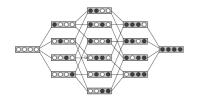
Supervised Learning

Wrapper methods



Learning goals

- Understand how wrapper methods work
- Understand how they could help in feature selection
- Know their advantages and disadvantages



INTRODUCTION

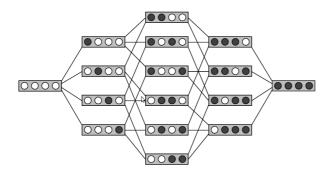
- Wrapper methods emerged from the idea that different sets of features can be optimal for different learners.
- Use the learner itself to assess the quality of the feature sets.
- Evaluation on a test set or resampling techniques are used.
- A wrapper is nothing else than a discrete search strategy for S, where the test error of a learner as a function of S is now the objective criterion.



INTRODUCTION

Wrappers have the following components:

- A set of starting values
- Operators to create new points out of the given ones
- A termination criterion



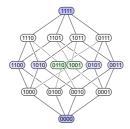


OBJECTIVE FUNCTION

Given p features, the **best-subset selection problem** is to find a subset $S \subseteq \{1, \dots p\}$ optimizing objective $\Psi : \Omega \to \mathbb{R}$:

$$S^* \in \operatorname{\mathsf{arg}} \min_{\mathcal{S} \in \Omega} \{ \Psi(\mathcal{S}) \}$$

- Ω = search space of all feature subsets $S \subseteq \{1, ..., p\}$. Usually we encode this by bit vectors, i.e., $\Omega = \{0, 1\}^p$ (1 = feat. selected)
- Objective Ψ can be different functions, e.g., AIC/BIC for LM or cross-validated performance of a learner.



Hasse diagram (source: Wikipedia)



HOW DIFFICULT IS BEST-SUBSET SELECTION?

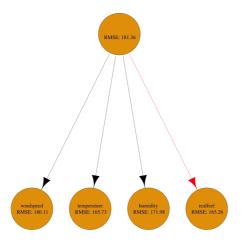
- Size of search space = 2^p , i.e., grows exponentially in p as it is the power set of $\{1, \ldots, p\}$.
- Finding best subset is discrete combinatorial optimization problem also known as *L*₀ regularization.
- It can be shown that this problem unfortunately can not be solved efficiently in general (NP hard; see, e.g., Natarajan, 1995)
- We can avoid having to search the entire space by employing efficient search strategies, moving through the search space in a smart way that finds performant feature subsets.



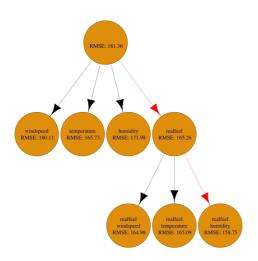
- Let $S \subset \{1, ..., p\}$, where $\{1, ..., p\}$ is an index set of all features.
- Start with the empty feature set $S = \emptyset$.
- For a given set S, generate all $S_j = S \cup \{j\}$ with $j \notin S$.
- Evaluate the classifier on all S_j and use the best S_j .
- Iterate over this procedure.
- Terminate if:
 - the performance measure doesn't improve enough.
 - a maximum number of features is used.
 - a given performance value is reached.



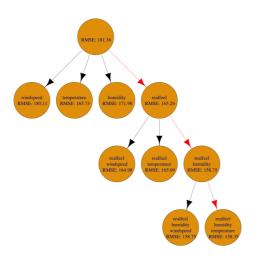
Example for greedy forward search on bike sharing data:



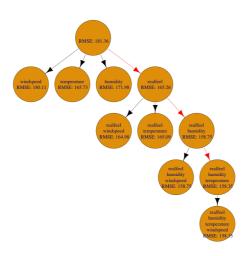




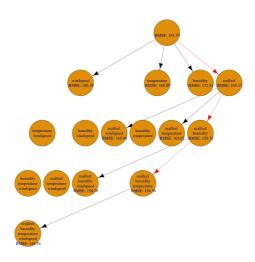












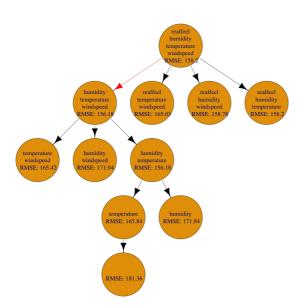


GREEDY BACKWARD SEARCH

- Start with the full index set of features $S = \{1, ..., p\}$.
- For a given set S generate all $S_j = S \setminus \{j\}$ with $j \in S$.
- Evaluate the classifier on all S_i and use the best S_i .
- Iterate over this procedure.
- Terminate if:
 - the performance drops drastically, or
 - a given performance value is undershot.



GREEDY BACKWARD SEARCH





EXTENSIONS

- Eliminate or add several features at once to increase speed.
- Allow alternating forward and backward search.
- Randomly create candidate feature sets in each iteration.
- Continue search based on the set of features where an improvement is present.
- Use improvements of earlier iterations.



EXTENSIONS

Algorithm A simple 1+1 genetic algorithm

- 1: Start with a random set of features *S* (bit vector *b*).
- 2: repeat
- 3: Flip a couple of bits in b with probability p.
- 4: Generate set S' and bit vector b'.
- 5: Measure the classifier's performance on S'.
- 6: If S' performs better than S, update $S \leftarrow S'$, otherwise $S \leftarrow S$.
- 7: **until** One of the following conditions is met:
 - A given performance value is reached.
 - Budget is exhausted.



WRAPPERS

Advantages:

- Can be combined with every learner.
- Can be combined with every performance measure.
- Optimizes the desired criterion directly.

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Disadvantages:

- Evaluating the target function is expensive.
- Does not scale well if number of features becomes large.
- Does not use much structure or available information from our model.