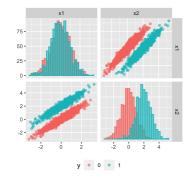
# **Supervised Learning**

## **Filter Methods: Examples and Caveats**



#### Learning goals

- Understand how filter methods can be misleading.
- Understand how filter methods work in practical applications.

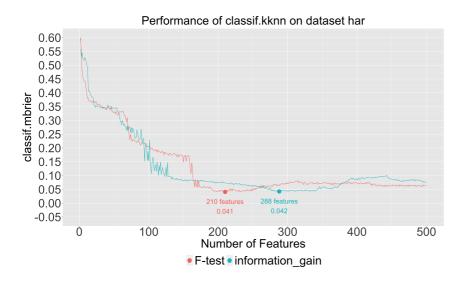


#### INTRODUCTION

- Filter methods construct a measure that quantifies the dependency between all features and the target variable.
- They yield a numerical score for each feature  $x_j$ , according to which we rank the features.
- They are model-agnostic and can be applied generically.
- Filter methods are strongly related to methods for determining variable importance.

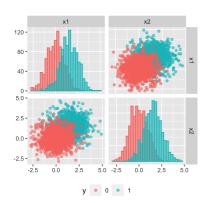


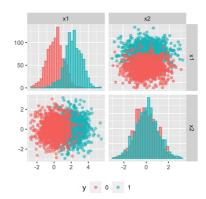
## **VISUALIZATION OF FILTER ALGORITHMS**





## FILTER METHODS CAN BE MISLEADING

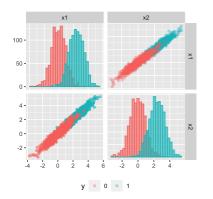


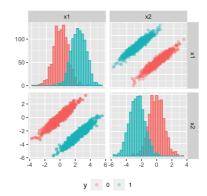




**IG** from presumably redundant variables. Left: 2 class problem with i.i.d. variables. Each class has Gaussian distr. with no covariance. Right: After 45 degree rotation, showing combination of 2 vars yields separation improvement by factor  $\sqrt{2}$ , showing i.i.d. vars are not truly redundant. For further details, see Guyon and Elisseeff, 2003.

## FILTER METHODS CAN BE MISLEADING

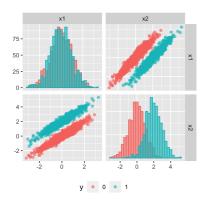


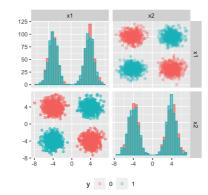




Intra-class covariance. In projection onto the axes, distribution of two variables are same as before. Left: Class conditional distribution have high cov. in direction of the line of the two class centers. Right: Class conditional distr. have high cov. in direction perpendicular to line of two class centers. Important separation gain is obtained by using both variables.

## FILTER METHODS CAN BE MISLEADING







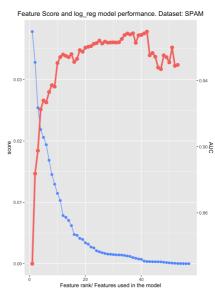
Variable useless by itself can be useful together with others. Left: One var has completely overlapping class conditional densities. Still, jointly with other variable separability can be improved. Right: XOR-like chessboard problem. Classes consist of "clumps" s.t. projection on the axes yield overlapping densities. Single vars have no separation power, only used together.

## **USING FILTER METHODS**

- Calculate filter score for each feature  $x_j$ .
- Rank features according to score values.
- **3** Choose  $\tilde{p}$  best features.
- Train model on  $\tilde{p}$  best features.

### How to choose $\tilde{p}$ ?

- It can be prescribed by the application.
- Eyeball estimation: read from filter plots
- Use resampling.





## **USING FILTER METHODS**

#### Advantages:

- Easy to calculate.
- Typically scales well with the number of features *p*.
- Generally interpretable.
- Model-agnostic.

## Disadvantages:

- Univariate analyses may ignore multivariate dependencies.
- Redundant features will have similar weights.
- Ignores the learning algorithm.

