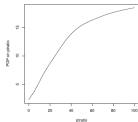
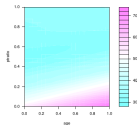
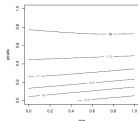
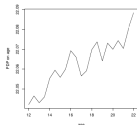


Interpretable Machine Learning

Introduction to Functional Decomposition



Learning goals

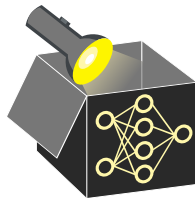
- Basic idea of additive functional decompositions
- Motivation and usefulness of functional decompositions
- Difficulty of obtaining or even defining a functional decomposition
- Several examples

PRELIMINARIES

Recap: Interactions

- Interactions between features: Effect of one feature on the prediction output depends on (one or more) other features
- Definition: f has interacting features x_j, x_k , if

$$\mathbb{E} \left[\left(\frac{\partial^2 f(\mathbf{x})}{\partial x_j \partial x_k} \right)^2 \right] > 0$$



PRELIMINARIES

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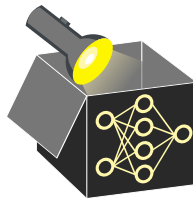
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Recap: GAMs

- Decomposition into only main effects
- Do not contain any interactions

$$\hat{f}(\mathbf{x}) = \theta_0 + g_1(x_1) + g_2(x_2) + \dots + g_p(x_p)$$



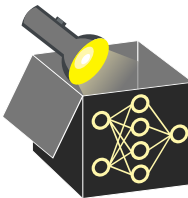
FIRST EXAMPLE: ADDITIVE DECOMPOSITION

Example

Consider

$$\hat{f}(x_1, x_2) = 4 - 2x_1 + 0.3e^{x_2} + |x_1|x_2$$

- Idea: Additive decomposition depending on which features used:



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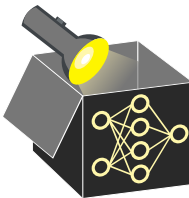
- Idea: Additive decomposition depending on which features used:

$g_0(x_1, x_2) = 4$ Part depending on no features at all (intercept)

$\left. \begin{array}{l} g_1(x_1, x_2) = 2x_1 \\ g_2(x_1, x_2) = 0.3e^{x_2} \end{array} \right\}$ Parts depending on a single feature (main effects) (1)

$g_{1,2}(x_1, x_2) = |x_1|x_2$ Part depending on both features (interaction)

→ single terms with immediate interpretation, full understanding of the model



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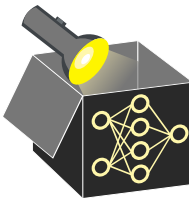
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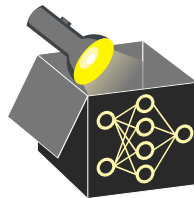
↔ Not possible with effects of single features (e.g. PDPs) or GAM surrogate model (miss interaction part)



ANOTHER EXAMPLE: ADDITIVE DECOMPOSITION

Goal in general: Given a black-box model $\hat{f} : \mathbb{R}^2 \rightarrow \mathbb{R}$, find a decomposition

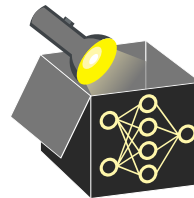
$$\hat{f}(x_1, x_2) = g_{\emptyset} + g_1(x_1) + g_2(x_2) + g_{1,2}(x_1, x_2) \quad (2)$$



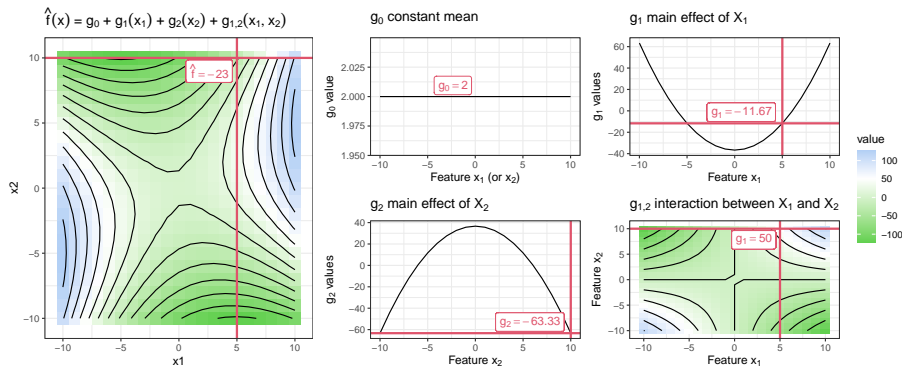
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Example



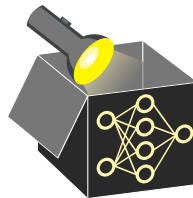
→ More details on this example later

ANOTHER EXAMPLE: ADDITIVE DECOMPOSITION

Example

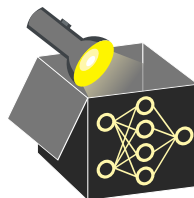
$$\hat{f}(x_1, x_2, x_3) = -2x_1 - 2\sin(x_3) + |x_1|x_2 + 0.5x_1x_2x_3 - \sin(x_2x_3) + 1$$

Again, read additive decomposition from formula:



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$$\hat{f}(x_1, x_2, x_3) = -2x_1 - 2\sin(x_3) + |x_1|x_2 + 0.5x_1x_2x_3 - \sin(x_2x_3) + 1$$

Again, read additive decomposition from formula:

$$\begin{aligned} g_{\emptyset}(x_1, x_2, x_3) &= 1 && \text{constant part, no effects} \\ \left. \begin{aligned} g_1(x_1, x_2, x_3) &= -2x_1 \\ g_2(x_1, x_2, x_3) &= 0 \\ g_3(x_1, x_2, x_3) &= -2\sin(x_3) \end{aligned} \right\} && \text{main effects, no interactions} \\ \left. \begin{aligned} g_{1,2}(x_1, x_2, x_3) &= |x_1|x_2 \\ g_{1,3}(x_1, x_2, x_3) &= 0 \\ g_{2,3}(x_1, x_2, x_3) &= -\sin(x_2x_3) \end{aligned} \right\} && \text{2-way interactions (depending on 2 features)} \\ g_{1,2,3}(x_1, x_2, x_3) &= 0.5x_1x_2x_3 && \text{3-way interactions} \end{aligned} \tag{3}$$

\Rightarrow 8 components in total, but some empty \rightsquigarrow Certain interactions not present

GENERAL FORM OF FUNCTIONAL DECOMPOSITION

► Li and Rabitz (2011)

► Chastaing et al. (2012)

Definition

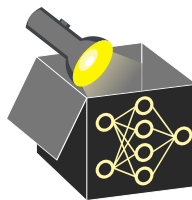
Functional decomposition: Additive decomposition of a function $\hat{f} : \mathbb{R}^p \mapsto \mathbb{R}$ into a sum of components of different dimensions w.r.t. inputs x_1, \dots, x_p :

$$\begin{aligned}\hat{f}(\mathbf{x}) &= \sum_{S \subseteq \{1, \dots, p\}} g_S(\mathbf{x}_S) \\ &= g_{\emptyset} + g_1(x_1) + g_2(x_2) + \dots + g_p(x_p) + \\ &\quad g_{1,2}(x_1, x_2) + \dots + g_{p-1,p}(x_{p-1}, x_p) + \dots + \\ &\quad g_{1,2,3}(x_1, x_2, x_3) + \dots + g_{1,2,3,4}(x_1, x_2, x_3, x_4) + \dots + g_{1,\dots,p}(x_1, \dots, x_p)\end{aligned}$$

\rightsquigarrow one component for every possible combination S of indices

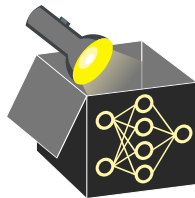
Sort terms according to degree of interaction:

- $g_{\emptyset} \hat{=}$ Constant mean (intercept)
- $g_j \hat{=}$ first-order or main effect of j -th feature alone on $\hat{f}(\mathbf{x})$
- $g_{j,k} \hat{=}$ second-order interaction effect of features j and k w.r.t. $\hat{f}(\mathbf{x})$
- $g_S(\mathbf{x}_S) \hat{=}$ $|S|$ -order effect, depends **only** on features in S



PROPERTIES OF THE DEFINITION

- **Interpretability:** Extremely powerful decomposition, reveals complete interaction structure

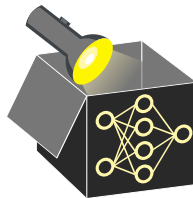


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- **Interpretability:** Extremely powerful decomposition, reveals complete interaction structure
- Compare to GAM: Same decomposition, but without interactions
⇒ Any GAM already comes with its decomposition

$$\hat{f}(\mathbf{x}) = g_{\emptyset} + g_1(x_1) + g_2(x_2) + \dots + g_p(x_p)$$

- Same for LMs: Decomposition explicitly modeled

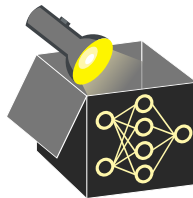


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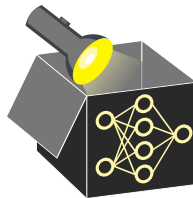


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- **Problem 1:** Calculating decomposition extremely difficult, often infeasible
 - For p features: Decomposition with 2^p terms → too many different terms, difficult to interpret

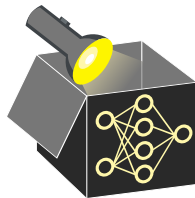


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- **Problem 1:** Calculating decomposition extremely difficult, often infeasible
 - For p features: Decomposition with 2^p terms → too many different terms, difficult to interpret
- **Problem 2:** Definition not complete: Decomposition not unique, many trivial decompositions not useful
 - More requirements or constraints needed to ensure decomposition is meaningful
 - Even worse once features are dependent or correlated (see later)

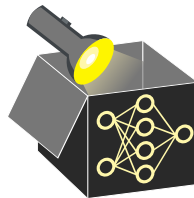


PROBLEM 2: DEFINITION NOT ENOUGH

Example

Again consider

$$\hat{f}(x_1, x_2, x_3) = -2x_1 - 2\sin(x_3) + |x_1|x_2 + 0.5x_1x_2x_3 - \sin(x_2x_3) + 1$$



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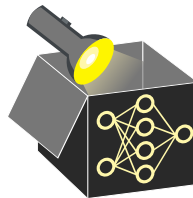
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Two possible decompositions (valid according to definition):

$$g_{1,\dots,p}(x_1, \dots, x_p) := \hat{f}(\mathbf{x}) \text{ and for all other terms } g_S(\mathbf{x}_S) := 0,$$

or:

$$\begin{aligned} g_{\emptyset} &= 1; \quad g_1(x_1) = x_1; \quad g_2(x_2) = 2x_2; \quad g_3(x_3) = 3x_3; \\ g_{1,2}(x_1, x_2) &= \frac{1}{2}x_1x_2; \quad g_{1,3}(x_1, x_3) = \frac{1}{3}x_1x_3; \quad g_{2,3}(x_2, x_3) = \frac{2}{3}x_2x_3; \\ \text{and } g_{1,2,3}(x_1, x_2, x_3) &= \hat{f}(x_1, x_2, x_3) - \sum_{S \subsetneq \{1,2,3\}} g_S(\mathbf{x}_S) \end{aligned}$$



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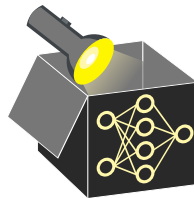
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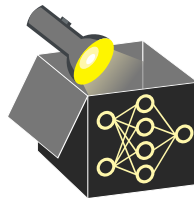
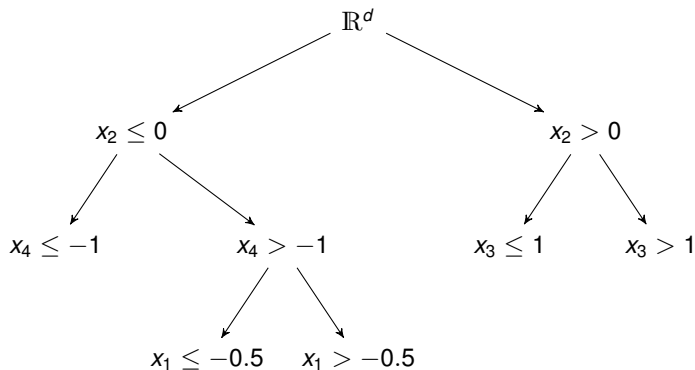
\Rightarrow Definition of decomposition not unique



EXAMPLE: DECISION TREES

Define *interaction type t* of a node: subset of features involved in constructing this node.

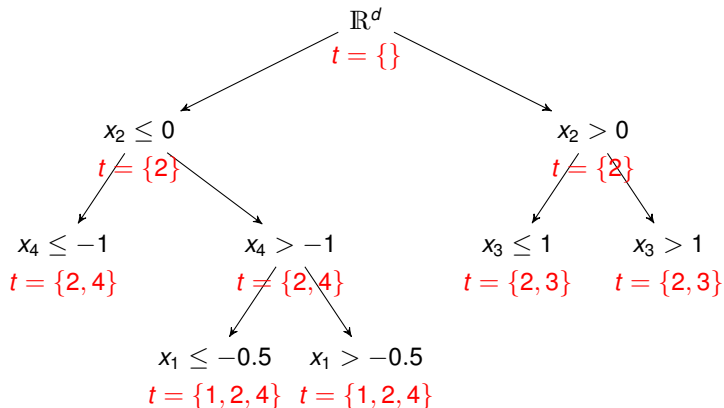
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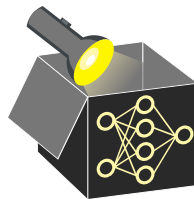
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Example:



⇒ Degree of interaction in each node is $|t|$.



DECOMPOSITION FOR DECISION TREES

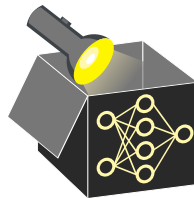
Here: Decomposition via indicator functions

$$\hat{f}(\mathbf{x}) = g_{\emptyset} + g_{2,4}(x_2, x_4) + g_{2,3}(x_2, x_3) + g_{1,2,4}(x_1, x_2, x_4)$$

⇒ Decomposition no main effect, but model certainly contains an effect of e.g. x_2

⇒ Lower-order effects “hidden” inside higher-order terms

↪ reading from decision tree not enough, “bad decomposition”



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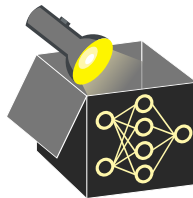
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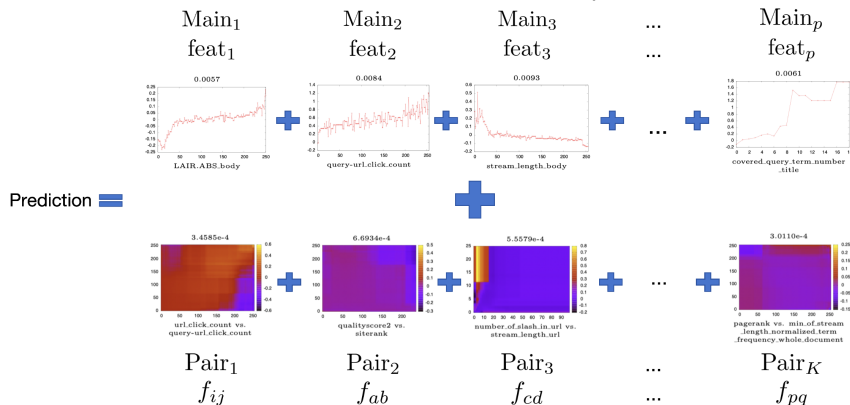
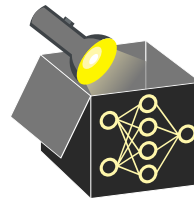
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Note: ▶ Yang (2024) propose a (quite complicated) solution for this case



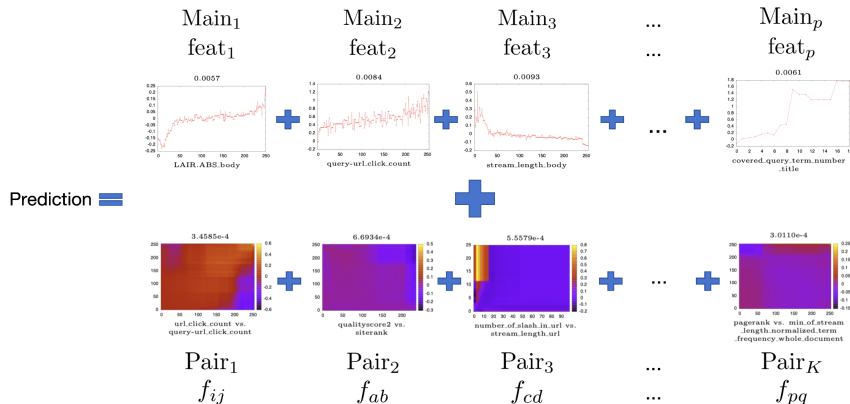
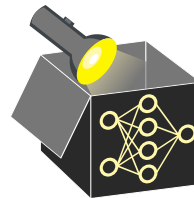
EXAMPLE: EBM

- See before: **GAMs** have functional decomposition by definition
- **EBMs**: Sum of the final one- and two-dimensional components



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- **EBMs**: Sum of the final one- and two-dimensional components



- In general: Model with functional decomposition up to max. order 2 is always “inherently interpretable”
- **Reason:** Visualization of all components