

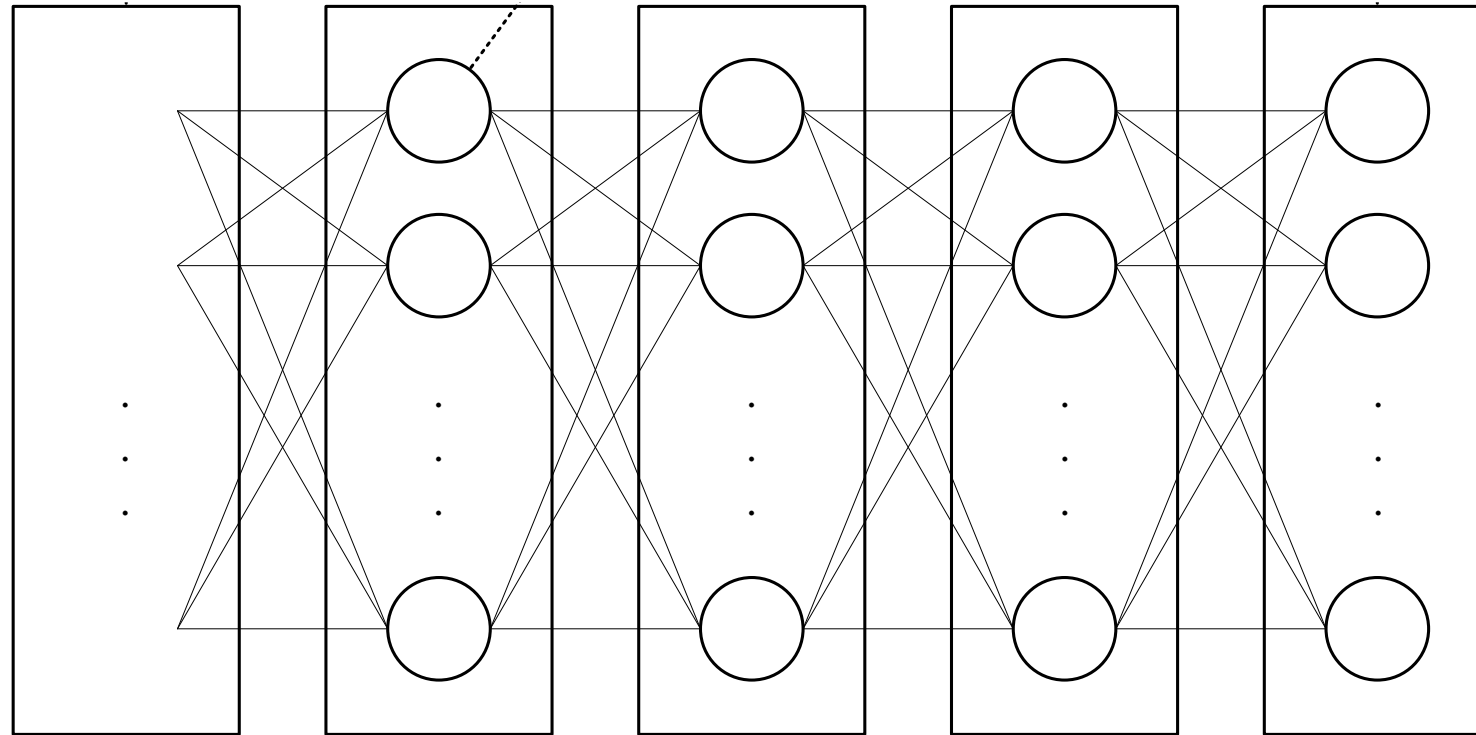


An Introduction to Convolutional Neural Networks



Problems with Fully Connected Networks

Fully Connected Network Structure



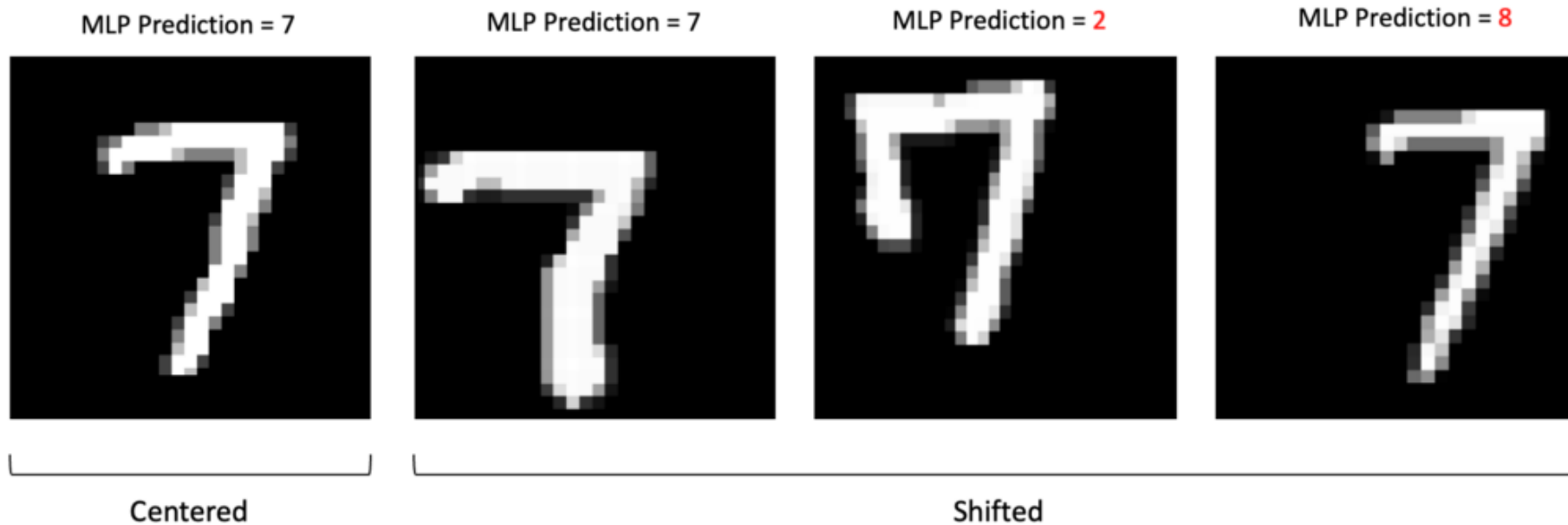
Problems with Fully Connected Networks

- As the networks grows in size, the number of parameters, especially weights, increases significantly.
- More parameters need stronger hardware for computation and storage.
- Can we reduce the number of the weights or even share them?



Problems with Fully Connected Networks

- Fully Connected Networks are not translation invariant.



Intuitive Explanation

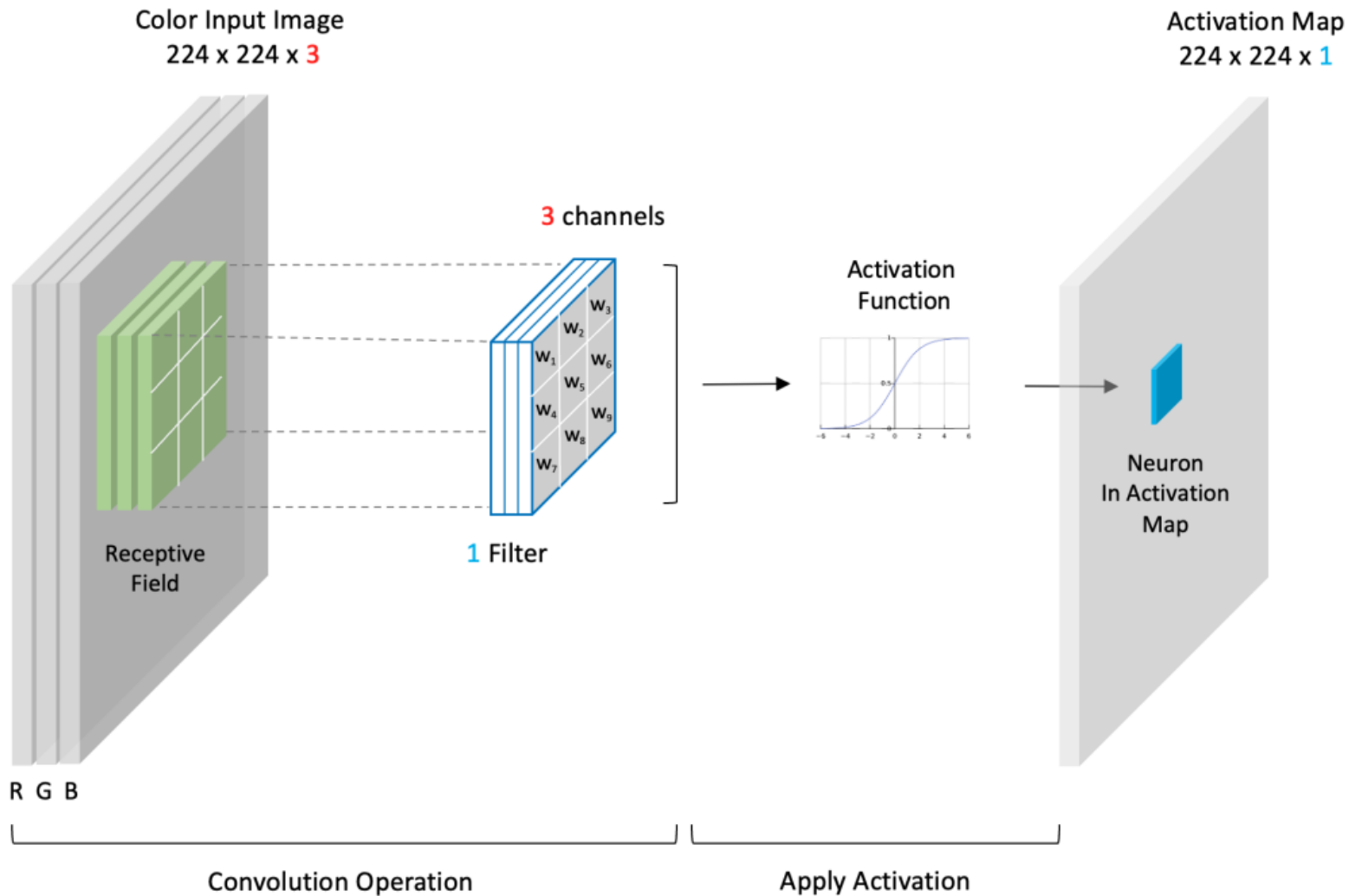
Case: Image Classification

- Consider a network that has to classify images as “bird” or “not bird”.
- A fully connected network is undesirable due to its limitations.
- Some patterns, e.g. the wings or the tail, are much smaller than the whole image.
- These patterns can appear in different parts of the images.



CNN Structure

Convolutional Layer



Convolution Operation

output

$$\begin{bmatrix} 0 & -1 & 0 \\ -1 & 5 & -1 \\ 0 & -1 & 0 \end{bmatrix}$$

7	6	5	5	6	7
6	4	3	3	4	6
5	3	2	2	3	5
5	3	2	2	3	5
6	4	3	3	4	6
7	6	5	5	6	7

input

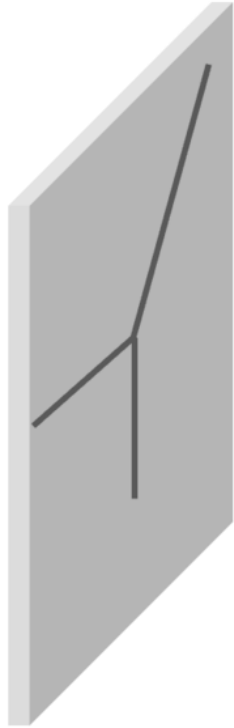


Filters

- Each filter gradually learns to detect a specific pattern.
- The number of channels in the output of a convolutional layer is equal to the number of its filters.

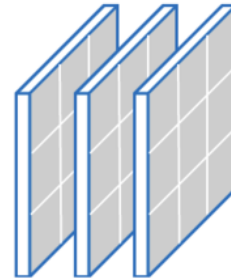


Filters



Input Image

Filters learn to detect structural patterns

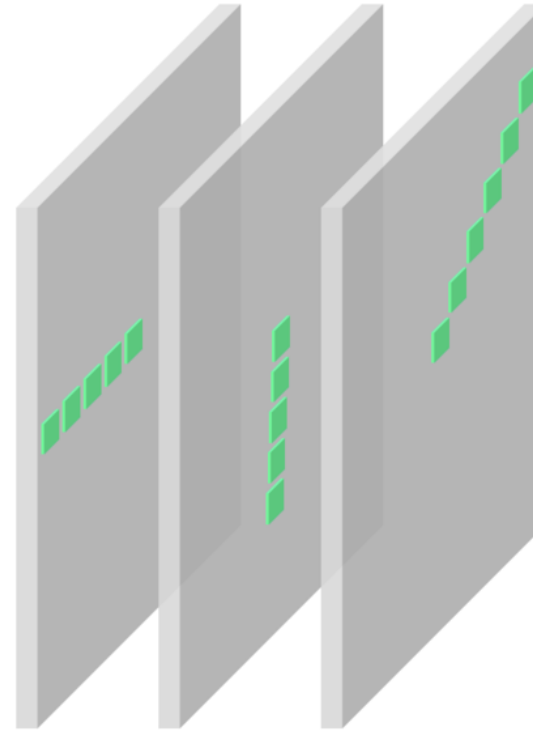


F_1 F_2 F_3


F_1 = Horizontal Lines

F_2 = Vertical Lines

F_3 = Diagonal Lines



Activation Maps

 = Highly activated neurons
in activation maps



Padding and Stride

- Padding in convolution refers to adding extra border pixels around the input image to preserve spatial dimensions after convolution.
- Stride refers to the number of pixels the filter kernel moves at each step during the convolution operation.



Max Pooling Layer

Single Depth Slice

7	2	5	2
4	5	4	7
3	3	4	2
6	4	8	6

Max Pooling

2x2 Filter & Stride of 2

7	7
6	8

Pooling Layers

- There are other types of pooling layers such as average pooling.
- However, max pooling is the most commonly used pooling layer in modern CNNs.



Convolutional Block

- A convolutional block typically contains one or more convolutional layers followed by a pooling layer.
- Other layers are also sometimes incorporated, but we will focus on these two layer types to keep things simple.



CNN Example: VGG-16

