point for a stable loop.
- perform full CM computation (mkModes0 in Control Matrix screen). Enter first the number of CPA blocks you wish to use. Computation takes a few minutes, and takes place in tmux session aol#mkmodes.

The following files are created:

File	Archived location D	escription
$aolN_{_}$	_DMmodes\/Imodes/DMmodes_\\${da	Mestan ∮diets
$aolN_{_}$	$_{ m respM}$ respM/respM_ ${ m spM}$ {datestr}	AFTS response to DM modes

Block-specific files:

File	Archived location Description		
aolN_	DMmodesDMmodes/DMmodesbb_DMdantedtes}ffintsblock bb		
aolN_1	aolN_respMbb respM/respMbb_\${date\hit\frac{1}{2}Sit\seponse to DM modes		
	for block bb		
aolN_o	contrMbb:fittsrM/contrMbb_\${datesatt}ofitsnatrix for block bb		
aolN_o	aolN_contrMcbbonfittsMc/contrMcbb_\${Clattlesps}editesontrol matrix for		
	block bb		
aolN_o	contrMcactbbMitsct/contrMcactbboll&bstatestu}tfitsmatrix for		
	block bb, only active actuators		

Note that at this point, the files are NOT loaded in shared memory, but the archieved file names are stored in "conf/conf_.txt" for future loading.

- Load CM files into shared memory (SMloadCM in Control Matrix screen)

3.7 Running the loop: Choosing hardware mode (CPU/GPU)

There are multiple ways to perform the computations on CPU and/or GPUs. The main 3 parameters are:

- GPU: 0 if matrix multiplication(s) done on CPU, >0 for GPU use
- **CMmode**: 1 if using a combined matrix between WFS pixels and DM actuators, skipping intermediate computation of modes
- **GPUall**: if using GPUall, then the WFS reference subtraction is wrapped inside the GPU matrix multiplication

GPU	CMmo	d G PUall	Description
>0	ON	ON	dark-subtracted WFS frame imWFS0 is multiplited by collapsed control matrix (only active pixels). normalization and WFS reference subtraction are wrapped in this GPU operation as subtraction of pre-computed vector output. This is the fastest mode.
>0	ON	OFF	WFS reference is subtracted from imWFS0 in CPU, yielding imWFS2. imWFS2 is multiplied by control matrix (only active pixels) in GPU.
>0	OFF	OFF	WFS reference is subtracted from imWFS0 in CPU, yiedling imWFS2. imWFS2 is multiplied (GPU) by control matrix to yield mode values. Mode coefficients then multiplied (GPU) by modes.

4 Virtual DM (dm-to-dm link)

In this mode, the AO loop controls a virtual DM. The virtual actuators are correspond to modes controlling the zero point offset of another loop. In this section, I assume that **loopA** is the main loop (directly controls a physical DM) and that **loopB** is the virtual loop.

5 Predictive control (experimental)

5.1 Scripts

File	Description
aolARPF	find auto-regressive predictive filter
aolARPFblock	AO find optimal AR linear predictive filter