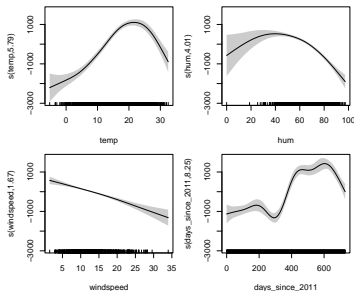


# Interpretable Machine Learning

## GAM & Boosting



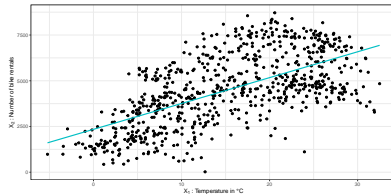
### Learning goals

- Generalized additive model
- Model-based boosting with simple base learners
- Feature effect and importance in model-based boosting

# GENERALIZED ADDITIVE MODEL (GAM)

► Hastie and Tibshirani (1986)

**Problem:** LM not suitable if relationship between features and target variable is not linear



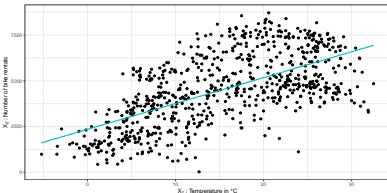
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**Workaround in LMs / GLMs:**

- Feature transformations (e.g., exp or log)
- Including high-order effects
- Categorization of features (i.e., intervals / buckets of feature values)



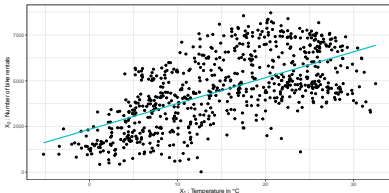
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## Idea of GAMs:

- Instead of linear terms  $\theta_j x_j$ , use flexible functions  $f_j(x_j) \rightsquigarrow$  splines

$$g(\mathbb{E}(y \mid \mathbf{x})) = \theta_0 + f_1(x_1) + f_2(x_2) + \dots + f_p(x_p)$$

- Preserves additive structure and allows to model non-linear effects
- Splines have a smoothness parameter to control flexibility (prevent overfitting)  
 $\rightsquigarrow$  Needs to be chosen, e.g., via cross-validation

# GENERALIZED ADDITIVE MODEL (GAM) - EXAMPLE

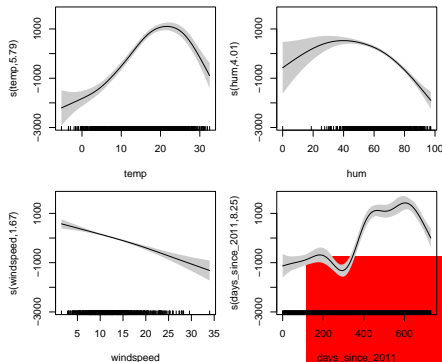
Fit a GAM with smooth splines for four numeric features of bike rental data

→ more flexible and better model fit but less interpretable than LM

	edf	p-value
s(temp)	5.8	0.00
s(hum)	4.0	0.00
s(windspeed)	1.7	0.00
s(days_since_2011)	8.3	0.00

## Interpretation

- Interpretation needs to be done visually and relative to average prediction
- Edf (effective degrees of freedom) represents complexity of smoothness



# MODEL-BASED BOOSTING

► Bühlmann and Yu 2003

- Recall: Boosting iteratively combines weak base learners (BL)
- Idea: Use simple linear BL to ensure interpretability (in general also spline BL possible)



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- In each iteration, fit a set of BLs and add the best BL to previous model (using step-size  $\nu$ ):

$$\hat{f}^{[1]} = \hat{f}_0 + \nu b^{[3]}(\mathbf{x}_3, \theta^{[1]})$$





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$$= \hat{f}_0 + \nu \left( b^{[3]}(x_3, \theta^{[1]} + \theta^{[2]}) + b^{[1]}(x_1, \theta^{[3]}) \right)$$

$$= \hat{f}_0 + \hat{f}_3(x_3) + \hat{f}_1(x_1)$$



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- Final model is additive (as GAMs), where each component function is interpretable



# MODEL-BASED BOOSTING - LINEAR EXAMPLE

Simple case: Use linear model with single feature (including intercept) as BL

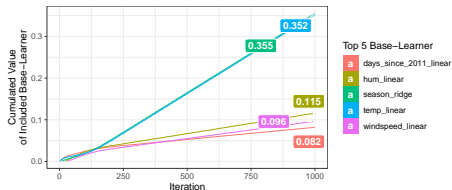
$$b^{[j]}(x_j, \theta) = x_j \theta + \theta_0 \quad \text{for } j = 1, \dots, p \rightsquigarrow \text{ordinary linear regression}$$

- Here: Interpretation of weights as in LM
- After many iterations, it converges to same solution as least square estimate of LMs

1000 iter. with $\nu = 0.1$	Intercept	Weights
days_since_2011	-1791.06	4.9
hum	1953.05	-31.1
season	0	WINTER: -323.4 SPRING: 539.5 SUMMER: -280.2 FALL: 67.2
temp	-1839.85	120.4
windspeed	725.70	-56.9
offset	4504.35	

⇒ Converges to solution of LM

Relative frequency of selected BLs across iterations



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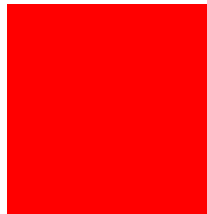
- Here: Interpretation of weights as in LM
- After many iterations, it converges to same solution as least square estimate of LMs
- Early stopping allows feature selection and might prevent overfitting (regularization)

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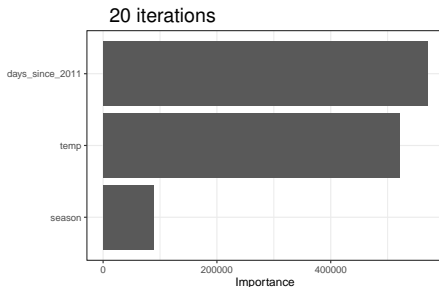
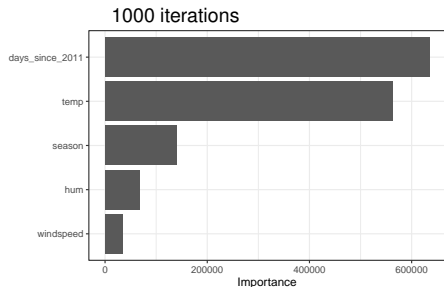
20 iter. with $\nu = 0.1$	Intercept	Weights
days_since_2011	-1210.27	3.3
season	0	WINTER: -276.9 SPRING: 137.6 SUMMER: 112.8 FALL: 20.3
temp	-1118.94	73.2
offset	4504.35	

⇒ 3 BLs selected after 20 iter. (feature selection)



# MODEL-BASED BOOSTING - LINEAR EXAMPLE: INTERPRETATION

## Feature importance (risk reduction over iterations)



⇒ days\_since\_2011 most important, followed by temp

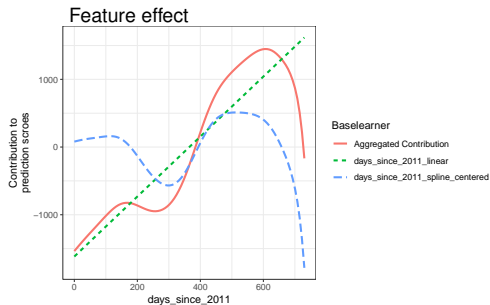
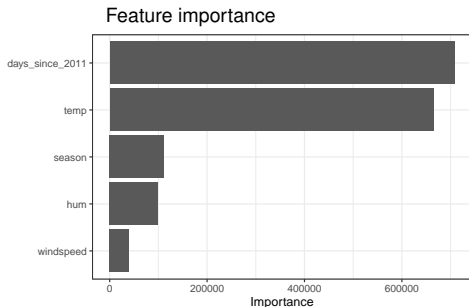
# MODEL-BASED BOOSTING - INTERPRETATION

- Fit model on bike data with different BL types ▶ Daniel Schalk et al. 2018
- BLs: linear and centered splines for numeric features, categorical for season



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- Total effect for days\_since\_2011  
    ↪ Combination of partial effects of linear BL and centered spline BL