

In #8 Jan 17, Given $A \in SO(2)$, $W \in \mathfrak{so}(2)$
 $A^{-1}WA = W$ is due to W being skew-symmetric
 and also $A^{-1} = A^T$ $W^T = -W$
 $\text{diag}(W) = 0$

$$A^{-1}WA = WA^{-1} \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} A, \quad A = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

$$= W \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix} = W$$

Aug 18 #4

a) To show, there is no nonvanishing vector field
 on S^2 (S^n)

By contradiction, $\exists v \in TS^n$, $v = \frac{V}{\|V\|}$.

WLOG, assume $\|v\| = 1$, i.e.

$$\|V(p)\| = 1 \quad p \in S^n$$

$\|\cdot\|$ norm induced by \mathbb{R}^{n+1}

$\langle \cdot, \cdot \rangle$ inner product of \mathbb{R}^{n+1}

$$\langle p, V(p) \rangle = 0$$

Define $F: S^n \times [0, \pi] \rightarrow S^n$

$$F(x, \theta) = x \cos \theta + V(x) \sin \theta \in S^n$$

F is well-defined on S^n

$$F(x, 0) = x, \quad F(x, \pi) = -x \quad (\text{antipodal map})$$

$= \text{Id}_x$

$\text{Id}_X \stackrel{\cong}{=} \text{Antipodal map}$

(assume M compact)

Define : Degree of a map $f: M \rightarrow N$ at $y \in N$

$$\deg f = \sum_{x \in f^{-1}(y)} \text{sign}(df_x)$$

If $f \stackrel{\cong}{=} g$ then $\deg f = \deg g$.

$$\deg(\text{Id}_X) = \text{sign}(df_x) = 1 \quad \mathbb{R}^{n+1} \simeq \mathbb{C}^{\frac{n+1}{2}}$$

$$\deg(-X) = \begin{cases} 1 & n+1 \text{ even} \\ -1 & n+1 \text{ odd} \end{cases} \Rightarrow \begin{cases} 1 & n \text{ odd} \\ -1 & n \text{ even} \end{cases}$$

$$\deg(\text{Id}_X) = \deg(-X) \Rightarrow n \text{ is odd}$$

S^2 is even. \square

b) $S^3 \subseteq \mathbb{R}^4 \simeq \mathbb{C}^2$, $\mathbb{C}^2 = (z_1, z_2)$

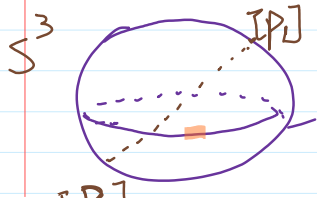
$x_1 = \text{Re } z_1, x_2 = \text{Im } z_1, x_3 = \text{Re } z_2, x_4 = \text{Im } z_2$
 $(x_1, x_2, x_3, x_4) \sim (z_1, z_2)$

$p \in S^3 \in \mathbb{R}^4$, $V(p) := i \cdot p = i(z_1, z_2)$

$V(p)$ is non-vanishing
 and $\langle V(p), p \rangle = 0$

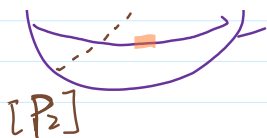
$V(p)$ is what we want. \square

c) $S^3 \xrightarrow{\pi} \mathbb{R}P^3$, $V(p)$ is defined above



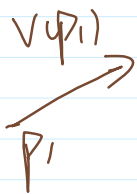
$$\pi_* V(p) \in T(\mathbb{R}P^3)$$

$\pi_*(V)(\cup D)$ is well-defined on S^3 .



$\pi_*(V)(p)$ is well-defined on S^3 .

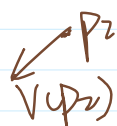
$$\pi(p_1) = \pi(p_2) = [p_1]$$



$$\pi_* v(p_1) \stackrel{?}{=} \pi_* v(p_2)$$

If yes,

$\pi_* v(p)$ is well-defined



$$F: M \rightarrow N, \quad v \in TM$$

$$F_* V(q) := dF_{F^{-1}(q)} V(F^{-1}(q)), \quad dF_p V(p)$$

$$q \in N$$

$$= (F_* \circ V) \circ F^{-1}$$

$$[x, y, \partial_x] \circ F^{-1}$$

$(dF)_p = \text{Jacobian of } F \text{ at } p.$

$$(dF)_{F^{-1}(q)}$$

Jacobian is of F 's

domain
 $(x, y) \in \mathbb{R}^2$
image
 $(u, t) \in \mathbb{R}^2$

$$q \in N \quad q = (x, y) \quad ((dF)_{F^{-1}(x, y)})(V(F^{-1}(x, y)))$$

$$F^{-1}(u, t) = (\sqrt{\frac{u}{t}}, \sqrt{ut}) \quad , \quad F(x, y) = (xy, \frac{y}{x})$$

$$F_* X(u, t) = dF_{F^{-1}(u, t)} F^{-1} = \begin{pmatrix} x = \sqrt{\frac{u}{t}} \\ y = \sqrt{ut} \end{pmatrix}$$

$$dF_p = J|_p = \begin{pmatrix} y & x \\ -\frac{y}{x^2} & \frac{1}{x} \end{pmatrix} = \begin{pmatrix} \sqrt{ut} & \sqrt{\frac{u}{t}} \\ -\frac{\sqrt{ut}}{\sqrt{u}t} & \sqrt{\frac{t}{u}} \end{pmatrix}, \quad \sqrt{\frac{u}{t}}, \quad \sqrt{\frac{t}{u}}$$

$$\begin{aligned}
 X(F|_{u,t}) &= \sqrt{u/t} \frac{\partial}{\partial x} + \sqrt{ut} \frac{\partial}{\partial y} = \begin{pmatrix} \sqrt{u/t} \\ \sqrt{ut} \end{pmatrix} \\
 &\begin{pmatrix} \sqrt{ut} & \sqrt{u/t} \\ -\frac{\sqrt{ut} \cdot t}{u} & \frac{t}{\sqrt{u}} \end{pmatrix} \cdot \begin{pmatrix} \sqrt{u/t} \\ \sqrt{ut} \end{pmatrix} = \begin{pmatrix} 2u \\ t-t \end{pmatrix} = \begin{pmatrix} 2u \\ 0 \end{pmatrix} \\
 &= 2u \frac{\partial}{\partial u} \\
 &= 2x \frac{\partial}{\partial x}
 \end{aligned}$$

change of basis