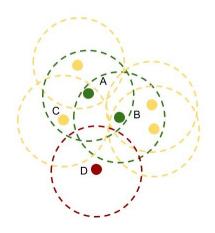
Interpretable Machine Learning

Increasing Trust in Explanations



Learning goals

- Understand the aspects that undermine users' trust in an explanation
- Learn diagnostic tools that could increase trust

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- Failing in one of these \leadsto undermining users' trust in the explanations

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 - The data for LIME's surrogate model
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 - Shapley value's permuted observations to calculate the marginal contributions
 - ICE curves grid data points
- Two very simple and intuitive approaches
 - Classifier for out-of-distribution
 - Clustering
- More complicated also possible, e.g., variational autoencoders [Daxberger et al. 2020]

OUT-OF-DISTRIBUTION DETECTION: OOD-CLASSIFIER

- Problem: we have only in-distribution data
- Idea: Hallucinate new (out-of-distribution) data by randomly sample data points
- Learn a binary classifier to distinguish between the origins of the data

OUT-OF-DISTRIBUTION DETECTION: OOD-CLASSIFIER

- Problem: we have only in-distribution data
- Idea: Hallucinate new (out-of-distribution) data by randomly sample data points
- → Learn a binary classifier to distinguish between the origins of the data
 - Study whether an explanation approach can be fooled Dylan Slack et al. 2020
 - Hide bias in the true (deployed) model, but use an unbiased model for all out-of-distribution samples
- → Important way to diagnose an explanation approach

- For this method, we define an ϵ -neighborhood: Given a dataset $X = \{\mathbf{x}^{(i)}\}_{i=1}^n$, an ϵ -neighborhood for $\mathbf{x} \in \mathcal{X}$ is defined as

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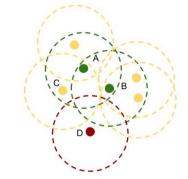
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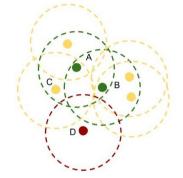
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- Border points
 - ullet Within $\mathcal{N}_{\epsilon}(\mathbf{x})$
 - Part of a cluster defined by a core point
- Noise points
 - ullet Are not within $\mathcal{N}_{\epsilon}(\mathbf{x})$
 - Not part of any cluster



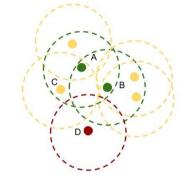
Example for DBSCAN, circles display ϵ -neighborhoods, m=4

 Green points A and B are core points and form one cluster since they lie in each others neighborhood, all yellow points are border points of this cluster



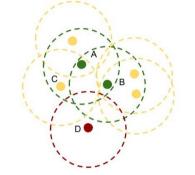
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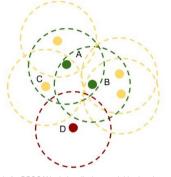
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- Disadvantages:
 - ullet Depending on the distance metric $d(\cdot)$, DBSCAN could suffer from the "curse of dimensionality"
 - The choice of ϵ and m is not clear a-priori

ROBUSTNESS

- Differentiate between different kinds of uncertainty:
 - Explanation uncertainty: Change of explanation if we repeat the process, e.g., the explanation could differ depending on which subset of data we use for the explanation method and which hyperparameters

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 - Explanation uncertainty: Change of explanation if we repeat the process, e.g., the explanation could differ depending on which subset of data we use for the explanation method and which hyperparameters
 - ② Process uncertainty: Change of explanation if the underlying model is changed

 → are ML models non-robust, e.g., because they are trained on noisy data?
- We focus on explanation uncertainty
 - Even with the same model and same (or similar) data points, we can receive different explanations

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 Alvarez-Melis and Jaakkola 2018

An explanation method $g:\mathcal{X} o \mathbb{R}^m$ is locally Lipschitz if

- ullet for every $\mathbf{x}_0 \in \mathcal{X}$ there exist $\delta > 0$ and $\omega \in \mathbb{R}$
- ullet such that $||\mathbf{x}-\mathbf{x}_0||<\delta$ implies $||g(\mathbf{x})-g(\mathbf{x}_0)||<\omega||\mathbf{x}-\mathbf{x}_0||$

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- ullet According to this, we can quantify the robustness of explanation models in terms of ω :
 - \rightarrow The closer ω is to 0, the more robust our explanation method is
- ullet ω is rarely known a-priori but it could be estimated as follows:

$$\hat{\omega}_X(\mathbf{x}) \in rg \max_{\mathbf{x}^{(i)} \in \mathcal{N}_{\epsilon}(\mathbf{x})} rac{||g(\mathbf{x}) - g(\mathbf{x}^{(i)})||_2}{d(\mathbf{x}, \mathbf{x}^{(i)})},$$

where $\mathcal{N}_{\epsilon}(\mathbf{x})$ is the ϵ -neighborhood of \mathbf{x}