

Big – O

From Lists:

- Linked List: insert – **O(1)**; remove – **O(n)**.
- Array List: insert – **O(n)**; remove – **O(n)**.
- All other operations have time complexity **O(1)**.
- Double linked list: operations insert – **O(1)**.
- remove – **O(1)**.

• Operation	• Array List	• Linked List	• Double-Linked List
• Empty	• O(1)	• O(1)	• O(1)
• Last	• O(1)	• O(1)	• O(1)
• Full	• O(1)	• O(1)	• O(1)
• FindFirst	• O(1)	• O(1)	• O(1)
• FindNext	• O(1)	• O(1)	• O(1)
• FindPrevious	• -	• -	• O(1)
• Retrieve	• O(1)	• O(1)	• O(1)
• Update	• O(1)	• O(1)	• O(1)
• Insert	• O(n)	• O(1)	• O(1)
• Remove	• O(n)	• O(n)	• O(1)

From Queue:

- Linked List: Enqueue is $O(n)$, Serve is $O(1)$.
- Array Implementation: Enqueue is $O(1)$, Serve is $O(1)$.
- Heap: Enqueue is $O(\log n)$, Serve is $O(\log n)$.

• Operation	• Queue (LL)	• Queue (CA)	• Priority Queue (LL)	• Priority Queue (CA)
• Full	• $O(1)$	• $O(1)$	• $O(1)$	• $O(1)$
• Length	• $O(1)$	• $O(1)$	• $O(1)$	• $O(1)$
• Enqueue	• $O(1)$	• $O(1)$	• $O(n)$	• $O(n)$
• Serve	• $O(1)$	• $O(1)$	• $O(1)$	• $O(1)$

From Stack:

- All operations are $O(1)$ (worst and best)

From Binary Trees:

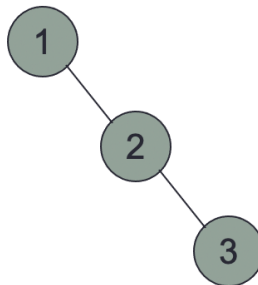
- FindKey: find an element of a particular key value in a binary tree.
- In binary tree this operation is $O(n)$.

Methods not mentioned here are $O(1)$.

method	Best case	Worst case
traverse	$O(n)$	$O(n)$
preorder	$O(n)$	$O(n)$
In order	$O(n)$	$O(n)$
postorder	$O(n)$	$O(n)$
FindParent	$O(1)$	$O(n)$
find	$O(1)$	$O(n)$
deleteSubtree	$O(1)$	$O(n)$

From Binary Search Trees:

- In a Binary Search Tree (BST) findkey operation can be performed very efficiently: $O(\log_2 n)$.
- Consider a situation when data elements are inserted in a BST in sorted order: 1, 2, 3, ...



- BST becomes a degenerate tree.
- Search operation **FindKey** takes **$O(n)$** , which is as inefficient as in a list.

In remove, insert, and findKey:

Best: $O(1)$

Average: $O(\log n)$

Worst: $O(n)$

From AVL Trees:

- insert and delete elements so that its height is guaranteed to be $O(\log n)$.
- Important operation *Findkey()* can be implemented in $O(\log n)$ time.

From Hash:

An important operation Findkey() has a time complexity:

$O(n)$ in Lists,

$O(n)$ in Binary Trees,

$O(\log n)$ in BSTs,

$O(\log n)$ in AVL trees.

Can Findkey() be implemented with a time complexity better than $O(\log n)$?

With Hash Tables it is possible to implement Findkey() with $O(1)$ time complexity.

From Heaps:

- Since a heap has height $O(\log n)$, upheap runs in $O(\log n)$ time
- Consider a priority queue with n items implemented by means of a heap
- the space used is $O(n)$
- methods enqueue and serve take $O(\log n)$ time
- methods length, full take time $O(1)$ time
- Using a heap-based priority queue, we can sort a sequence of n elements in $O(n \log n)$ time

	• Running time
• siftUp (upHeap)	• $O(\log n)$
• siftDown (downHeap)	• $O(\log n)$
• enqueue in heap priority queue	• $O(\log n)$
• serve() in heap priority queue	• $O(\log n)$
• Bottom-up construction of a heap	• $O(n)$
• Heap sort	• $O(n \log n)$

From Graphs:

- Adjacency Matrix representation is very simple, but the space requirement is $O(n^2)$ if the number of vertices is n .
- In an Adjacency list the space requirement is $O(e + n)$ where e is the number of edges and n is the number of vertices.