

# Blip-2: Bootstrapping language-image pre-training with frozen image encoders and large language models

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# Introduction

VL 모델의 pre training 비용이 end-to-end 훈련으로 인해 부담이 높다.

본 논문에서는, pretrained image Encoder와 frozen LLM을 통해 VL을 bootstrap하는 전략인 BLIP-2 제안

- Query Transformer를 통해 modality gap 해소
  - 1) frozen image encoder로부터 vision-language representation 학습을 bootstrap
  - 2) frozen language encoder로부터 vision-language generative 학습을 bootstrap

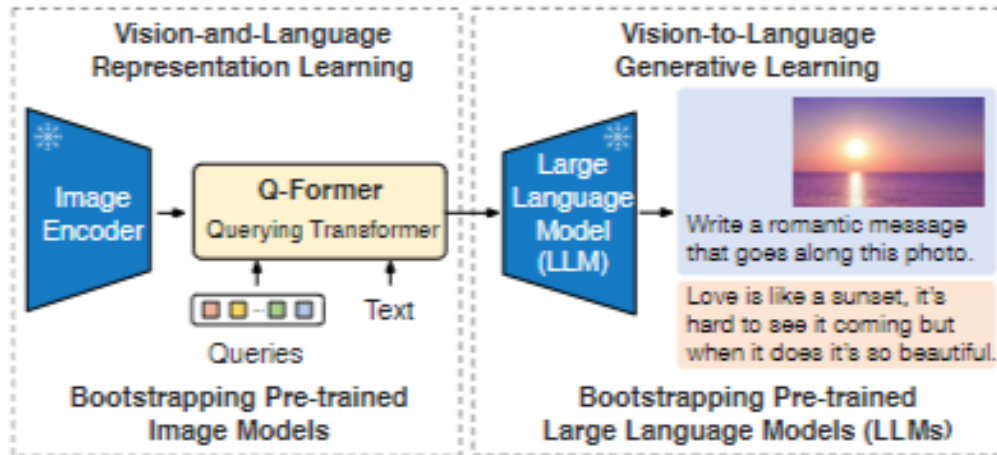
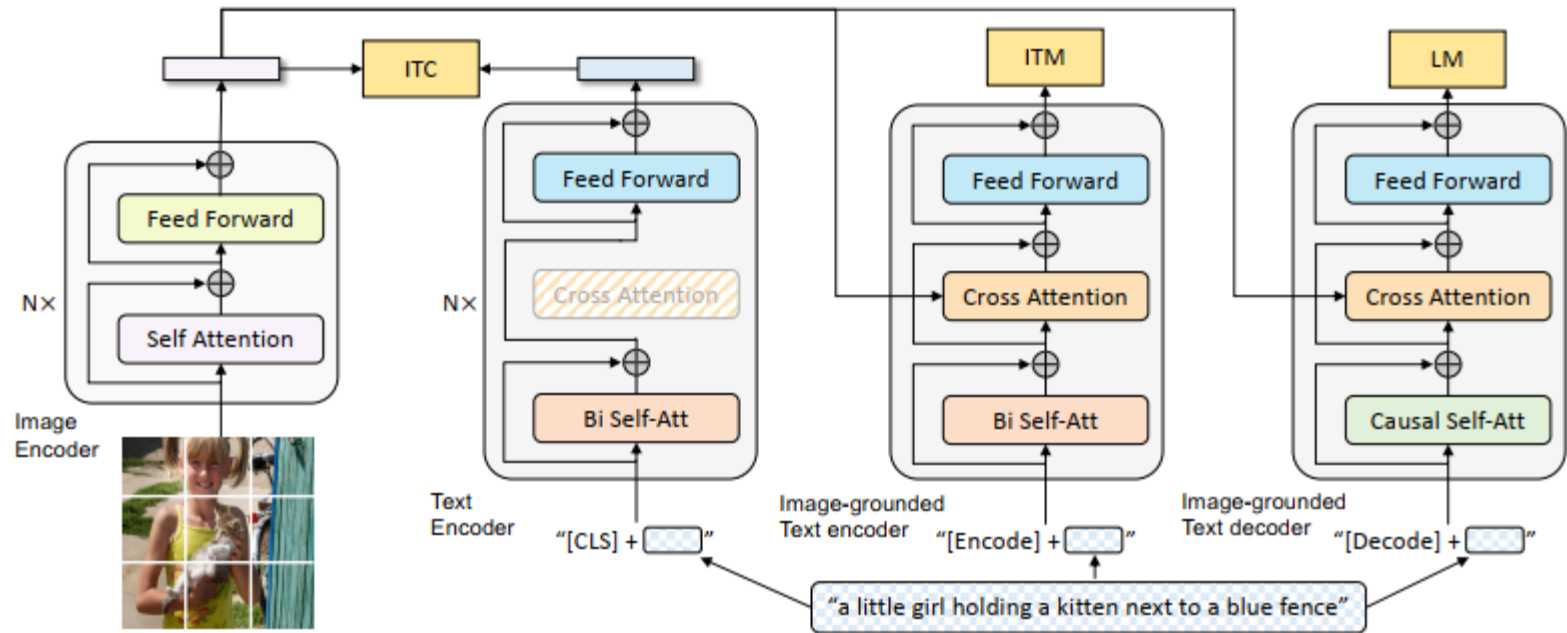


Figure 1. Overview of BLIP-2's framework. We pre-train a

성과

- 기존 method에 비해 train 매개변수가 적었음에도 불구하고 SOTA 달성
- Zero-shot 이미지 텍스트 생성능력 향상

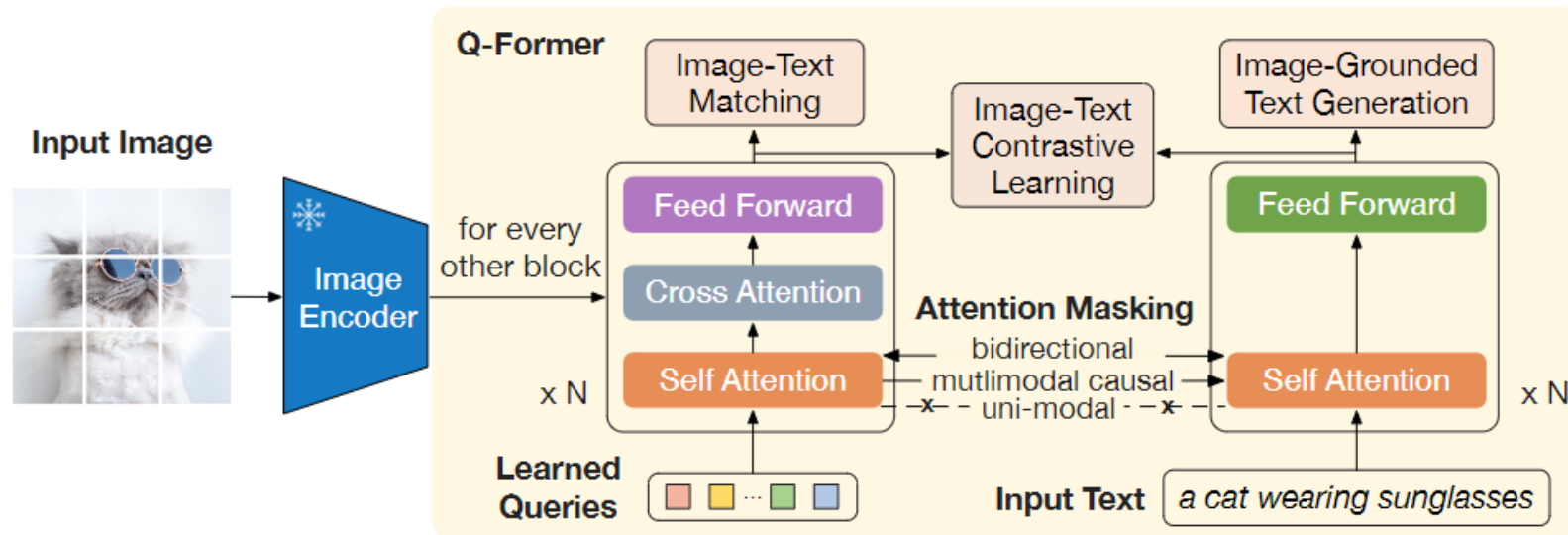
# Introduction



Blip architecture

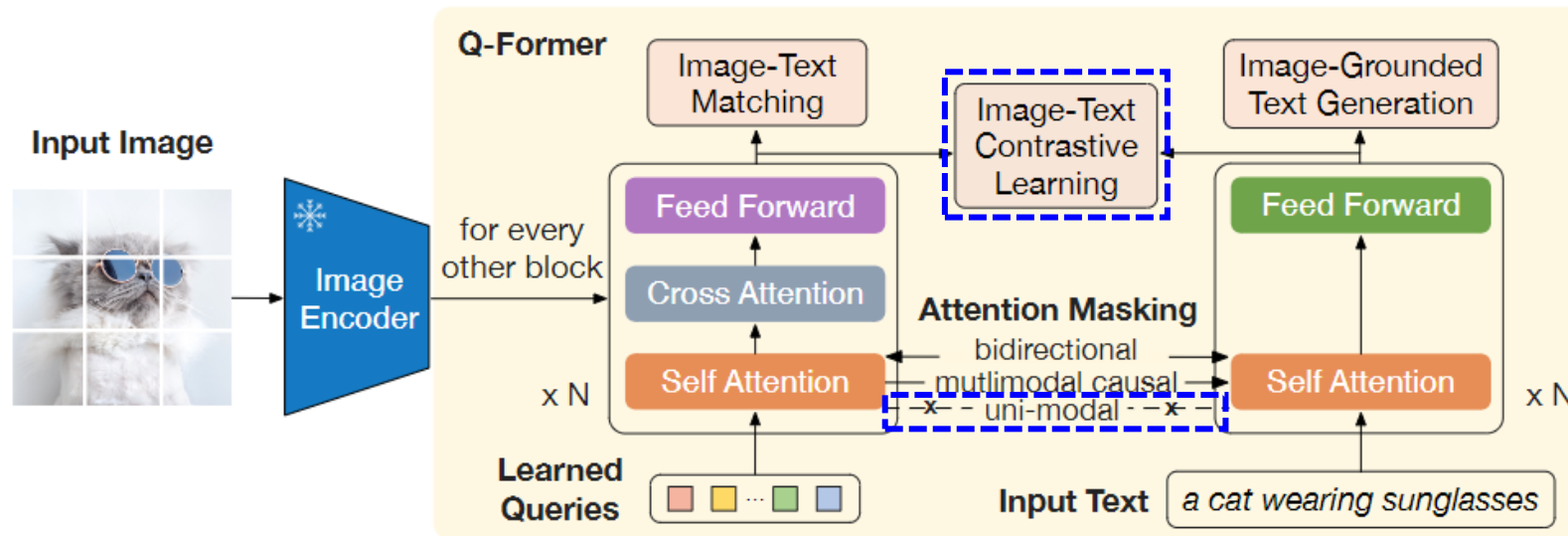
# Method

1. Frozen Image Encoder    2. Q-Former



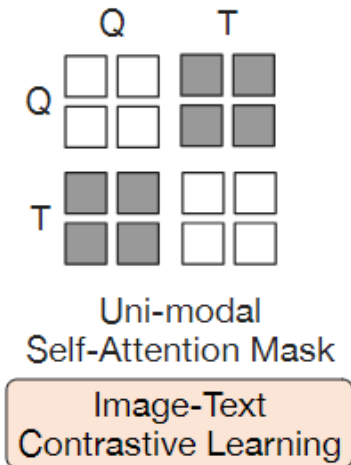
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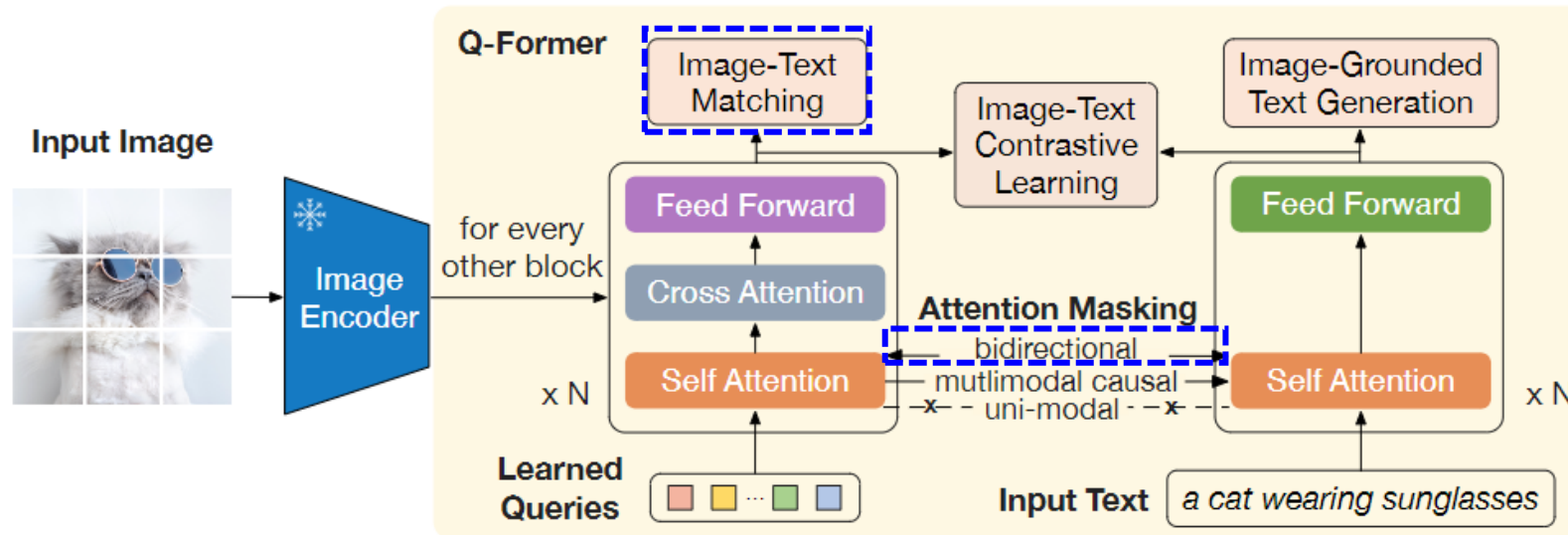
**Q**: query token positions; **T**: text token positions.

■ masked □ unmasked



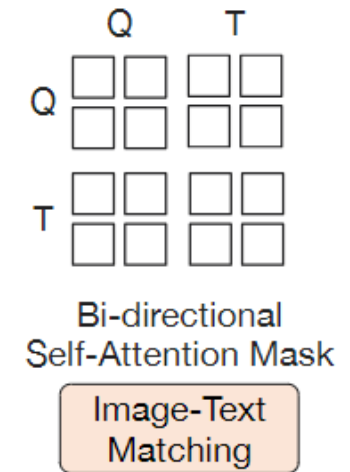
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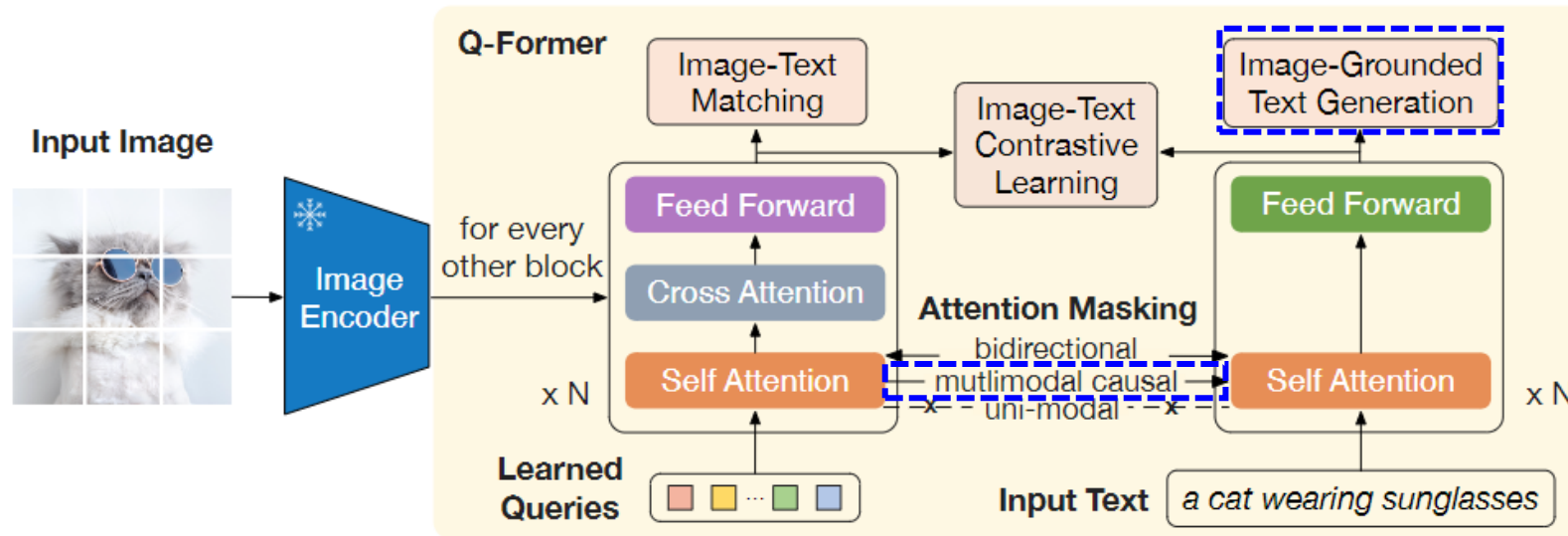
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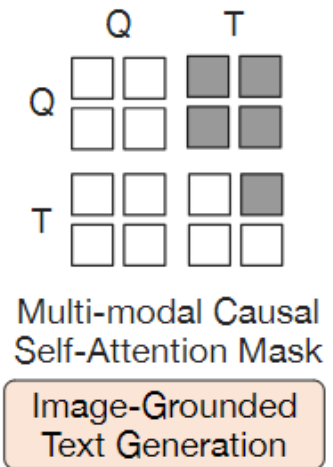
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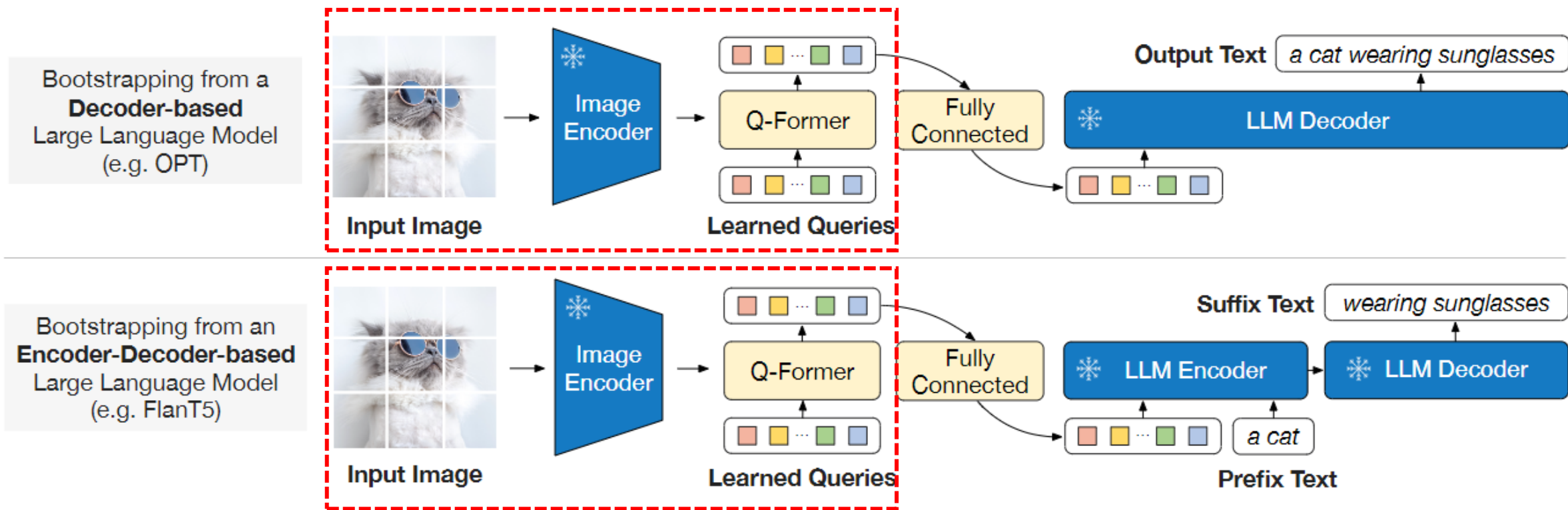
**Q**: query token positions; **T**: text token positions.

■ masked □ unmasked



# Method

## 3. Frozen LLM





# Experiments

Models	#Trainable Params	#Total Params	VQAv2		OK-VQA	GQA
			val	test-dev	test	test-dev
VL-T5 <sub>no-vqa</sub>	224M	269M	13.5	-	5.8	6.3
FewVLM (Jin et al., 2022)	740M	785M	47.7	-	16.5	29.3
Frozen (Tsimpoukelli et al., 2021)	40M	7.1B	29.6	-	5.9	-
VLKD (Dai et al., 2022)	406M	832M	42.6	44.5	13.3	-
Flamingo3B (Alayrac et al., 2022)	1.4B	3.2B	-	49.2	41.2	-
Flamingo9B (Alayrac et al., 2022)	1.8B	9.3B	-	51.8	44.7	-
Flamingo80B (Alayrac et al., 2022)	10.2B	80B	-	56.3	<b>50.6</b>	-
BLIP-2 ViT-L OPT <sub>2.7B</sub>	104M	3.1B	50.1	49.7	30.2	33.9
BLIP-2 ViT-g OPT <sub>2.7B</sub>	107M	3.8B	53.5	52.3	31.7	34.6
BLIP-2 ViT-g OPT <sub>6.7B</sub>	108M	7.8B	54.3	52.6	36.4	36.4
BLIP-2 ViT-L FlanT5 <sub>XL</sub>	103M	3.4B	62.6	62.3	39.4	<u>44.4</u>
BLIP-2 ViT-g FlanT5 <sub>XL</sub>	107M	4.1B	<u>63.1</u>	<u>63.0</u>	40.7	44.2
BLIP-2 ViT-g FlanT5 <sub>XXL</sub>	108M	12.1B	<b>65.2</b>	<b>65.0</b>	<u>45.9</u>	<b>44.7</b>

Table 2. Comparison with state-of-the-art methods on zero-shot visual question answering.

Models	#Trainable Params	NoCaps Zero-shot (validation set)								COCO Fine-tuned Karpathy test	
		in-domain		near-domain		out-domain		overall		B@4	C
		C	S	C	S	C	S	C	S		
OSCAR (Li et al., 2020)	345M	-	-	-	-	-	-	80.9	11.3	37.4	127.8
VinVL (Zhang et al., 2021)	345M	103.1	14.2	96.1	13.8	88.3	12.1	95.5	13.5	38.2	129.3
BLIP (Li et al., 2022)	446M	114.9	15.2	112.1	14.9	115.3	14.4	113.2	14.8	40.4	136.7
OFA (Wang et al., 2022a)	930M	-	-	-	-	-	-	-	-	<b>43.9</b>	<u>145.3</u>
Flamingo (Alayrac et al., 2022)	10.6B	-	-	-	-	-	-	-	-	-	138.1
SimVLM (Wang et al., 2021b)	~1.4B	113.7	-	110.9	-	115.2	-	112.2	-	40.6	143.3
BLIP-2 ViT-g OPT <sub>2.7B</sub>	1.1B	<u>123.0</u>	<u>15.8</u>	117.8	<u>15.4</u>	123.4	<b>15.1</b>	119.7	<u>15.4</u>	<u>43.7</u>	<b>145.8</b>
BLIP-2 ViT-g OPT <sub>6.7B</sub>	1.1B	<b>123.7</b>	<u>15.8</u>	<u>119.2</u>	15.3	<u>124.4</u>	14.8	<u>121.0</u>	15.3	43.5	145.2
BLIP-2 ViT-g FlanT5 <sub>XL</sub>	1.1B	<b>123.7</b>	<b>16.3</b>	<b>120.2</b>	<b>15.9</b>	<b>124.8</b>	<b>15.1</b>	<b>121.6</b>	<b>15.8</b>	42.4	144.5

Models	#Trainable Params	VQAv2	
		test-dev	test-std
<i>Open-ended generation models</i>			
ALBEF (Li et al., 2021)	314M	75.84	76.04
BLIP (Li et al., 2022)	385M	78.25	78.32
OFA (Wang et al., 2022a)	930M	82.00	82.00
Flamingo80B (Alayrac et al., 2022)	10.6B	82.00	82.10
<b>BLIP-2 ViT-g FlanT5<sub>XL</sub></b>	1.2B	81.55	81.66
<b>BLIP-2 ViT-g OPT<sub>2.7B</sub></b>	1.2B	81.59	81.74
<b>BLIP-2 ViT-g OPT<sub>6.7B</sub></b>	1.2B	<b>82.19</b>	<b>82.30</b>
<i>Closed-ended classification models</i>			
VinVL	345M	76.52	76.60
SimVLM (Wang et al., 2021b)	~1.4B	80.03	80.34
CoCa (Yu et al., 2022)	2.1B	82.30	82.30
BEiT-3 (Wang et al., 2022b)	1.9B	<b>84.19</b>	<b>84.03</b>

Table 4. Comparison with state-of-the-art models fine-tuned for visual question answering.

Comparison with state-of-the-art image captioning methods on NoCaps and COCO Caption

# Experiments



Explain the advantages of this product.

The audi e-tron quattro concept is a plug-in hybrid electric sports car that has a range of 310 miles and can accelerate from 0 to 60 mph in just 4 seconds.



Tell me something about the history of this place.

The great wall of china was built in 221 bc by emperor qin shi Huang to protect the emperor's capital from invaders from the north.



Is this photo unusual?

Yes, it's a house that looks like it's upside down.

How could someone get out of the house?

It has a slide on the side of the house.

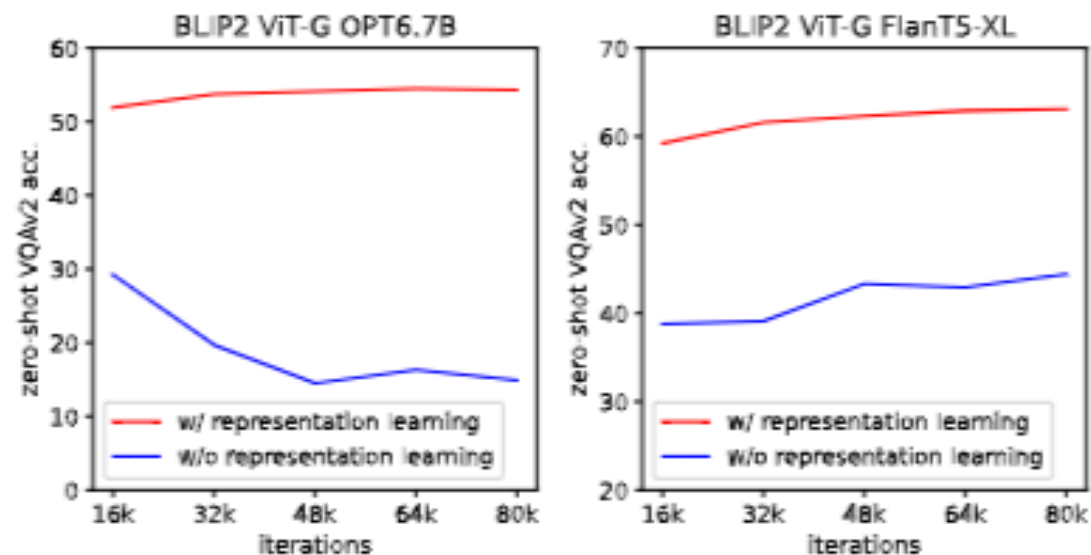


What are shown in the photo?

A man and a chicken.

What does the man feel and why?

He is scared of the chicken because it is flying at him.



Effect of vision-language representation learning on vision-to-language generative learning.

instructed zero-shot image-to-text generation using a BLIP-2 model

# Conclusions

LLM이 단일 Image-Text 대응관계를 학습했기 때문에 텍스트 표현 다양성이 부족. 추후 다중 데이터셋을 개발할 예정이라고 함  
또한, LLM 모델의 성능에 크게 의존할 수 있다는 한계점

Frozen model간의 modality gap을 메우기 위한 새로운 방법을 제안하고, 다양한 VL task에서 성능을 개선  
또한 Pre-Training 과정에서의 Trainable Parameter 개수를 줄여 학습 효율성을 높임