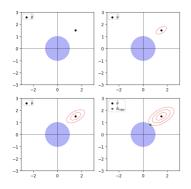
Introduction to Machine Learning

Ridge Regression



Learning goals

- Know the regularized linear model
- Know ridge regression (L2 penalty)
- Understand correspondence to constrained optimization



REGULARIZATION IN THE LINEAR MODEL

- Linear models can also overfit if we operate in a high-dimensional space with not that many observations.
- The OLS estimator requires a full-rank design matrix.
- For highly correlated features, OLS becomes highly sensitive to random errors in the observed response, producing a large variance in the fit.
- We now add a complexity penalty to the loss:

$$\mathcal{R}_{\mathsf{reg}}(oldsymbol{ heta}) = \sum_{i=1}^n \left(oldsymbol{y}^{(i)} - oldsymbol{ heta}^{ op} \mathbf{x}^{(i)}
ight)^2 + \lambda \cdot J(oldsymbol{ heta}).$$



Intuitive measure of model complexity is deviation from 0-origin, as 0-model contains no effects. So we measure $J(\theta)$ through a vector norm, shrinking coefs closer 0 (**shrinkage methods**).

ridge regression uses a simple *L*2 penalty:

$$\hat{\theta}_{\text{ridge}} = \underset{\boldsymbol{\theta}}{\operatorname{arg\,min}} \sum_{i=1}^{n} \left(\boldsymbol{y}^{(i)} - \boldsymbol{\theta}^{T} \boldsymbol{x}^{(i)} \right)^{2} + \lambda \sum_{j=1}^{p} \theta_{j}^{2}$$

$$= \underset{\boldsymbol{\theta}}{\operatorname{arg\,min}} \left(\boldsymbol{y} - \boldsymbol{X} \boldsymbol{\theta} \right)^{\top} \left(\boldsymbol{y} - \boldsymbol{X} \boldsymbol{\theta} \right) + \lambda \underbrace{\boldsymbol{\theta}^{\top} \boldsymbol{\theta}}_{\|\boldsymbol{\theta}\|_{2}^{2}}$$

Optimization is possible (as in the normal LM) in analytical form:

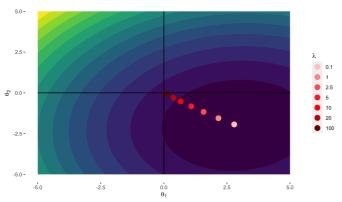
$$\hat{ heta}_{\mathsf{ridge}} = (\mathbf{X}^T\mathbf{X} + \lambda \mathbf{I})^{-1}\mathbf{X}^T\mathbf{y}$$

Name comes from the fact that we add positive entries along the diagonal "ridge" $\mathbf{X}^T\mathbf{X}$



Let $y = 3x_1 - 2x_2 + \epsilon$, $\epsilon \sim N(0, 1)$. The true minimizer is $\theta^* = (3, -2)^T$, with $\hat{\theta}_{\text{ridge}} = \arg\min_{\theta} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|^2 + \lambda \|\boldsymbol{\theta}\|^2$.

Effect of L2 Regularization on Linear Model Solutions

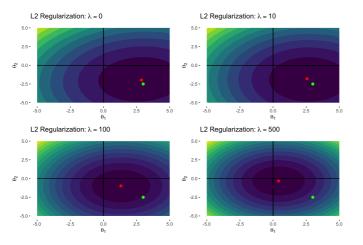


With increasing regularization, $\hat{\theta}_{ridge}$ is pulled back to the origin (contour lines show unregularized objective).



Contours of regularized objective for different λ values.

$$\hat{\theta}_{\text{ridge}} = \arg\min_{\boldsymbol{\theta}} \|\mathbf{y} - \mathbf{X}\boldsymbol{\theta}\|^2 + \lambda \|\boldsymbol{\theta}\|^2.$$



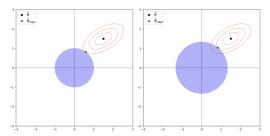
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Green = true minimizer of the unreg.objective and red = ridge solution.

We understand the geometry of these 2 mixed components in our regularized risk objective much better, if we formulate the optimization as a constrained problem (see this as Lagrange multipliers in reverse).

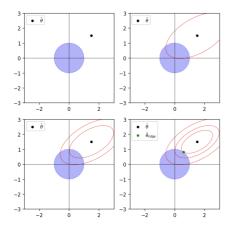
$$\min_{\boldsymbol{\theta}} \qquad \sum_{i=1}^{n} \left(y^{(i)} - f\left(\mathbf{x}^{(i)} \mid \boldsymbol{\theta}\right) \right)^{2}$$

s.t.
$$\|\theta\|_{2}^{2} \leq t$$



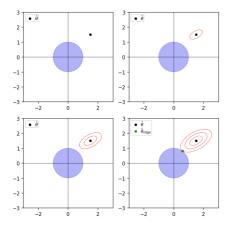
NB: There is a bijective relationship between λ and t: $\lambda \uparrow \Rightarrow t \downarrow$ and vice versa.





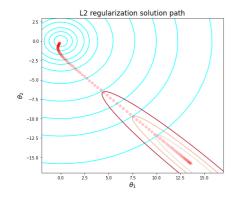
- Inside constraints perspective: From origin, jump from contour line to contour line (better) until you become infeasible, stop before.
- We still optimize the $\mathcal{R}_{emp}(\theta)$, but cannot leave a ball around the origin.
- $\mathcal{R}_{emp}(\theta)$ grows monotonically if we move away from $\hat{\theta}$ (elliptic contours).
- Solution path moves from origin to border of feasible region with minimal L₂ distance.





- Outside constraints perspective: From $\hat{\theta}$, jump from contour line to contour line (worse) until you become feasible, stop then.
- So our new optimum will lie on the boundary of that ball.
- Solution path moves from unregularized estimate to feasible region of regularized objective with minimal L₂ distance.





- Here we can see entire solution path for ridge regression
- Cyan contours indicate feasible regions induced by different λs
- Red contour lines indicate different levels of the unreg. objective
- Ridge solution (red points) gets pulled toward origin for increasing λ



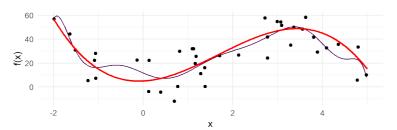
EXAMPLE: POLYNOMIAL RIDGE REGRESSION

Consider $y = f(x) + \epsilon$ where the true (unknown) function is $f(x) = 5 + 2x + 10x^2 - 2x^3$ (in red).

We now fit the data using a dth-order polynomial

$$f(x) = \theta_0 + \theta_1 x + \cdots + \theta_d x^d = \sum_{j=0}^d \theta_j x^j.$$

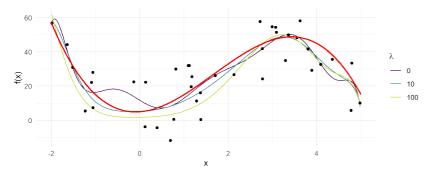
Using model complexity d = 10 overfits:





EXAMPLE: POLYNOMIAL RIDGE REGRESSION

With an L2 penalty we can now select d "too large" but regularize our model by shrinking its coefficients. Otherwise we have to optimize over the discrete d.



λ	θ_0	θ_1	θ_2	θ_3	θ_4	θ_5	θ_6	θ_7	θ_8	θ_9	θ_{10}
0.00	12.00	-16.00	4.80	23.00	-5.40	-9.30	4.20	0.53	-0.63	0.13	-0.01
10.00	5.20	1.30	3.70	0.69	1.90	-2.00	0.47	0.20	-0.14	0.03	-0.00
100.00	1.70	0.46	1.80	0.25	1.80	-0.94	0.34	-0.01	-0.06	0.02	-0.00

