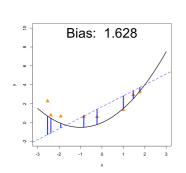
Introduction to Machine Learning

Advanced Risk Minimization
Bias-Variance 2:
Approximation and Estimation error



Learning goals

- Decomposing excess risk
- Into estimation, approx. and optim. error

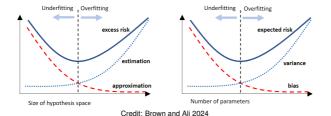


APPROXIMATION AND ESTIMATION > Brown and Ali 2024

BV decomp often confused with related (but different) decomp:

$$\underbrace{\mathcal{R}(\hat{\mathit{f}}_{\mathcal{H}}) - \mathcal{R}(\mathit{f}^*_{\mathcal{H}_{\mathit{all}}})}_{\text{excess risk}} = \underbrace{\mathcal{R}(\hat{\mathit{f}}_{\mathcal{H}}) - \mathcal{R}(\mathit{f}^*_{\mathcal{H}})}_{\text{estimation error}} + \underbrace{\mathcal{R}(\mathit{f}^*_{\mathcal{H}}) - \mathcal{R}(\mathit{f}^*_{\mathcal{H}_{\mathit{all}}})}_{\text{approx. error}}$$

Both commonly described using same figure and analogies



BV decomp. only holds for certain losses, above is universal



APPROX./ESTIMATION ERROR > Brown and Ali 2024

- Approx. error is a structural property of \mathcal{H}
- Estimation error is random due to dependence on data in \hat{f}
- Estimation error occurs as we choose $f \in \mathcal{H}$ with limited train data minimizing \mathcal{R}_{emp} instead of \mathcal{R}
- Knowing $\hat{f}_{\mathcal{H}} \in \arg\inf_{f \in \mathcal{H}} \mathcal{R}_{emp}(f)$ assumes we found a global minimizer of \mathcal{R}_{emp} , which is often impossible (e.g. ANNs)
- In practice, optimizing \mathcal{R}_{emp} gives us "best guess" $\tilde{f}_{\mathcal{H}} \in \mathcal{H}$ of $\hat{f}_{\mathcal{H}}$
- Can now decompose its excess risk finer as

$$\underbrace{\mathcal{R}(\tilde{\mathit{f}}_{\mathcal{H}}) - \mathcal{R}(\mathit{f}^*_{\mathcal{H}_{\mathit{all}}})}_{\text{excess risk}} = \underbrace{\mathcal{R}(\tilde{\mathit{f}}_{\mathcal{H}}) - \mathcal{R}(\hat{\mathit{f}}_{\mathcal{H}})}_{\text{optim. error}} + \underbrace{\mathcal{R}(\hat{\mathit{f}}_{\mathcal{H}}) - \mathcal{R}(\mathit{f}^*_{\mathcal{H}})}_{\text{estimation error}} + \underbrace{\mathcal{R}(\mathit{f}^*_{\mathcal{H}}) - \mathcal{R}(\mathit{f}^*_{\mathcal{H}_{\mathit{all}}})}_{\text{approx. error}}$$

• NB: Optim err. can be < 0, but $\mathcal{R}_{emp}(\tilde{f}_{\mathcal{H}}) \geq \mathcal{R}_{emp}(\hat{f}_{\mathcal{H}})$ always



APPROX./ESTIMATION ERROR > Brown and Ali 2024

 We can further decompose estimation error more finely by defining the *centroid* model or "systematic" model part.



- For $\hat{t}_{\mathcal{H}} \in \arg\min_{f \in \mathcal{H}} \mathcal{R}_{emp}(f)$ centroid model under L2 loss is mean prediction at each x over all \mathcal{D}_n , $f_{\mathcal{H}}^{\circ} := \mathbb{E}_{\mathcal{D}_n \sim \mathbb{P}_n^n}[\hat{f}_{\mathcal{H}}]$
- With $f_{\mathcal{U}}^{\circ}$, can decompose expected estimation error as

$$\underbrace{\mathbb{E}_{\mathcal{D}_{n} \sim \mathbb{P}_{xy}^{n}}\left[\mathcal{R}(\hat{f}_{\mathcal{H}}) - \mathcal{R}(f_{\mathcal{H}}^{*})\right]}_{\text{expected estimation error}} = \underbrace{\mathbb{E}_{\mathcal{D}_{n} \sim \mathbb{P}_{xy}^{n}}\left[\mathcal{R}(\hat{f}_{\mathcal{H}}) - \mathcal{R}(f_{\mathcal{H}}^{\circ})\right]}_{\text{estimation bias}} + \underbrace{\mathcal{R}(f_{\mathcal{H}}^{\circ}) - \mathcal{R}(f_{\mathcal{H}}^{*})}_{\text{estimation bias}}$$

- Estimation bias measures distance of centroid model to risk minimizer over \mathcal{H} .
- Estimation var. spread of ERM around centroid model induced by randomness due to \mathcal{D}_n

APPROX./ESTIMATION ERROR > Brown and Ali 2024

- Can now connect derived quantities back to bias and variance
- Bias is not only approx. error and variance is not estimation error
- Many details skipped here, see paper!

 $\mbox{bias} = \mbox{approximation error} + \mbox{estimation bias}$ $\mbox{variance} = \mbox{optimization error} + \mbox{estimation variance}$



 NB: For special case of LM and L2 loss, we have very small optim / numerical error and estimation bias; so both decomps agree

