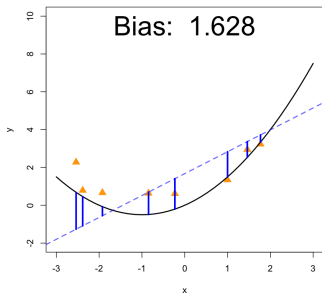
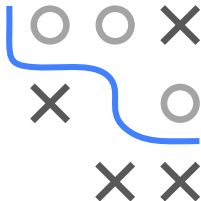


Introduction to Machine Learning

Advanced Risk Minimization

Bias-Variance 2:

Approximation and Estimation error



Learning goals

- Decomposing excess risk
- Into estimation, approx. and optim. error

► **Brown and Ali 2024**

-
- A 3x3 grid with a blue path starting at the top-left cell (row 1, column 1) and ending at the bottom-right cell (row 3, column 3). The path consists of the following cells: (1,1), (1,2), (2,2), (2,3), and (3,3). The cells (1,3), (2,1), and (3,1) are empty. The cells (1,2), (2,2), and (3,3) contain a grey circle. The cells (2,1), (2,3), and (3,1) contain a grey 'X'.

- Both commonly described using same figure and analogies



- BV decomp. only holds for certain losses, above is universal

- Approx. error is a structural property of \mathcal{H}
- Estimation error is random due to dependence on data in \hat{f}
- Estimation error occurs as we choose $f \in \mathcal{H}$ with limited train data minimizing \mathcal{R}_{emp} instead of \mathcal{R}
- Knowing $\hat{f}_{\mathcal{H}} \in \arg \inf_{f \in \mathcal{H}} \mathcal{R}_{\text{emp}}(f)$ assumes we found a global minimizer of \mathcal{R}_{emp} , which is often impossible (e.g. ANNs)
- In practice, optimizing \mathcal{R}_{emp} gives us “best guess” $\tilde{f}_{\mathcal{H}} \in \mathcal{H}$ of $\hat{f}_{\mathcal{H}}$
- Can now decompose its excess risk finer as

$$\underbrace{\mathcal{R}(\tilde{f}_{\mathcal{H}}) - \mathcal{R}(f_{\mathcal{H}_{\text{all}}}^*)}_{\text{excess risk}} = \underbrace{\mathcal{R}(\tilde{f}_{\mathcal{H}}) - \mathcal{R}(\hat{f}_{\mathcal{H}})}_{\text{optim. error}} + \underbrace{\mathcal{R}(\hat{f}_{\mathcal{H}}) - \mathcal{R}(f_{\mathcal{H}}^*)}_{\text{estimation error}} + \underbrace{\mathcal{R}(f_{\mathcal{H}}^*) - \mathcal{R}(f_{\mathcal{H}_{\text{all}}}^*)}_{\text{approx. error}}$$

- NB: Optim err. can be < 0 , but $\mathcal{R}_{\text{emp}}(\tilde{f}_{\mathcal{H}}) \geq \mathcal{R}_{\text{emp}}(\hat{f}_{\mathcal{H}})$ always



- We can further decompose estimation error more finely by defining the *centroid* model or “systematic” model part
- For $\hat{f}_{\mathcal{H}} \in \arg \min_{f \in \mathcal{H}} \mathcal{R}_{\text{emp}}(f)$ centroid model under L2 loss is mean prediction at each x over all \mathcal{D}_n , $f_{\mathcal{H}}^{\circ} := \mathbb{E}_{\mathcal{D}_n \sim \mathbb{P}_{xy}^n} [\hat{f}_{\mathcal{H}}]$
- With $f_{\mathcal{H}}^{\circ}$, can decompose expected estimation error as

$$\underbrace{\mathbb{E}_{\mathcal{D}_n \sim \mathbb{P}_{xy}^n} [\mathcal{R}(\hat{f}_{\mathcal{H}}) - \mathcal{R}(f_{\mathcal{H}}^*)]}_{\text{expected estimation error}} = \underbrace{\mathbb{E}_{\mathcal{D}_n \sim \mathbb{P}_{xy}^n} [\mathcal{R}(\hat{f}_{\mathcal{H}}) - \mathcal{R}(f_{\mathcal{H}}^{\circ})]}_{\text{estimation variance}} + \underbrace{\mathcal{R}(f_{\mathcal{H}}^{\circ}) - \mathcal{R}(f_{\mathcal{H}}^*)}_{\text{estimation bias}}$$

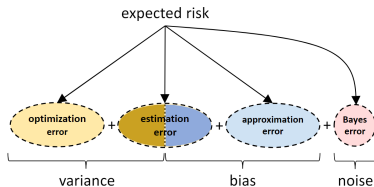
- Estimation bias measures distance of centroid model to risk minimizer over \mathcal{H}
- Estimation var. spread of ERM around centroid model induced by randomness due to \mathcal{D}_n



- Can now connect derived quantities back to bias and variance
- Bias is not only approx. error and variance is not estimation error
- Many details skipped here, see paper!

bias = approximation error + estimation bias

variance = optimization error + estimation variance



Credit: Brown and Ali 2024

- **NB:** For special case of LM and L2 loss, we have very small optim / numerical error and estimation bias; so both decomp agree

