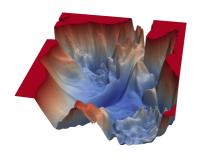
Introduction to Machine Learning

Properties of Loss Functions



Learning goals

- Statistical properties
- Robustness
- Numerical properties
- Some fundamental terminology



THE ROLE OF LOSS FUNCTIONS

Why should we care about the choice of the loss function $L(y, f(\mathbf{x}))$?

- **Statistical** properties: choice of loss implies statistical assumptions about the distribution of $y \mid \mathbf{x} = \mathbf{x}$ (see *maximum likelihood estimation vs. empirical risk minimization*).
- Robustness properties: some loss functions are more robust towards outliers than others.
- Numerical properties: the computational complexity of

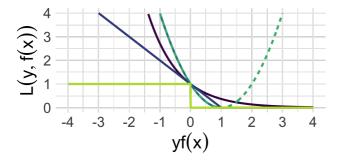
$$\operatorname*{\mathsf{arg\;min}}_{oldsymbol{ heta}\in\Theta}\mathcal{R}_{\mathsf{emp}}(oldsymbol{ heta})$$

is influenced by the choice of the loss function.



SOME BASIC TERMINOLOGY

Classification losses are usually expressed in terms of the **margin**: $\nu := y \cdot f(\mathbf{x})$.



- Exponential
- Squared (scores)

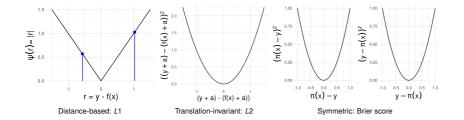
— Hinge

- - 0-1
- Squared hinge



SOME BASIC TERMINOLOGY

- Regression losses often only depend on the **residuals** $r := y f(\mathbf{x})$.
- Losses are called **symmetric** if $L(y, f(\mathbf{x})) = L(f(\mathbf{x}), y)$.
- A loss is translation-invariant if $L(y + a, f(\mathbf{x}) + a) = L(y, f(\mathbf{x})), a \in \mathbb{R}$.
- A loss is called distance-based if
 - it can be written in terms of the residual, i.e., $L(y, f(\mathbf{x})) = \psi(r)$ for some $\psi : \mathbb{R} \to \mathbb{R}$, and
 - $\psi(r) = 0 \Leftrightarrow r = 0$.





ROBUSTNESS

2.0

1.5

1.0

0.5 0.0 -

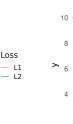
_

Outliers (in y) have large residuals $r = y - f(\mathbf{x})$. Some losses are more affected by large residuals than others. If loss goes up superlinearly (e.g. L2) it is not robust, linear (L1) or even sublinear losses are more robust.

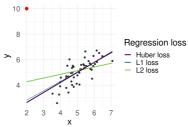
$y - \hat{f}(\mathbf{x})$	<i>L</i> 1	L2	Huber ($\epsilon=5$)
1	1	1	0.5
5	5	25	12.5
10	10	100	37.5
50	50	2500	237.5

r = v - f(x)

As a consequence, a model is less influenced by outliers than by "inliers" if the loss is robust. Outliers e.g. strongly influence *L*2.



Loss

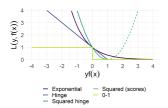




NUMERICAL PROPERTIES: SMOOTHNESS

- Smoothness of a function is a property measured by the number of continuous derivatives.
- ullet Derivative-based optimization requires smoothness of the risk $\mathcal{R}_{\mathsf{emp}}(oldsymbol{ heta})$
 - If loss is unsmooth, we might have to use derivative-free optimization (or worse, in case of 0-1)
 - Smoothness of $\mathcal{R}_{emp}(\theta)$ not only depends on L, but also requires smoothness of $f(\mathbf{x})$!





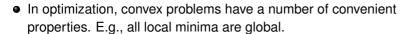
Squared loss, exponential loss and squared hinge loss are continuously differentiable. Hinge loss is continuous but not differentiable. 0-1 loss is not even continuous.

NUMERICAL PROPERTIES: CONVEXITY

ullet A function $\mathcal{R}_{\mathsf{emp}}(oldsymbol{ heta})$ is convex if

$$\mathcal{R}_{\mathsf{emp}}\left(t\cdot oldsymbol{ heta} + (\mathsf{1}-t)\cdot ilde{oldsymbol{ heta}}
ight) \leq t\cdot \mathcal{R}_{\mathsf{emp}}\left(oldsymbol{ heta}
ight) + (\mathsf{1}-t)\cdot \mathcal{R}_{\mathsf{emp}}\left(ilde{oldsymbol{ heta}}
ight)$$

 $\forall t \in [0,1], \ \theta, \tilde{\theta} \in \Theta$ (strictly convex if the above holds with strict inequality).



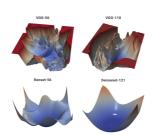
- \rightarrow strictly convex function has at most **one** global min (uniqueness).
- For $\mathcal{R}_{emp} \in \mathcal{C}^2$, \mathcal{R}_{emp} is convex iff Hessian $\nabla^2 \mathcal{R}_{emp}(\theta)$ is psd.



NUMERICAL PROPERTIES: CONVEXITY

- Convexity of $\mathcal{R}_{emp}(\theta)$ depends both on convexity of $L(\cdot)$ (given in most cases) and $f(\mathbf{x} \mid \theta)$ (often problematic).
- If we model our data using an exponential family distribution, we always get convex losses
 - For $f(\mathbf{x} \mid \theta)$ linear in θ , linear/logistic/softmax/poisson/... regression are convex problems (all GLMs)!

Li et al., 2018: Visualizing the Loss Landscape of Neural Nets. The problem on the bottom right is convex, the others are not (note that very high-dimensional surfaces are coerced into 3D here).





NUMERICAL PROPERTIES: CONVERGENCE

In case of complete separation, optimization might even fail entirely, e.g.:

 Margin-based loss that is strictly monotonicly decreasing in y · f, e.g., Bernoulli loss:

$$L(y, f(\mathbf{x})) = \log(1 + \exp(-yf(\mathbf{x})))$$

- f linear in θ , e.g., logistic regression with $f(\mathbf{x} \mid \theta) = \theta^{\top} \mathbf{x}$
- Data perfectly separable by our learner, so we can find θ :

$$y^{(i)} f\left(\mathbf{x}^{(i)} \mid \boldsymbol{\theta}\right) = y^{(i)} \boldsymbol{\theta}^T \mathbf{x}^{(i)} > 0 \ \forall \mathbf{x}^{(i)}$$

• Can now a construct a strictly better θ

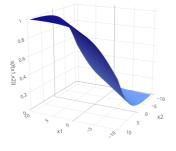
$$\mathcal{R}_{\mathsf{emp}}(2 \cdot oldsymbol{ heta}) = \sum_{i=1}^n L\left(2 oldsymbol{y}^{(i)} oldsymbol{ heta}^{\mathsf{T}} \mathbf{x}^{(i)}
ight) < \mathcal{R}_{\mathsf{emp}}(oldsymbol{ heta})$$

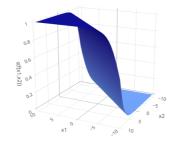
- ullet As $||m{ heta}||$ increases, sum strictly decreases, as argument of L is strictly larger
- We can iterate that, so there is no local (or global) optimum, and no numerical procedure can converge



NUMERICAL PROPERTIES: CONVERGENCE

• Geometrically, this translates to an ever steeper slope of the logistic/softmax function, i.e., increasingly sharp discrimination:







- In practice, data are seldomly linearly separable and misclassified examples act as counterweights to increasing parameter values.
- Besides, we can use regularization to encourage convergence to robust solutions.