Hayden Goodfellow

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• HaydenGoodfellow

Languages: C, C++, Python, C#, Verilog, Assembly (ARMv7-A)

Web: JavaScript, JQuery, CSS, HTML, Bootstrap

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Technologies: PyTorch, NumPy, Git, PostgreSQL, OpenCV, Unity, Linux, LaTeX

Education

Bachelor of Applied Science in Computer Engineering - University of Toronto

· Minors in Machine Learning and Engineering Business

Graduation Expected 2022

Work Experience

Software Developer - Amnesia Escape Games

Summer 2019

- · Developed software to monitor and control a distributed system containing over 30 devices such as RFID readers, actuators, and sensors which were connected to 11 Arduino Nano controllers
- · Created, using C++, a multithreaded master controller for the entire system which communicated using an RS-485 half-duplex bus and socket connections
- · Used OpenCV in Python with remote cameras connected via sockets to create part of a puzzle
- · Utilized a PostgreSQL database to log and analyze sensor data for testing and balance purposes

District Referee - Ontario Soccer Association

2012 - 2018

Projects

Python • PyTorch Machine Learning & Computer Vision Team - UTRA - Autonomous Rover NumPy • OpenCV

- · Currently developing, with PyTorch and OpenCV, a ML model which can detect various road signs and markings and instantaneously relay this information to other systems on the rover
- · Created, with Python and OpenCV, a web scraper which gathers images and applies multiple perspective transforms to generate large, high-quality datasets

Geographic Information System

C++ • LibCurl • GTK

- \cdot Developed, using C++, a full-scale multithreaded mapping application tailored to users with vision impairments, such as colour blindness
- · Retrieved and displayed real-time weather and transportation information using LibCurl
- · Utilized optimal algorithms/data structures to ensure strong performance (such as A* and KD-trees)

Social Isolation Simulator

C

- · Created, using C, a simulator showing the effects of social isolation on a pandemic
- · Developed a custom VGA controller which utilizes page flipping for smooth animations

User-Level Multithreading Package

C

- · Full multithreading package for user-level threads which virtualize one or more kernel threads
- · Includes blocking/sleeping threads and preemptive or cooperative thread scheduling
- · Assured thread safety with self-implemented blocking and spin locks using atomic instructions

Autonomous Robot - Space Engineering & Exploration Kompetition (SEEK) Arduino • C

- · Developed an autonomous AI for a rover which was capable of navigating quickly and safely around obstacles and inclines. Rover could also be controlled manually using Bluetooth
- · Optimized our pathfinding algorithm to ultimately finish in 2nd out of over 40 teams