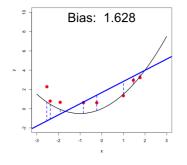
Introduction to Machine Learning

Deep Dive: Bias-Variance Decomposition





Learning goals

- Understand how to decompose the generalization error of a learner into
 - Bias of the learner
 - Variance of the learner
 - Inherent noise in the data

BIAS-VARIANCE DECOMPOSITION

Let us take a closer look at the generalization error of a learning algorithm \mathcal{I}_L . This is the expected error of an induced model $\hat{f}_{\mathcal{D}_n}$, on training sets of size n, when applied to a fresh, random test observation.

$$GE_{n}(\mathcal{I}_{L}) = \mathbb{E}_{\mathcal{D}_{n} \sim \mathbb{P}_{xy}^{n}, (\mathbf{x}, y) \sim \mathbb{P}_{xy}} \left(L\left(y, \hat{f}_{\mathcal{D}_{n}}(\mathbf{x})\right) \right) = \mathbb{E}_{\mathcal{D}_{n}, xy} \left(L\left(y, \hat{f}_{\mathcal{D}_{n}}(\mathbf{x})\right) \right)$$

We therefore need to take the expectation over all training sets of size n, as well as the independent test observation.

We assume that the data is generated by

$$y = f_{\text{true}}(\mathbf{x}) + \epsilon$$
,

with zero-mean homoskedastic error $\epsilon \sim (0, \sigma^2)$ independent of ${\bf x}$.



BIAS-VARIANCE DECOMPOSITION / 2

By plugging in the *L*2 loss $L(y, f(\mathbf{x})) = (y - f(\mathbf{x}))^2$ we get

$$GE_{n}(\mathcal{I}_{L}) = \mathbb{E}_{\mathcal{D}_{n},xy}\left(L\left(y,\hat{f}_{\mathcal{D}_{n}}(\mathbf{x})\right)\right) = \mathbb{E}_{\mathcal{D}_{n},xy}\left(\left(y-\hat{f}_{\mathcal{D}_{n}}(\mathbf{x})\right)^{2}\right)$$

$$\stackrel{\text{LIE}}{=} \mathbb{E}_{xy}\left[\mathbb{E}_{\mathcal{D}_{n}}\left(\left(y-\hat{f}_{\mathcal{D}_{n}}(\mathbf{x})\right)^{2} \mid \mathbf{x},y\right)\right]$$

$$\stackrel{\text{(*)}}{=}$$



Let us consider the error (*) conditioned on one fixed test observation (\mathbf{x}, y) first. (We omit the $|\mathbf{x}, y|$ for better readability for now.)

$$(*) = \mathbb{E}_{\mathcal{D}_n} \left(\left(y - \hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right)^2 \right)$$

$$= \underbrace{\mathbb{E}_{\mathcal{D}_n} \left(y^2 \right)}_{=y^2} + \underbrace{\mathbb{E}_{\mathcal{D}_n} \left(\hat{f}_{\mathcal{D}_n}(\mathbf{x})^2 \right)}_{(1)} - 2 \underbrace{\mathbb{E}_{\mathcal{D}_n} \left(y \hat{f}_{\mathcal{D}_n}(\mathbf{x}) \right)}_{(2)}$$

by using the linearity of the expectation.

BIAS-VARIANCE DECOMPOSITION / 3

$$(*) = \mathbb{E}_{\mathcal{D}_n}\left(\left(y - \hat{f}_{\mathcal{D}_n}(\mathbf{x})\right)^2\right) = y^2 + \underbrace{\mathbb{E}_{\mathcal{D}_n}\left(\hat{f}_{\mathcal{D}_n}(\mathbf{x})^2\right)}_{(1)} - 2\underbrace{\mathbb{E}_{\mathcal{D}_n}\left(y\hat{f}_{\mathcal{D}_n}(\mathbf{x})\right)}_{(2)} =$$

Using that $\mathbb{E}(z^2) = \text{Var}(z) + \mathbb{E}^2(z)$, we see that

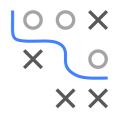
$$\mathbf{x} = \mathbf{y}^2 + \mathsf{Var}_{\mathcal{D}_n}\left(\hat{f}_{\mathcal{D}_n}(\mathbf{x})\right) + \mathbb{E}_{\mathcal{D}_n}^2\left(\hat{f}_{\mathcal{D}_n}(\mathbf{x})\right) - 2\mathbf{y}\mathbb{E}_{\mathcal{D}_n}\left(\hat{f}_{\mathcal{D}_n}(\mathbf{x})\right)$$

Plug in the definition of y

$$=\mathit{f}_{\mathsf{true}}(\mathbf{x})^{2}+2\epsilon\mathit{f}_{\mathsf{true}}(\mathbf{x})+\epsilon^{2}+\mathsf{Var}_{\mathcal{D}_{n}}\left(\hat{\mathit{f}}_{\mathcal{D}_{n}}(\mathbf{x})\right)+\mathbb{E}_{\mathcal{D}_{n}}^{2}\left(\hat{\mathit{f}}_{\mathcal{D}_{n}}(\mathbf{x})\right)-2\left(\mathit{f}_{\mathsf{true}}(\mathbf{x})+\epsilon\right)\mathbb{E}_{\mathcal{D}_{n}}\left(\hat{\mathit{f}}_{\mathcal{D}_{n}}(\mathbf{x})\right)\right)$$

Reorder terms and use the binomial formula

$$\mathbf{r} = \epsilon^2 + \mathsf{Var}_{\mathcal{D}_n}\left(\hat{t}_{\mathcal{D}_n}(\mathbf{x})\right) + \left(f_{\mathsf{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_n}\left(\hat{t}_{\mathcal{D}_n}(\mathbf{x})\right)\right)^2 + 2\epsilon\left(f_{\mathsf{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_n}\left(\hat{t}_{\mathcal{D}_n}(\mathbf{x})\right)\right)^2$$



BIAS-VARIANCE DECOMPOSITION / 4

$$(*) = \epsilon^2 + \mathsf{Var}_{\mathcal{D}_n}\left(\hat{\mathit{f}}_{\mathcal{D}_n}(\mathbf{x})\right) + \left(\mathit{f}_{\mathsf{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_n}\left(\hat{\mathit{f}}_{\mathcal{D}_n}(\mathbf{x})\right)\right)^2 + 2\epsilon\left(\mathit{f}_{\mathsf{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_n}\left(\hat{\mathit{f}}_{\mathcal{D}_n}(\mathbf{x})\right)\right)$$

Let us come back to the generalization error by taking the expectation over all fresh test observations $(\mathbf{x}, y) \sim \mathbb{P}_{xy}$:



$$\begin{aligned} \textit{GE}_{\textit{n}}\left(\mathcal{I}_{\textit{L}}\right) &= \underbrace{\sigma^{2}}_{\textit{Variance of the data}} + \mathbb{E}_{\textit{xy}}\left[\underbrace{\mathsf{Var}_{\mathcal{D}_{\textit{n}}}\left(\hat{f}_{\mathcal{D}_{\textit{n}}}(\mathbf{x}) \mid \mathbf{x}, y\right)}\right]_{\textit{Variance of learner at }(\mathbf{x}, y)} \\ &+ \mathbb{E}_{\textit{xy}}\left[\left(\left(f_{\textit{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_{\textit{n}}}\left(\hat{f}_{\mathcal{D}_{\textit{n}}}(\mathbf{x})\right)\right)^{2} \mid \mathbf{x}, y\right)\right] + \underbrace{0}_{\textit{As ϵ is zero-mean and independer}} \\ &+ \mathbb{E}_{\textit{xy}}\left[\left(\left(f_{\textit{true}}(\mathbf{x}) - \mathbb{E}_{\mathcal{D}_{\textit{n}}}\left(\hat{f}_{\mathcal{D}_{\textit{n}}}(\mathbf{x})\right)\right)^{2} \mid \mathbf{x}, y\right)\right] + \underbrace{0}_{\textit{As ϵ is zero-mean and independer}} \end{aligned}$$