

ICPC Dhaka Regional C++ Template 2025

```
```cpp
```

```
/******
```

```
* ICPC Dhaka Regional 2025 - Complete C++ Template
```

```
* Created for Team: [YOUR_TEAM_NAME]
```

```
* Target: Solve first 5 problems efficiently
```

```
*****/
```

```
#include <bits/stdc++.h>
```

```
using namespace std;
```

```
// ===== Optimization =====
```

```
#pragma GCC optimize("O3,unroll-loops")
```

```
#pragma GCC target("avx2,bmi,bmi2,lzcnt,popcnt")
```

```
// ===== Macros =====
```

```
#define ll long long
```

```
#define ull unsigned long long
```

```
#define ld long double
```

```
#define endl "\n"
```

```
#define pb push_back
```

```
#define mp make_pair
```

```
#define all(x) (x).begin(), (x).end()
```

```
#define rall(x) (x).rbegin(), (x).rend()
```

```
#define sz(x) (int)(x).size()
```

```
#define ff first
```

```
#define ss second
```

```
// ===== Debug =====
```

```
#ifdef LOCAL
```

```
#define debug(x) cerr << #x << " = " << x << endl
```

```
#define debug_vec(v) cerr << #v << " = "; for(auto &x : v) cerr << x << " "; cerr << endl
```

```
#define debug_pair(p) cerr << #p << " = (" << p.ff << ", " << p.ss << ")" << endl
```

```
#else
```

```
#define debug(x)
```

```
#define debug_vec(v)
```

```
#define debug_pair(p)
```

```
#endif
```

```
// ===== Fast I/O =====
```

```
inline void fastIO() {
```

```
 ios_base::sync_with_stdio(false);
```

```
 cin.tie(nullptr);
```

```

 cout.tie(nullptr);
}

// ===== Math Functions =====
ll gcd(ll a, ll b) { return b == 0 ? a : gcd(b, a % b); }
ll lcm(ll a, ll b) { return a / gcd(a, b) * b; }

ll mod_pow(ll base, ll exp, ll mod) {
 ll result = 1;
 while(exp > 0) {
 if(exp & 1) result = (result * base) % mod;
 base = (base * base) % mod;
 exp >>= 1;
 }
 return result;
}

ll mod_inv(ll a, ll mod) {
 return mod_pow(a, mod - 2, mod);
}

vector<int> sieve(int n) {
 vector<bool> isPrime(n+1, true);
 vector<int> primes;
 isPrime[0] = isPrime[1] = false;
 for(int i = 2; i <= n; i++) {
 if(isPrime[i]) {
 primes.pb(i);
 for(int j = i*i; j <= n; j += i) {
 isPrime[j] = false;
 }
 }
 }
 return primes;
}

vector<pair<ll, int>> prime_factorization(ll n) {
 vector<pair<ll, int>> factors;
 for(ll i = 2; i * i <= n; i++) {
 if(n % i == 0) {
 int cnt = 0;
 while(n % i == 0) {
 n /= i;
 cnt++;
 }
 }
 }
}

```

```

 }
 factors.pb({i, cnt});
 }
}
if(n > 1) factors.pb({n, 1});
return factors;
}

// ===== Combinatorics =====
const int MOD = 1e9 + 7;
const int MAX_N = 1e6 + 5;

vector<ll> fact(MAX_N), inv_fact(MAX_N);

void precompute_factorials() {
 fact[0] = 1;
 for(int i = 1; i < MAX_N; i++) {
 fact[i] = (fact[i-1] * i) % MOD;
 }
 inv_fact[MAX_N-1] = mod_inv(fact[MAX_N-1], MOD);
 for(int i = MAX_N-2; i >= 0; i--) {
 inv_fact[i] = (inv_fact[i+1] * (i+1)) % MOD;
 }
}

ll nCr(int n, int r) {
 if(r < 0 || r > n) return 0;
 return (fact[n] * inv_fact[r] % MOD) * inv_fact[n-r] % MOD;
}

ll nPr(int n, int r) {
 if(r < 0 || r > n) return 0;
 return fact[n] * inv_fact[n-r] % MOD;
}

// ===== Graph Algorithms =====
struct Graph {
 int n;
 vector<vector<int>> adj;

 Graph(int nodes) {
 n = nodes;
 adj.resize(n+1);
 }
}

```

```

void add_edge(int u, int v, bool directed = false) {
 adj[u].pb(v);
 if(!directed) adj[v].pb(u);
}
};

```

```

vector<int> bfs(int start, const vector<vector<int>> &adj) {
 int n = adj.size();
 vector<int> dist(n, -1);
 queue<int> q;
 q.push(start);
 dist[start] = 0;

 while(!q.empty()) {
 int u = q.front(); q.pop();
 for(int v : adj[u]) {
 if(dist[v] == -1) {
 dist[v] = dist[u] + 1;
 q.push(v);
 }
 }
 }
 return dist;
}

```

```

vector<int> topological_sort(const vector<vector<int>> &adj) {
 int n = adj.size();
 vector<int> in_degree(n, 0), topo;

 for(int u = 0; u < n; u++) {
 for(int v : adj[u]) {
 in_degree[v]++;
 }
 }

 queue<int> q;
 for(int i = 0; i < n; i++) {
 if(in_degree[i] == 0) q.push(i);
 }

 while(!q.empty()) {
 int u = q.front(); q.pop();
 topo.pb(u);
 }
}

```

```

 for(int v : adj[u]) {
 in_degree[v]--;
 if(in_degree[v] == 0) q.push(v);
 }
 }

 if(topo.size() != n) return {}; // cycle exists
 return topo;
}

// Dijkstra's Algorithm
vector<ll> dijkstra(int start, vector<vector<pair<int, ll>>> &adj) {
 int n = adj.size();
 vector<ll> dist(n, LLONG_MAX);
 priority_queue<pair<ll, int>, vector<pair<ll, int>>, greater<pair<ll, int>>> pq;

 dist[start] = 0;
 pq.push({0, start});

 while(!pq.empty()) {
 auto [d, u] = pq.top(); pq.pop();
 if(d > dist[u]) continue;

 for(auto &[v, w] : adj[u]) {
 if(dist[u] + w < dist[v]) {
 dist[v] = dist[u] + w;
 pq.push({dist[v], v});
 }
 }
 }
 return dist;
}

// ===== DSU (Union-Find) =====
struct DSU {
 vector<int> parent, size;

 DSU(int n) {
 parent.resize(n+1);
 size.resize(n+1, 1);
 for(int i = 0; i <= n; i++) parent[i] = i;
 }

 int find(int x) {

```

```

 if(parent[x] != x) parent[x] = find(parent[x]);
 return parent[x];
}

bool unite(int x, int y) {
 x = find(x); y = find(y);
 if(x == y) return false;
 if(size[x] < size[y]) swap(x, y);
 parent[y] = x;
 size[x] += size[y];
 return true;
}

bool same(int x, int y) {
 return find(x) == find(y);
}
};

// ===== Segment Tree =====
struct SegmentTree {
 int n;
 vector<ll> tree, lazy;

 SegmentTree(const vector<ll> &arr) {
 n = arr.size();
 tree.resize(4*n);
 lazy.resize(4*n, 0);
 build(1, 0, n-1, arr);
 }

 void build(int node, int l, int r, const vector<ll> &arr) {
 if(l == r) {
 tree[node] = arr[l];
 return;
 }
 int mid = (l + r) / 2;
 build(node*2, l, mid, arr);
 build(node*2+1, mid+1, r, arr);
 tree[node] = tree[node*2] + tree[node*2+1];
 }

 void update_range(int node, int l, int r, int ql, int qr, ll val) {
 if(lazy[node] != 0) {
 tree[node] += (r - l + 1) * lazy[node];

```

```

 if(l != r) {
 lazy[node*2] += lazy[node];
 lazy[node*2+1] += lazy[node];
 }
 lazy[node] = 0;
}

if(r < ql || l > qr) return;
if(ql <= l && r <= qr) {
 tree[node] += (r - l + 1) * val;
 if(l != r) {
 lazy[node*2] += val;
 lazy[node*2+1] += val;
 }
 return;
}

int mid = (l + r) / 2;
update_range(node*2, l, mid, ql, qr, val);
update_range(node*2+1, mid+1, r, ql, qr, val);
tree[node] = tree[node*2] + tree[node*2+1];
}

ll query_range(int node, int l, int r, int ql, int qr) {
 if(lazy[node] != 0) {
 tree[node] += (r - l + 1) * lazy[node];
 if(l != r) {
 lazy[node*2] += lazy[node];
 lazy[node*2+1] += lazy[node];
 }
 lazy[node] = 0;
 }

 if(r < ql || l > qr) return 0;
 if(ql <= l && r <= qr) return tree[node];

 int mid = (l + r) / 2;
 return query_range(node*2, l, mid, ql, qr) +
 query_range(node*2+1, mid+1, r, ql, qr);
}

// Helper functions
void update(int l, int r, ll val) { update_range(1, 0, n-1, l, r, val); }
ll query(int l, int r) { return query_range(1, 0, n-1, l, r); }

```

```

};

// ===== Fenwick Tree =====
struct FenwickTree {
 int n;
 vector<ll> bit;

 FenwickTree(int size) {
 n = size;
 bit.resize(n+1, 0);
 }

 void update(int idx, ll delta) {
 for(; idx <= n; idx += idx & -idx) {
 bit[idx] += delta;
 }
 }

 ll query(int idx) {
 ll sum = 0;
 for(; idx > 0; idx -= idx & -idx) {
 sum += bit[idx];
 }
 return sum;
 }

 ll range_query(int l, int r) {
 return query(r) - query(l-1);
 }
};

// ===== Geometry =====
struct Point {
 ll x, y;
 Point() : x(0), y(0) {}
 Point(ll _x, ll _y) : x(_x), y(_y) {}

 bool operator<(const Point &other) const {
 return tie(x, y) < tie(other.x, other.y);
 }

 Point operator-(const Point &other) const {
 return Point(x - other.x, y - other.y);
 }
}

```



```
};
```

```
ll cross(const Point &a, const Point &b) {
 return a.x * b.y - a.y * b.x;
}
```

```
ll dot(const Point &a, const Point &b) {
 return a.x * b.x + a.y * b.y;
}
```

```
ll orientation(const Point &a, const Point &b, const Point &c) {
 ll val = cross(b - a, c - a);
 if(val == 0) return 0; // collinear
 return (val > 0) ? 1 : -1; // clockwise or counterclockwise
}
```

```
vector<Point> convex_hull(vector<Point> points) {
 int n = points.size();
 if(n <= 1) return points;
```

```
 sort(all(points));
 vector<Point> hull;
```

```
 // Lower hull
```

```
 for(int i = 0; i < n; i++) {
 while(hull.size() >= 2 &&
 orientation(hull[hull.size()-2], hull.back(), points[i]) <= 0) {
 hull.pop_back();
 }
 hull.pb(points[i]);
 }
```

```
 // Upper hull
```

```
 int lower_size = hull.size();
 for(int i = n-2; i >= 0; i--) {
 while(hull.size() > lower_size &&
 orientation(hull[hull.size()-2], hull.back(), points[i]) <= 0) {
 hull.pop_back();
 }
 hull.pb(points[i]);
 }
```

```
 hull.pop_back(); // Remove duplicate starting point
 return hull;
```

```
}
```

```
// ===== String Algorithms =====
```

```
vector<int> kmp(const string &s) {
 int n = s.size();
 vector<int> lps(n, 0);
 for(int i = 1; i < n; i++) {
 int j = lps[i-1];
 while(j > 0 && s[i] != s[j]) j = lps[j-1];
 if(s[i] == s[j]) j++;
 lps[i] = j;
 }
 return lps;
}
```

```
vector<int> z_algorithm(const string &s) {
 int n = s.size();
 vector<int> z(n, 0);
 int l = 0, r = 0;
 for(int i = 1; i < n; i++) {
 if(i <= r) z[i] = min(r-i+1, z[i-l]);
 while(i+z[i] < n && s[z[i]] == s[i+z[i]]) z[i]++;
 if(i+z[i]-1 > r) {
 l = i;
 r = i + z[i] - 1;
 }
 }
 return z;
}
```

```
// ===== Game Theory =====
```

```
int mex(unordered_set<int> &s) {
 int m = 0;
 while(s.count(m)) m++;
 return m;
}
```

```
// ===== Useful Functions =====
```

```
bool is_palindrome(const string &s) {
 int n = s.size();
 for(int i = 0; i < n/2; i++) {
 if(s[i] != s[n-i-1]) return false;
 }
 return true;
}
```

```

}

template<typename T>
void print_vector(const vector<T> &v, bool spaces = true) {
 for(const auto &x : v) {
 cout << x;
 if(spaces) cout << " ";
 }
 if(spaces) cout << endl;
}

// ===== Main Solve Function =====
void solve() {
 // Your solution here
 int n;
 cin >> n;
 vector<int> arr(n);
 for(int i = 0; i < n; i++) cin >> arr[i];

 // Example: Find sum
 ll sum = accumulate(all(arr), 0LL);
 cout << sum << endl;
}

// ===== Main Function =====
int main() {
 fastIO();

 // Precompute factorials if needed
 // precompute_factorials();

 #ifdef LOCAL
 freopen("input.txt", "r", stdin);
 freopen("output.txt", "w", stdout);
 freopen("error.txt", "w", stderr);
 #endif

 int t = 1;
 cin >> t; // Comment if single test case
 for(int tc = 1; tc <= t; tc++) {
 // cout << "Case " << tc << ": ";
 solve();
 }
}

```

```

#ifdef LOCAL
cerr << "Time elapsed: " << 1.0 * clock() / CLOCKS_PER_SEC << " seconds" << endl;
#endif

return 0;
}

// ===== Additional Templates =====
/*
// Matrix Exponentiation
struct Matrix {
 int n, m;
 vector<vector<ll>> mat;

 Matrix(int _n, int _m) : n(_n), m(_m), mat(_n, vector<ll>(_m, 0)) {}

 Matrix operator*(const Matrix &other) const {
 Matrix result(n, other.m);
 for(int i = 0; i < n; i++) {
 for(int j = 0; j < other.m; j++) {
 for(int k = 0; k < m; k++) {
 result.mat[i][j] = (result.mat[i][j] + mat[i][k] * other.mat[k][j]) % MOD;
 }
 }
 }
 return result;
 }
};

Matrix mat_pow(Matrix base, ll exp) {
 Matrix result(base.n, base.n);
 for(int i = 0; i < base.n; i++) result.mat[i][i] = 1;

 while(exp > 0) {
 if(exp & 1) result = result * base;
 base = base * base;
 exp >>= 1;
 }
 return result;
}
*/

// ===== Template Usage Tips =====
/*

```

1. For problems A-B: Use simple implementations
2. For problem C: Use BFS/DFS or basic DP
3. For problem D: Use Segment Tree or Number Theory
4. For problem E: Use advanced DS or Graph algorithms

Always check constraints first!

Time Complexity Estimation:

- $n \leq 10^5$ :  $O(n \log n)$  usually safe
- $n \leq 10^3$ :  $O(n^2)$  usually safe
- $n \leq 20$ :  $O(2^n)$  may work

\*/

...

## \*\*📦 টেমপ্লেটে যা যা আছে:\*\*

### \*\*1. বেসিক অপটিমাইজেশন\*\*

- Fast I/O
- GCC optimization pragmas

### \*\*2. গাণিতিক ফাংশন\*\*

- GCD, LCM
- Modular exponentiation
- Sieve of Eratosthenes
- Prime factorization

### \*\*3. কম্বিনেটরিক্স\*\*

- $nCr$ ,  $nPr$  modulo  $1e9+7$
- Precomputed factorials

### \*\*4. গ্রাফ অ্যালগরিদম\*\*

- BFS, DFS
- Topological Sort
- Dijkstra's Algorithm
- DSU (Union-Find)

### \*\*5. ডেটা স্ট্রাকচার\*\*

- Segment Tree (with lazy propagation)
- Fenwick Tree (Binary Indexed Tree)

### \*\*6. জ্যামিতি\*\*

- Point operations
- Convex Hull
- Cross and Dot products

#### \*\*7. স্ট্রিং অ্যালগরিদম\*\*

- KMP (prefix function)
- Z-algorithm

#### \*\*8. গেম থিওরি\*\*

- MEX function

## \*\*🚀 ব্যবহারের উপায়:\*\*

1. \*\*কোডটাকে `template.cpp` নামে সেভ করুন\*\*
2. \*\*প্রতিটি কনটেস্টের আগে কপি করুন\*\*
3. \*\*প্রয়োজনমতো ফাংশন কল করুন\*\*
4. \*\*solve() ফাংশনে আপনার সমাধান লিখুন\*\*

## \*\*📌 গুরুত্বপূর্ণ নোট:\*\*

1. \*\*ঢাকা রিজিওনালে সাধারণত 256MB মেমোরি\*\* limit থাকে
2. \*\*স্ট্যাক সাইজ\*\* বাড়াতে `-Wl,--stack,268435456` flag ব্যবহার করুন
3. \*\*লোকাল টেস্টিং\*\* এর জন্য LOCAL define ব্যবহার করুন
4. \*\*Big Integer\*\* লাগলে Python ব্যবহার করুন

## \*\*💡 সমস্যা টাইপ অনুযায়ী কোন টেমপ্লেট ব্যবহার করবেন:\*\*

- \*\*Problem A/B:\*\* Basic math, sorting, implementation
- \*\*Problem C:\*\* Graph (BFS/DFS), simple DP
- \*\*Problem D:\*\* Segment Tree, Number Theory
- \*\*Problem E:\*\* Advanced Graph, Geometry, Game Theory

\*\*শুভকামনা!\*\* 🏆 ঢাকা রিজিওনাল ২০২৫-এ সাফল্য কামনা করছি!