

# ECE159 Cheat Sheet

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ECE 159

## Basic Concepts

*Foundation for all circuit analyses.*

## Voltage, Current & Power

$$V = \int_C \mathbf{E} \cdot d\mathbf{l} = \frac{dW}{dq}, \quad I = \frac{dq}{dt}, \quad P = VI$$

$$W = \int_{t_0}^{t_1} P(t) dt$$

## Fields & Energy Density

$$F = qE, \quad U_E = \frac{1}{2}CV^2, \quad u_E = \frac{1}{2}\epsilon_r\epsilon_0 E^2$$

$$U_B = \frac{1}{2}Li^2, \quad u_B = \frac{1}{2\mu_r\mu_0} B^2$$

## Basic DC Analysis

*Use for resistive network calculations.*

## Ohm's Law

$$V = IR$$

## Resistors

$$R_{eq} = \sum R_i, \quad \frac{1}{R_{eq}} = \sum \frac{1}{R_i}, \quad P = I^2 R = \frac{V^2}{R}$$

## Division Rules

$$V_i = V \frac{R_i}{R_{eq}}, \quad I_i = I \frac{G_i}{G_{eq}} = I \frac{1/R_i}{\sum 1/R_i}$$

## Kirchhoff's Laws

$$\sum I_{in} = \sum I_{out} \quad (\text{KCL}), \quad \sum V = 0 \quad (\text{KVL})$$

## Maximum Power Transfer

*Select load to maximize delivered power.*

$$R_L = R_{th}, \quad P_{\max} = \frac{V_{th}^2}{4R_{th}}$$

*For AC circuit*

$$Z_L = Z_{th}^*$$

$$P_{\text{avg}} = \frac{|V_{th}|^2}{8R_L}, \quad P_{\max} = \frac{|V_{th}|^2}{4R_L}$$

## Operational Amplifiers

*Assume ideal unless specs given.*

## Ideal Assumptions

$$V_+ = V_-, \quad I_+ = I_- = 0$$

## Common Configs

$$\text{Inverting: } V_{out} = -\frac{R_f}{R_{in}} V_{in},$$

$$\text{Non-inv.: } V_{out} = \left(1 + \frac{R_f}{R_{in}}\right) V_{in},$$

$$\text{Buffer: } V_{out} = V_{in}.$$

## First-Order Circuits

*Transient response: exponential approach to steady state.*

## RC (Voltage)

$$v(t) = v_{\infty} + (v_0 - v_{\infty})e^{-t/RC}, \quad \tau = RC$$

## RL (Current)

$$i(t) = i_{\infty} + (i_0 - i_{\infty})e^{-tR/L}, \quad \tau = \frac{L}{R}$$

## Capacitor

Blocks DC, smoothing/filtering.

$$C = \frac{Q}{V}, \quad X_C = \frac{1}{\omega C}$$

$$i(t) = C \frac{dV}{dt}, \quad V(t) = \frac{1}{C} \int i(t) dt$$
$$E_C = \frac{1}{2} CV^2$$

## Inductor

Passes DC, used in chokes/filters.

$$X_L = \omega L$$

$$v(t) = L \frac{di}{dt}, \quad i(t) = \frac{1}{L} \int v(t) dt$$
$$E_L = \frac{1}{2} LI^2$$

## Power

Compute  $p(t)$  in time domain,  $P$  in steady-state AC.

### General

$$p(t) = v(t)i(t), \quad p_R = i^2 R = \frac{v^2}{R}$$

### AC Average

$$P = \frac{1}{2} V_p I_p \cos \theta = V_{rms} I_{rms} \cos \theta$$

### Product-to-Sum

$$\cos A \cos B = \frac{1}{2} [\cos(A - B) + \cos(A + B)]$$

## Complex & Reactive Power

Use phasors for AC analysis,  $P$  and  $Q$  form a right angled  $\Delta$

$$S = P + jQ, \quad |S| = \sqrt{P^2 + Q^2},$$

$$Q = V_{rms} I_{rms} \sin \theta,$$

$$pf = \cos \theta = \frac{P}{|S|}$$

In General, we have (bold = complex):

$$\begin{aligned} S &= P + jQ = \mathbf{V}_{rms}(\mathbf{I}_{rms})^* \\ &= V_{rms} I_{rms} \angle(\theta_v - \theta_i) \\ &= \frac{1}{2} \mathbf{V}_m \mathbf{I}_m^* \\ &= \mathbf{Z} I_{rms}^2 \\ &= \frac{V_{rms}^2}{\mathbf{Z}^*} \\ &= \frac{\mathbf{Z}}{|Z|} |S| \end{aligned}$$

## Power Factor

### Power Factor

$$\theta = \theta_v - \theta_i$$

Leading pf:  $\theta < 0$  ; Lagging pf:  $\theta > 0$

### PFC

Add  $C$  to // to the load adjust reactive power.

$$Q_{old} = P \tan(\cos^{-1} pf_{old}),$$

$$Q_{new} = P \tan(\cos^{-1} pf_{new}),$$

$$Q_{corr} = Q_{old} - Q_{new}$$

$$X_C = \frac{V_{rms}^2}{Q_{corr}}, \quad C = \frac{1}{\omega X_C}, \quad Z_{corr} = \frac{1}{j\omega C}$$

## Impedance & Resonance

Series/parallel combinations; LC resonance.

$$Z_{ser} = \sum Z_i, \quad \frac{1}{Z_{par}} = \sum \frac{1}{Z_i}, \quad f_0 = \frac{1}{2\pi\sqrt{LC}}$$

Db formula.

$$H_{dB} = 20 \log_{10} H$$

## Mutual Inductance

Phasor-domain relations and dot-convention.

$$V_1 = j\omega L_1 I_1 + j\omega M I_2,$$

$$V_2 = j\omega M I_1 + j\omega L_2 I_2$$

### Dot Convention:

- If  $I_1$  enters the dotted terminal of coil 1, the induced voltage in coil 2 at its dotted terminal is  $+j\omega MI_1$ .
- If  $I_1$  enters the undotted end, the induced voltage at the dotted end of coil 2 is  $-j\omega MI_1$ .
- Polarity: “dots” mark the same instantaneous polarity of induced voltages.

## Maths

*Useful tricks and identities for signal and circuit math.*

### Trig Conversions

$$\sin(x) = \cos\left(\frac{\pi}{2} - x\right), \quad -\sin(x) = \cos\left(x + \frac{\pi}{2}\right)$$

$$\cos(x) = \sin\left(\frac{\pi}{2} - x\right), \quad -\cos(x) = \sin\left(x + \frac{\pi}{2}\right)$$

## Cramer's Rule (2x2)

*Solve linear systems:  $Ax = b$*

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} e \\ f \end{bmatrix}$$

$$\Delta = ad - bc, \quad x = \frac{ed - bf}{\Delta}, \quad y = \frac{af - ec}{\Delta}$$

## Complex Number Tricks

- $z = a + jb$  (Rectangular)
- $z = re^{j\theta} = r(\cos \theta + j \sin \theta)$
- $|z| = \sqrt{a^2 + b^2}, \quad \theta = \tan^{-1}(b/a)$
- $z^* = a - jb$  (Conjugate)
- $\frac{1}{j} = -j, \quad j^2 = -1$
- Multiplying:  $z_1 z_2 = r_1 r_2 e^{j(\theta_1 + \theta_2)}$
- Dividing:  $\frac{z_1}{z_2} = \frac{r_1}{r_2} e^{j(\theta_1 - \theta_2)}$