

# **Advanced Machine learning Mastering Course**

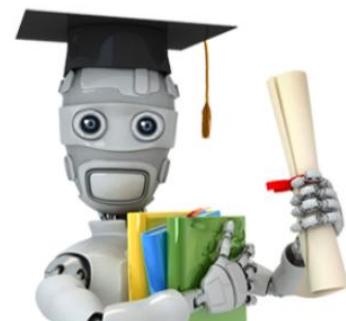
Introduced by

# **George Samuel**

Master in computer science  
Cairo University

Innovisionray.com

**2024**



# Agenda

1 Supervised Learning

2 Introduction to Regression

3 More Regression

4 Regression in Sklearn

5 Gradient decent-Normal equation

6 Regularization

7 Logistic Regression

8 Decision Tree

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15 Bayesian Inference

16 Ensemble B&B

17 Finding donors for CharityML

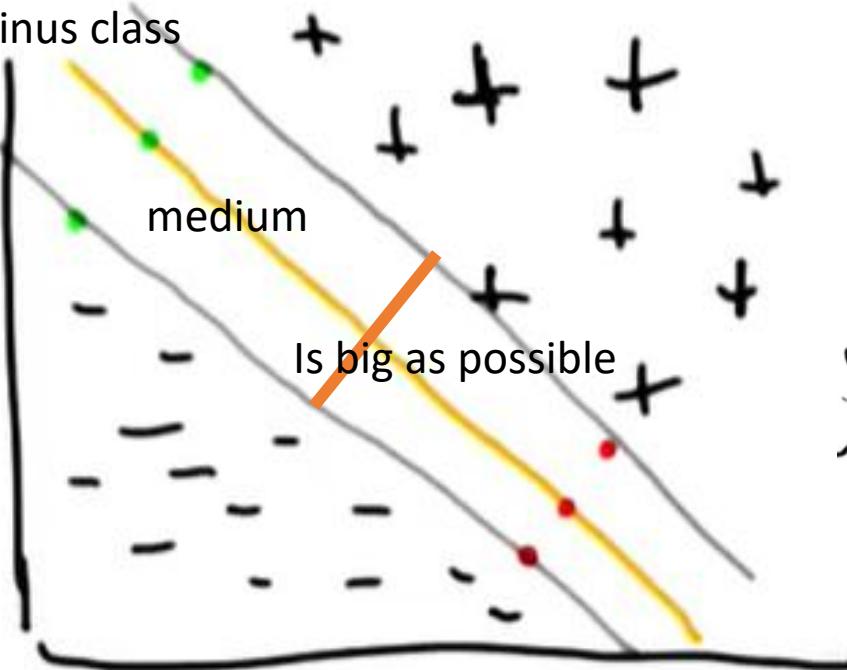
$$\omega^T x_1 + b = 1$$

$$\omega^T x_2 + b = -1$$

QUIZ!

CLOSE to plus class

CLOSE to Minus class

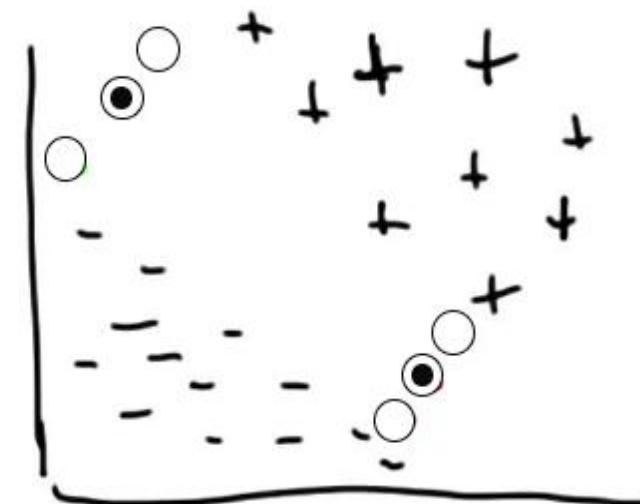


$$\omega^T x + b = 1$$

$$\omega^T x + b = 0$$

$$\omega^T x + b = -1$$

WHICH IS THE BEST



Quiz

$$\begin{array}{r} \omega^T x_1 + b = 1 \\ - \omega^T x_2 + b = -1 \\ \hline \end{array}$$

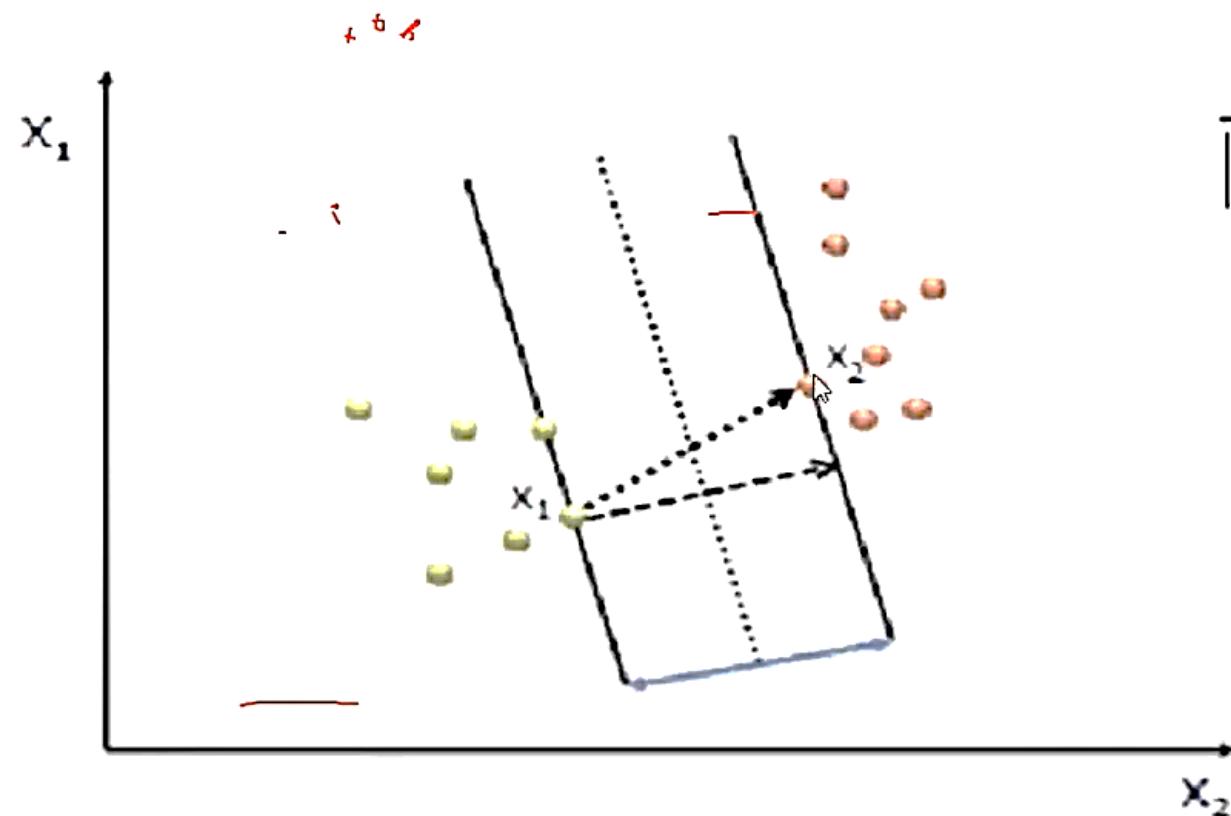
wtx<sub>1</sub>-wtx<sub>2</sub>=2

$$\omega^T(x_1 - x_2) = 2$$

$$\frac{\omega^T(x_1 - x_2)}{\|\omega\|} = \frac{2}{\|\omega\|}$$

$$\frac{\omega^T(x_1 - x_2)}{\|\omega\|} = \frac{2}{\|\omega\|}$$

m margin



$$\frac{w}{\|w\|} \cdot (x_2 - x_1) = \text{width} = \frac{2}{\|w\|}$$

$$w \cdot x_2 + b = 1$$

$$w \cdot x_1 + b = -1$$

$$w \cdot x_2 + b - w \cdot x_1 - b = 1 - (-1)$$

$$w \cdot x_2 - w \cdot x_1 = 2$$

$$\frac{w}{\|w\|} (x_2 - x_1) = \frac{2}{\|w\|}$$

$$\max \frac{2}{\|\omega\|} \quad \text{while classifying everything correctly}$$

$$y_i(\omega^T x_i + b) \geq 1 \quad \forall i$$

- $\min \frac{1}{2} \|\omega\|^2$

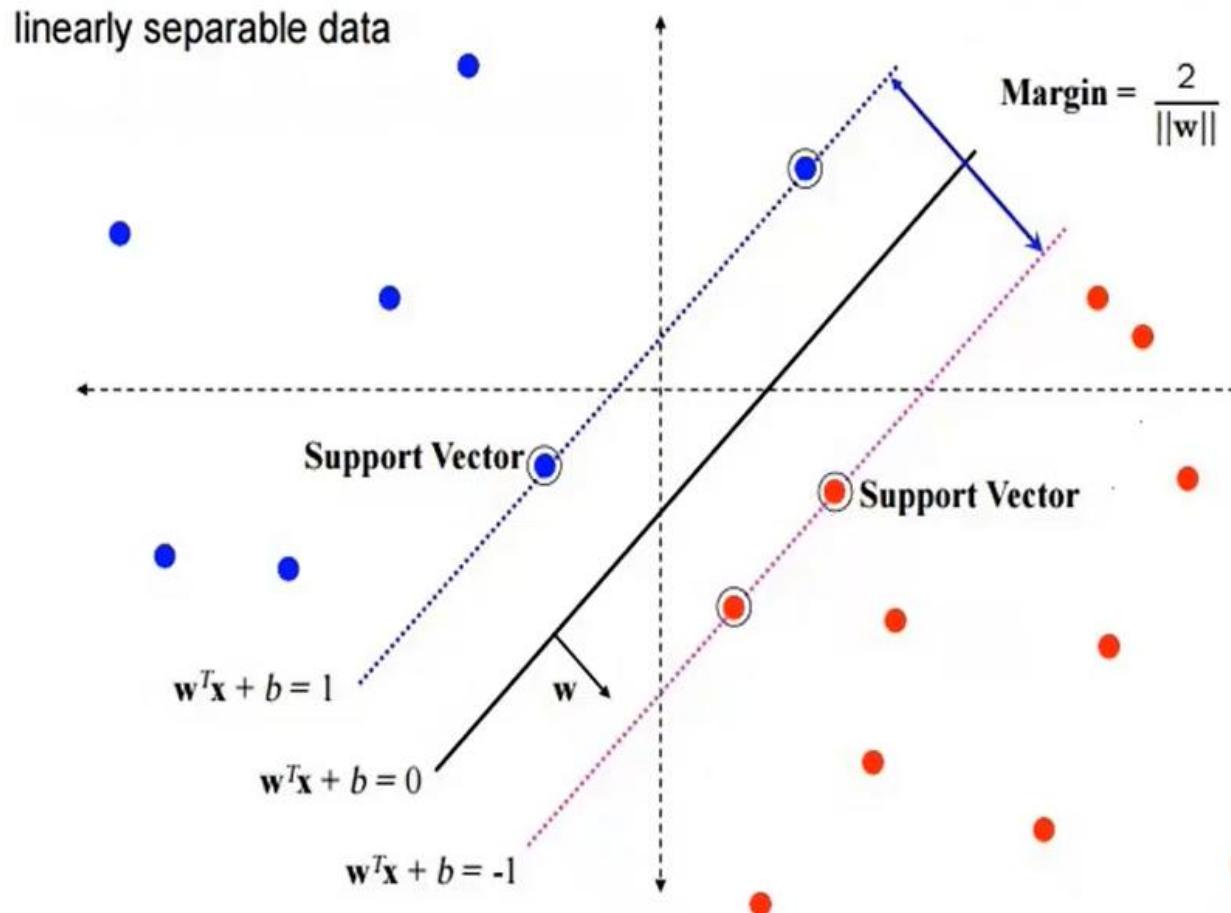
quadratic programming

- $W(\alpha) = \sum_i \alpha_i - \frac{1}{2} \sum_{ij} \alpha_i \alpha_j y_i y_j x_i^T x_j$

~~max~~

- $\text{s.t. } \alpha_i \geq 0, \sum_i \alpha_i y_i = 0$

# Support Vector Machine



Support Vector Machines (SVM) can be framed as a minimization problem in the context of both classification and regression. The objective is to find the optimal hyperplane that separates data points of different classes with the maximum margin in the case of classification, or to fit the best possible regression line with minimal error in the case of regression. Here's how SVM can be formulated as a minimization problem for both cases:

## 1. SVM for Classification

### Primal Form

The primal form of the SVM optimization problem can be written as:

Minimize:

$$\frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^n \xi_i$$

Subject to:

$$y_i(\mathbf{w} \cdot \mathbf{x}_i + b) \geq 1 - \xi_i, \quad \forall i$$

$$\xi_i \geq 0, \quad \forall i$$

where:

- $\mathbf{w}$  is the weight vector.
- $b$  is the bias term.
- $C$  is the regularization parameter that controls the trade-off between maximizing the margin and minimizing the classification error.
- $\xi_i$  are the slack variables that allow for some misclassification.
- $y_i$  are the class labels (+1 or -1).
- $\mathbf{x}_i$  are the feature vectors of the training samples.

### Dual Form

The dual form of the SVM optimization problem can be written as:

Maximize:

$$\sum_{i=1}^n \alpha_i - \frac{1}{2} \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j y_i y_j \mathbf{x}_i \cdot \mathbf{x}_j$$

Subject to:

$$\sum_{i=1}^n \alpha_i y_i = 0$$

$$0 \leq \alpha_i \leq C, \quad \forall i$$

where:

- $\alpha_i$  are the Lagrange multipliers.

$$\min \frac{1}{2} \|\mathbf{w}\|^2 \quad \text{s.t.} \quad y_i(\mathbf{x}_i \cdot \mathbf{w} + b) - 1 \geq 0 \quad \forall_i$$

In order to cater for the constraints in this minimization, we need to allocate them Lagrange multipliers  $\alpha$ , where  $\alpha_i \geq 0 \quad \forall_i$ :

$$\begin{aligned} L_P &\equiv \frac{1}{2} \|\mathbf{w}\|^2 - \alpha [y_i(\mathbf{x}_i \cdot \mathbf{w} + b) - 1 \quad \forall_i] \\ &\equiv \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^L \alpha_i [y_i(\mathbf{x}_i \cdot \mathbf{w} + b) - 1] \\ &\equiv \frac{1}{2} \|\mathbf{w}\|^2 - \sum_{i=1}^L \alpha_i y_i (\mathbf{x}_i \cdot \mathbf{w} + b) + \sum_{i=1}^L \alpha_i \end{aligned}$$

We wish to find the w and b which minimizes, and the  $\alpha$  which maximizes LP(whilst keeping  $\alpha_i \geq 0 \quad \forall i$ ) We can do this by differentiating LP with respect to w and b and setting the derivatives to zero:

$$\frac{\partial L_P}{\partial \mathbf{w}} = 0 \Rightarrow \mathbf{w} = \sum_{i=1}^L \alpha_i y_i \mathbf{x}_i$$

$$\frac{\partial L_P}{\partial b} = 0 \Rightarrow \sum_{i=1}^L \alpha_i y_i = 0$$

## 2. SVM for Regression (Support Vector Regression, SVR)

In the case of SVR, the objective is to find a function  $f(\mathbf{x}) = \mathbf{w} \cdot \mathbf{x} + b$  that deviates from the actual observed values  $y_i$  by at most  $\epsilon$  for all training data points.

### Primal Form

The primal form of the SVR optimization problem can be written as:

Minimize:

$$\frac{1}{2} \|\mathbf{w}\|^2 + C \sum_{i=1}^n (\xi_i + \xi_i^*)$$

Subject to:

$$y_i - (\mathbf{w} \cdot \mathbf{x}_i + b) \leq \epsilon + \xi_i$$

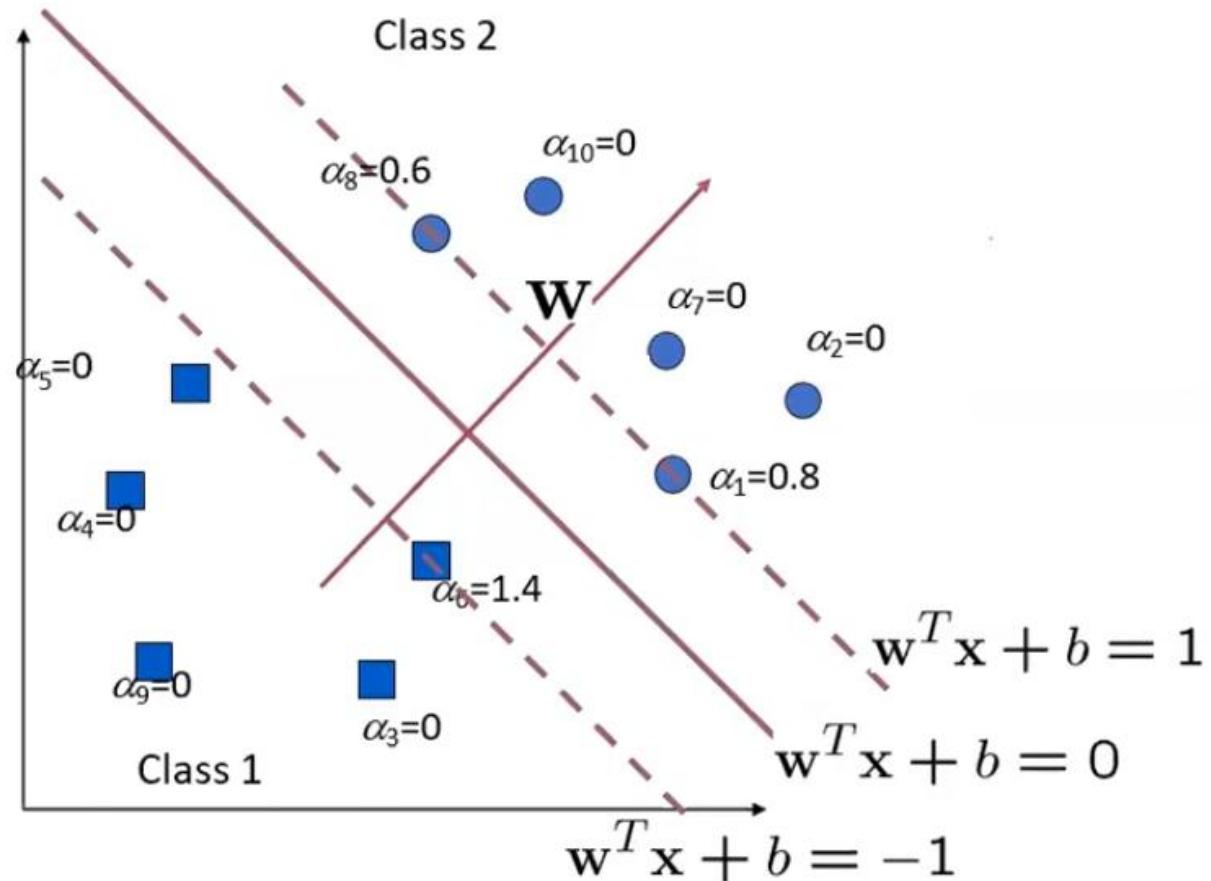
$$(\mathbf{w} \cdot \mathbf{x}_i + b) - y_i \leq \epsilon + \xi_i^*$$

$$\xi_i, \xi_i^* \geq 0, \quad \forall i$$

where:

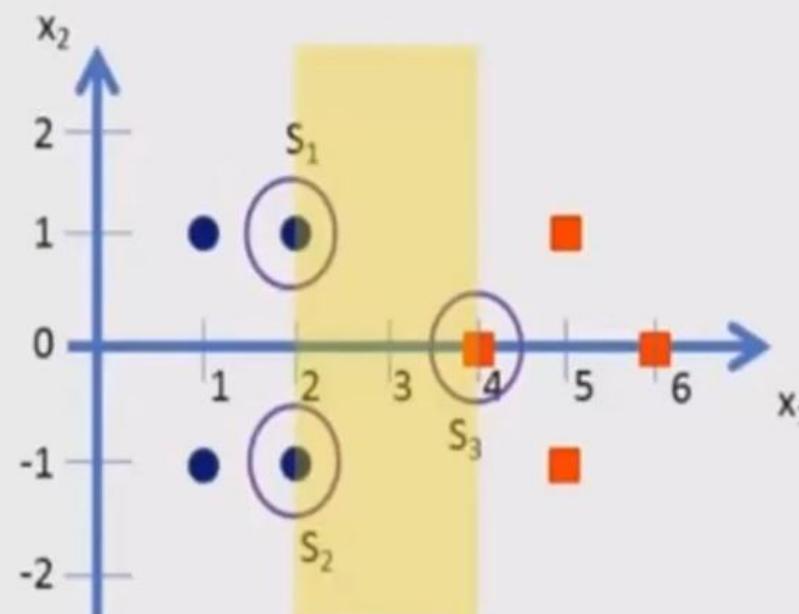
- $\mathbf{w}$  is the weight vector.
- $b$  is the bias term.
- $C$  is the regularization parameter.
- $\xi_i$  and  $\xi_i^*$  are the slack variables that measure the deviations of predictions from the actual values.
- $\epsilon$  is the margin of tolerance.

# A Geometrical Interpretation



# Example

- Here we select 3 Support Vectors to start with.
- They are  $S_1, S_2$  and  $S_3$ .



$$S_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$S_2 = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

$$S_3 = \begin{pmatrix} 4 \\ 0 \end{pmatrix}$$

$$S_1 = \begin{pmatrix} 2 \\ 1 \end{pmatrix}$$

$$S_2 = \begin{pmatrix} 2 \\ -1 \end{pmatrix}$$

$$S_3 = \begin{pmatrix} 4 \\ 0 \end{pmatrix}$$

$$\tilde{S}_1 = \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix}$$

$$\tilde{S}_2 = \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix}$$

$$\tilde{S}_3 = \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix}$$

Now we need to find 3 parameters  $\alpha_1$ ,  $\alpha_2$  and  $\alpha_3$  based on the following 3 linear equations:

$$\alpha_1 \tilde{S}_1 \cdot \tilde{S}_1 + \alpha_2 \tilde{S}_2 \cdot \tilde{S}_1 + \alpha_3 \tilde{S}_3 \cdot \tilde{S}_1 = -1 \text{ } (-ve \text{ class})$$

$$\alpha_1 \tilde{S}_1 \cdot \tilde{S}_2 + \alpha_2 \tilde{S}_2 \cdot \tilde{S}_2 + \alpha_3 \tilde{S}_3 \cdot \tilde{S}_2 = -1 \text{ } (-ve \text{ class})$$

$$\alpha_1 \tilde{S}_1 \cdot \tilde{S}_3 + \alpha_2 \tilde{S}_2 \cdot \tilde{S}_3 + \alpha_3 \tilde{S}_3 \cdot \tilde{S}_3 = +1 \text{ } (+ve \text{ class})$$

Let's substitute the values for  $\tilde{S}_1$ ,  $\tilde{S}_2$  and  $\tilde{S}_3$  in the above equations.

$$\alpha_1 \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} + \alpha_2 \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} + \alpha_3 \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} = -1$$

$$\alpha_1 \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} + \alpha_2 \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} + \alpha_3 \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} = -1$$

$$\alpha_1 \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} + \alpha_2 \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} + \alpha_3 \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} \cdot \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} = +1$$

After simplification we get

$$6\alpha_1 + 4\alpha_2 + 9\alpha_3 = -1$$

$$4\alpha_1 + 6\alpha_2 + 9\alpha_3 = -1$$

$$9\alpha_1 + 9\alpha_2 + 17\alpha_3 = +1$$

Simplifying the above 3 simultaneous equation we get

$$\alpha_1 = -3.25 \quad \alpha_2 = -3.25 \quad \text{and} \quad \alpha_3 = 3.5$$

The hyperplane that discriminates the positive class from negative class is given by:

$$\tilde{w} = \sum_i \alpha_i \tilde{s}_i$$

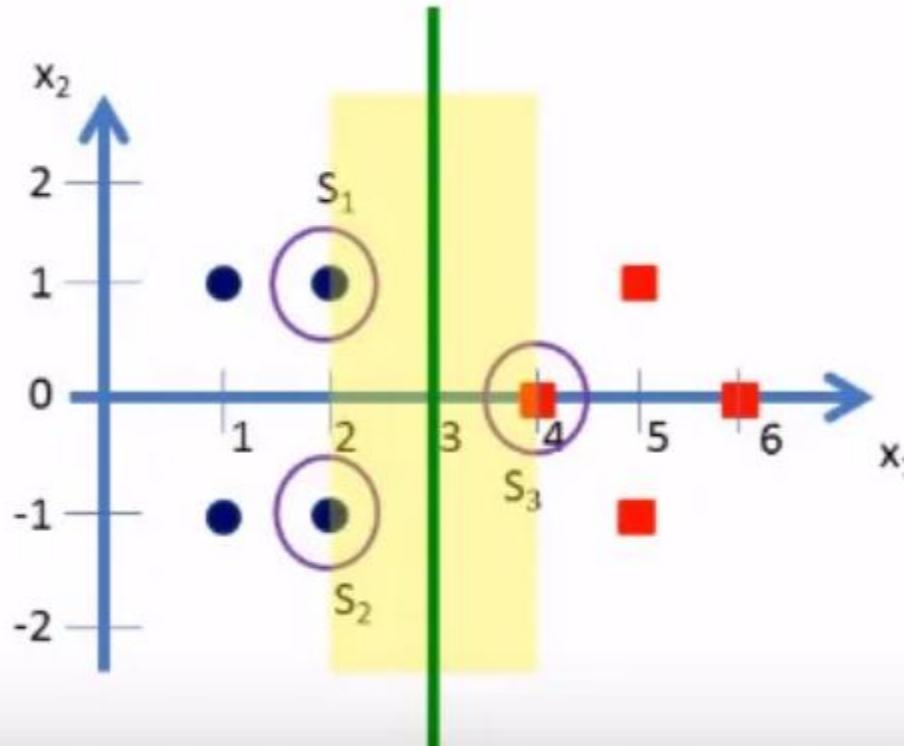
$$\tilde{w} = \alpha_1 \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} + \alpha_2 \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} + \alpha_3 \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix}$$
$$\tilde{w} = (-3.25) \cdot \begin{pmatrix} 2 \\ 1 \\ 1 \end{pmatrix} + (-3.25) \cdot \begin{pmatrix} 2 \\ -1 \\ 1 \end{pmatrix} + (3.5) \cdot \begin{pmatrix} 4 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix}$$

Our Vectors are augmented with a bias.

Hence we can equate the entry in  $\tilde{w}$  as the hyperplane with an offset b.

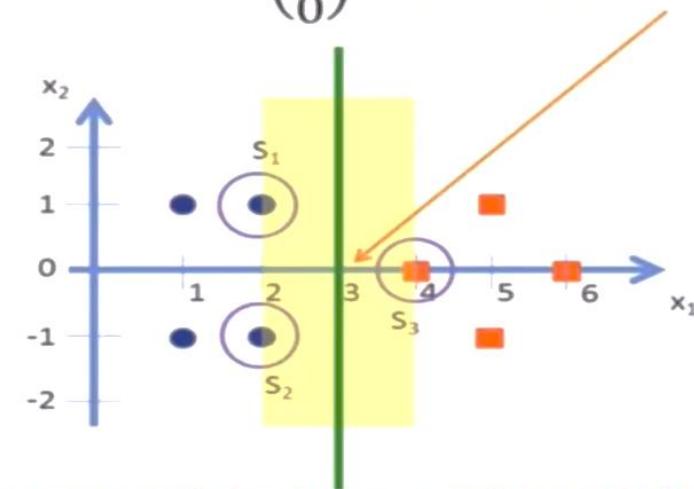
Therefore the separating hyperplane equation

$$y = w \cdot x + b \quad w = \begin{pmatrix} 1 \\ 0 \end{pmatrix} \quad \text{and offset } b = -3$$



## Support Vector Machines

- $y = wx + b$  with  $w = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$  and offset  $b = -3$ .



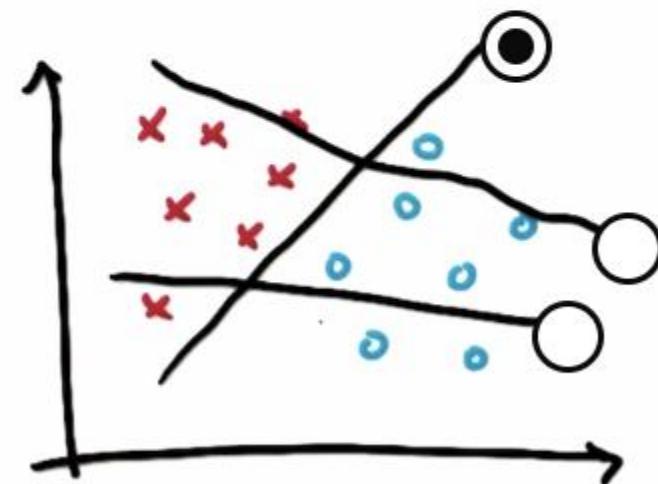
- This is the expected decision surface of the LSVM.

This is the expected decision surface of the LSVM.

## Quiz

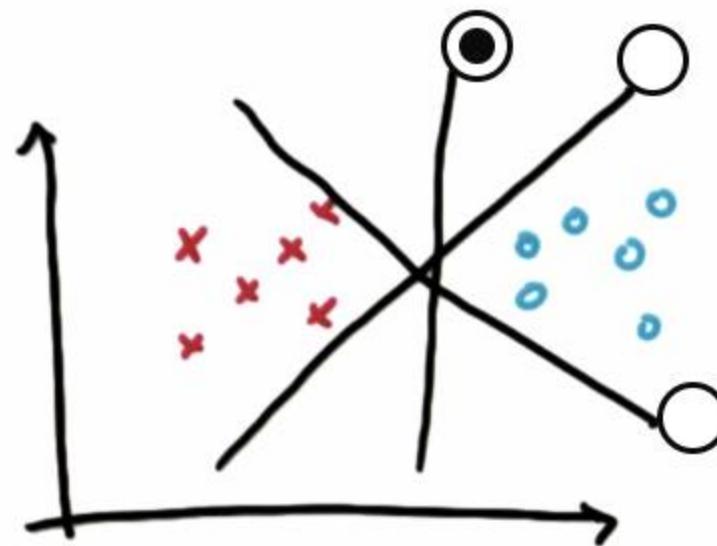
## Separating Line

SUPPORT VECTOR MACHINE



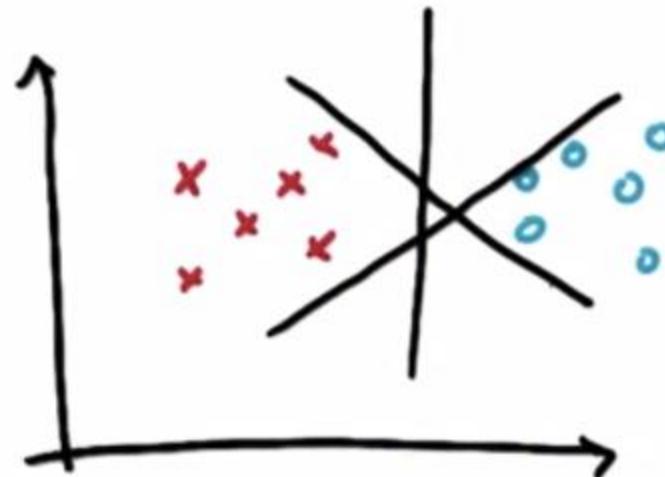
# Choosing Between Separating Lines

SUPPORT VECTOR MACHINE



# What Makes A Good Separating Line

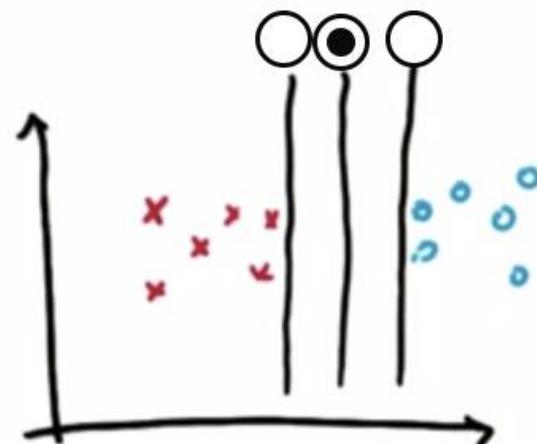
SUPPORT VECTOR MACHINE



- SIMPLE
- RANDOM
- SOMETHING ELSE

## Practice with Margins

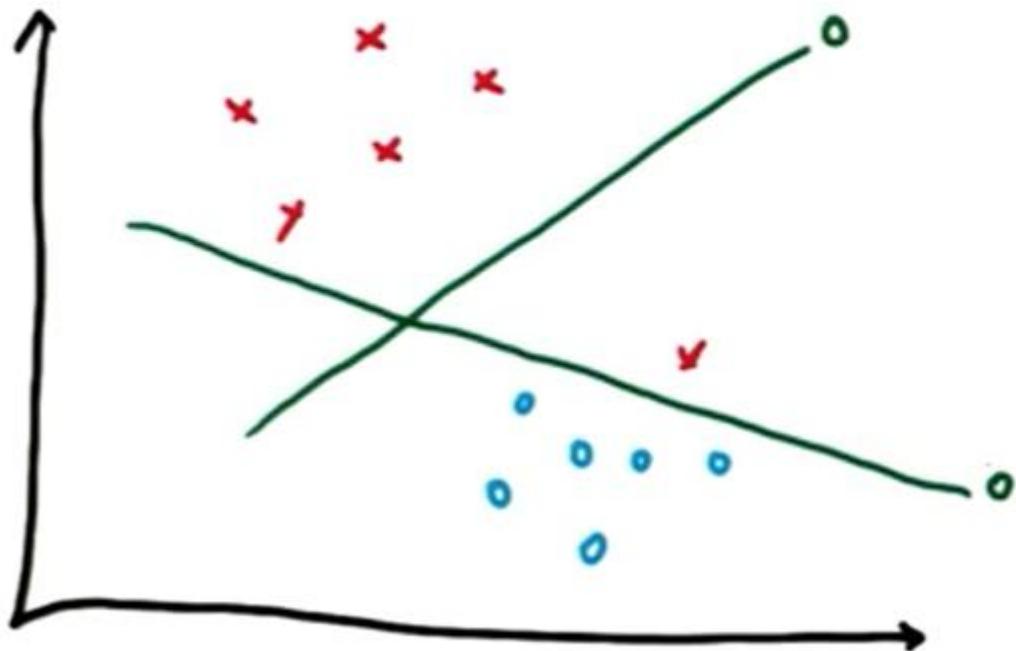
SUPPORT VECTOR MACHINE



MAXIMIZES DISTANCE TO NEAREST POINT  
= MARGIN

Which is the best line

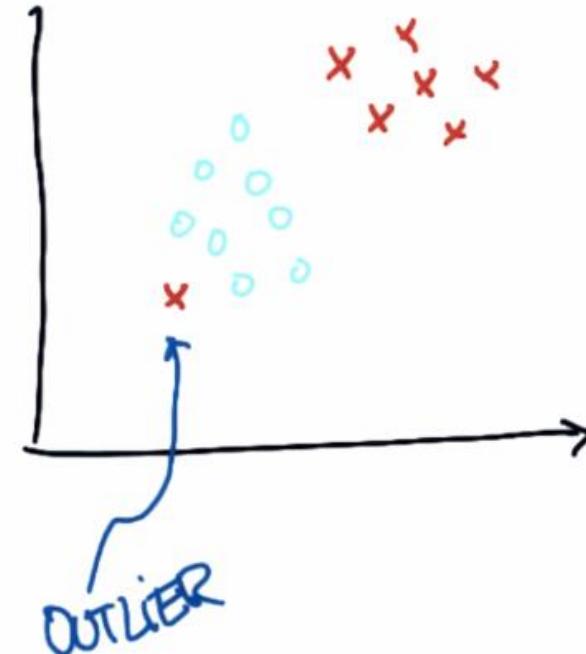
# SUPPORT VECTOR MACHINES



svm puts first and foremost the correct classification of the labels and then maximize the margin so for svm you are trying to classify correctly and subject to that constrain you maximize the margin

## SVM Response to Outliers

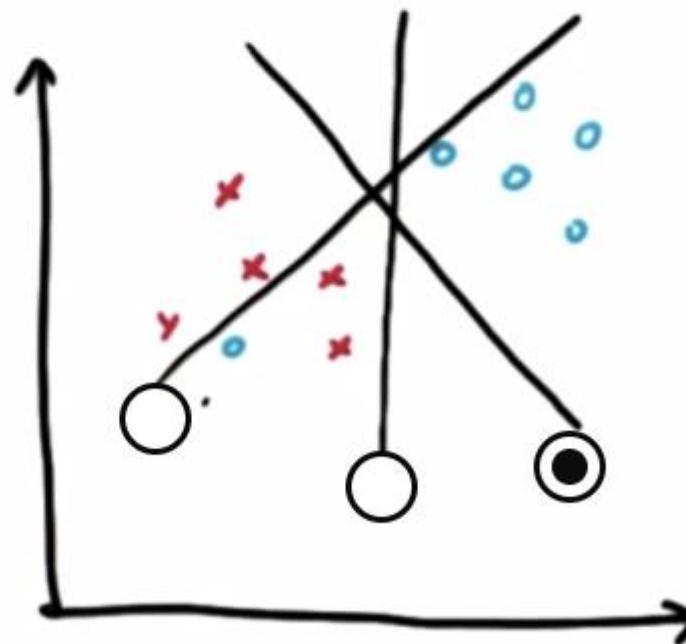
SVMs - OUTLIERS



- GIVE UP
- SAY SOMETHIN'S RANDOM
- DO THE BEST IT CAN

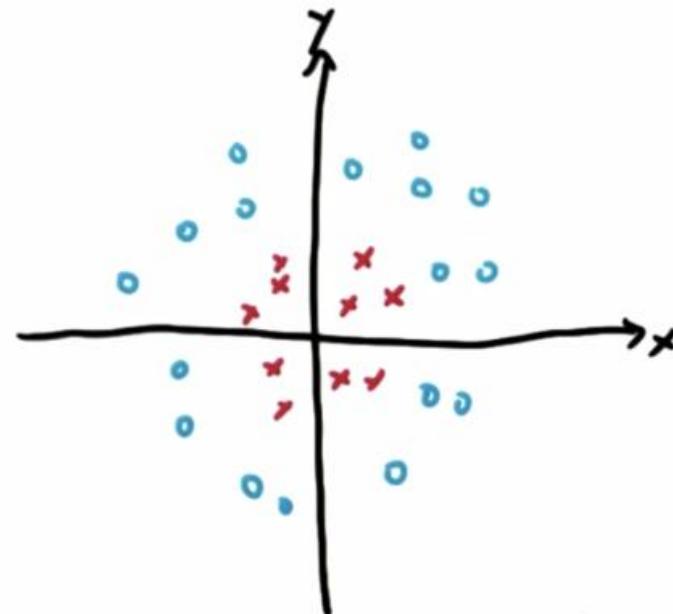
# SVM Outlier Practice

SVMs - OUTLIERS



## Nonlinear Data

SVM

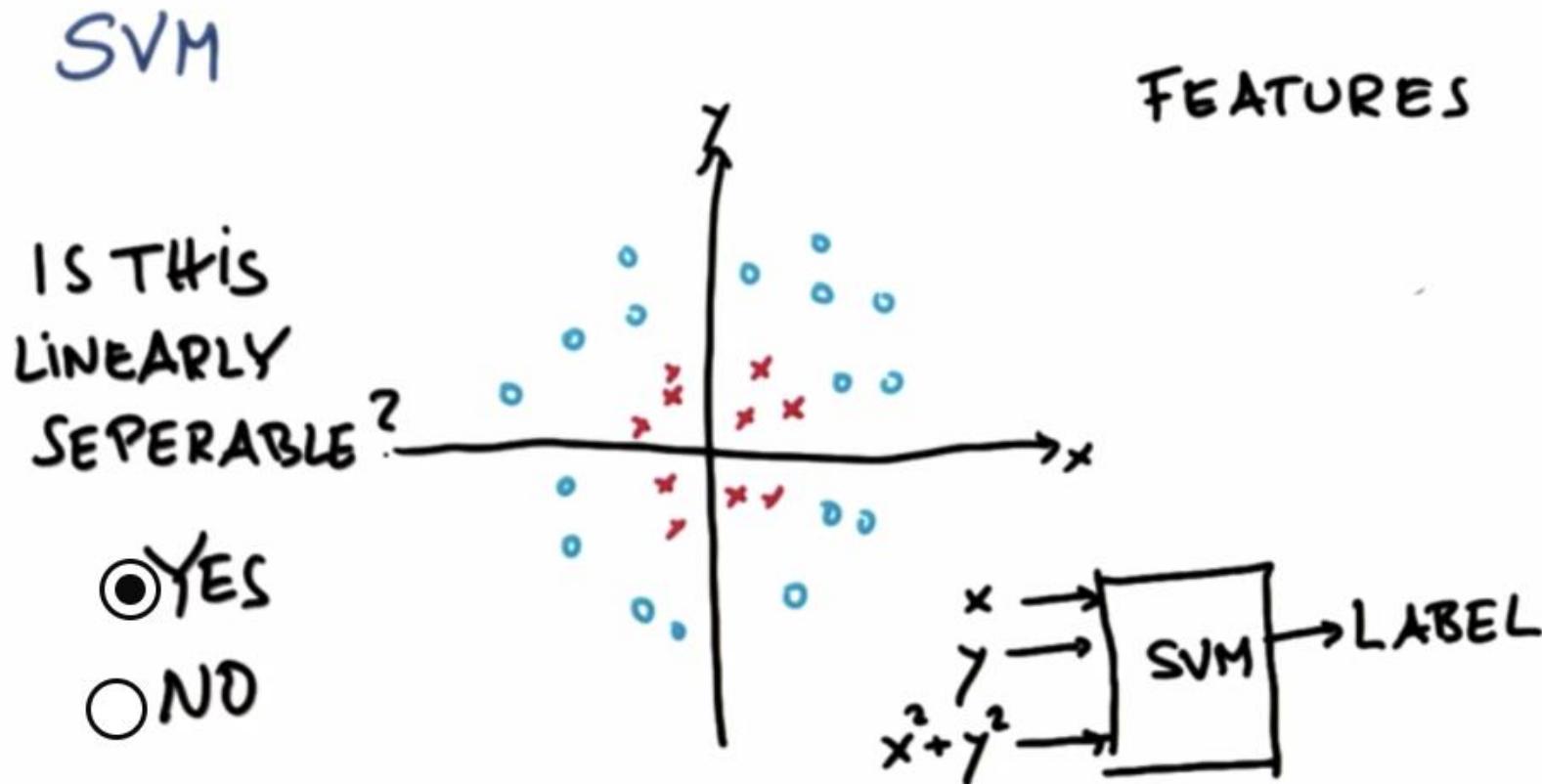


WILL SVMs WORK?

YES

NO

# A New Feature



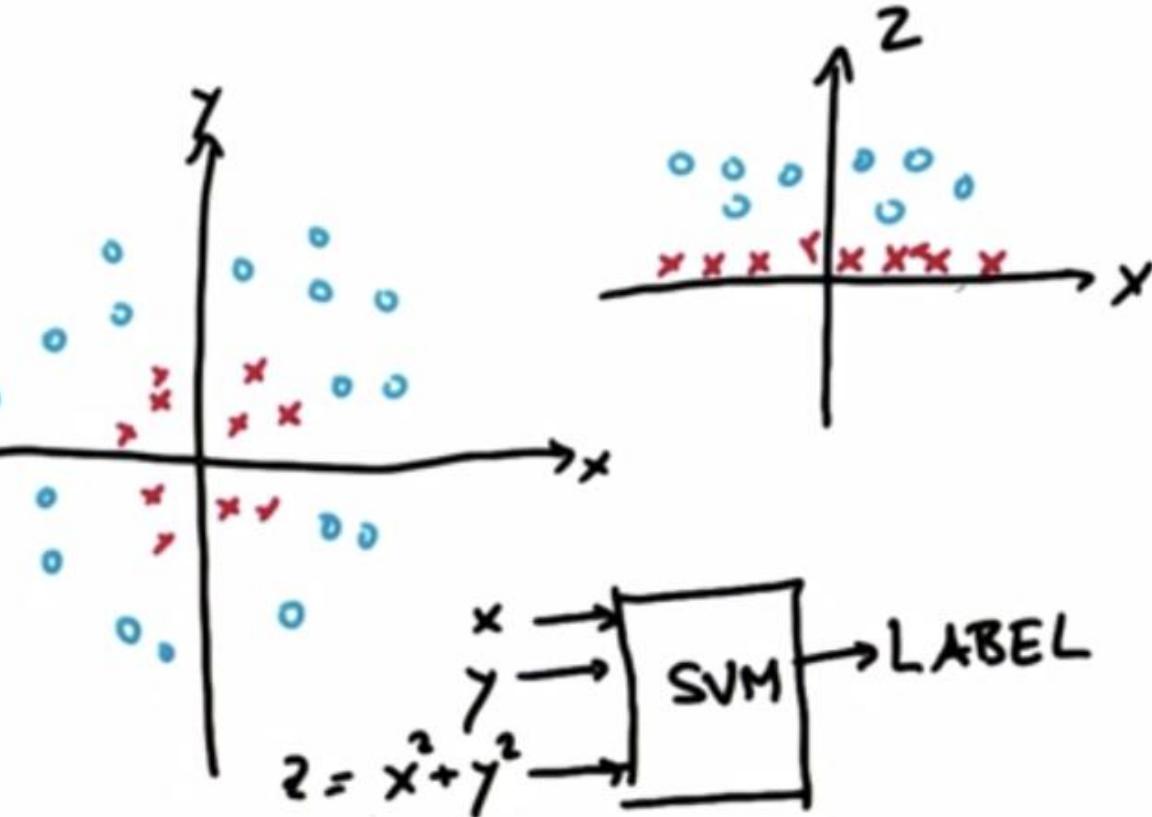
# Separating with the New Feature

SVM

IS THIS  
LINEARLY  
SEPERABLE?

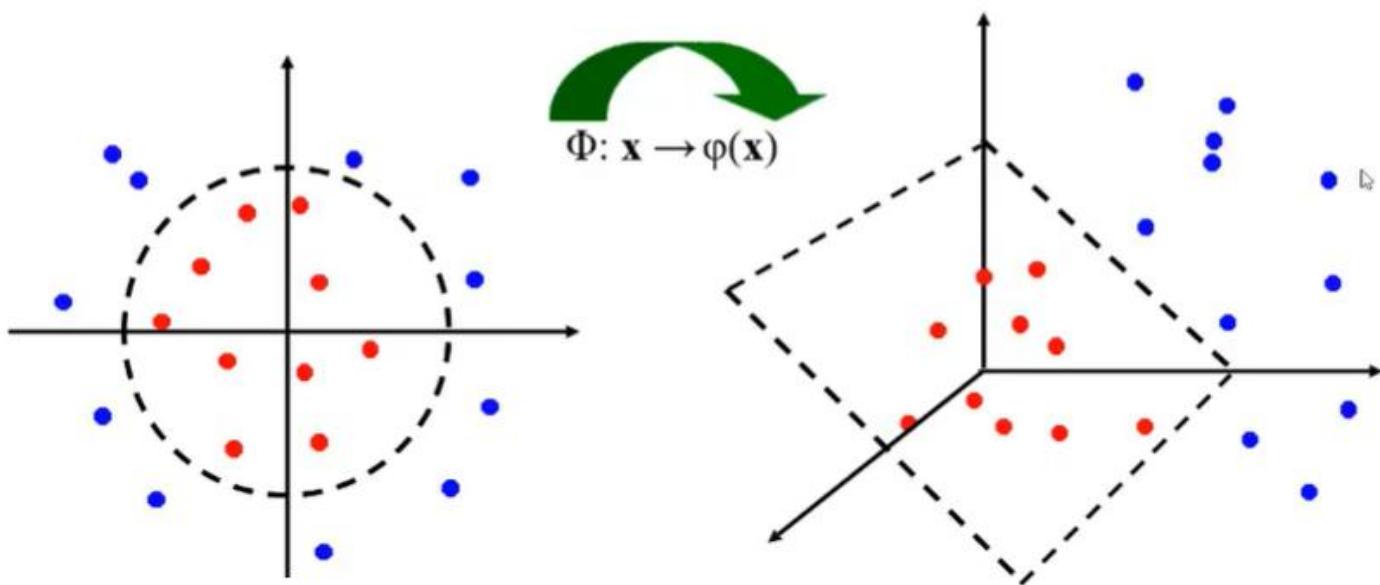
YES

NO

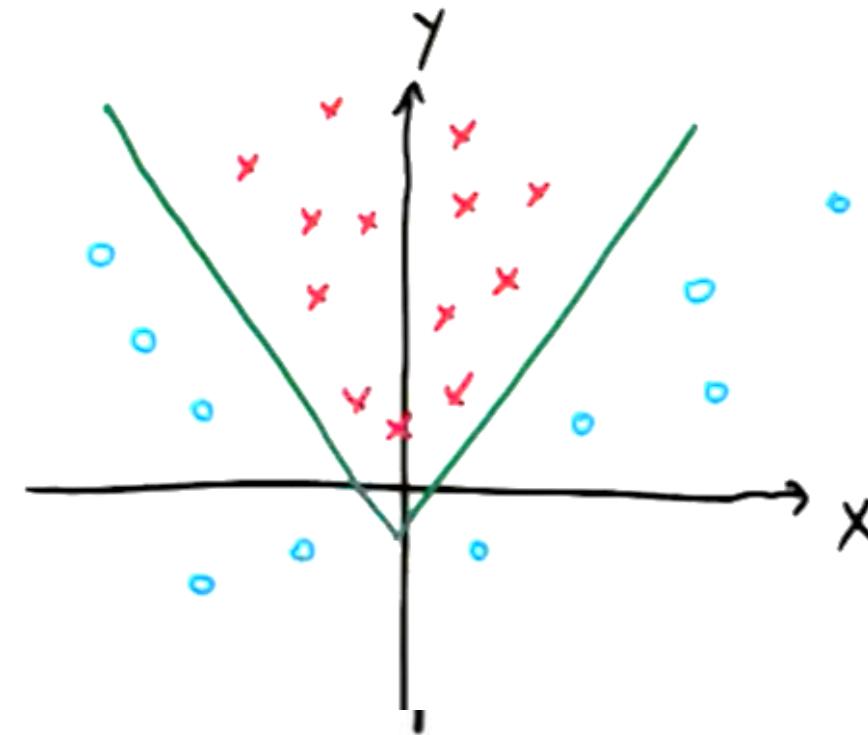


## Non-linear SVMs: Feature spaces

- General idea: the original feature space can always be mapped to some higher-dimensional feature space where the training set is separable:



# Practice Making a New Feature



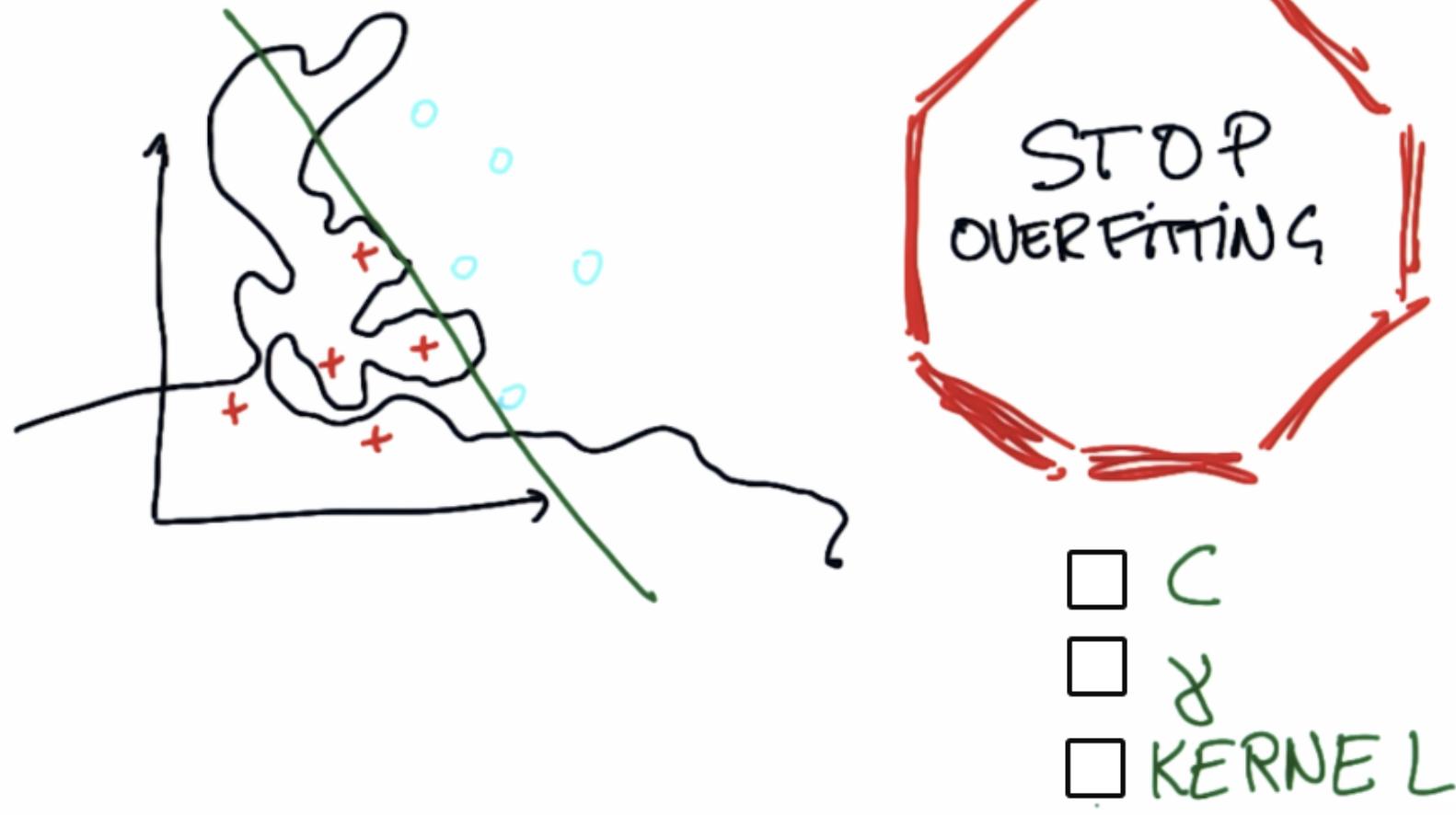
ADD FEATURE<sup>E</sup>

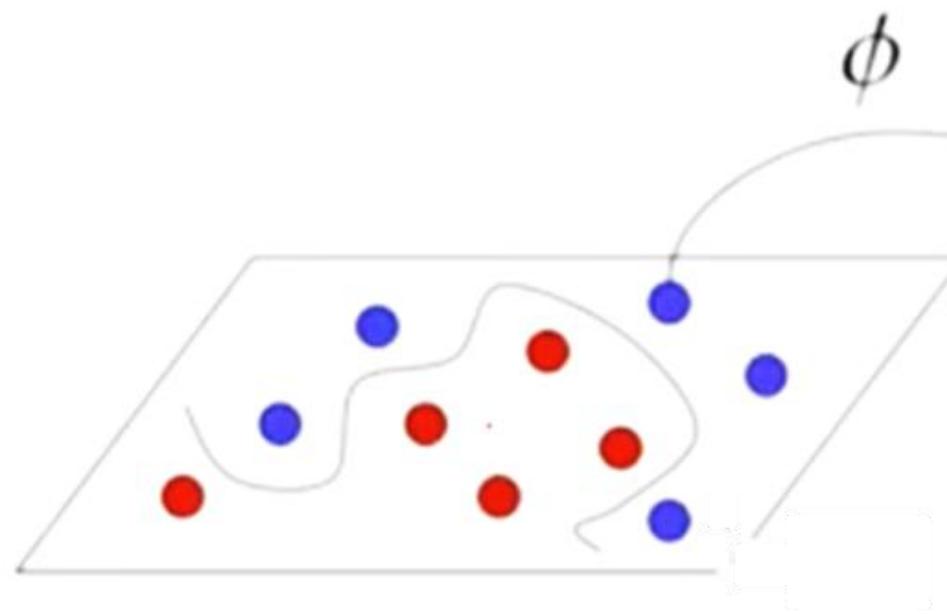
$$\circ x^2 + y^2$$

$$\circ |x|$$

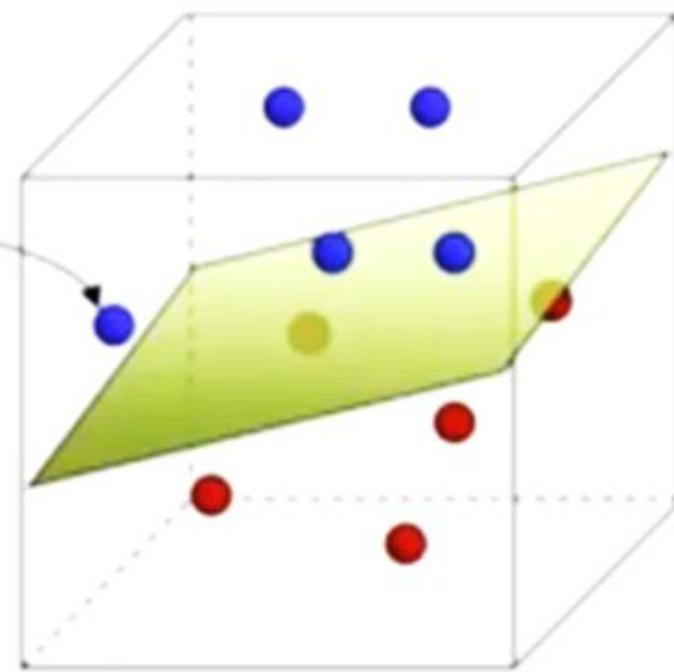
$$\circ |y|$$

# Overfitting



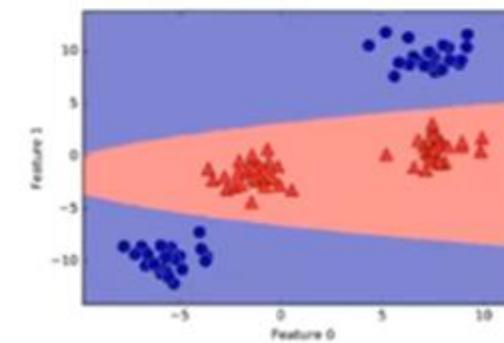
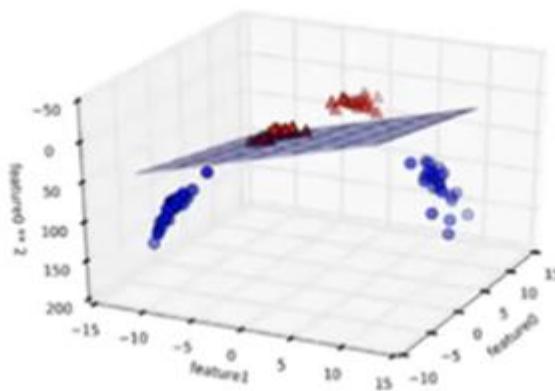
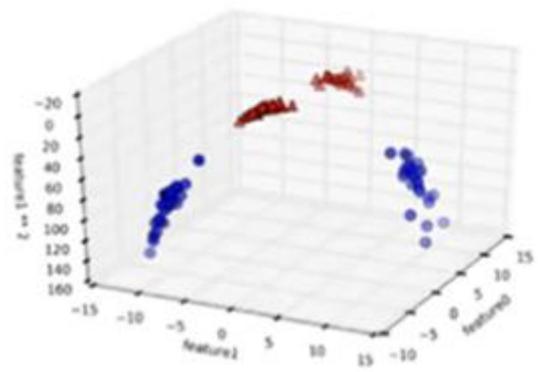
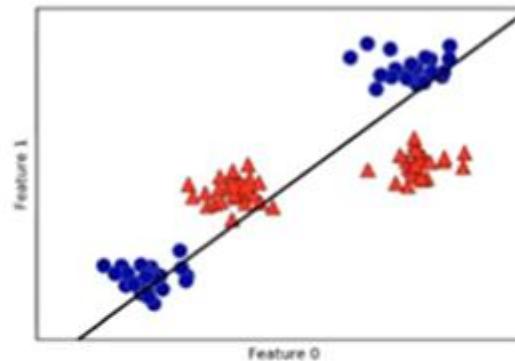
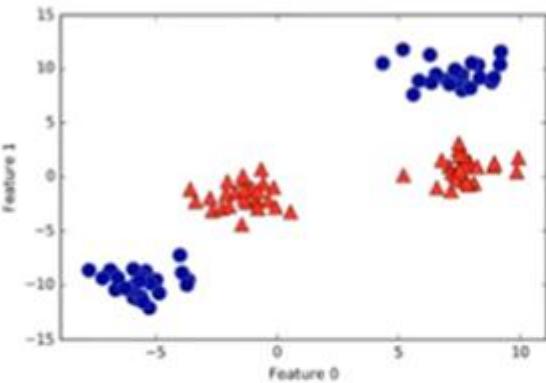


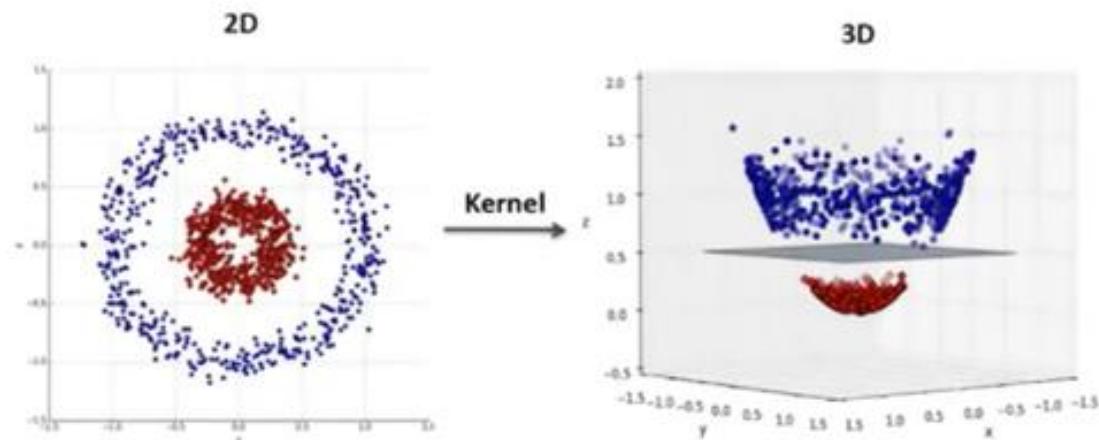
Input Space



Feature Space

# (Applying Kernel Function)





No	Kernel function	Formula	Optimization parameter
1	Dot -product	$K(x_n, x_i) = (x_n, x_i)$	C
2	RBF	$K(x_n, x_i) = \exp(-\gamma \ x_n - x_i\ ^2 + C)$	C and $\gamma$
3	Sigmoid	$K(x_n, x_i) = \tanh(\gamma(x_n, x_i) + r)$	C, $\gamma$ , and r
4	Poly- nomial	$K(x_n, x_i) = (\gamma(x_n, x_i) + r)^d$	C, $\gamma$ , r, d

# Thank You