

# Data analysis and Unsupervised Learning

## Dimensionality Reduction: PCA

MAP 573, 2020 – Julien Chiquet

École Polytechnique, Autumn semester, 2020

<https://jchiquet.github.io/MAP573>



# Part I

## Introduction

### Packages required for reproducing the slides

```
library(tidyverse) # opinionated collection of packages for data manipulation
library(GGally)    # extension to ggplot vizualization system
library(FactoMineR) # PCA and oter linear method for dimension reduction
library(factoextra) # fancy plotting for FactoMineR output
# color and plots themes
library(RColorBrewer)
pal <- brewer.pal(10, "Set3")
theme_set(theme_bw())
```

# Dimension Reduction?



Figure: source: F. Belardi

- How to view a high-dimensional dataset ?
- High-dimension: dimension larger than 2!
- *Projection* in a 2D space.

# Dimension Reduction?

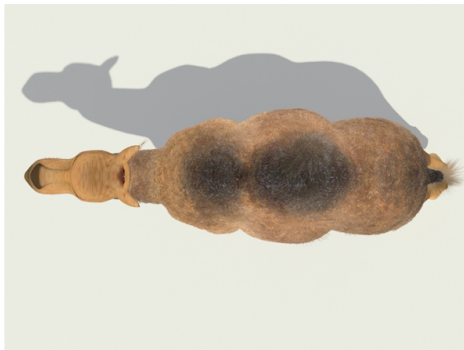


Figure: source: F. Belardi

- How to view a high-dimensional dataset ?
- High-dimension: dimension larger than 2!
- *Projection* in a 2D space.

# Dimension Reduction?



Figure: source: F. Belardi

- How to view a high-dimensional dataset ?
- High-dimension: dimension larger than 2!
- *Projection* in a 2D space.

# Companion data set: 'crabs'

## Morphological Measurements on Leptograpsus Crabs

**Description:** *small data, low-dimensional*

The crabs data frame has 200 rows and 8 columns, describing 5 morphological measurements on 50 crabs each of two colour forms and both sexes, of the species *Leptograpsus variegatus* collected at Fremantle, W. Australia.



**Figure:** A leptograpsus Crab

# Companion data set: 'crabs' I

## Table header

```
crabs <- MASS::crabs %>% select(-index) %>%  
  rename(sex = sex,  
         species = sp,  
         frontal_lob = FL,  
         rear_width = RW,  
         carapace_length = CL,  
         carapace_width = CW,  
         body_depth = BD)  
crabs %>% select(sex, species) %>% summary() %>% knitr::kable("latex")
```

	sex	species
	F:100	B:100
	M:100	O:100

```
dim(crabs)
```

```
## [1] 200 7
```

# Companion data set: 'crabs' II

## Table header

```
crabs %>% head(15) %>% knitr::kable("latex")
```

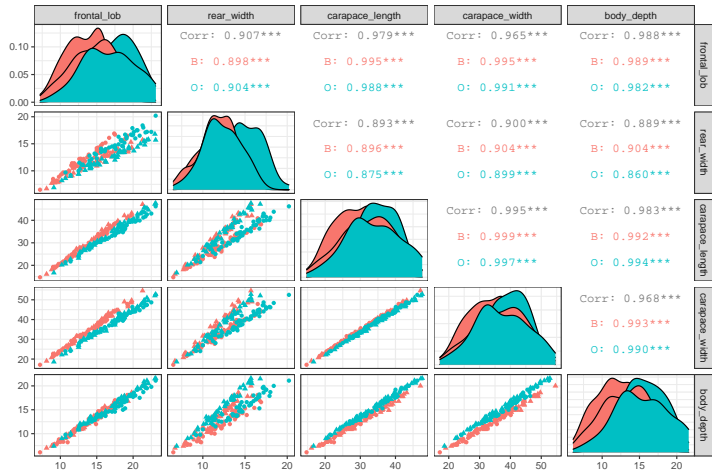
species	sex	frontal_lob	rear_width	carapace_length	carapace_width	body_depth
B	M	8.1	6.7	16.1	19.0	7.0
B	M	8.8	7.7	18.1	20.8	7.4
B	M	9.2	7.8	19.0	22.4	7.7
B	M	9.6	7.9	20.1	23.1	8.2
B	M	9.8	8.0	20.3	23.0	8.2
B	M	10.8	9.0	23.0	26.5	9.8
B	M	11.1	9.9	23.8	27.1	9.8
B	M	11.6	9.1	24.5	28.4	10.4
B	M	11.8	9.6	24.2	27.8	9.7
B	M	11.8	10.5	25.2	29.3	10.3
B	M	12.2	10.8	27.3	31.6	10.9
B	M	12.3	11.0	26.8	31.5	11.4
B	M	12.6	10.0	27.7	31.7	11.4
B	M	12.8	10.2	27.2	31.8	10.9
B	M	12.8	10.9	27.4	31.5	11.0



# Companion data set: 'crabs'

Pairs plot of attributes

```
ggpairs(crabs, columns = 3:7, aes(colour = species, shape = sex))
```



⇒ Pairs plot don't help...

# Companion data set: 'crabs'

## Correlation matrix

```
crabs %>% select(-species, -sex) %>% cor( ) %>% kable('latex', digits = 3)
```

	frontal_lob	rear_width	carapace_length	carapace_width	body_depth
frontal_lob	1.000	0.907	0.979	0.965	0.988
rear_width	0.907	1.000	0.893	0.900	0.889
carapace_length	0.979	0.893	1.000	0.995	0.983
carapace_width	0.965	0.900	0.995	1.000	0.968
body_depth	0.988	0.889	0.983	0.968	1.000

## Very high correlation!

- much redundancy?
- hidden factor?

~> dimension reduction might help

# Another example: 'snp'

Genetics variant in European population

Description: *medium/large data, high-dimensional*

500, 000 Genetics variants (SNP – Single Nucleotide Polymorphism) for 3000 individuals (1 meter  $\times$  166 meter (height  $\times$  width))

- SNP : 90 % of human genetic variations
- coded as 0, 1 or 2 (10, 1 or 2 allele different against the population reference)

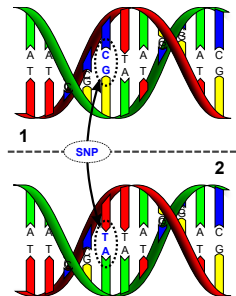


Figure: SNP (wikipedia)

# Summarize 500,000 variables in 2

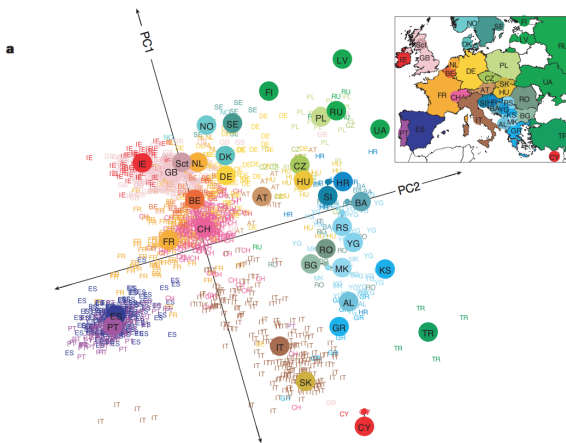


Figure: PCA output source: Nature "Gene Mirror Geography Within Europe", 2008

⇒ How much information is lost?

# Theoretical argument: dimensionality Curse

## High Dimension Geometry Curse

- Folks theorem: In high dimension, everyone is alone.
- Theorem: If  $\mathbf{x}_1, \dots, \mathbf{x}_n$  in the hypercube of dimension  $d$  such that their coordinates are i.i.d then

$$d^{-1/2} (\max \|\mathbf{x}_i - \mathbf{x}_{i'}\|_2 - \min \|\mathbf{x}_i - \mathbf{x}_{i'}\|_2) = 0 + O\left(\sqrt{\frac{\log n}{d}}\right)$$
$$\frac{\max \|\mathbf{x}_i - \mathbf{x}_{i'}\|_2}{\min \|\mathbf{x}_i - \mathbf{x}_{i'}\|_2} = 1 + O\left(\sqrt{\frac{\log n}{d}}\right).$$

$\rightsquigarrow$  When  $d$  is large, all the points are almost equidistant

Hopefully, the data **are not really leaving in  $d$**  dimension (think of the SNP example)

# Dimension reduction: general goals

**Main objective:** find a **low-dimensional representation** that captures the "essence" of (high-dimensional) data

## Application in Machine Learning

### Preprocessing, Regularization

- Compression, denoising, anomaly detection
- Reduce overfitting in supervised learning

## Application in Statistics/Data analysis

### Better understanding of the data

- descriptive/exploratory methods
- visualization (difficult to plot and interpret  $> 3d!$ )

# Dimension reduction: problem setup

## Settings

- **Training data** :  $\mathcal{D} = \{\mathbf{x}_1, \dots, \mathbf{x}_n\} \in \mathbb{R}^d$ , (i.i.d.)
- Space  $\mathbb{R}^d$  of possibly high dimension ( $n \ll d$ )

## Dimension Reduction Map

Construct a map  $\Phi$  from the space  $\mathbb{R}^d$  into a space  $\mathbb{R}^{d'}$  of **smaller dimension**:

$$\begin{aligned}\Phi : \quad \mathbb{R}^d &\rightarrow \mathbb{R}^{d'}, d' \ll d \\ \mathbf{x} &\mapsto \Phi(\mathbf{x})\end{aligned}$$

# How should we design/construct $\Phi$ ?

## Criterion

- **Geometrical approach**
- Reconstruction error
- Relationship preservation

## Form of the map $\Phi$

- **Linear** or non-linear ?
- tradeoff between **interpretability** and versatility ?
- tradeoff between high or **low** computational resource



## Part II

# Principal Component Analysis

# Some references. . .

. . . biased choices!



Analyse en composantes principales, Course AgroParisTech  
Carine Ruby, Stéphane Robin

<http://www.agroparistech.fr/IMG/pdf/AnalyseComposantesPrincipales-AgroParisTech.pdf>



Exploratory Multivariate Analysis by Example using R,  
Husson, Le, Pages, 2017.  
Chapman & Hall



Multiple Factor Analysis by Example using R,  
J. Pagès 2015.  
CRC Press



An Introduction to Statistical Learning  
G. James, D. Witten, T. Hastie and R. Tibshirani

<http://faculty.marshall.usc.edu/gareth-james/ISL/>

# PCA and classical Linear methods

**Principal component Analysis (PCA) is for continuous data**

Non continuous data

- Correspondence analysis (CA): contingency table
- Multiple correspondence analysis (MCA): categorical data
- Multiple factor analysis (MFA): multi-table, array data

↪ Basic **adaptations that build on PCA** to deal with non-continuous data

↪ smart encoding of non-continuous data to continuous ones

**We will focus on PCA**, as the mother or most linear (and non-linear) methods.

# The data matrix

The data set is a  $n \times d$  matrix  $\mathbf{X} = (x_{ij})$  with values in  $\mathbb{R}$ :

- each row  $\mathbf{x}_i$  represents an individual/observation
- each col  $\mathbf{x}^j$  represents a variable/attribute

```
crabs %>% head(6) %>% knitr::kable("latex")
```

species	sex	frontal_lob	rear_width	carapace_length	carapace_width	body_depth
B	M	8.1	6.7	16.1	19.0	7.0
B	M	8.8	7.7	18.1	20.8	7.4
B	M	9.2	7.8	19.0	22.4	7.7
B	M	9.6	7.9	20.1	23.1	8.2
B	M	9.8	8.0	20.3	23.0	8.2
B	M	10.8	9.0	23.0	26.5	9.8

# Objectives

## Individual/Observations

- similarity between observations with respect to all the variables
- Find pattern ( $\sim$  partition) between individuals

## Variables

- linear relationships between variables
- visualization of the correlation matrix
- find synthetic variables

## Link between the two

- characterization of the groups of individuals with variables
- specific observations to understand links between variables

# Outline

## Principal Component Analysis

- ① Geometric approach to PCA
- ② Principal axes and variance maximization
- ③ Representation and interpretation
- ④ Additional tools and Complements

# The data matrix

The data set is a  $n \times d$  matrix  $\mathbf{X} = (x_{ij})$  with values in  $\mathbb{R}$ :

- each row  $\mathbf{x}_i$  represents an individual/observation
- each col  $\mathbf{x}^j$  represents a variable/attribute

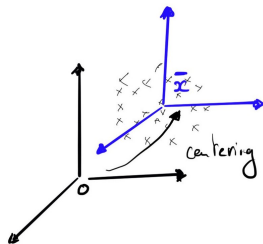
$$\mathbf{X} = \begin{matrix} & \mathbf{x}^1 & \mathbf{x}^2 & \dots & \mathbf{x}^j & \dots & \mathbf{x}^d \\ \mathbf{x}_1 & x_{11} & x_{12} & \dots & x_{1j} & \dots & x_{1d} \\ \mathbf{x}_2 & x_{21} & x_{22} & \dots & x_{2j} & \dots & x_{2d} \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \mathbf{x}_i & x_{i1} & x_{i2} & \dots x_{ij} & \dots & x_{id} & \\ \vdots & \vdots & \vdots & \vdots & \vdots & \vdots & \vdots \\ \mathbf{x}_n & x_{n1} & x_{n2} & \dots x_{nj} & \dots & x_{nd} & \end{matrix}$$

```
crabs %>% head(3) %>% knitr::kable("latex")
```

species	sex	frontal_lob	rear_width	carapace_length	carapace_width	body_depth
B	M	8.1	6.7	16.1	19.0	7.0
B	M	8.8	7.7	18.1	20.8	7.4
B	M	9.2	7.8	19.0	22.4	7.7

# Cloud of observation in $\mathbb{R}^d$

Individuals can be represented in the **variable space**  $\mathbb{R}^d$  as a point cloud



**Figure:** Example in  $\mathbb{R}^3$

Center of Inertia

(or barycentrum, or empirical mean)

$$\bar{\mathbf{x}} = \frac{1}{n} \sum_{i=1}^n \mathbf{x}_i = \begin{pmatrix} \sum_{i=1}^n x_{i1}/n \\ \sum_{i=1}^n x_{i2}/n \\ \vdots \\ \sum_{i=1}^n x_{id}/n \end{pmatrix}$$

We center the cloud  $\mathbf{X}$  around  $\bar{\mathbf{x}}$  denote this by  $\mathbf{X}^c$

$$\mathbf{X}^c = \begin{pmatrix} x_{11} - \bar{x}_1 & \dots & x_{1j} - \bar{x}_j & \dots & x_{1d} - \bar{x}_d \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{i1} - \bar{x}_1 & \dots & x_{ij} - \bar{x}_j & \dots & x_{id} - \bar{x}_d \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ x_{n1} - \bar{x}_1 & \dots & x_{nj} - \bar{x}_j & \dots & x_{nd} - \bar{x}_d \end{pmatrix}$$



# Inertia and Variance

**Total Inertia:** distance of the individuals to the center of the cloud

$$I_T = \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^d (x_{ij} - \bar{x}_j)^2 = \frac{1}{n} \sum_{i=1}^n \|\mathbf{x}_i - \bar{\mathbf{x}}\|^2 = \frac{1}{n} \sum_{i=1}^n \text{dist}^2(\mathbf{x}_i, \bar{\mathbf{x}})$$

$I_T$  is proportional to the total variance

Let  $\hat{\Sigma}$  be the empirical variance-covariance matrix

$$I_T = \frac{1}{n} \sum_{j=1}^p \sum_{i=1}^n (x_{ij} - \bar{x}_j)^2 = \sum_{j=1}^n \frac{1}{n} \|\mathbf{x}^j - \bar{x}_j\|^2 = \sum_{j=1}^n \mathbb{V}(\mathbf{x}^j) = \text{trace}(\hat{\Sigma})$$

↪ Good representation has large inertia (much variability)

↪ Large dispersion  $\sim$  Large distances between points

## Inertia with respect to an axis

The Inertia of the cloud wrt axis  $\Delta$  is the sum of the distances between all points and their orthogonal projection on  $\Delta$ .

$$I_{\Delta} = \frac{1}{n} \sum_{i=1}^n \text{dist}^2(\mathbf{x}_i, \Delta)$$

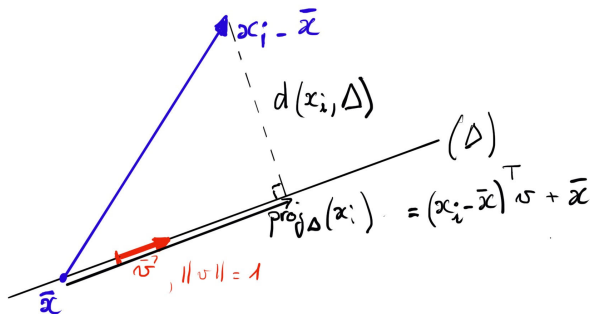
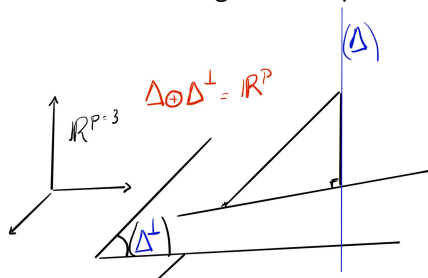


Figure: Projection of  $\mathbf{x}_i$  onto a line  $\Delta$  passing through  $\bar{\mathbf{x}}$

# Decomposition of total Inertia (1)

Let  $\Delta^\perp$  the orthogonal subspace  $\Delta$  is  $\mathbb{R}^n$



## Theorem (Huygens)

A consequence of the above (Pythagoras Theorem) is the decomposition of the following total inertia:

$$I_T = I_\Delta + I_{\Delta^\perp}$$

By projecting the cloud  $\mathbf{X}$  onto  $\Delta$ , with loss the inertia measured by  $\Delta^\perp$

## Decomposition of total Inertia (2)

Consider only subspaces with dimension 1 (that is, lines or axes). We can decompose  $\mathbb{R}^p$  as the sum of  $p$  orthogonal axes.

$$\mathbb{R}^p = \Delta_1 \oplus \Delta_2 \oplus \cdots \oplus \Delta_p$$

↪ These axes form a new basis for representing the point cloud.

Theorem (Huygens)

$$I_T = I_{\Delta_1} + I_{\Delta_2} + \cdots + I_{\Delta_p}$$

# Outline

## Principal Component Analysis

- ① Geometric approach to PCA
- ② Principal axes and variance maximization
- ③ Representation and interpretation
- ④ Additional tools and Complements

# Finding the best axis (1)

## Definition of the problem

- The best axis  $\Delta_1$  is the "closest" to the point cloud
- Inertia of  $\Delta_1$  measures the distance between the data and  $\Delta_1$
- $\Delta_1$  is defined by the director vector  $\mathbf{u}_1$ , such as  $\|\mathbf{u}_1\| = 1$
- $\Delta_1^\perp$  is defined by the normal vector  $\mathbf{u}_1$ , such as  $\|\mathbf{u}_1\| = 1$

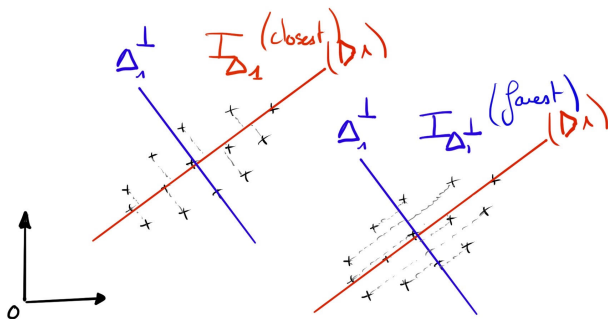
↪ The best axis  $\Delta_1$  is the one with the minimal Inertia.

# Finding the best axis (2)

## Stating the optimization problem

Since  $\Delta_1 \oplus \Delta_1^\perp = \mathbb{R}^p$  and  $I_T = I_{\Delta_1} + I_{\Delta_1^\perp}$ , then

$$\underset{\mathbf{u} \in \mathbb{R}^p: \|\mathbf{u}\|=1}{\text{minimize}} I_{\Delta_1} \Leftrightarrow \underset{\mathbf{u} \in \mathbb{R}^p: \|\mathbf{u}\|=1}{\text{maximize}} I_{\Delta_1^\perp}$$



# Finding the best axis (3)

Stating the problem (algebraically)

Find  $\mathbf{u}_1$ ;  $\|\mathbf{u}_1\| = 1$  that maximizes

$$\begin{aligned} I_{\Delta_1^\perp} &= \frac{1}{n} \sum_{i=1}^n \text{dist}(\mathbf{x}_i, \Delta_1^\perp)^2 \\ &= \frac{1}{n} \sum_{i=1}^n \mathbf{u}_1^\top (\mathbf{x}_i - \bar{\mathbf{x}}) (\mathbf{x}_i - \bar{\mathbf{x}})^\top \mathbf{u}_1 \\ &= \mathbf{u}_1^\top \left( \sum_{i=1}^n \frac{1}{n} (\mathbf{x}_i - \bar{\mathbf{x}}) (\mathbf{x}_i - \bar{\mathbf{x}})^\top \right) \mathbf{u}_1 \\ &= \mathbf{u}_1^\top \hat{\Sigma} \mathbf{u}_1 \end{aligned}$$

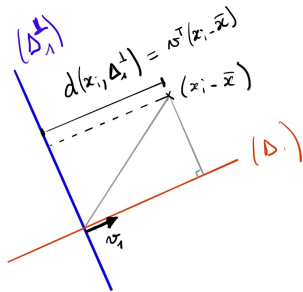


Figure: Geometrical insight



## Finding the best axis (4)

We solve a simple constraint maximization problem with the method of Lagrange multipliers:

$$\underset{\mathbf{u}_1: \|\mathbf{u}_1\|=1}{\text{maximize}} \mathbf{u}_1^\top \hat{\Sigma} \mathbf{u}_1 \Leftrightarrow \underset{\mathbf{u}_1 \in \mathbb{R}^p, \lambda_1 > 0}{\text{maximize}} \mathbf{u}_1^\top \hat{\Sigma} \mathbf{u}_1 - \lambda_1 (\|\mathbf{u}_1\|^2 - 1)$$

By straightforward (vector) differentiation, and using that  $\mathbf{u}_1^\top \mathbf{u}_1 = 1$

$$\begin{cases} 2\hat{\Sigma}\mathbf{u}_1 - 2\lambda_1\mathbf{u}_1 = 0 \\ \mathbf{u}_1^\top \mathbf{u}_1 - 1 = 0 \end{cases} \Leftrightarrow \begin{cases} \hat{\Sigma}\mathbf{u}_1 = \lambda_1\mathbf{u}_1 \\ \mathbf{u}_1^\top \hat{\Sigma}\mathbf{u}_1 = \lambda_1 \mathbf{u}_1^\top \mathbf{u}_1 = \lambda_1 = I_{\Delta_1}^\perp \end{cases}$$

- $\mathbf{u}_1$  is the first (normalized) eigen vector of  $\hat{\Sigma}$
- $\lambda_1$  is the first eigen value of  $\hat{\Sigma}$

$\rightsquigarrow \Delta_1$  is defined by the first eigen vector of  $\hat{\Sigma}$

$\rightsquigarrow$  Variance "carried" by  $\Delta_1$  is equal to the largest eigen value of  $\hat{\Sigma}$

# Finding the following axes

## Second best axis

Find  $\Delta_2$  with dimension 1, director vector  $\mathbf{u}_2$  orthogonal to  $\Delta_1$  solving

$$\underset{\mathbf{u}_2 \in \mathbb{R}^p}{\text{maximize}} I_{\Delta_2^\perp} = \mathbf{u}_2^\top \hat{\Sigma} \mathbf{u}_2, \quad \text{with } \|\mathbf{u}_2\| = 1, \mathbf{u}_1^\top \mathbf{u}_2 = 0.$$

$\rightsquigarrow \mathbf{u}_2$  is the second eigen vector of  $\hat{\Sigma}$  with eigen value  $\lambda_2$

And so on!

PCA is roughly a matrix factorisation problem

$$\hat{\Sigma} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^\top, \quad \mathbf{U} = (\mathbf{u}_1 \quad \mathbf{u}_2 \quad \dots \quad \mathbf{u}_p), \quad \mathbf{\Lambda} = \text{diag}(\lambda_1, \dots, \lambda_p)$$

- $\mathbf{U}$  is an orthogonal matrix of normalized eigen vectors.
- $\mathbf{\Lambda}$  is diagonal matrix of ordered eigen values.

# Finding the following axes

## Second best axis

Find  $\Delta_2$  with dimension 1, director vector  $\mathbf{u}_2$  orthogonal to  $\Delta_1$  solving

$$\underset{\mathbf{u}_2 \in \mathbb{R}^p}{\text{maximize}} I_{\Delta_2^\perp} = \mathbf{u}_2^\top \hat{\Sigma} \mathbf{u}_2, \quad \text{with } \|\mathbf{u}_2\| = 1, \mathbf{u}_1^\top \mathbf{u}_2 = 0.$$

$\rightsquigarrow \mathbf{u}_2$  is the second eigen vector of  $\hat{\Sigma}$  with eigen value  $\lambda_2$

And so on!

PCA is roughly a matrix factorisation problem

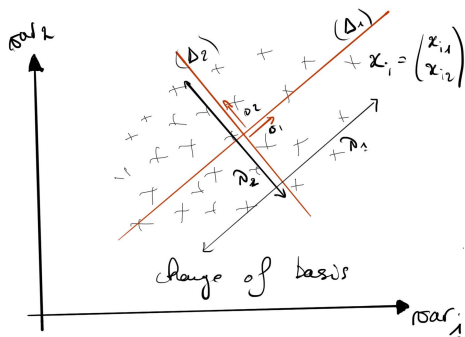
$$\hat{\Sigma} = \mathbf{U} \mathbf{\Lambda} \mathbf{U}^\top, \quad \mathbf{U} = (\mathbf{u}_1 \quad \mathbf{u}_2, \quad \dots \quad \mathbf{u}_p), \quad \mathbf{\Lambda} = \text{diag}(\lambda_1, \dots, \lambda_p)$$

- $\mathbf{U}$  is an orthogonal matrix of normalized eigen vectors.
- $\mathbf{\Lambda}$  is diagonal matrix of ordered eigen values.

## Interpretation in $\mathbb{R}^p$

$\mathbf{U}$  describes a new orthogonal basis and a rotation of data in this basis  
 $\rightsquigarrow$  PCA is an appropriate rotation on axes that maximizes the variance

$$\left\{ \begin{array}{ccccc} \Delta_1 & \oplus & \dots & \oplus & \Delta_p \\ \mathbf{u}_1 & \perp & \dots & \perp & \mathbf{u}_2 \\ \lambda_1 & > & \dots & > & \lambda_p \\ I_{\Delta_1^\perp} & > & \dots & > & I_{\Delta_p^\perp} \end{array} \right.$$



# Outline

## Principal Component Analysis

- 1 Geometric approach to PCA
- 2 Principal axes and variance maximization
- 3 Representation and interpretation**
  - Quality of the reconstruction
  - Individuals point of view
  - Variables point of view
- 4 Additional tools and Complements

# Outline

## Principal Component Analysis

- 1 Geometric approach to PCA
- 2 Principal axes and variance maximization
- 3 Representation and interpretation
  - Quality of the reconstruction
  - Individuals point of view
  - Variables point of view
- 4 Additional tools and Complements

# Contribution of each axis and quality of the representation

$\Delta_k$  is carrying inertia/variance defined by its orthogonal, thus

$$I_T = I_{\Delta_1^\perp} + \cdots + I_{\Delta_p^\perp} = \lambda_1 + \cdots + \lambda_p$$

Relative contribution of axis  $k$

$$\text{contrib}(\Delta_k) = \frac{\lambda_k}{\sum_{j=1}^p \lambda_j} = \frac{\lambda_k}{\text{trace}(\hat{\Sigma})} \times 100$$

↪ Percentage of explained inertia/variance explained

Global quality of the representation on the first  $k$  axes

$$\text{contrib}(\Delta_1, \dots, \Delta_k) = \frac{\lambda_1 + \cdots + \lambda_k}{\text{trace}(\hat{\Sigma})} \times 100$$

A few axes may explain a large proportion of the total variance.

↪ This paves the way for dimension reduction

## Contribution of each axis and quality of the representation

$\Delta_k$  is carrying inertia/variance defined by its orthogonal, thus

$$I_T = I_{\Delta_1^\perp} + \cdots + I_{\Delta_p^\perp} = \lambda_1 + \cdots + \lambda_p$$

Relative contribution of axis  $k$

$$\text{contrib}(\Delta_k) = \frac{\lambda_k}{\sum_{j=1}^p \lambda_j} = \frac{\lambda_k}{\text{trace}(\hat{\Sigma})} \times 100$$

↪ Percentage of explained inertia/variance explained

Global quality of the representation on the first  $k$  axes

$$\text{contrib}(\Delta_1, \dots, \Delta_k) = \frac{\lambda_1 + \cdots + \lambda_k}{\text{trace}(\hat{\Sigma})} \times 100$$

A few axes may explain a large proportion of the total variance.

↪ This paves the way for dimension reduction



## Contribution of each axis and quality of the representation

$\Delta_k$  is carrying inertia/variance defined by its orthogonal, thus

$$I_T = I_{\Delta_1^\perp} + \cdots + I_{\Delta_p^\perp} = \lambda_1 + \cdots + \lambda_p$$

Relative contribution of axis  $k$

$$\text{contrib}(\Delta_k) = \frac{\lambda_k}{\sum_{j=1}^p \lambda_j} = \frac{\lambda_k}{\text{trace}(\hat{\Sigma})} \times 100$$

↪ Percentage of explained inertia/variance explained

Global quality of the representation on the first  $k$  axes

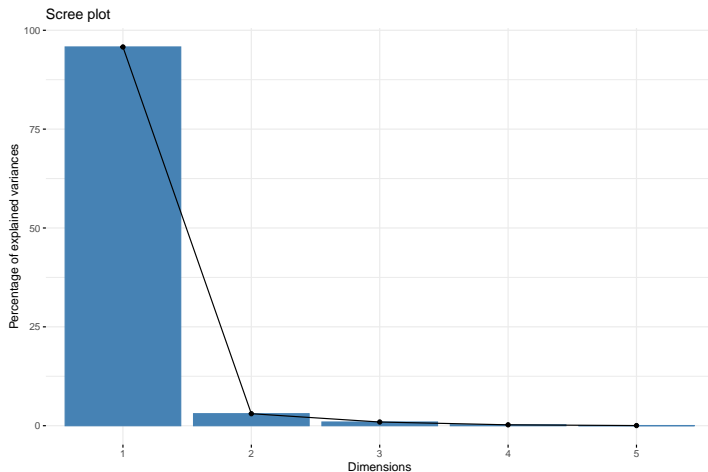
$$\text{contrib}(\Delta_1, \dots, \Delta_k) = \frac{\lambda_1 + \cdots + \lambda_k}{\text{trace}(\hat{\Sigma})} \times 100$$

A few axes may explain a large proportion of the total variance.

↪ This paves the way for dimension reduction

# Scree plot: 'crabs'

```
crabs_pca <- select(crabs, -species, -sex) %>% FactoMineR::PCA(graph = FALSE)
fviz_eig(crabs_pca)
```



# Outline

## Principal Component Analysis

- 1 Geometric approach to PCA
- 2 Principal axes and variance maximization
- 3 Representation and interpretation**
  - Quality of the reconstruction
  - Individuals point of view**
  - Variables point of view
- 4 Additional tools and Complements

# Individuals: representation in the new basis

Projection of point  $\mathbf{x}_i$  axis  $k$

The projection of  $\mathbf{x}_i$  onto axis  $\Delta_k$  is  $c_{ik}\mathbf{u}_k$ , with

$$c_{ik} = \mathbf{u}_k^\top (\mathbf{x}_i - \bar{\mathbf{x}}),$$

the coordinate of  $i$  in the basis  $\mathbf{u}_k$  (along axis  $\Delta_k$ ).

Coordinates of  $i$  in the new basis

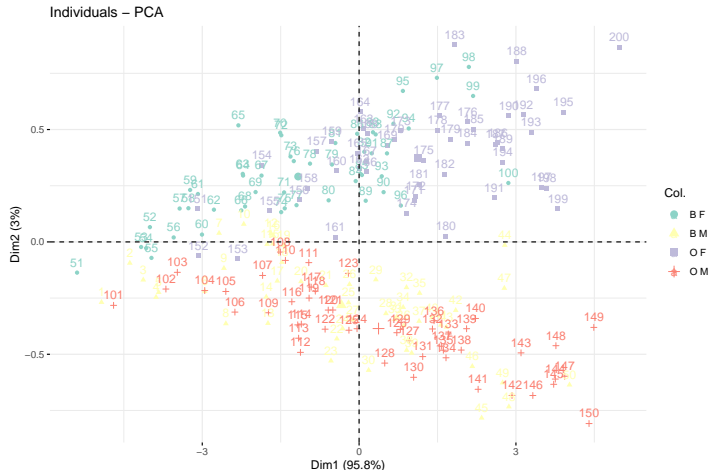
Coordinates of  $i$  in the new basis  $\{\mathbf{u}_1, \dots, \mathbf{u}_d\}$  is thus

$$\mathbf{c}_i = (\mathbf{U}^\top (\mathbf{x}_i - \bar{\mathbf{x}}))^\top = (\mathbf{x}_i - \bar{\mathbf{x}})^\top \mathbf{U} = \mathbf{X}_i^c \mathbf{U}, \quad \mathbf{c}_i \in \mathbb{R}^p.$$

- $\mathbf{U}$  are often called the **loadings**, or **weights**
- $\mathbf{c}_i$  are the **scores** or **coordinates** in the new space for the individuals

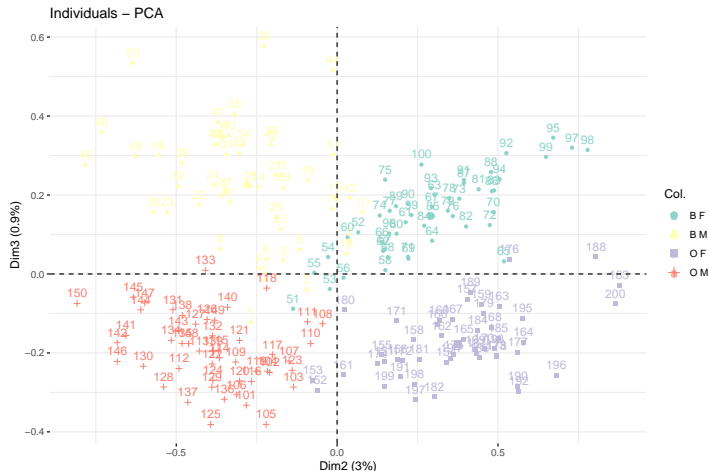
# Individual visualization: projection in the new basis (1)

```
fviz_pca_ind(crabs_pca, col.ind = paste(crabs$species, crabs$sex), palette = pal)
```



# Individual visualization: projection in the new basis (2)

```
fviz_pca_ind(crabs_pca, axes = c(2,3), col.ind = paste(crabs$species, crabs$sex), p
```



# Warning: about distances after projection

Close projection doesn't mean close individuals!

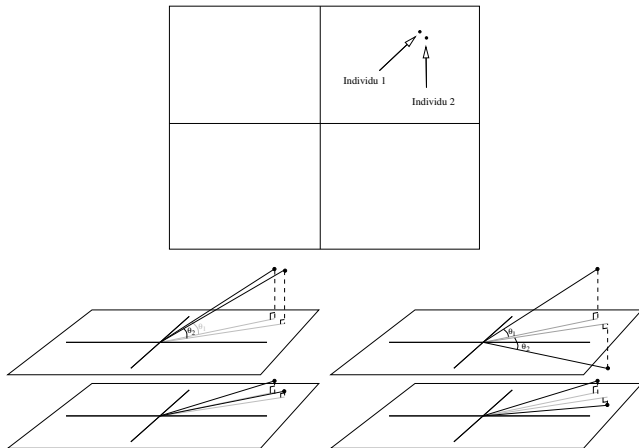


Figure: Same projections but different situations (source: E. Matzner)

⇒ Only work when individuals are well represented in the lower space

# Individual: quality of the representation

## Property

- An individual  $i$  is well represented by  $\Delta_k$  if it is close to this axis.
- In other word, vector  $\mathbf{x}_i - \bar{\mathbf{x}}$  and  $\mathbf{u}_k$  are close to collinear

We use the cosine of the angle  $\theta_{ik}$  between  $\mathbf{x}_i - \bar{\mathbf{x}}$  and  $\mathbf{u}_k$  to measure the degree of co-linearity:

$$\cos^2(\theta_{ik}) = \frac{\left( \mathbf{u}_k^\top (\mathbf{x}_i - \bar{\mathbf{x}}) \right)^2}{\|\mathbf{x}_i - \bar{\mathbf{x}}\|^2 \|\mathbf{u}_k\|^2}$$

```
factoextra::get_pca_ind(crabs_pca)$cos2 %>% head(3) %>% kable("latex")
```

Dim.1	Dim.2	Dim.3	Dim.4	Dim.5
0.9961694	0.0029565	0.0006132	6.29e-05	1.98e-04
0.9994582	0.0004598	0.0000800	1.60e-06	5.00e-07
0.9980940	0.0016699	0.0000663	8.50e-05	8.48e-05



# Individual: contribution to an axis

## Property

- Inertia "explained" by  $\Delta_k$  is inertia of  $\Delta_k^\perp$
- $I_{\Delta_k^\perp} = n^{-1} \sum_{i=1}^n \text{dist}^2(\Delta_k^\perp, \mathbf{x}_i)$

Contribution of  $\mathbf{x}_i$  to axis  $\Delta_k$  is the proportion of variance/inertia carried by individual  $i$ :

$$\text{contr}(\mathbf{x}_i) = \frac{n^{-1} \text{dist}^2(\Delta_k^\perp, \mathbf{x}_i)}{I_{\Delta_k^\perp}} = \frac{\left( \mathbf{u}_k^\top (\mathbf{x}_i - \bar{\mathbf{x}}) \right)^2}{n \lambda_k}$$

```
factoextra::get_pca_ind(crabs_pca)$contr %>% head(3) %>% kable("latex")
```

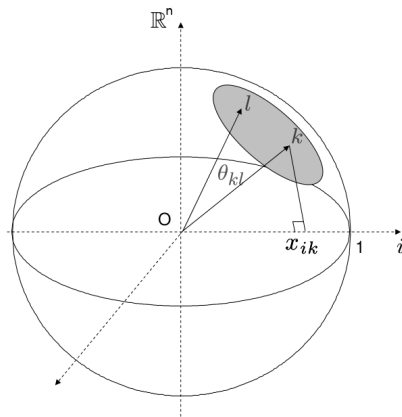
Dim.1	Dim.2	Dim.3	Dim.4	Dim.5
2.535166	0.2375409	0.1602617	0.0688010	1.4097141
2.008687	0.0291717	0.0165027	0.0013421	0.0027214
1.779751	0.0940074	0.0121362	0.0651696	0.4231593

# Outline

## Principal Component Analysis

- 1 Geometric approach to PCA
- 2 Principal axes and variance maximization
- 3 Representation and interpretation
  - Quality of the reconstruction
  - Individuals point of view
  - Variables point of view**
- 4 Additional tools and Complements

## Cloud of variables in $\mathbb{R}^n$



Direct equivalence between geometry and statistics (collinearity  $\equiv$  correlation)

$$\cos(\theta_{kl}) = \frac{\langle \mathbf{x}^k, \mathbf{x}^\ell \rangle}{\|\mathbf{x}^k\| \|\mathbf{x}^\ell\|} = \rho(\mathbf{x}^k, \mathbf{x}^\ell)$$

# Principal Components

## Dual representation

A symmetric reasoning can be made in  $\mathbb{R}^n$  for the variables, like with the individuals in  $\mathbb{R}^p$ .

↪ New axes are linear combination of the original variables, which can be seen as **new variables** in the new latent space

## Principal component

It is the linear combination formed by the original variables with weights given by the loadings  $\mathbf{u}_k$

$$\mathbf{f}_k = \sum_{j=1}^p \mathbf{u}_k (\mathbf{x}^j - \bar{x}_j) = \mathbf{X}^c \mathbf{u}_k, \quad \mathbf{f}_k \in \mathbb{R}^n$$

Sometimes called "**factors**" in factor analysis, as **latent (hidden) variables**.

# Variable representation in the new space

## Connection with original variables

- essential for interpretation
- answer to the question: how to read the axes of the individual map
- use correlation to measure connection to original variable

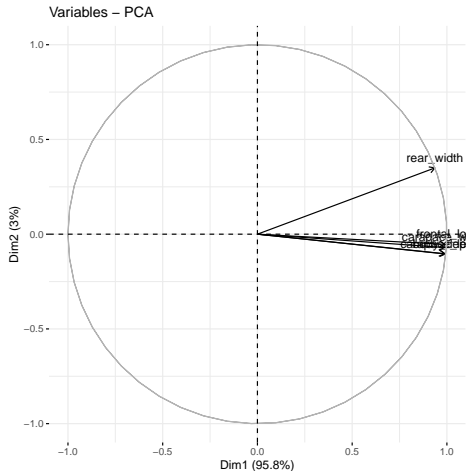
$$\mathbb{V}(\mathbf{f}_k) = \frac{1}{n} \mathbb{V}(\mathbf{X}^c \mathbf{u}_k) = \mathbf{u}_k^\top \frac{1}{n} (\mathbf{X}^c)^\top \mathbf{X}^c \mathbf{u}_k = \mathbf{u}_k^\top \hat{\Sigma} \mathbf{u}_k = \lambda_k$$

$$\text{cov}(\mathbf{f}_k, (\mathbf{x}^j - \bar{x}_j)) = \mathbf{u}_k^\top \mathbf{X}^{c\top} \mathbf{X}^c \mathbf{e}_j = \mathbf{u}_k^\top \lambda_k \mathbf{e}_j = \lambda_k \mathbf{u}_{kj}$$

$$\text{cor}(\mathbf{f}_k, (\mathbf{x}^j - \bar{x}_j)) = \sqrt{\frac{\lambda_k}{\mathbb{V}(\mathbf{x}^j)}} \mathbf{u}_{kj}$$

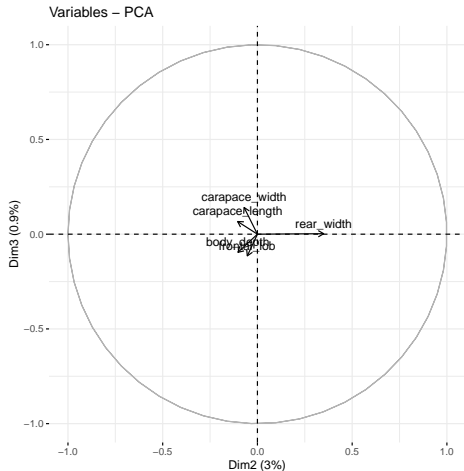
# Variable vizualisation: correlation circle (1)

```
fviz_pca_var(crabs_pca)
```



## Variable vizualisation: correlation circle (2)

```
fviz_pca_var(crabs_pca, axes = c(2,3))
```



## Warning: about angle after projection

Close projection doesn't mean close variable!

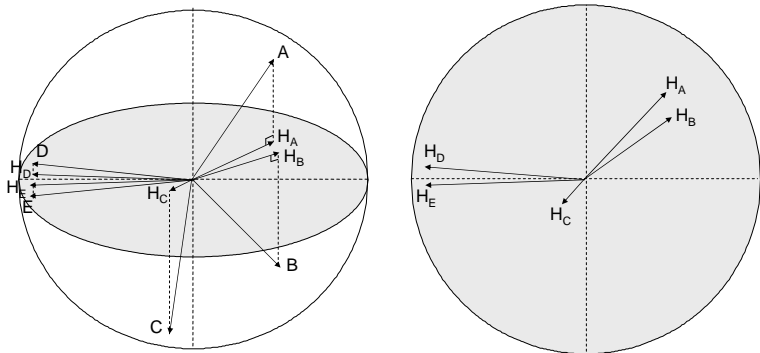


Figure: Same angle but different situations (source: J. Josse)

⇒ Only work when variables are well represented in the latent space



# Variable: quality of the representation

Same story as for individuals

## Property

- An variable  $j$  is well represented by  $\Delta_k$  if its projection is close to  $\mathbf{f}_k$ .
- High collinearity means high absolute correlation and high cosine.
- use cosine to the square of the angle between the original and new variables.

↪ The projection of  $j$  must be close to the boundary of the correlation circle

```
factoextra::get_pca_var(crabs_pca)$cos2 %>% head(3) %>% kable("latex")
```

	Dim.1	Dim.2	Dim.3	Dim.4	Dim.5
frontal_lob	0.9785672	0.0028712	0.0131372	0.0054085	0.0000159
rear_width	0.8775551	0.1223552	0.0000067	0.0000780	0.0000051
carapace_length	0.9835409	0.0109140	0.0044722	0.0000000	0.0010728

## Variable: contribution to an axis

Similarly to individuals, we can measure the contribution of the original variables to the construction of the new ones.

```
factoextra::get_pca_var(crabs_pca)$contr %>% kable("latex")
```

	Dim.1	Dim.2	Dim.3	Dim.4	Dim.5
frontal_lob	20.43435	1.892860	28.171511	48.5702186	0.9310620
rear_width	18.32502	80.663877	0.014350	0.7006226	0.2961274
carapace_length	20.53821	7.195170	9.590266	0.0002087	62.6761450
carapace_width	20.35027	3.261487	42.584703	0.7954467	33.0080946
body_depth	20.35215	6.986605	19.639170	49.9335034	3.0885710

⇒ What do you think of the first axe ?

# Outline

## Principal Component Analysis

- ① Geometric approach to PCA
- ② Principal axes and variance maximization
- ③ Representation and interpretation
- ④ Additional tools and Complements

# Unifying view of variables and individuals

## Principal components

The full matrix of principal component connects individual coordinates to latent factors:

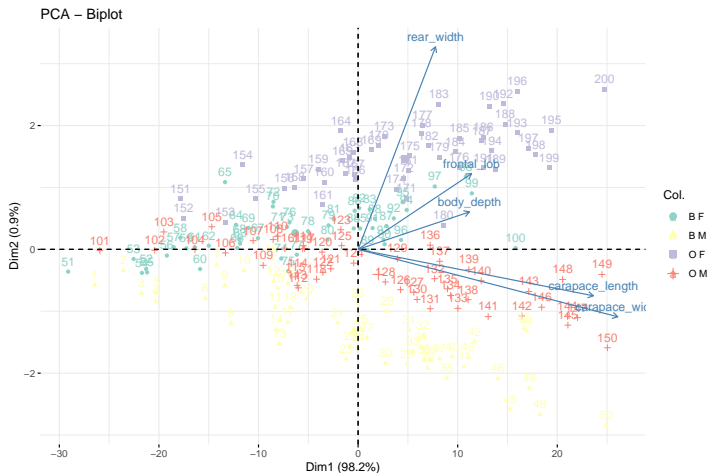
$$PC = \mathbf{X}^c \mathbf{U} = (\mathbf{f}_1 \quad \mathbf{f}_2 \quad \dots \quad \mathbf{f}_d) = \begin{pmatrix} \mathbf{c}_1^\top \\ \mathbf{c}_2^\top \\ \dots \\ \mathbf{c}_d^\top \end{pmatrix}$$

- new variables (latent factor) are seen column-wise
- new coordinates are seen row-wise

↪ Everything can be interpreted on a single plot, called the biplot

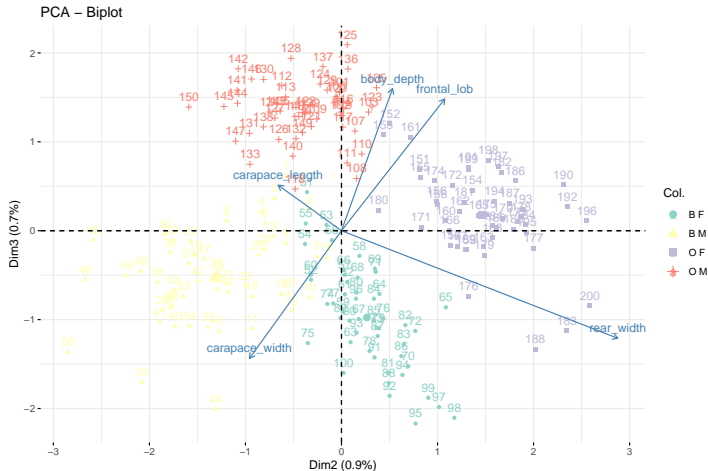
# Biplot (1)

```
FactoMineR::PCA(select(crabs, -species, -sex), scale.unit = FALSE, graph = FALSE) %  
  factoextra::fviz_pca_biplot(  
    axes = c(1,2), col.ind = paste(crabs$species, crabs$sex), palette = pal  
  )
```



# Biplot (2)

```
FactoMineR::PCA(select(crabs, -species, -sex), scale.unit = FALSE, graph = FALSE) %  
  factoextra::fviz_pca_biplot(  
    axes = c(2,3), col.ind = paste(crabs$species, crabs$sex), palette = pal  
  )
```



## Reconstruction formula

Recall that  $\mathbf{F} = (\mathbf{f}_1, \dots, \mathbf{f}_d)$  is the matrix of Principal components. Then,

- $\mathbf{f}_k = \mathbf{X}^c \mathbf{u}_k$  for projection on axis  $k$
- $\mathbf{F} = \mathbf{X}^c \mathbf{U}$  for all axis.

Using orthogonality of  $\mathbf{U}$ , we get back the original data as follows, without loss ( $\mathbf{U}^T$  performs the inverse rotation of  $\mathbf{U}$ ):

$$\mathbf{X}^c = \mathbf{F} \mathbf{U}^T$$

We obtain an approximation  $\tilde{\mathbf{X}}^c$  (compression) of the data  $\mathbf{X}^c$  by considering a subset  $\mathcal{S}$  of PC, typically  $\mathcal{S} = 1, \dots, K$  with  $K \ll d$ .

$$\tilde{\mathbf{X}}^c = \mathbf{F}_{\mathcal{S}} \mathbf{U}_{\mathcal{S}}^T = \mathbf{X}^c \mathbf{U}_{\mathcal{S}} \mathbf{U}_{\mathcal{S}}^T$$

$\rightsquigarrow$  This is a rank  $K$  approximation of  $\mathbf{X}$  (information captured by the first  $K$  axes).

## Reconstruction formula

Recall that  $\mathbf{F} = (\mathbf{f}_1, \dots, \mathbf{f}_d)$  is the matrix of Principal components. Then,

- $\mathbf{f}_k = \mathbf{X}^c \mathbf{u}_k$  for projection on axis  $k$
- $\mathbf{F} = \mathbf{X}^c \mathbf{U}$  for all axis.

Using orthogonality of  $\mathbf{U}$ , we get back the original data as follows, without loss ( $\mathbf{U}^T$  performs the inverse rotation of  $\mathbf{U}$ ):

$$\mathbf{X}^c = \mathbf{F} \mathbf{U}^T$$

We obtain an approximation  $\tilde{\mathbf{X}}^c$  (compression) of the data  $\mathbf{X}^c$  by considering a subset  $\mathcal{S}$  of PC, typically  $\mathcal{S} = 1, \dots, K$  with  $K \ll d$ .

$$\tilde{\mathbf{X}}^c = \mathbf{F}_{\mathcal{S}} \mathbf{U}_{\mathcal{S}}^T = \mathbf{X}^c \mathbf{U}_{\mathcal{S}} \mathbf{U}_{\mathcal{S}}^T$$

$\rightsquigarrow$  This is a rank  $K$  approximation of  $\mathbf{X}$  (information captured by the first  $K$  axes).



# Remove size effect I

Carried by the 1st principal component

## First component

$$\mathbf{f}_1 = \mathbf{X}^c \mathbf{u}_1.$$

We extract the best rank-1 approximation of  $\mathbf{X}$  to remove the *size effect*, carried by the first axis, and return to the original space,

$$\tilde{\mathbf{X}}^{(1)} = \mathbf{f}_1 \mathbf{u}_1^\top.$$

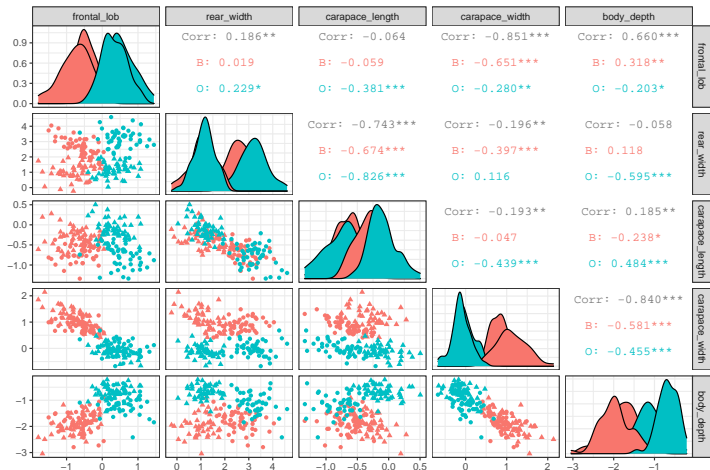
```
attributes <- select(crabs, -sex, -species) %>% as.matrix()
u1 <- eigen(cov(attributes))$vectors[, 1, drop = FALSE]
attributes_rank1 <- attributes %*% u1 %*% t(u1)
crabs_corrected <- crabs
crabs_corrected[, 3:7] <- attributes - attributes_rank1
```

↪ Axis 1 explains a latent effect, here the size in the case at hand, common to all attributes.

# Remove size effect II

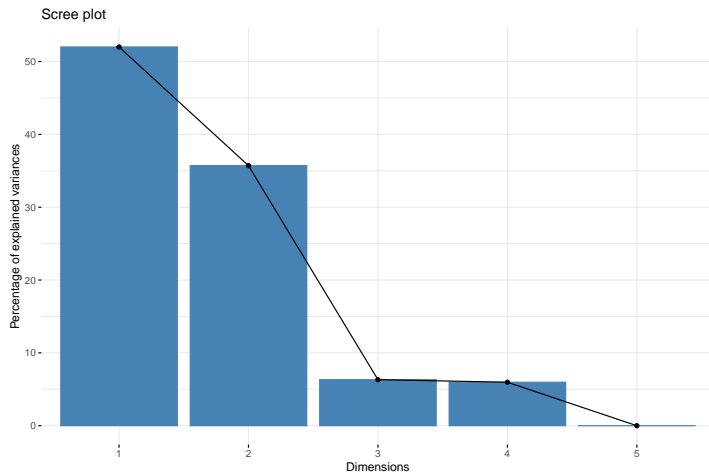
Carried by the 1st principal component

```
ggpairs(crabs_corrected, columns = 3:7, aes(colour = species, shape = sex))
```



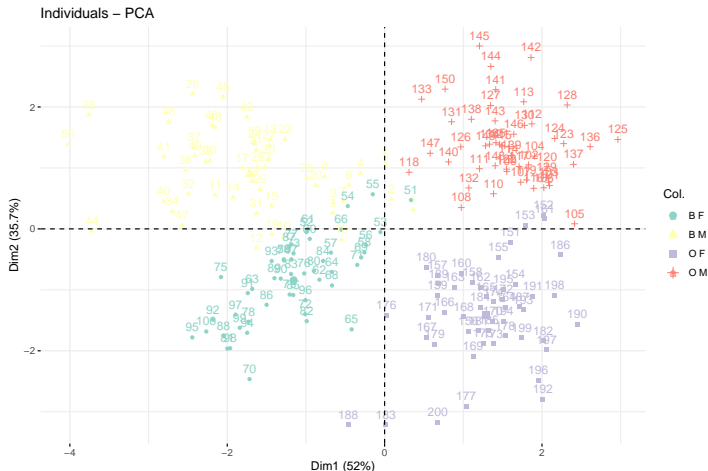
# PCA on corrected data (1)

```
crabs_pca_corrected <- select(crabs_corrected, -species, -sex) %>% FactoMineR::PCA  
fviz_eig(crabs_pca_corrected)
```



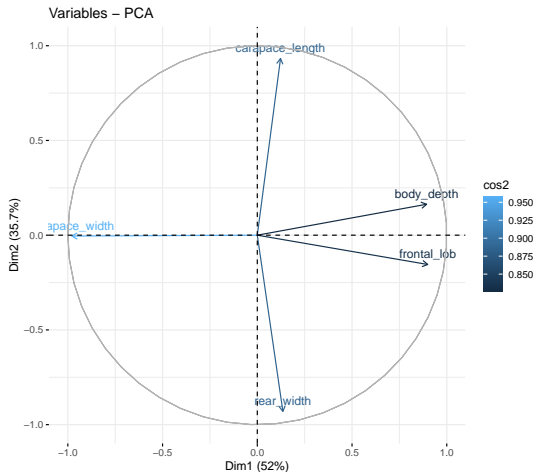
## PCA on corrected data (2)

```
fviz_pca_ind(crabs_pca_corrected,  
  col.ind = paste(crabs_corrected$species, crabs_corrected$sex), palette = pal)
```



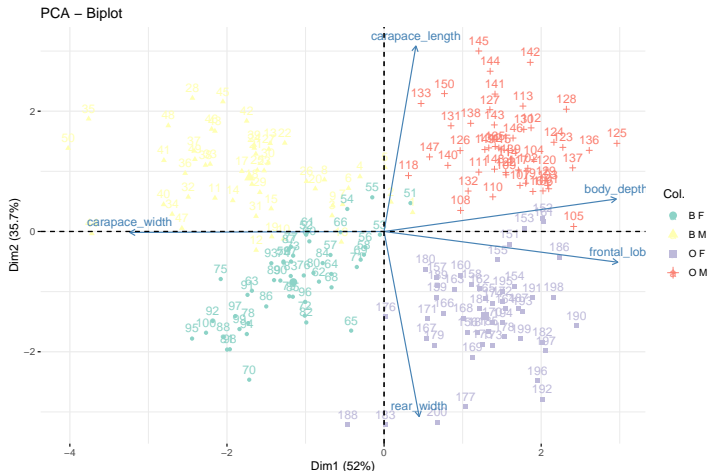
## PCA on corrected data (3)

```
fviz_pca_var(crabs_pca_corrected, col.var = 'cos2')
```



# PCA on corrected data (3)

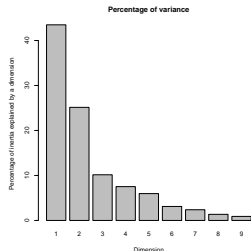
```
fviz_pca_biplot(crabs_pca_corrected,  
  col.ind = paste(crabs_corrected$species, crabs_corrected$sex), palette = pal)
```



# Choosing the number of components

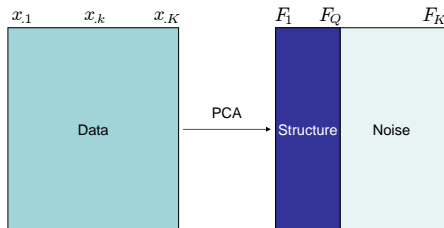
Various solutions, open question

Scree plot, test on eigenvalues, confidence interval, cross-validation, generalized cross-validation, etc.



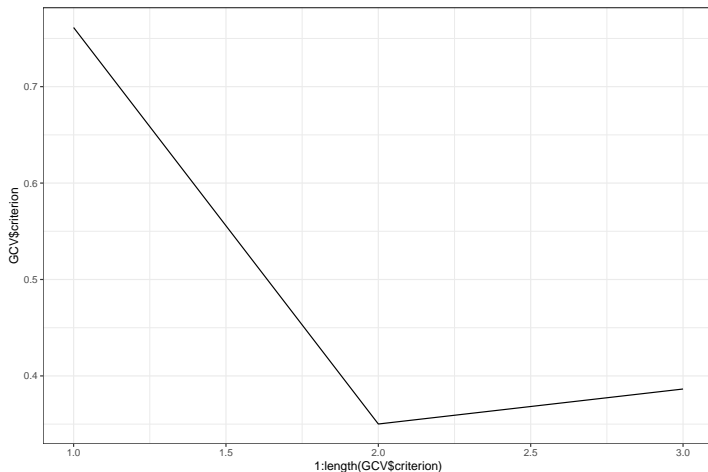
## Objectives

- Interpretation
- Separate structure and noise
- Data compression



# Example: Generalized Cross Validation

```
GCV <- select(crabs_corrected, -species, -sex) %>%  
  FactoMineR::estim_ncp(ncp.min = 1, ncp.max = 3)  
qplot(1:length(GCV$criterion), GCV$criterion, geom = "line") + labs("number of axis")
```





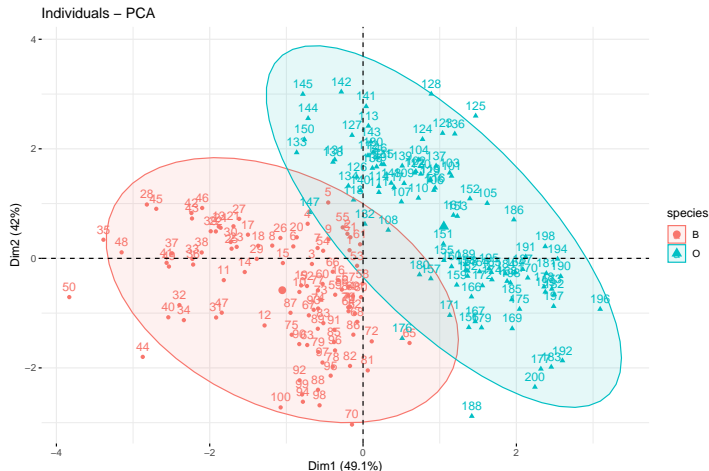
## Supplementary information

- continuous variables: projection (correlation with dimensions)
- observations: projection
- categorical variables: projection of the categories at the barycentre of the observations which take the categories

```
crabs_pca_corrected <- crabs_corrected %>%  
  FactoMineR::PCA(graph = FALSE, quanti.sup = 7, quali.sup = c(1,2))
```

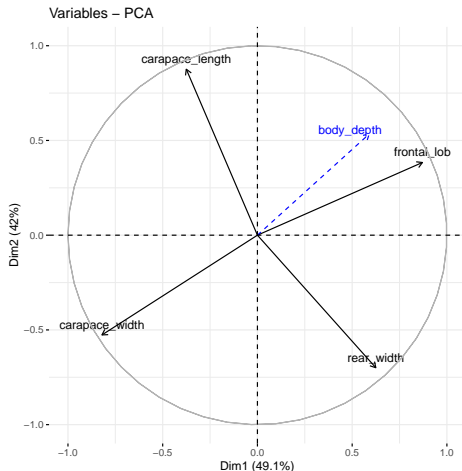
# Supplementary information: example (1)

```
fviz_pca_ind(crabs_pca_corrected, habillage = "species", col.ind.sup = "black", add
```



## Supplementary information: example (2)

```
factoextra::fviz_pca_var(crabs_pca_corrected)
```



# Description of dimensions

## Using continuous variables

- correlation between variable and the principal components
- sort correlation coefficients and give significant ones (with tests)

## Using categorical variables

One-way anova with the coordinates of the observations ( $F_{.q}$ ) explained by the categorical variable

- F-test by variable
- for each category, a Student's  $T$ -test to compare the average of the category with the general mean

# Description of dimensions: example

```
FactoMineR::dimdesc(crabs_pca_corrected, axes = 1)
```

```
## $Dim.1
## $quanti
##           correlation      p.value
## frontal_lob      0.8707523 5.928707e-63
## rear_width       0.6248516 4.683973e-23
## body_depth       0.5898360 3.935692e-20
## carapace_length  -0.3755928 4.244401e-08
## carapace_width   -0.8206976 5.086379e-50
##
## $quali
##           R2      p.value
## species 0.5653531 1.124006e-37
## sex      0.2446104 9.801298e-14
##
## $category
##           Estimate      p.value
## species=0  1.0535355 1.124006e-37
## sex=F      0.6929897 9.801298e-14
## sex=M     -0.6929897 9.801298e-14
## species=B -1.0535355 1.124006e-37
##
## attr(,"class")
## [1] "condes" "list"
```