

# **Description**

For the electronic measurement of currents : DC, AC, pulsed, mixed, with a galvanic isolation between the primary circuit and the secondary circuit.

#### **Features**

- ◆ Hall effect measuring principle
- ◆ Galvanic isolation between primary and secondary circuit
- ◆ Compact design for PCB mounting
- ◆ Low power consumption
- ◆ Extended measuring range (3 \*I<sub>PN</sub>)
- ◆ Insulated plastic case recognized according to UL 94-V0

## **Advantages**

- **♦** Easy installation
- ◆ Excellent accuracy
- ◆ No insertion losses
- ◆ Excellent performance and price
- Only one design for wide current ratings range
- ♦ High immunity against external Interference



 $I_{PN} = 50...600A$ 

 $V_{OUT} = \pm 4 V$ 

# **Industrial applications**

- ◆ AC variable speed drives
- ♦ Battery supplied applications
- ◆ Uninterruptible Power Supplies (UPS)
- ◆ Power supplies for welding applications
- ◆ Static converters for DC motor drives
- ◆ Switched-Mode Power Supplies (SMPS)

TYPES OF PRODUCTS					
Туре	Primary nominal current r. m. s I <sub>PN</sub> (A)	Primary current measuring range I <sub>PM</sub> (A)			
BSY2 -50/4IOV2	50	±150			
BSY2 -75/4IOV2	75	+225			
BSY2-100/4IOV2	100	±300			
BSY2-150/4IOV2	150	±450			
BSY2-200/4IOV2	200	±600			
BSY2-300/4IOV2	300	±900			
BSY2-400/4IOV2	400	±900			
BSY2-500/4IOV2	500	±900			
BSY2-600/4IOV2	600	±900			

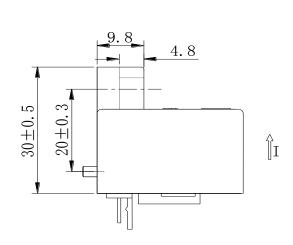
## **Parameters Table**

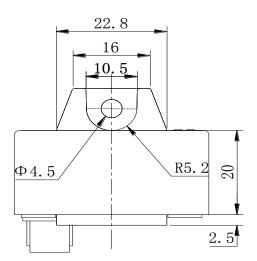
PARAMETERS	SYMBOL	UNIT	VALUE	CONDITIONS	
Electrical data					
Supply voltage(±5%) <sup>(1)</sup>	$V_{\rm C}$	V	±15		
Current consumption	Ic	mA	±15		
Output voltage(Analog)	V <sub>OUT</sub>	mV	±4V ±40	@ $\pm I_{PN}$ , $R_L = 10 \text{ k}\Omega$ , $T_A = 25 \text{ C}$	
Overload capability(1ms)	IPC	At	50* I <sub>PN</sub>		
Isolation resistance	R <sub>IS</sub>	ΜΩ	>1000	@ 500 VDC	
Output internal resistance	Rout	Ω	100	approx	
Load resistance <sup>(2)</sup>	RL	ΚΩ	>10		
R. m. s voltage for AC isolation test	V <sub>d</sub>	KV	3	@50Hz, 1 min	
R. m. s rated voltage, safe separation	V <sub>b</sub>	V	500		
Accuracy - Dynamic perform	ance data		•		
Linearity <sup>(3)</sup> $(0 \pm I_{PN})$	$\epsilon_{ m L}$	% of I <sub>PN</sub>	<±1		
Accuracy	X	%	<±1	@ I <sub>PN</sub> , T <sub>A</sub> = 25 °C (without offset)	
Electrical offset voltage	Voe	mV	< <u>+2</u> 0	@T <sub>A</sub> = 25 ℃	
Hysteresis offset voltage	Voh	mV	<±20	@ I <sub>P</sub> = 0; after an excursion of 1* I <sub>PN</sub>	
Temperature coefficient of V <sub>OE</sub>	TCV <sub>OE</sub>	mV/K	< <u>±2</u>	@BSY2 50—75/4IOV2	
			<±1	@BSY2 100—600/4IOV2	
Temperature coefficient of Vout	TCV <sub>OUT</sub>	%/K	< <u>±</u> 0.1	@% of reading	
Response time	t <sub>r</sub>	μS	<3	@ 90% of I <sub>PN</sub> step	
di/dt accurately followed	d <sub>i</sub> /d <sub>t</sub>	A/μS	>50		
Frequency bandwidth (4)	BW	kHz	DC~50	@-3dB	
General data					
Ambient operating temperature	T <sub>A</sub>	$^{\circ}\!\mathbb{C}$	-40+85		
Ambient storage temperature	Ts	$^{\circ}\!\mathbb{C}$	-40+105		
Mass	m	g	approx 60		

#### **Notes:**

- (1) Operating at  $\pm 12V \le V_C < \pm 15V$  will reduce the measuring range.
- (2) If the customer uses 1  $K\Omega$  of the load resistor, the primary current has to be limited as the nominal. To measure the full defined measuring range, the load resistor should be at minimum 10  $K\Omega$ .
- (3) Linearity data exclude the electrical offset.
- (4) Please refer to derating curves in the technical file to avoid excessive core heating at high frequency.

## **Dimensions BSY2-IOV2** (in mm. 1 mm = 0.0394 inch)





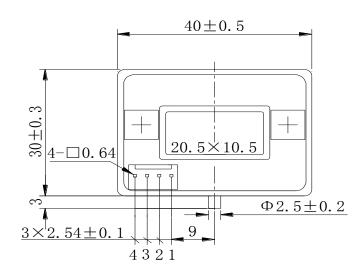
Pins Arrangement

3. OUTPUT

4. 0V

General Tolerance:  $\pm 0.5$  mm





#### **◆Instructions of use**

- 1. When the test current passes through the sensors you can get the size of the output voltage. (Warning: wrong connection may lead to sensors damage.)
- 2. Based on user needs, the sensors output range can be appropriately regulated.
- 3. According to user needs, different rated input currents and output voltages of the sensors can be customized.



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