

Interpretable Machine Learning

Introduction and Background



Learning goals

- Interpretable Models

HIGH-DIMENSIONAL MODEL REPRESENTATION

- A high-dimensional model representation (HDMR) decomposes the model into a sum of effect terms of increasing order:

$$\hat{f}(x) = g_{\{0\}} + g_{\{1\}}(x_1) + g_{\{2\}}(x_2) + \dots + g_{\{1,2\}}(x_1, x_2) \\ + \dots + g_{\{1,\dots,p\}}(x_1, \dots, x_p)$$

- The features need to be independent to make the HDMR unique.
- Different techniques to estimate an additive decomposition exist, e.g., repeated expectations (partial dependence / PD) or accumulated local effects (ALE).

ADDITIVE DECOMPOSITION OF A PREDICTION FUNCTION

Consider the estimation via iterative expectations:

$$g_{\{0\}} = \mathbb{E}_X [\hat{f}(x)]$$

$$g_{\{1\}}(x_1) = \mathbb{E}_{X_{-1}} [\hat{f}(x) \mid X_1] - g_{\{0\}}$$

$$g_{\{2\}}(x_2) = \mathbb{E}_{X_{-2}} [\hat{f}(x) \mid X_2] - g_{\{0\}}$$

$$g_{\{1,2\}}(x_1, x_2) = \mathbb{E}_{X_{-\{1,2\}}} [\hat{f}(x) \mid X_1, X_2] - g_{\{2\}}(x_2) - g_{\{1\}}(x_1) - g_{\{0\}}$$

\vdots

$$\begin{aligned} g_{\{1,\dots,p\}}(x) &= \hat{f}(x) - \dots - g_{\{1,2\}}(x_1, x_2) \\ &\quad - g_{\{2\}}(x_2) - g_{\{1\}}(x_1) - g_{\{0\}} \end{aligned}$$

FUNCTIONAL ANOVA

After \hat{f} has been decomposed, we can conduct a functional analysis of variance (functional ANOVA / FANOVA):



$$\begin{aligned} \text{Var} [\hat{f}(x)] = & \text{Var} [g_{\{0\}} + g_{\{1\}}(x_1) + g_{\{2\}}(x_2) + \dots + g_{\{1,2\}}(x_1, x_2) \\ & + \dots + g_{\{1,\dots,p\}}(x)] \end{aligned}$$

- If the features are independent, the variance can be additively decomposed without covariances:

$$\begin{aligned} \text{Var} [\hat{f}(x)] = & \text{Var} [g_{\{0\}}] + \text{Var} [g_{\{1\}}(x_1)] + \text{Var} [g_{\{2\}}(x_2)] \\ & + \text{Var} [g_{\{1,2\}}(x_1, x_2)] + \dots + \text{Var} [g_{\{1,\dots,p\}}(x)] \end{aligned}$$

FUNCTIONAL ANOVA

- Dividing by the prediction variance results in the fraction of variance explained by each term:

$$1 = \frac{\text{Var} [g_{\{0\}}]}{\text{Var} [\hat{f}(x)]} + \frac{\text{Var} [g_{\{1\}}(x_1)]}{\text{Var} [\hat{f}(x)]} + \frac{\text{Var} [g_{\{2\}}(x_2)]}{\text{Var} [\hat{f}(x)]} \\ + \frac{\text{Var} [g_{\{1,2\}}(x_1, x_2)]}{\text{Var} [\hat{f}(x)]} + \dots + \frac{\text{Var} [g_{\{1,\dots,p\}}(x)]}{\text{Var} [\hat{f}(x)]}$$

- The fraction of variance explained by a term is referred to as the Sobol index:

$$S_j = \frac{\text{Var} [g_{\{j\}}(x_j)]}{\text{Var} [\hat{f}(x)]}$$