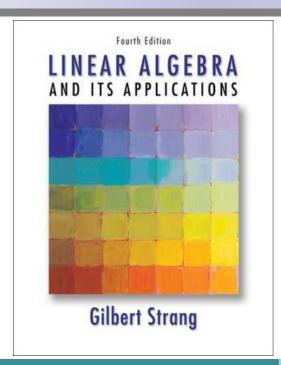
Linear Algebra



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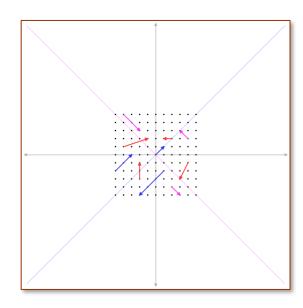
5

Eigenvalues and Eigenvectors (特征值与特征向量)

5.5

COMPLEX MATRICES

Operations in the Complex Case
Hermitian Matrices
Unitary Matrices



Since $|A - \lambda I|$ is a polynomial of degree n, the equation always has exactly n roots, counting multiplicities, provided that possibly complex roots are included.

A real matrix has real coefficients in $|A - \lambda I|$, but the eigenvalues (as in rotations) may be *complex*.



We cannot avoid complex numbers and vectors any more.

The key is to let A act on the space \mathbb{C}^n .

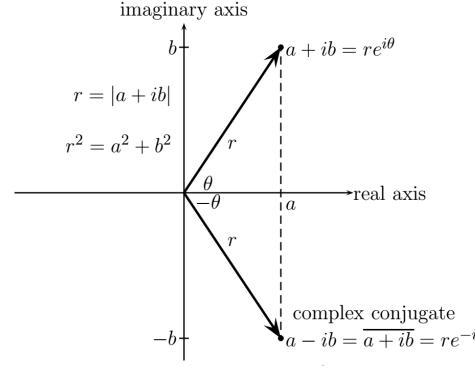
The new definitions coincide with the old when the vectors and matrices are *real*.

Main results:

- 1. Every symmetric matrix (and Hermitian matrix) has real eigenvalues.
- 2. Its eigenvectors can be chosen to be orthonormal.

I. Some Definitions in the Complex Case

- (1) Take a complex number z = a + ib, where $i = \sqrt{-1}$.
 - Conjugate (共轭) $\bar{z} = a ib$.
 - Absolute value $r = |z| = \sqrt{a^2 + b^2}$.
 - Polar form: $a + ib = r(\cos\theta + i\sin\theta) = r\mathbf{e}^{i\theta}$.



Complex addition

$$(a+ib) + (c+id)$$

= $(a+c) + i(b+d)$.

Multiplication

$$(a+ib)(c+id)$$

$$= (ac-bd) + i(bc+ad).$$

The complex plane, with $a + ib = re^{i\theta}$ and its conjugate $a - ib = re^{-i\theta}$.

Three important properties:

1. The conjugate of a product equals the product of the conjugates:

$$\overline{(a+ib)(c+id)} = (ac-bd) - i(bc+ad)$$
$$= \overline{(a+ib)} \overline{(c+id)}.$$

2. The conjugate of a sum equals the sum of the conjugates:

$$\overline{(a+c)+i(b+d)} = (a+c)-i(b+d)$$
$$= \overline{(a+ib)} + \overline{(c+id)}.$$

3. Multiplying any a + ib by its conjugate a - ib produces a real number $a^2 + b^2$:

$$(a+ib)(a-ib) = a^2 + b^2 = r^2.$$

This distance r is the absolute value $|a + ib| = \sqrt{a^2 + b^2}$.

For example,

x = 3 + 4i times its conjugate $\bar{x} = 3 - 4i$ is the absolute value squared:

$$x\bar{x} = (3+4i)(3-4i) = 25 = |x|^2$$

so
$$r = |x| = 5$$
.

To divide by 3 + 4i, multiply numerator and denominator by its conjugate 3 - 4i:

$$\frac{2+i}{3+4i} = \frac{2+i}{3+4i} \cdot \frac{3-4i}{3-4i} = \frac{10-5i}{25}.$$

In *polar coordinates*(极坐标), multiplication and division are easy: $re^{i\theta}$ times $Re^{i\alpha}$ has absolute value rR and angle $\theta + \alpha$. $re^{i\theta}$ divided by $Re^{i\alpha}$ has absolute value r/R and angle $\theta - \alpha$.

(2) Pick a complex vector
$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \in \mathbf{C}^n$$
 (the complex vector space

containing all vectors with n complex components), where $x_j = a_j + ib_j$.

- Vector addition: $\mathbf{x} + \mathbf{y} = (x_1 + y_1, x_2 + y_2, ..., x_n + y_n)^T$.
- Scalar multiplication: cx, $c \in C$.
- The vectors $v_1, v_2, ..., v_k$ are linearly *dependent* if some *nontrivial* combination gives $c_1v_1 + \cdots + c_kv_k = 0$; the c_j may now be complex.
- C^n is a complex vector space of dimension n. (The unit coordinate vectors are still in C^n ; they are still independent; and they still form a basis.)

For $x, y \in \mathbb{C}^n$,

- The length squared $||x||^2 = |x_1|^2 + |x_2|^2 + \cdots + |x_n|^2$.
- The conjugate: $\overline{x} = (\bar{x}_1, \bar{x}_2, ..., \bar{x}_n)^T$.
- Inner product: $\overline{\boldsymbol{x}}^{T}\boldsymbol{y} = \bar{x}_{1}y_{1} + \cdots + \bar{x}_{n}y_{n}$. In particular, $\overline{\boldsymbol{x}}^{T}\boldsymbol{x} = \bar{x}_{1}x_{1} + \cdots + \bar{x}_{n}x_{n} = \|\boldsymbol{x}\|^{2}$.

Attention: Length is computed differently.

The inner product, the definitions of symmetric and orthogonal matrices, all need to be modified for complex numbers.

For example,

$$\boldsymbol{x} = \begin{bmatrix} 1 \\ i \end{bmatrix}$$
, then $\|\boldsymbol{x}\|^2 = 2$.

$$y = \begin{bmatrix} 2+i \\ 2-4i \end{bmatrix}$$
, then $||y||^2 = 25$.

Also
$$\overline{y}^{T}y = \overline{(2+i)}(2+i) + \overline{(2-4i)}(2-4i) = 5 + 20 = 25.$$

- (3) Let $\mathbf{A} = [a_{ij}]_{m \times n}$ be a complex matrix.
 - The conjugate: $\overline{A} = [\overline{a}_{ij}]_{m \times n}$.
 - The conjugate transpose (共轭转置): $\overline{A}^{T} = [\overline{a}_{ji}]_{n \times m}$,

called 'A Hermitian' (A的厄米特矩阵), denoted by A^H .

(Instead of a bar for the conjugate and a T for the transpose, a superscript H combines both operations)

For example,
$$\begin{bmatrix} 2+i & 3i \\ 4-i & 5 \\ 0 & 0 \end{bmatrix}^H = \begin{bmatrix} 2-i & 4+i & 0 \\ -3i & 5 & 0 \end{bmatrix}$$
.

• For
$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$
, $\mathbf{x}^H = (\bar{x}_1, \bar{x}_2, \dots, \bar{x}_n)$.

- Inner product $\overline{x}^T y$ can also be written as $x^H y$. Orthogonal vectors have $x^H y = 0$. $(AB)^H = B^H A^H,$ and $(A^H)^H = A$.
- The squared length of x is $x^H x$.

Remark We note

II. Hermitian Matrices and Properties

Real cases: Symmetric matrices: $A = A^{T}$.

With complex entries, this idea of symmetry has to be extended.

Generalization: matrices that equal their conjugate transpose.

Definition 1 A matrix A is called a **Hermitian matrix** (A是厄米特矩阵) if $A^H = A$. (即满足: A的共轭转置矩阵等于它本身)

For example,

$$A = \begin{bmatrix} 2 & 3-3i \\ 3+3i & 5 \end{bmatrix} = A^H$$
, so A is a Hermitian matrix.

The diagonal entries must be real; Each off-diagonal entry is matched with its mirror image across the main diagonal.

Remark A real symmetric matrix is certainly Hermitian. (For real matrices there is no difference between A^{T} and A^{H} .)

Property 1 If $\mathbf{A} = \mathbf{A}^H$, then for all complex vectors \mathbf{x} , the number $\mathbf{x}^H \mathbf{A} \mathbf{x}$ is real.

Proof. Notice that $x^H A x$ is a number, and

$$(\mathbf{x}^H \mathbf{A} \mathbf{x})^H = \mathbf{x}^H \mathbf{A}^H (\mathbf{x}^H)^H = \mathbf{x}^H \mathbf{A} \mathbf{x}.$$

That is to say, $x^H A x$ is a number which is equal to its conjugate.

So $x^H Ax$ is a real number.

Property 2 If $A = A^H$, then every eigenvalue is a real number.

Proof. Let A be a Hermitian matrix, and assume $Ax = \lambda x$.

Then
$$x^H A x = x^H \lambda x = \lambda x^H x = \lambda ||x||^2$$
.

By Property 1, $x^H A x$ is real.

And since $x \neq 0$, $||x||^2$ is real and positive,

thus $\lambda = \frac{x^H A x}{\|x\|^2}$, and so λ is a real number.

Property 2 If $A = A^H$, then every eigenvalue is a real number.

A Second Proof. (without using Property 1)

$$\bar{\lambda}x^Hx = (\lambda x)^Hx = (Ax)^Hx = x^HA^Hx = x^HAx = \lambda x^Hx.$$

So $\bar{\lambda} = \lambda$, and λ is a real number.

For example,

$$A = \begin{bmatrix} 2 & 3-3i \\ 3+3i & 5 \end{bmatrix} = A^H$$
, so A is a Hermitian matrix.

Then

$$|A - \lambda I| = \begin{vmatrix} 2 - \lambda & 3 - 3i \\ 3 + 3i & 5 - \lambda \end{vmatrix}$$

= $\lambda^2 - 7\lambda + 10 - |3 - 3i|^2$
= $\lambda^2 - 7\lambda - 8 = (\lambda - 8)(\lambda + 1)$.

The eigenvalues of A are 8 and -1.

Property 3 Let A be a Hermitian matrix (i.e., $A = A^H$), and λ_1, λ_2 be two different eigenvalues of A. Then the eigenvectors corresponding to λ_1, λ_2 are orthogonal to each other.

In particular, this is true for real symmetric matrices.

Proof. Let x_1, x_2 be the eigenvectors of A corresponding to λ_1, λ_2 , respectively. Then

$$Ax_1 = \lambda_1 x_1$$
, and $Ax_2 = \lambda_2 x_2$.

Hence

$$\lambda_1 x_1^H x_2 = (\lambda_1 x_1)^H x_2 = (A x_1)^H x_2 = x_1^H A^H x_2$$

= $x_1^H A x_2 = x_1^H \lambda_2 x_2 = \lambda_2 x_1^H x_2$.

Since $\lambda_1 \neq \lambda_2$, we conclude that $\mathbf{x}_1^H \mathbf{x}_2 = 0$, and $\mathbf{x}_1, \mathbf{x}_2$ are orthogonal.

For example,

$$A = \begin{bmatrix} 2 & 3-3i \\ 3+3i & 5 \end{bmatrix} = A^H$$
, so A is a Hermitian matrix.

The eigenvalues of A are 8 and -1.

$$(A - 8I)x = \begin{bmatrix} -6 & 3 - 3i \\ 3 + 3i & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad x = \begin{bmatrix} 1 \\ 1 + i \end{bmatrix}.$$

$$(\mathbf{A} + \mathbf{I})\mathbf{y} = \begin{bmatrix} 3 & 3 - 3i \\ 3 + 3i & 6 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}, \quad \mathbf{y} = \begin{bmatrix} 1 - i \\ -1 \end{bmatrix}.$$

The two eigenvectors are orthogonal:

$$\mathbf{x}^H \mathbf{y} = \begin{bmatrix} 1 & 1 - i \end{bmatrix} \begin{bmatrix} 1 - i \\ -1 \end{bmatrix} = 0.$$

The next is one of the great theorems in linear algebra.

Theorem 1 (Spectral Theorem, part I) A real symmetric matrix (实对称矩阵) A can be factored into

$$A = \mathbf{Q} \Lambda \mathbf{Q}^T.$$

Its orthonormal eigenvectors are in the orthogonal matrix Q and its eigenvalues are in Λ .

Proof. (We only prove this for **A** with distinct eigenvalues.)

Let Q be the matrix with columns being n eigenvectors of A which are orthonormal. Then

$$\mathbf{Q}^{-1}\mathbf{A}\mathbf{Q} = \mathbf{\Lambda} = \operatorname{diag}(\lambda_1, \lambda_2, \dots, \lambda_n),$$

and so $\mathbf{A} = \mathbf{Q} \Lambda \mathbf{Q}^{-1} = \mathbf{Q} \Lambda \mathbf{Q}^{\mathrm{T}}$.

(Even with repeated eigenvalues, a symmetric matrix still has a complete set of orthonormal eigenvectors. – Next section)

Remark 1

$$A = \mathbf{Q} \Lambda \mathbf{Q}^{T} = \begin{bmatrix} \mathbf{x}_{1} & \dots & \mathbf{x}_{n} \end{bmatrix} \begin{bmatrix} \lambda_{1} & & & \\ & \ddots & & \\ & & \lambda_{n} \end{bmatrix} \begin{bmatrix} \mathbf{x}_{1}^{T} \\ \vdots \\ \mathbf{x}_{n}^{T} \end{bmatrix}$$
$$= \lambda_{1} \mathbf{x}_{1} \mathbf{x}_{1}^{T} + \lambda_{2} \mathbf{x}_{2} \mathbf{x}_{2}^{T} + \dots + \lambda_{n} \mathbf{x}_{n} \mathbf{x}_{n}^{T}.$$

So A becomes a combination of one-dimensional projections—which are the special matrices $x_i x_i^T$ of rank 1, multiplied by λ_i .

Example 1 $A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$ has eigenvalues $\lambda_1 = 1$ and $\lambda_2 = 3$.

The eigenvectors, with length scaled to 1, are

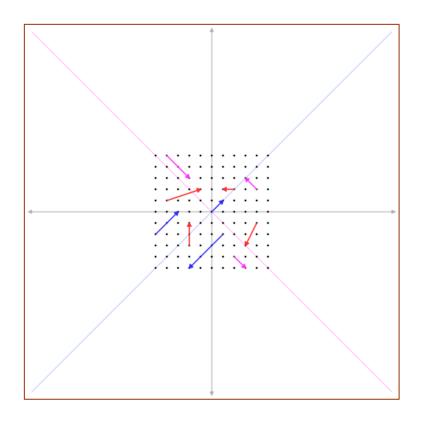
$$\mathbf{x}_{1} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \text{ and } \mathbf{x}_{2} = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ 1 \end{bmatrix}.$$

$$\mathbf{A} = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} = \begin{bmatrix} \frac{1}{2} & -\frac{1}{2} \\ -\frac{1}{2} & \frac{1}{2} \end{bmatrix} + 3 \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{bmatrix} = \lambda_{1} \mathbf{x}_{1} \mathbf{x}_{1}^{T} + \lambda_{2} \mathbf{x}_{2} \mathbf{x}_{2}^{T}.$$

— combination of two one-dimensional projections.

For example,

$$A = \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$



The Eigenvectors

$$k_{1} \begin{bmatrix} 1 \\ -1 \end{bmatrix} \qquad k_{2} \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

$$(k_{1} \neq 0) \qquad (k_{2} \neq 0)$$

Corresponding respectively to the Eigenvalues:

$$\lambda_1 = 1$$
 $\lambda_2 = 3$

Remark 2 If *A* is *real* and its eigenvalues *happen to be real*, then its eigenvectors are also real.

(solve
$$(A - \lambda I)x = 0$$
 and compute by elimination.)

But they will not be orthogonal unless \boldsymbol{A} is symmetric:

$$A = Q\Lambda Q^{T}$$
 leads to $A^{T} = A$.

Remark 3 If A is *real*, all complex eigenvalues come in conjugate pairs: $Ax = \lambda x$ and $A\overline{x} = \overline{\lambda} \overline{x}$.

(This is true because
$$A\overline{x} = \overline{Ax} = \overline{\lambda}\overline{x} = \overline{\lambda}\overline{x}$$
)

Hence $\bar{\lambda}$ is also an eigenvalue of \boldsymbol{A} , with $\overline{\boldsymbol{x}}$ a corresponding eigenvector.

If a + ib is an eigenvalue of a real matrix, so is a - ib.

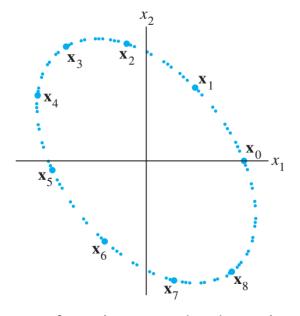
(If
$$A = A^{T}$$
 then $b = 0$. 实对称矩阵的特征值都是实数)

For example,
$$A = \begin{bmatrix} 0.5 & -0.6 \\ 0.75 & 1.1 \end{bmatrix}$$

The eigenvalues are $\lambda_{1.2} = 0.8 \pm 0.6i$.

The basis for the eigenspace corresponding to λ_1 and λ_2 are

$$\boldsymbol{v}_1 = \begin{bmatrix} -2+4i \\ 5 \end{bmatrix}$$
 and $\boldsymbol{v}_2 = \begin{bmatrix} -2-4i \\ 5 \end{bmatrix}$.



Iterates of a point x_0 under the action of a matrix with a complex eigenvalue

One way to see how multiplication by \boldsymbol{A} affects points is to plot an arbitrary initial point – say, $\boldsymbol{x}_0 = (2,0)^T$ – and then to plot

$$x_1 = Ax_0, x_2 = Ax_1, x_3 = Ax_2, \dots$$

Example 2 Let
$$A = \begin{bmatrix} 2 & 2 & -2 \\ 2 & 5 & -4 \\ -2 & -4 & 5 \end{bmatrix}$$
.

Find an orthogonal matrix Q such that $Q^{-1}AQ$ is a diagonal matrix.

Solution

$$|A - \lambda I| = \begin{vmatrix} 2 - \lambda & 2 & -2 \\ 2 & 5 - \lambda & -4 \\ -2 & -4 & 5 - \lambda \end{vmatrix} = \begin{vmatrix} 2 - \lambda & 2 & -2 \\ 0 & 1 - \lambda & 1 - \lambda \\ -2 & -4 & 5 - \lambda \end{vmatrix}$$

$$= \begin{vmatrix} 2 - \lambda & 2 & -4 \\ 0 & 1 - \lambda & 0 \\ -2 & -4 & 9 - \lambda \end{vmatrix} = (1 - \lambda) \begin{vmatrix} 2 - \lambda & -4 \\ -2 & 9 - \lambda \end{vmatrix}$$

$$= (1 - \lambda)^2 (10 - \lambda).$$

So the eigenvalues of A are $\lambda_1 = 1$ (Algebraic multiplicity is 2) and $\lambda_2 = 10$ (Algebraic multiplicity is 1).

For the eigenvalue $\lambda_1=1$, by $(A-\lambda_1 I)x=0$, i.e.,

$$\begin{bmatrix} 1 & 2 & -2 \\ 2 & 4 & -4 \\ -2 & -4 & 4 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$$

The basis for the eigenspace of λ_1 : $x_1 = (-2, 1, 0)^T$, $x_2 = (2, 0, 1)^T$.

By Gram-Schmidt orthogonalization, let

$$\boldsymbol{\beta}_1 = \boldsymbol{x}_1 = (-2, 1, 0)^{\mathrm{T}},$$

$$\boldsymbol{\beta}_2 = \boldsymbol{x}_2 - \frac{\boldsymbol{x}_2^T \boldsymbol{\beta}_1}{\boldsymbol{\beta}_1^T \boldsymbol{\beta}_1} \boldsymbol{\beta}_1 = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix} - \frac{-4}{5} \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} \frac{2}{5} \\ \frac{4}{5} \\ 1 \end{bmatrix} = \frac{1}{5} \begin{bmatrix} 2 \\ 4 \\ 5 \end{bmatrix},$$

and normalize β_1 , β_2 into:

$$\gamma_1 = \frac{\beta_1}{\|\beta_1\|} = \frac{\sqrt{5}}{5} \begin{bmatrix} -2, & 1, & 0 \end{bmatrix}^T, \quad \gamma_2 = \frac{\beta_2}{\|\beta_2\|} = \frac{\sqrt{5}}{15} \begin{bmatrix} 2, & 4, & 5 \end{bmatrix}^T.$$

For the eigenvalue
$$\lambda_2 = 10$$
, by $(\mathbf{A} - \lambda_2 \mathbf{I}) \mathbf{x} = \mathbf{0}$, i.e., $\begin{bmatrix} -8 & 2 & -2 \\ 2 & -5 & -4 \\ -2 & -4 & -5 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix}$

We can get $x_3 = (1, 2, -2)^T$ and the corresponding unit vector:

$$\gamma_3 = \frac{1}{3} \begin{bmatrix} 1, & 2, & -2 \end{bmatrix}^T$$
.

Take the orthogonal matrix

$$\mathbf{Q} = \begin{bmatrix} \gamma_1, \gamma_2, \gamma_3 \end{bmatrix} = \begin{bmatrix} -2\sqrt{5}/5 & 2\sqrt{5}/15 & 1/3 \\ \sqrt{5}/5 & 4\sqrt{5}/15 & 2/3 \\ 0 & \sqrt{5}/3 & -2/3 \end{bmatrix}$$

which will make

$$Q^{-1}AQ = diag(\lambda_1, \lambda_2, \lambda_3) = diag(1, 1, 10).$$

III. Unitary Matrices

A *real* orthogonal matrix— $\mathbf{Q}^{\mathrm{T}}\mathbf{Q} = \mathbf{I}$.

For *complex* matrices, the transpose will be replaced by the conjugate transpose. The condition will become $U^H U = I$.

The new letter *U* reflects the new name: *A complex matrix with orthonormal columns is called a unitary matrix*.

Definition 2 A matrix U is called a unitary matrix (酉矩阵) if $U^H = U^{-1}$.

Equivalently, $U^H U = I$, and $U U^H = I$.

Unitary matrices have many nice properties.

Theorem 2 Let *U* be a unitary matrix. Then the following hold.

1. Inner products and lengths are preserved by **U**.

Proof.
$$(Ux)^{H}(Uy) = x^{H}U^{H}Uy = x^{H}y$$
, and $||Ux||^{2} = ||x||^{2}$.

- 2. Every eigenvalue of **U** has absolute value $|\lambda| = 1$.
- **Proof.** This follows directly from $Ux = \lambda x$, by comparing the lengths of the two sides: ||Ux|| = ||x||, and always $||\lambda x|| = |\lambda| \cdot ||x||$. Therefore $|\lambda| = 1$.
- 3. Eigenvectors of **U** corresponding to different eigenvalues are orthogonal (and can be scaled to orthonormal).
- **Proof.** Start with $Ux = \lambda_1 x$ and $Uy = \lambda_2 y$, and take inner products: $x^H y = (Ux)^H (Uy) = (\lambda_1 x)^H (\lambda_2 y) = \overline{\lambda_1} \lambda_2 x^H y$.

Comparing the left to the right, $\overline{\lambda_1}\lambda_2 = 1$ or $\mathbf{x}^H\mathbf{y} = 0$. But Property 2 is $\overline{\lambda_1}\lambda_1 = 1$, so we cannot also have $\overline{\lambda_1}\lambda_2 = 1$. Thus $\mathbf{x}^H\mathbf{y} = 0$ and the eigenvectors are orthogonal (and can be scaled to unit length).

Check the properties by working on the following matrices.

Example 3
$$U = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$
 has eigenvalues $\mathbf{e}^{i\theta}$ and $\mathbf{e}^{-i\theta}$

Example 3 $U = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$ has eigenvalues $\mathbf{e}^{i\theta}$ and $\mathbf{e}^{-i\theta}$. The orthonormal eigenvectors are $\mathbf{x}_1 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ -i \end{bmatrix}$ and $\mathbf{x}_2 = \frac{1}{\sqrt{2}} \begin{bmatrix} 1 \\ i \end{bmatrix}$.

Example 4
$$P = \begin{bmatrix} 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 \end{bmatrix}$$
 has eigenvalues $-1, i, -i, 1$.

The orthonormal eigenvectors are
$$\begin{bmatrix} -\frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ \frac{i}{2} \\ -\frac{1}{2} \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ -\frac{i}{2} \\ -\frac{1}{2} \end{bmatrix}, \begin{bmatrix} -\frac{1}{2} \\ -\frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}.$$

Let A be a matrix of degree n. Let λ be an eigenvalue of A.

The *eigenspace* V_{λ} is the subspace spanned by the eigenvectors of A corresponding to λ .

By Gram-Schmidt procedure, an eigenspace has an orthonormal basis.

Lemma 1 A Hermitian matrix has a complete set of orthonormal eigenvectors. (more discussions in Section 5.6)

Remark Assume that *A* is Hermitian. From each eigenspace of *A*, choose an orthonormal basis by Gram-Schmidt process.

Since any two vectors corresponding to different eigenvalues are orthogonal, the eigenvectors in these orthonormal bases are orthonormal, i.e., there are *n* eigenvectors of *A* which are orthonormal.

Let A be a Hermitian matrix of degree n, and let v_1, v_2, \ldots, v_n be a complete set of orthonormal eigenvectors, corresponding to eigenvalues $\lambda_1, \lambda_2, \ldots, \lambda_n$ respectively.

Let
$$U = [v_1, v_2, ..., v_n]$$
, then U is a unitary matrix, and $AU = A[v_1 v_2 ... v_n] = [Av_1 Av_2 ... Av_n]$
= $[\lambda_1 v_1 \lambda_2 v_2 ... \lambda_n v_n] = U \operatorname{diag}(\lambda_1, \lambda_2, ..., \lambda_n)$.

Thus U diagonalizes A: $U^{-1}AU = \text{diag}(\lambda_1, \lambda_2, ..., \lambda_n)$.

This gives the following important theorem.

Theorem 3 (Spectral Theorem)

- (1) Each real symmetric matrix \mathbf{A} can be diagonalized by an orthogonal matrix \mathbf{Q} .
- (2) Every Hermitian matrix **A** can be diagonalized by a unitary matrix **U**.

The columns of Q (or U) consist of orthonormal eigenvectors of A.

Skew-Hermitian matrices

- Skew-symmetric matrices satisfy $K^{T} = -K$.
- Skew-Hermitian matrices (反厄米特矩阵) satisfy $K^{H} = -K$.

Property If A is Hermitian then K = iA is skew-Hermitian.

(i.e., If
$$\mathbf{A} = \mathbf{A}^{\mathrm{H}}$$
, and $\mathbf{K} = i\mathbf{A}$, then $\mathbf{K}^{\mathrm{H}} = -\mathbf{K}$.)

Remark The eigenvalues of *K* are purely imaginary instead of purely real (反厄米特矩阵的特征值是纯虚数). For example,

$$A = \begin{bmatrix} 2 & 3-3i \\ 3+3i & 5 \end{bmatrix} = A^{H}$$
, so A is a Hermitian matrix.

$$\mathbf{K} = i\mathbf{A} = \begin{bmatrix} 2i & 3+3i \\ -3+3i & 5i \end{bmatrix} = -\mathbf{K}^{\mathrm{H}}.$$

The diagonal entries are multiples of i (allowing zero).

The eigenvalues are 8i and -i.

The eigenvectors are still orthogonal, and we still have $K = U\Lambda U^{H}$ — with a unitary U instead of a real orthogonal Q, and with 8i and -i on the diagonal of Λ .

Real	l versus	Comp.	lex
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$$\mathbf{R}^n$$
 (n real components) \leftrightarrow \mathbf{C}^n (n complex components)length: $||x||^2 = x_1^2 + \cdots + x_n^2$ \leftrightarrow length: $||x||^2 = |x_1|^2 + \cdots + |x_n|^2$ transpose: $A_{ij}^T = A_{ji}$ \leftrightarrow Hermitian transpose: $A_{ij}^H = \overline{A_{ji}}$ $(AB)^T = B^T A^T$ \leftrightarrow $(AB)^H = B^H A^H$ inner product: $x^T y = x_1 y_1 + \cdots + x_n y_n$ \leftrightarrow inner product: $x^H y = \overline{x_1} y_1 + \cdots + \overline{x_n} y_n$ $(Ax)^T y = x^T (A^T y)$ \leftrightarrow $(Ax)^H y = x^H (A^H y)$ orthogonality: $x^T y = 0$ \leftrightarrow orthogonality: $x^H y = 0$ symmetric matrices: $A^T = A$ \leftrightarrow Hermitian matrices: $A^H = A$ $A = Q\Lambda Q^{-1} = Q\Lambda Q^T$ (real Λ) \leftrightarrow $A = U\Lambda U^{-1} = U\Lambda U^H$ (real Λ)skew-symmetric $K^T = -K$ \leftrightarrow skew-Hermitian $K^H = -K$ orthogonal $Q^T Q = I$ or $Q^T = Q^{-1}$ \leftrightarrow unitary $U^H U = I$ or $U^H = U^{-1}$ $(Qx)^T (Qy) = x^T y$ and $||Qx|| = ||x||$ \leftrightarrow $(Ux)^H (Uy) = x^H y$ and $||Ux|| = ||x||$

The columns, rows, and eigenvectors of Q and U are orthonormal, and every $|\lambda| = 1$

Key words:

Real Hermitian matrices are symmetric; real unitary matrices are orthogonal.

Spectral Theorem:

- (1) Each real symmetric matrix \mathbf{A} can be diagonalized by an orthogonal matrix \mathbf{Q} .
- (2) Every Hermitian matrix **A** can be diagonalized by a unitary matrix **U**.

Homework

See Blackboard

