



Comparison of Pix2Pix and CycleGAN's performances for illustration colorization

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Introduction

Image to Image translation

Task of automatically translating images from one domain to another.

Examples:

- *Paintings* → *Images*
- *Edges* → *Real objects*
- *B&W* → *Color*

Comparison

We aim to compare the Pix2Pix and CycleGAN architectures, both provided by Jun-Yan Zhu and Teasung Park.

Our project

How does each architecture fit our dataset?

We provide a set of experiments and their respective results.

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Colorization

“Technique of adding color to black and white pictures”



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Dataset

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Dataset

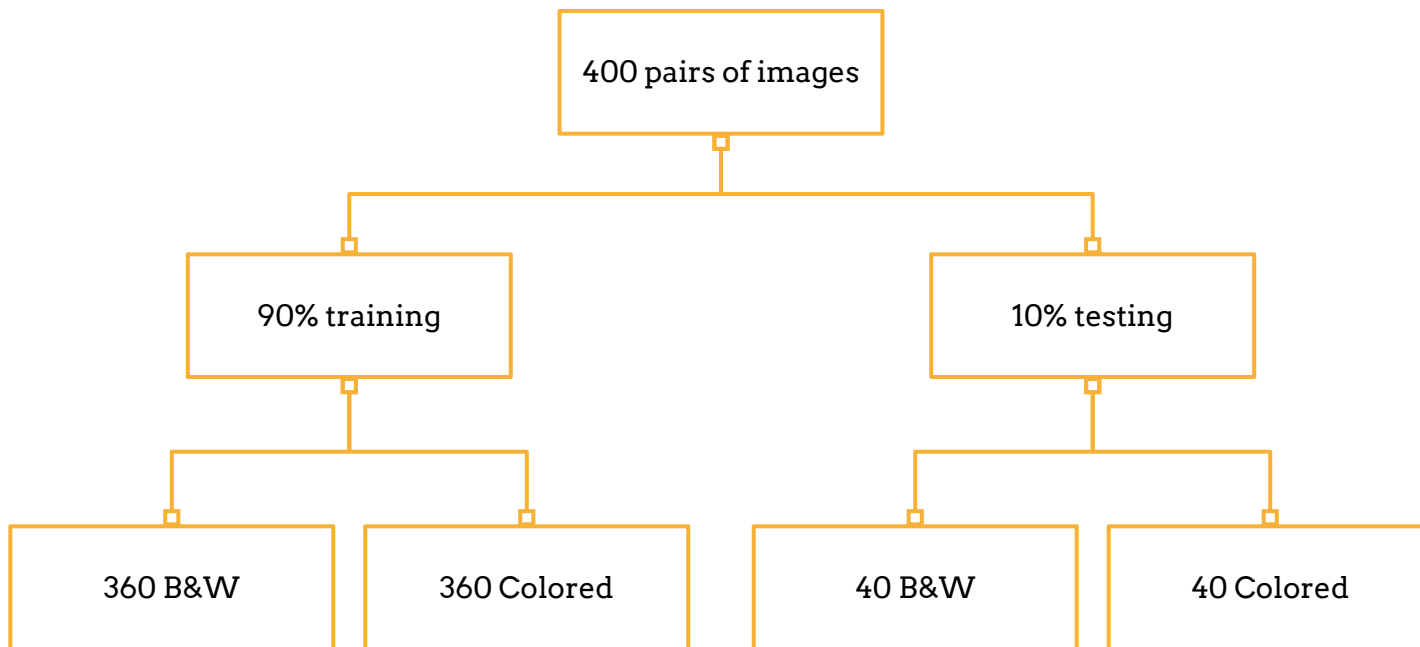
400 pairs of illustrations from the Victorian era:

1. B&W + Colored
2. Resized versions (256x256)
3. High resolution



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Experiments - Dataset

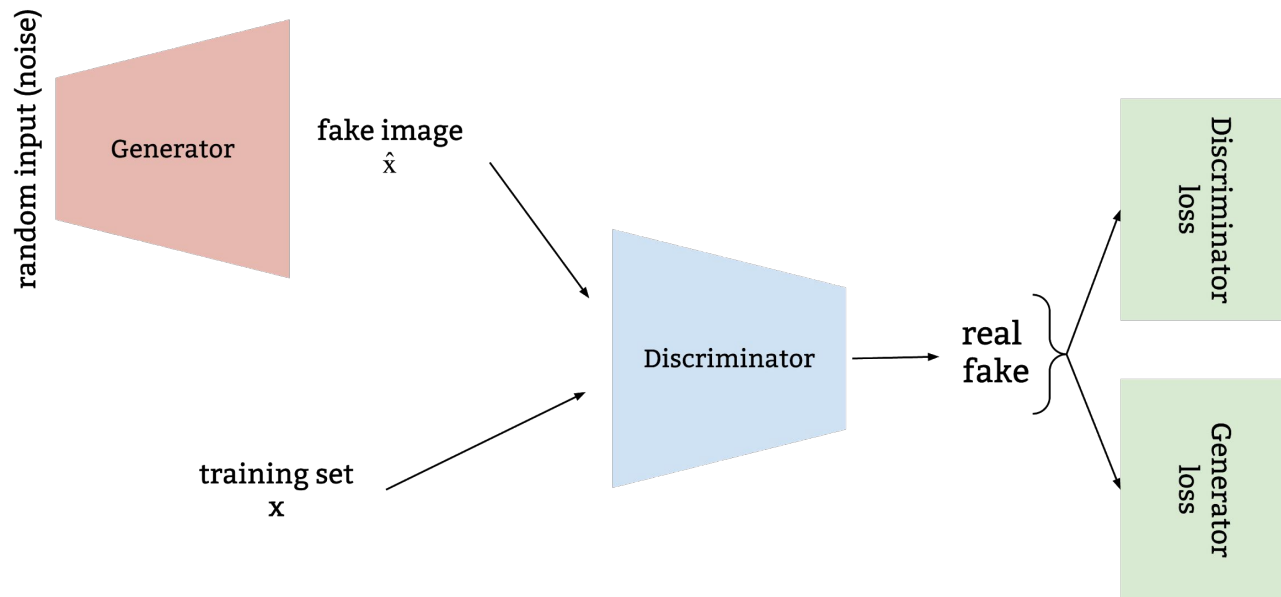


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Generative Adversarial Networks (GANs)

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GAN structure

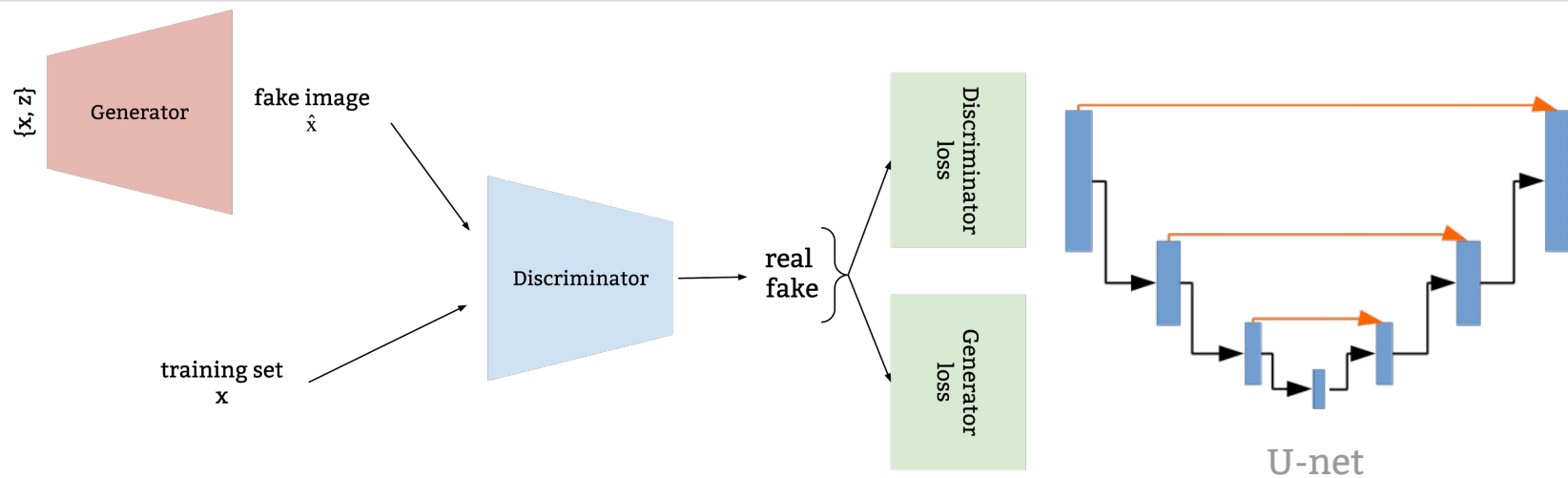


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Pix2Pix architecture

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cGAN structure



Objective function:
Loss of conditional GAN + L1 distance

Objective function

$$G^* = \arg \min_G \max_D \mathcal{L}_{cGAN}(G, D) + \lambda \mathcal{L}_{L1}(G)$$

Objective of a conditional GAN

$$\mathcal{L}_{cGAN}(G, D) = \mathbb{E}_{x,y} [\log D(x, y)] + \mathbb{E}_{x,z} [\log(1 - D(x, G(x, z)))]$$

L1 distance

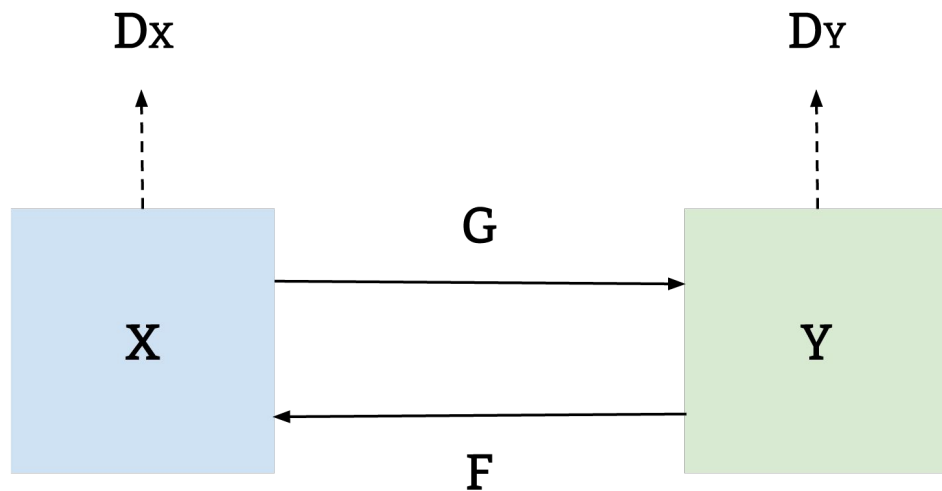
$$\mathcal{L}_{L1}(G) = \mathbb{E}_{x,y,z} [\|y - G(x, z)\|_1]$$

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Cycle-GAN

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Cycle-GAN structure



$$F(G(x)) \approx x$$

$$G(F(y)) \approx y$$

Objective function:

Adversarial losses + cycle consistency loss

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Cycle-GAN objectives

Objective function

$$G^*, F^* = \arg \min_{G, F} \max_{D_X, D_Y} \mathcal{L}(G, F, D_X, D_Y)$$

Loss function

$$\mathcal{L}(G, F, D_X, D_Y) = \mathcal{L}_{GAN}(G, D_Y, X, Y) + \mathcal{L}_{GAN}(F, D_X, Y, X) + \lambda \mathcal{L}_{cyc}(G, F)$$

Adversarial losses

$$\mathcal{L}_{GAN}(G, D_Y, X, Y) = \mathbb{E}_{y \sim p_{data}(y)} [\log D_Y(y)] + \mathbb{E}_{x \sim p_{data}(x)} [\log(1 - D_Y(G(x)))]$$

$$\mathcal{L}_{GAN}(F, D_X, Y, X) = \mathbb{E}_{x \sim p_{data}(x)} [\log D_X(x)] + \mathbb{E}_{y \sim p_{data}(y)} [\log(1 - D_X(F(y)))]$$

Cycle consistency loss

$$\mathcal{L}_{cyc}(G, F) = \mathbb{E}_{x \sim p_{data}(x)} [\|F(G(x)) - x\|_1] + \mathbb{E}_{y \sim p_{data}(y)} [\|G(F(y)) - y\|_1]$$

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How they differ?

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How they differ?

Pix2Pix

- **Pairwise domain**

(Needs paired images from the two corresponding domains.)

- **Only forward mapping**

CycleGAN

- **Non-pairwise domain**

(Works with unordered image collections.)

- **Forward & backward mapping**

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Experiments

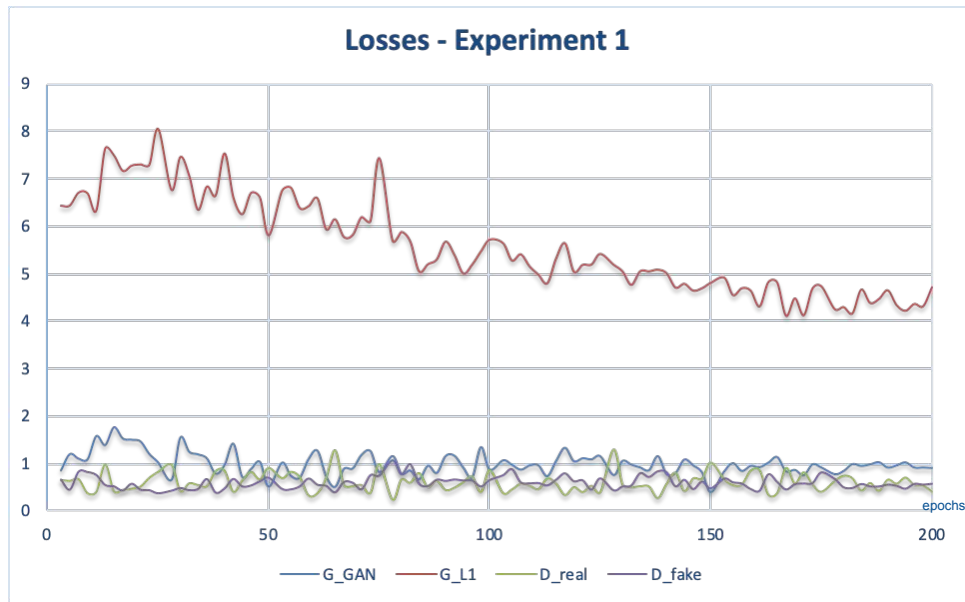
4	Experiments			
EXPERIMENT	#1	#2	#3	#4
Model	Pix2Pix		CycleGAN	
Batch size	32	1	1	1
Training Dataset	90% 720 paired images	90% 720 paired images	45% 360 unpaired img.	90% 720 images
	- 360 colored - 360 B&W model generated	- 360 colored - 360 B&W model generated	- 180 colored - 180 B&W	- 360 colored - 360 B&W

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Results

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Training - Results



Training time

 $\approx 1.5h$ # Param.
Network G

54.410 M

Losses last
iter

G_GAN

0.89

G_L1

4.721

D_real

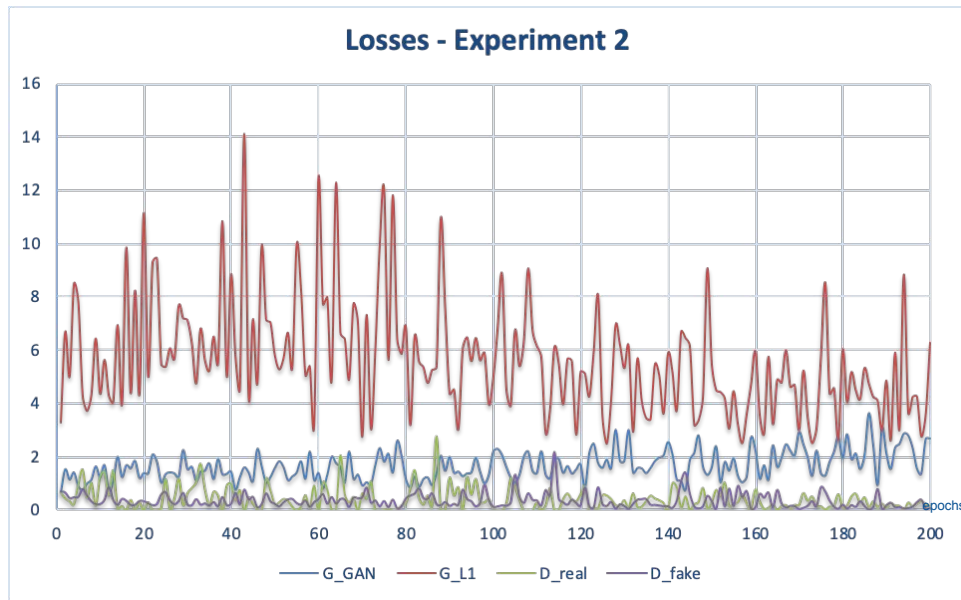
0.411

D_fake

0.565

5

Training - Results



Training time

 $\approx 3.5h$ # Param.
Network G

54.410 M

Losses last
iter

G_GAN

2.710

G_L1

6.290

D_real

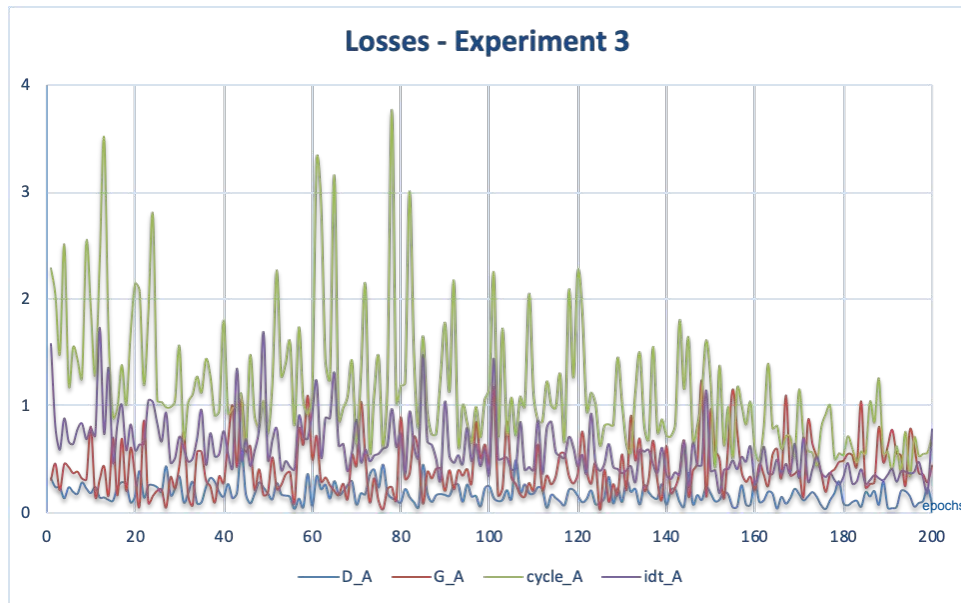
0.180

D_fake

0.100

5

Training - Results



Training time

 $\approx 5.7\text{h}$ (for both transf)# Param.
Network G_A

11.378 M

Losses last
iter

D_A

0.085

G_A

0.438

cycle_A

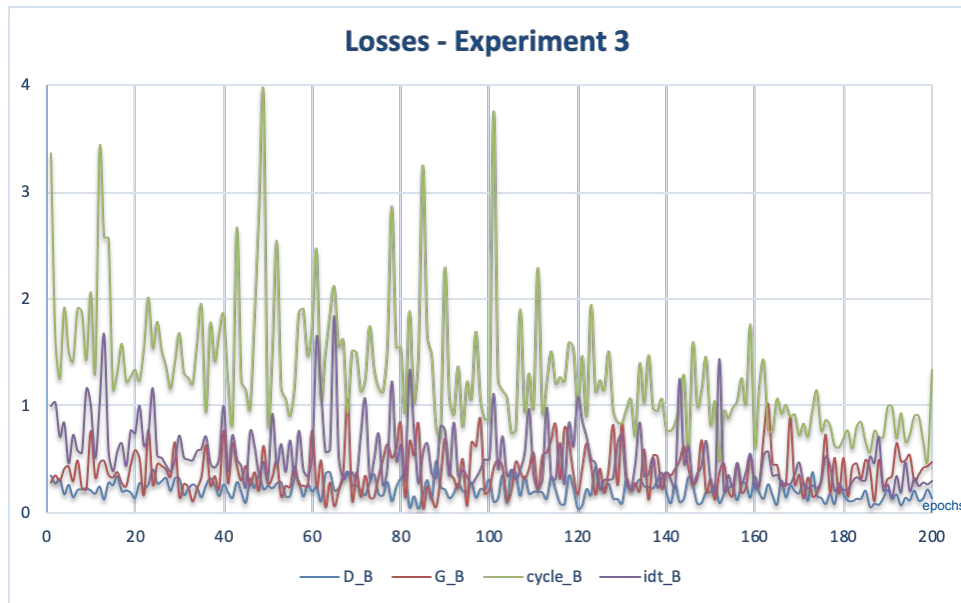
0.714

idt_A

0.780

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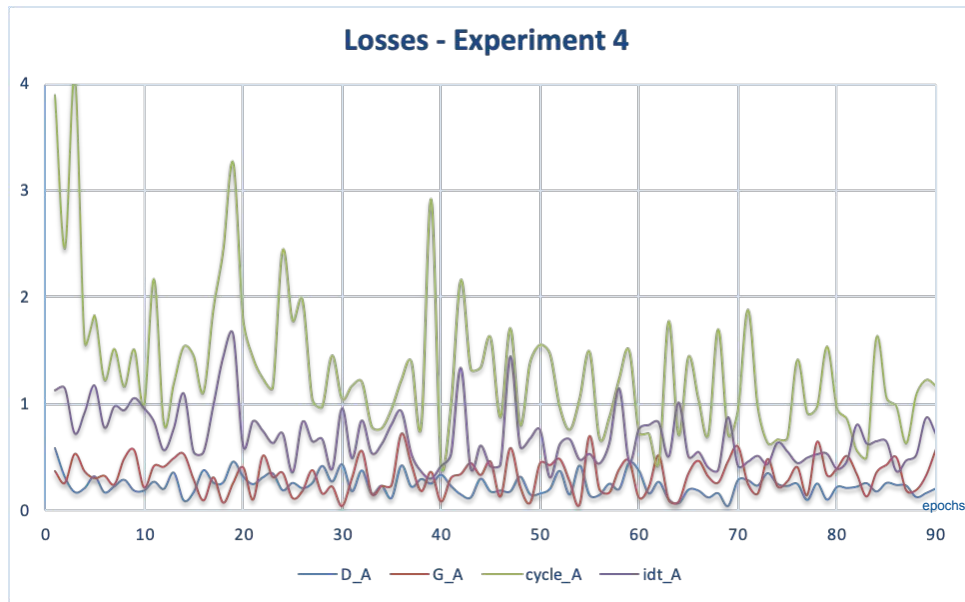
Training - Results



Training time	≈ 5.7h (for both transf)	
# Param. Network G_B	11.378 M	
Losses last iter	D_B	0.134
	G_B	0.472
	cycle_B	1.333
	idt_B	0.290

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Training - Results



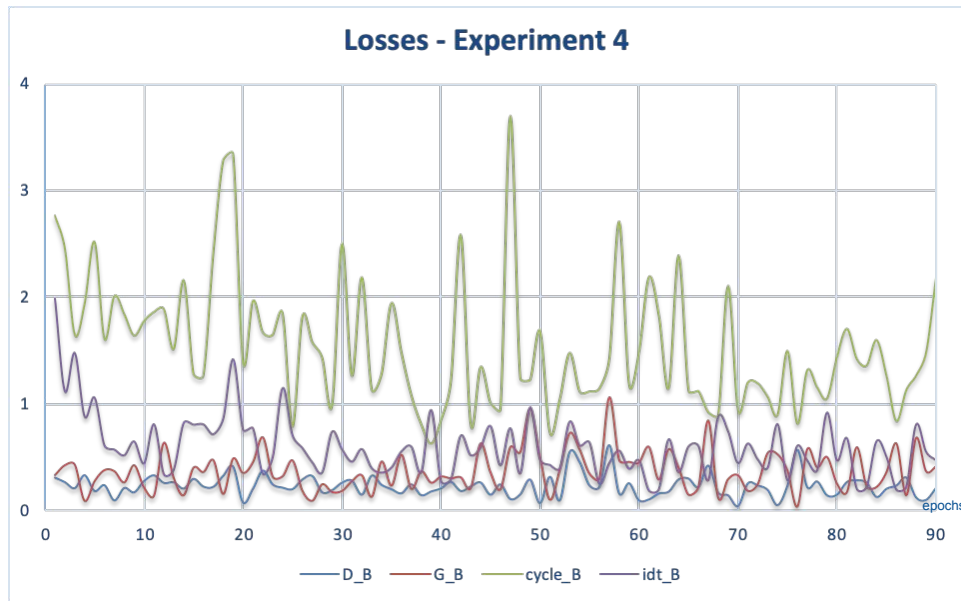
Training time	$\approx 5.4\text{h}$ (for both transf)
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# Param. Network G_A	11.378 M
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Losses last iter	D_A	0.203
	G_A	0.585
	cycle_A	1.165
	idt_A	0.723

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Training - Results



Training time	$\approx 5.4\text{h}$ (for both transf)
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# Param. Network G_B	11.378 M
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Losses last iter	D_B	0.218
	G_B	0.408
	cycle_B	2.180
	idt_B	0.479

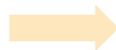
5

Results

Training time

Same

Batch size
Amount of data
Num. of iterations



Pix2Pix converges faster but
learns only one transformation

Qualitative testing

- AMT

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Testing - Results

Original pair



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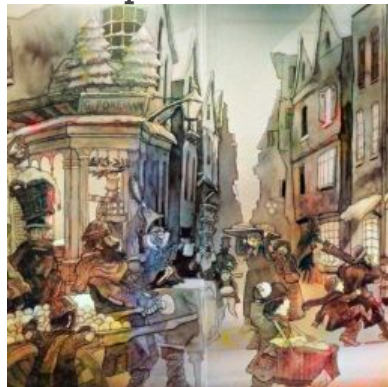
Testing - Results

Pix2Pix

Original B&W



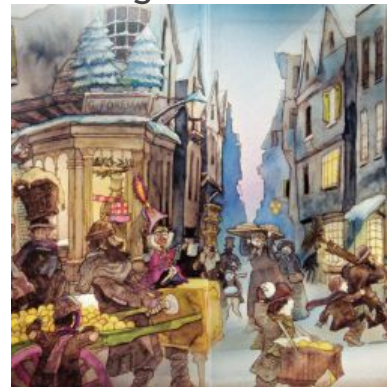
Experiment 1



Experiment 2



Original Color



Only difference between Experiment 1 and Experiment 2 is the batch size

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Testing - Results

CycleGAN: B&W → Color

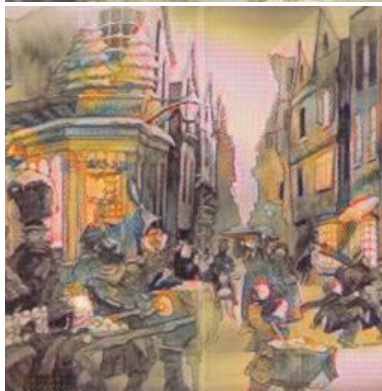
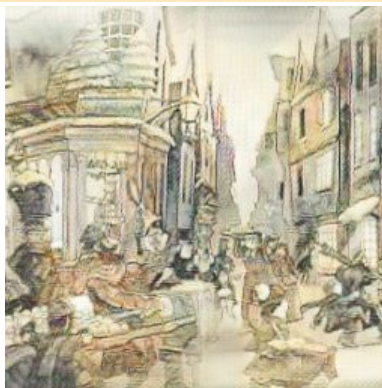
Fake colored

Reconstructed

Experiment 3



Experiment 4



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Testing - Results

CycleGAN: Color \rightarrow B&W

Fake B&W

Reconstructed

Experiment 3

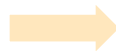


Experiment 4

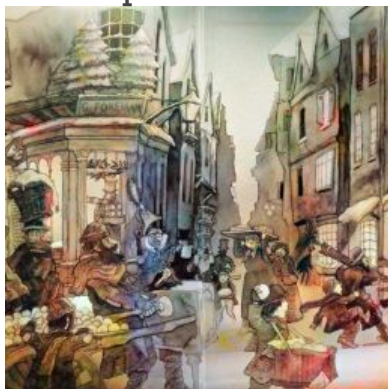


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Testing - Results



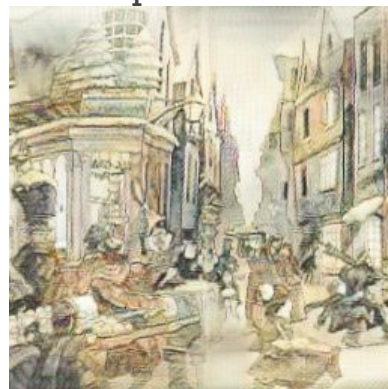
Experiment 1



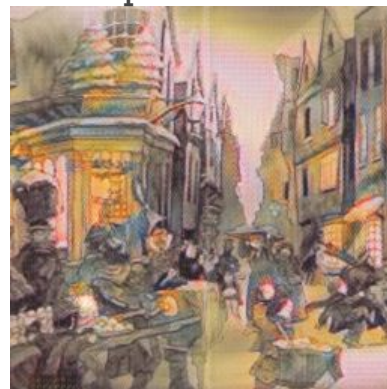
Experiment 2



Experiment 3



Experiment 4



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Conclusions

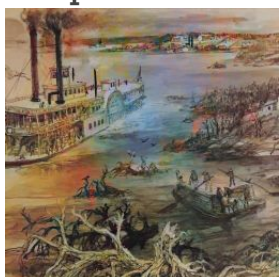
6

Conclusions

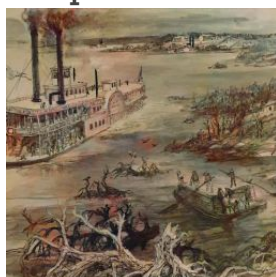
Original



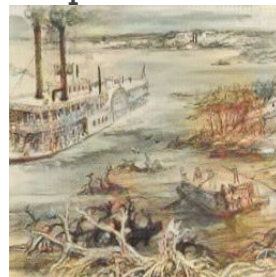
Experiment 1



Experiment 2



Experiment 3



GT



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References

- [1] Hoyoel, K. (2019). Victorian400. Retrieved from <https://www.kaggle.com/elibooklover/victorian400>
- [2] Phillip Isola, Jun-Yan Zhu, Tinghui Zhou, & Alexei A. Efros. (2018). Image-to-Image Translation with Conditional Adversarial Networks. Retrieved from <https://arxiv.org/pdf/1611.07004.pdf>
- [3] Jun-Yan Zhu, Taesung Park, Phillip Isola, & Alexei A. Efros. (2018). Unpaired Image-to-Image Translation using Cycle-Consistent Adversarial Networks. Retrieved from <https://arxiv.org/pdf/1703.10593.pdf>
- [4] junyanz/pytorch-CycleGAN-and-pix2pix. (2018). Retrieved from <https://github.com/junyanz/pytorch-CycleGAN-and-pix2pix>

Our repository:

Maria Alba, Berta Benet, Marilena Budan (2020). Comparison of Pix2Pix and CycleGAN's performances for illustration colorization. https://github.com/marilenabudan/Colorization_Pix2Pix_CycleGAN



Thank you for listening

Any questions?