

website: vanderbi.lt/codegraf

QT Py RP2040 introduction

Presenter: Steve Baskauf
steve.baskauf@vanderbilt.edu



Jean & Alexander Heard
LIBRARIES

CodeGraf landing page

- vanderbi.it/codegraf

website: vanderbi.lt/codegraf

CircuitPython



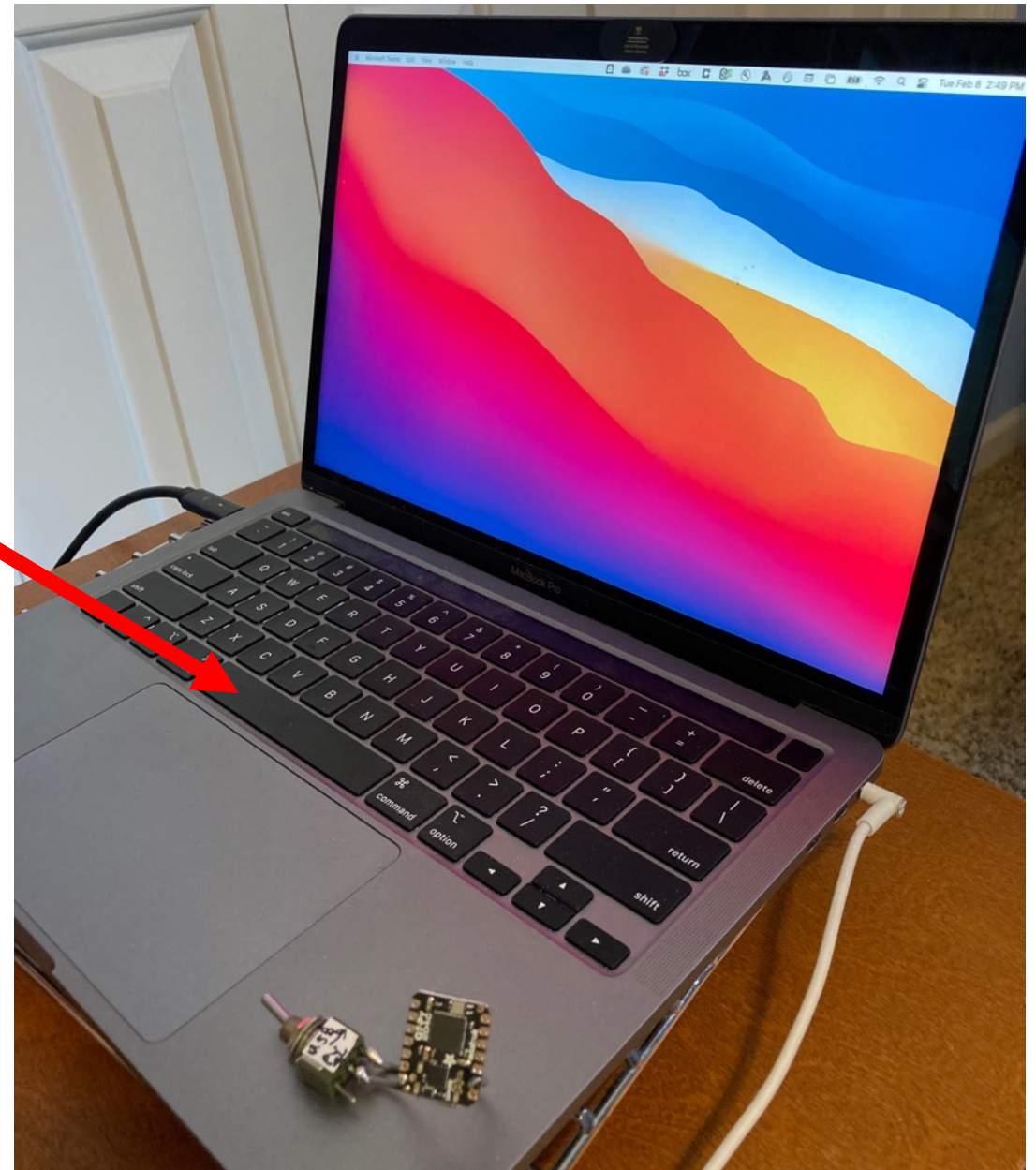
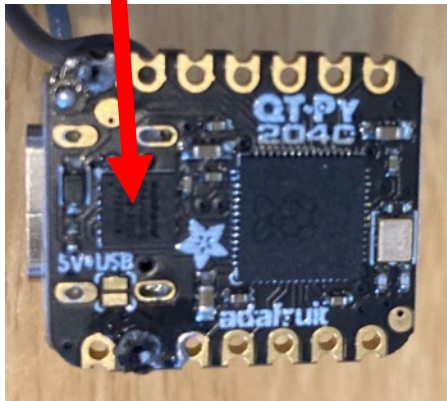
Jean & Alexander Heard
LIBRARIES

Storage requirements

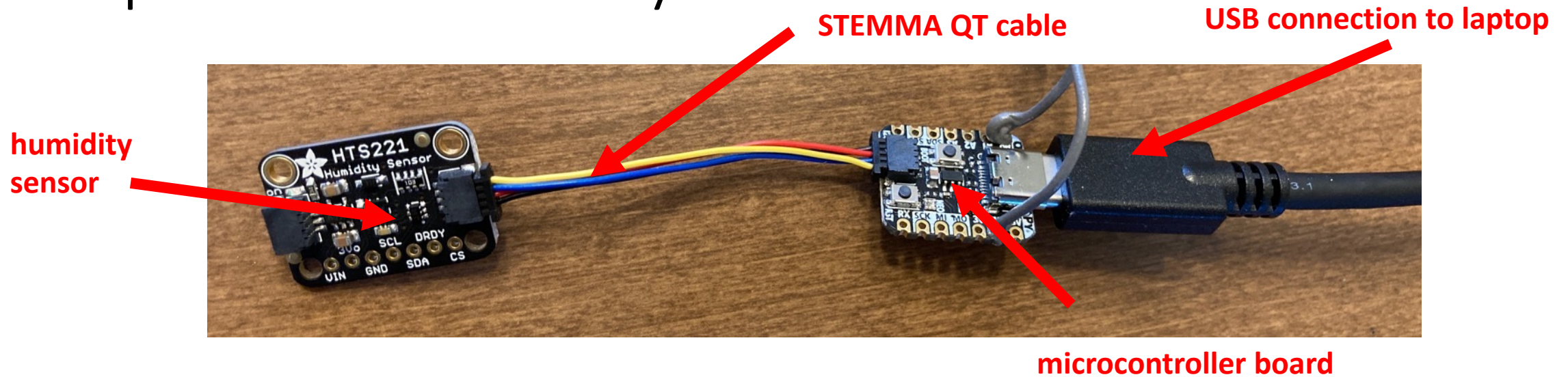
Standard cPython installation: 90 MB

Laptop: up to 1 TB (1 million MB)

QT Py RP2040: 8 MB flash memory

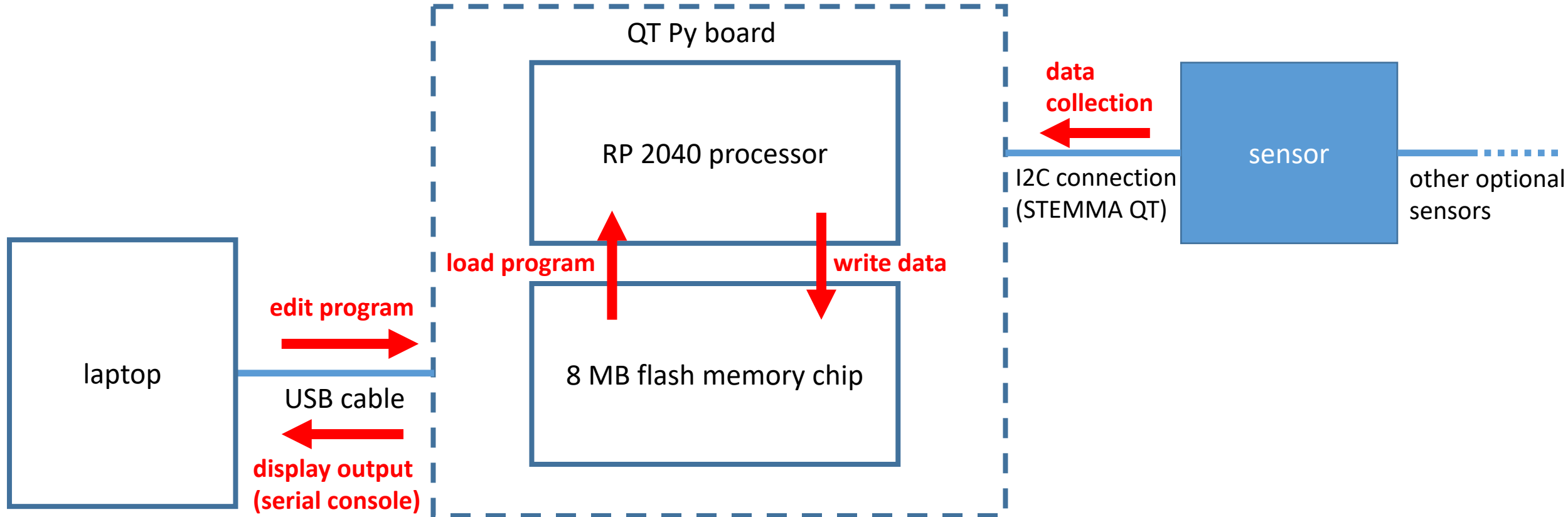


Aspects of CircuitPython



- Stripped down Python language code
- Includes "operating system" for microcontroller board
- Individually installed device libraries support 300 connected devices
- Simplified communication with laptop via USB
- Automated launching of **code.py** file

System architecture



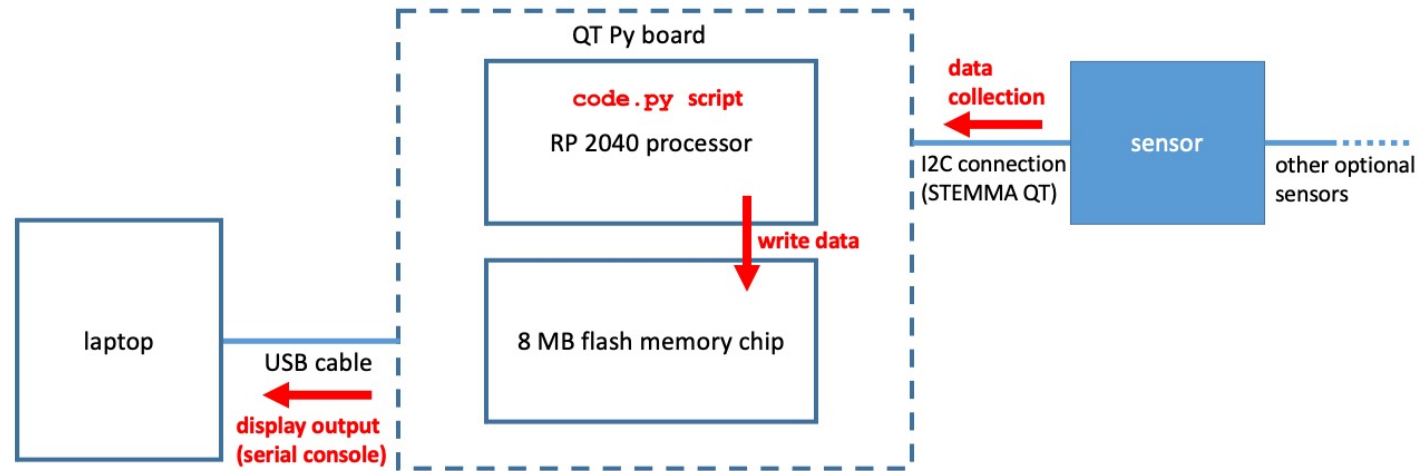
website: vanderbi.lt/codegraf

The `code.py` script



Jean & Alexander Heard
LIBRARIES

What does the `code.py` script do?



The **`code.py`** script is a special file in CircuitPython.

It controls interactions with sensors, memory, and the serial console.

It is executed when:

- the board is powered up.
- when you save something in the "drive" memory (including **`code.py`**).
- when you do a "hard reset" by pushing the reset button on the board
- when you do a "soft reset" (CTRL-D) from the console

Example: code.py for VCNL4040 proximity sensor

load code modules

```
import time
import board
import adafruit_vcnl4040
```

instantiate objects

```
i2c = board.I2C()
sensor = adafruit_vcnl4040.VCNL4040(i2c)
```

read sensors
and report

```
while True:
    print("Proximity:", sensor.proximity)
    print("Light: %d lux" % sensor.lux)
    time.sleep(1.0)
```

website: vanderbi.lt/codegraf

Review of modules



Jean & Alexander Heard
LIBRARIES

What are modules?

- **Modules** are reusable code loaded from a file. "Library" is a similar term to "module".
- They're loaded as needed using an **import** statement.
- Modules in the **standard library** are ready to load.
- Modules not in the standard library must be **installed**.
- In standard Python, the command line **installer application PIP** is typically used to install modules:

```
pip install requests
```

Modules in CircuitPython

- Modules are installed manually in CircuitPython
- Download the CircuitPython Library Bundle to get all the library files for a microcontroller board.
- Library files have an **.mpy** extension.
- Copy manually from the **lib** directory in the bundle to the **lib** directory on your board to install.
- Modules from copied library files can be imported into a script.
- Typically, modules that need to be installed have very specific code for particular sensors.

Example: code.py for VCNL4040 proximity sensor

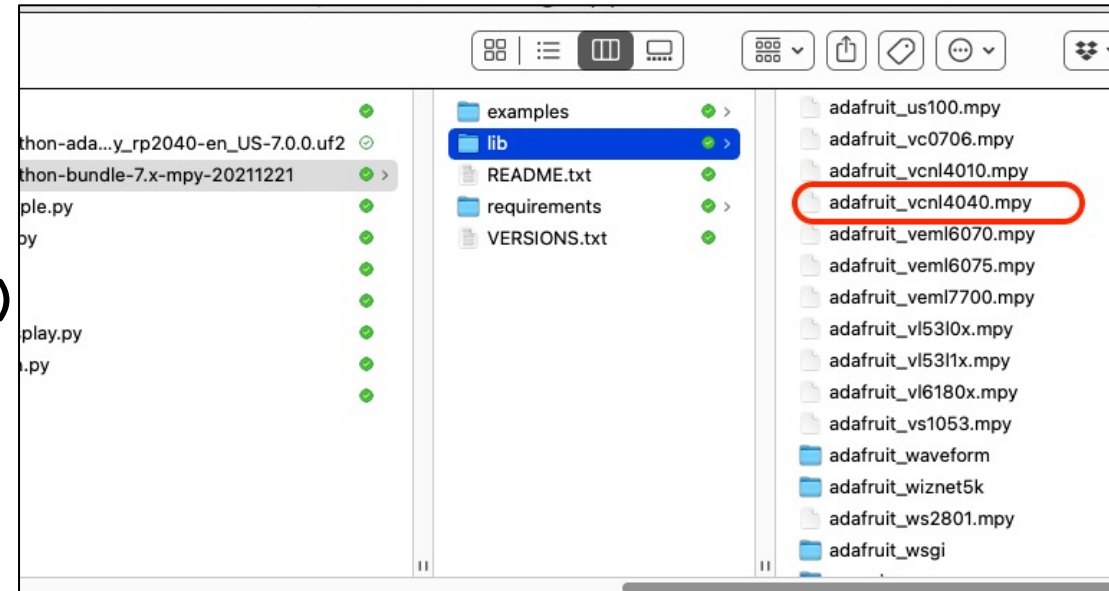
```
import time
import board
import adafruit_vcnl4040
```

← standard library modules (don't need to be installed)

← module in Library Bundle (needs to be copied)

```
i2c = board.I2C()
sensor = adafruit_vcnl4040.VCNL4040(i2c)

while True:
    print("Proximity:", sensor.proximity)
    print("Light: %d lux" % sensor.lux)
    time.sleep(1.0)
```



What is Blinka?

- Sensors can be also be run from a laptop or a single-board computer like a Raspberry Pi.
- The Blinka library can be installed using PIP in standard CPython (Linux, Mac OS, Windows)
- It contains modules that correspond to the modules that are installed manually from the CircuitPython Library Bundle.
- Modules from Blinka are imported in the normal way.



website: vanderbi.lt/codegraf

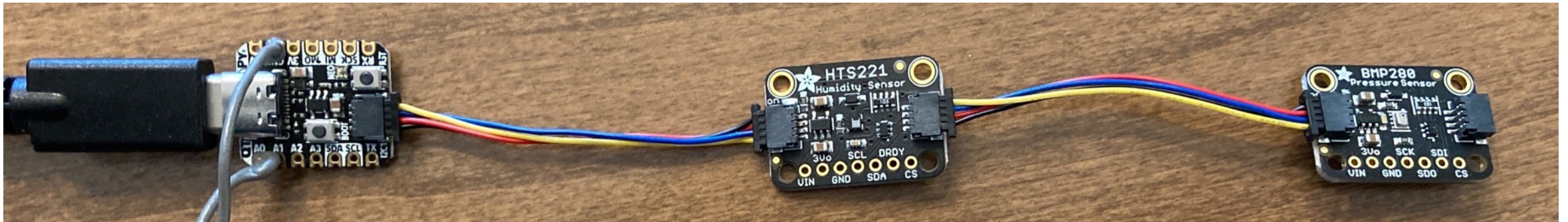
Connecting sensors



Jean & Alexander Heard
LIBRARIES

What is I2C ?

- I2C (pronounced "eye squared C") is a simple communications protocol
- It requires only 2 wires (clock and data).
- All devices share the same 2 wires and can be chained.
- Devices are identified by a unique address (127 possible).



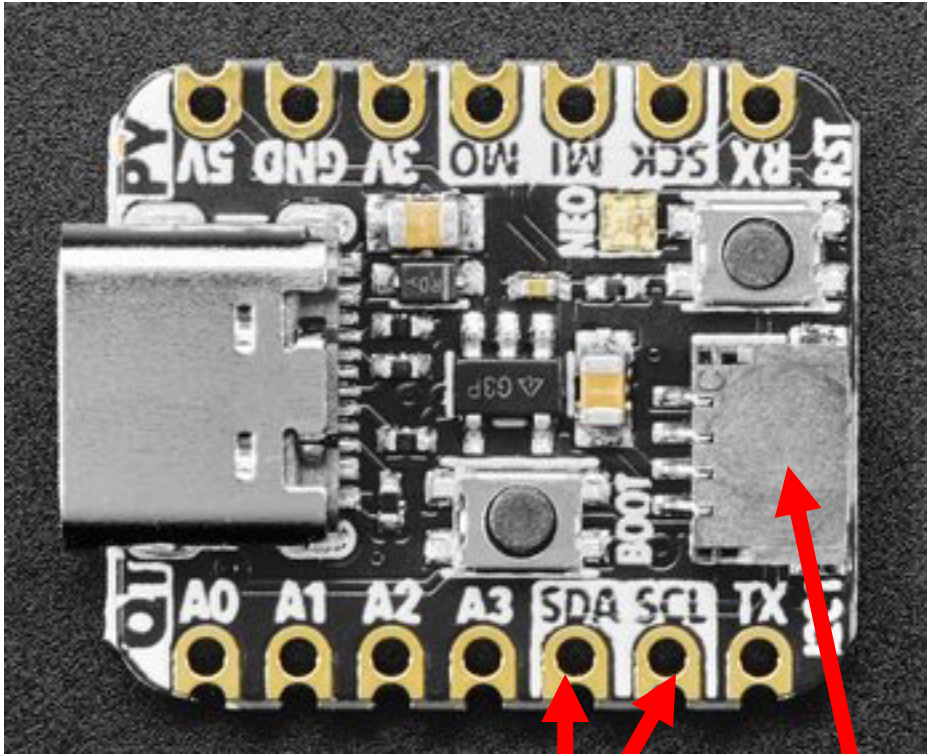
QT Py RP2040
using I2C controller 1

wires
(only 2
needed)

HTS221
Humidity/Temp sensor
address: 0x5F

BMP280
Barometric Pressure sensor
address: 0x76

I2C connections



I2C0 connections on board pads (must be soldered)

I2C1 connections on STEMMA QT connector

QT Py RP2040 has two I2C controllers. They are accessed via:

- **SDA** and **SCL** pads on board (**I2C0**)
- STEMMA QT connector (**I2C1**)

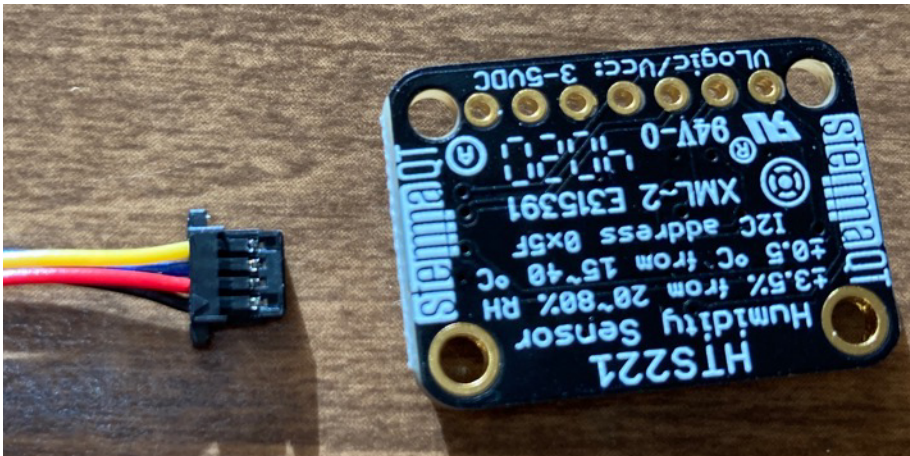
They are addressed in code as:

- `board.SCL` and `board.SDA` (**I2C0**)
- `board.SCL1` and `board.SDA1` (**I2C1**)

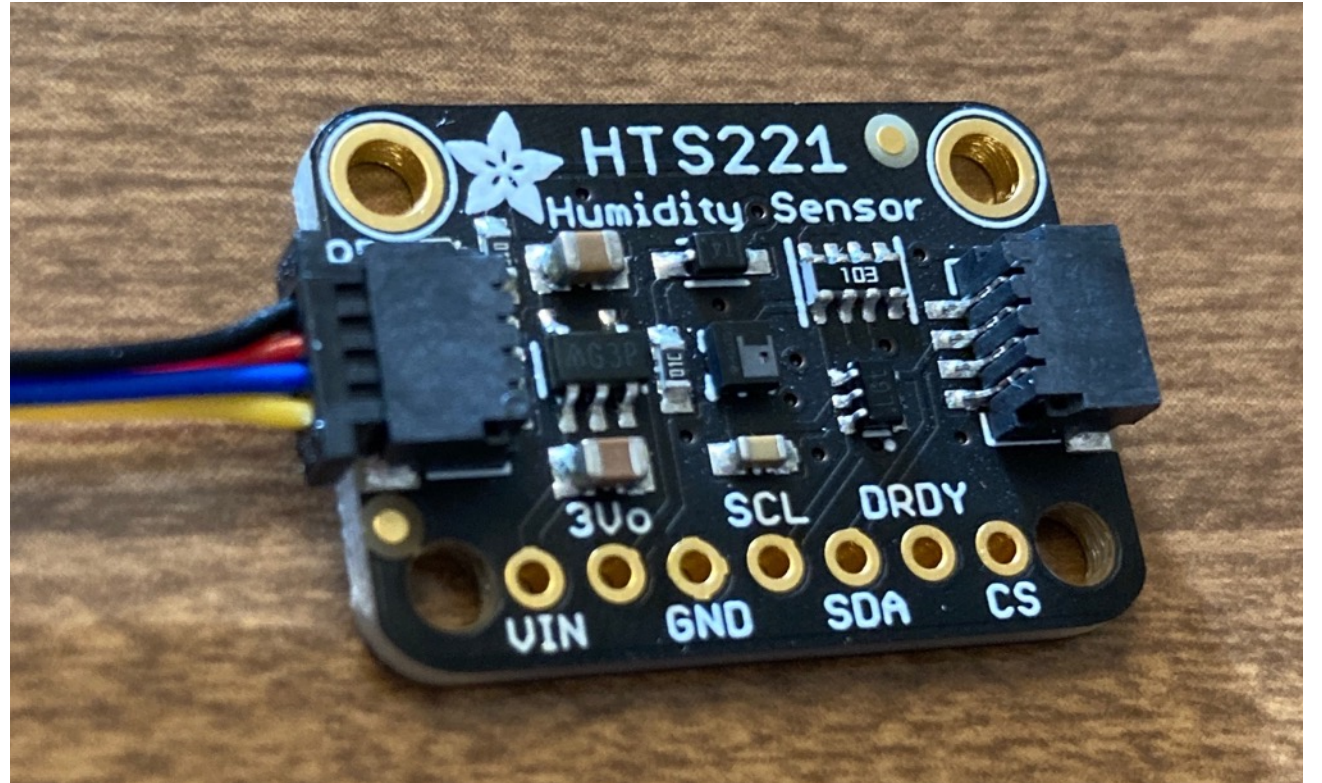
STEMMA QT connectors



top view



bottom view



cable firmly seated in connector
(either connector can be used)

website: vanderbi.lt/codegraf

CircuitPython objects

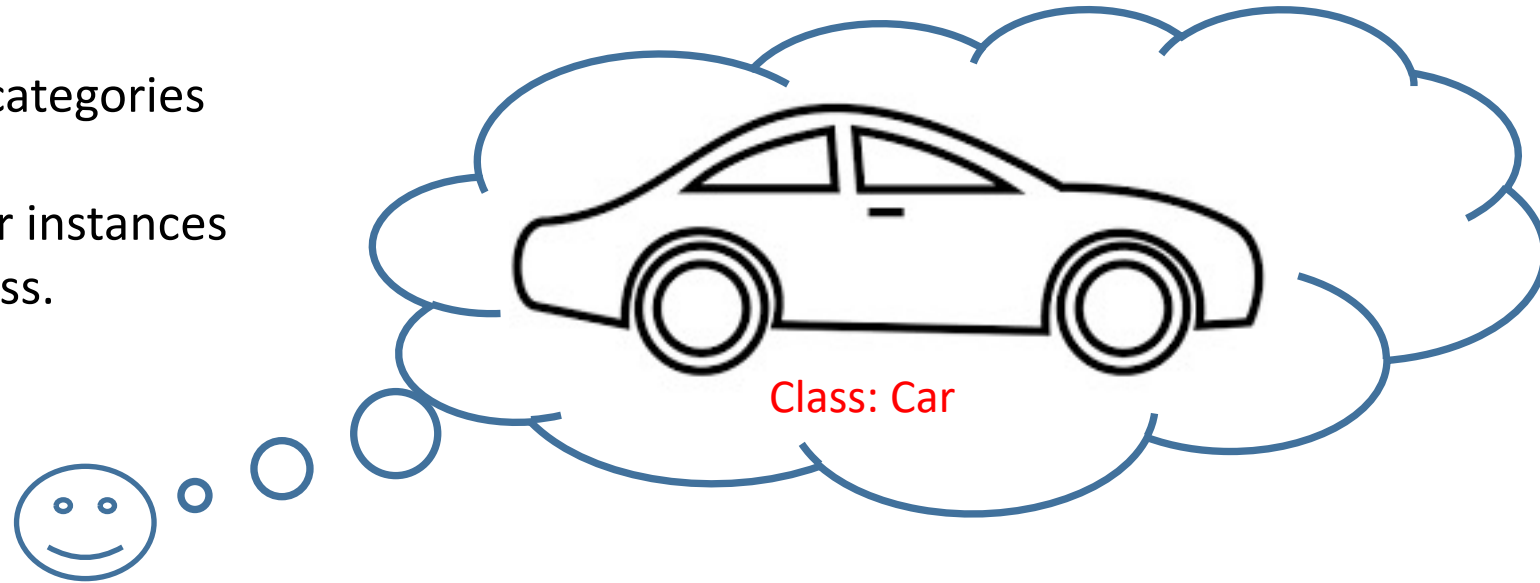


Jean & Alexander Heard
LIBRARIES

classes and objects

Classes are abstract categories of things.

Objects are particular instances or individuals of a class.



object: toyotaPrius



object: ferrari



object: volkswagenBeetle

Instantiating a custom object

- Python has many built-in **classes** or object types (e.g. lists, dictionaries, strings)
- Programmers can define custom classes using Object Oriented Programming. Class names are usually **capitalized**.
- Creating an object of a particular class is called **instantiating** the object. Example:

```
sort_button = Button()
```

- If the class is defined in a module, the **module** name must be prepended to the class name when the object is created. Example:

```
fitness_matrix = algebra.Matrix()
```

- Sometimes **arguments** need to be passed into the class when the object is created. Example:

```
the_raven = Poem(title='The Raven', text='Quoth the Raven, nevermore!')
```

CircuitPython code example

```
import time
import board
import busio
import adafruit_vcnl4040

i2c = busio.I2C(board.SCL1, board.SDA1)
sensor = adafruit_vcnl4040.VCNL4040(i2c)

while True:
    print("Proximity:", sensor.proximity)
    print("Light: %d lux" % sensor.lux)
    time.sleep(1.0)
```

create an instance of the I2C class from the `busio` module

arguments passed in are attributes of the board object describing the clock and data pins for I2C bus 1 (wired to the Stemma QT connector).

argument passes in the I2C object you instantiated in the previous line

create an instance of the `VCNL4040` class from the `adafruit_vcnl4040` module

the `sensor` object instantiated here has its attributes (`.proximity`, `.lux`) read in the code

website: vanderbi.lt/codegraf

Code for reading sensors



Jean & Alexander Heard
LIBRARIES

CircuitPython code example: fixed number of measurements

```
import time
import board
import busio
import adafruit_vcnl4040
```

```
i2c = busio.I2C(board.SCL1, board.SDA1)
sensor = adafruit_vcnl4040.VCNL4040(i2c)
```

```
for reading in range(10):
    print("Proximity:", sensor.proximity)
    print("Light: %d lux" % sensor.lux)
    time.sleep(1.0)
```

for loop executes code block 10 times

Access sensor object's attribute `.proximity`

Access sensor object's attribute `.lux`

wait 1 second between measurements

Infinite loops

- Normally we don't want code to run forever.
- **while** loops run until a condition becomes **False**
- We might want a sensor to run indefinitely.
- They will run forever if the condition is hard-coded to **True**
- Terminate an infinite loop using CTRL-Z or CTRL-C

```
1  count = 0
2  while count < 10:
3      |   count += 1
4      |   print(count, 'yaaaa!')
5
```

normal while loop


```
1  count = 0
2  while True:
3      |   count += 1
4      |   print(count, 'yaaaa!')
5
```

infinite while loop

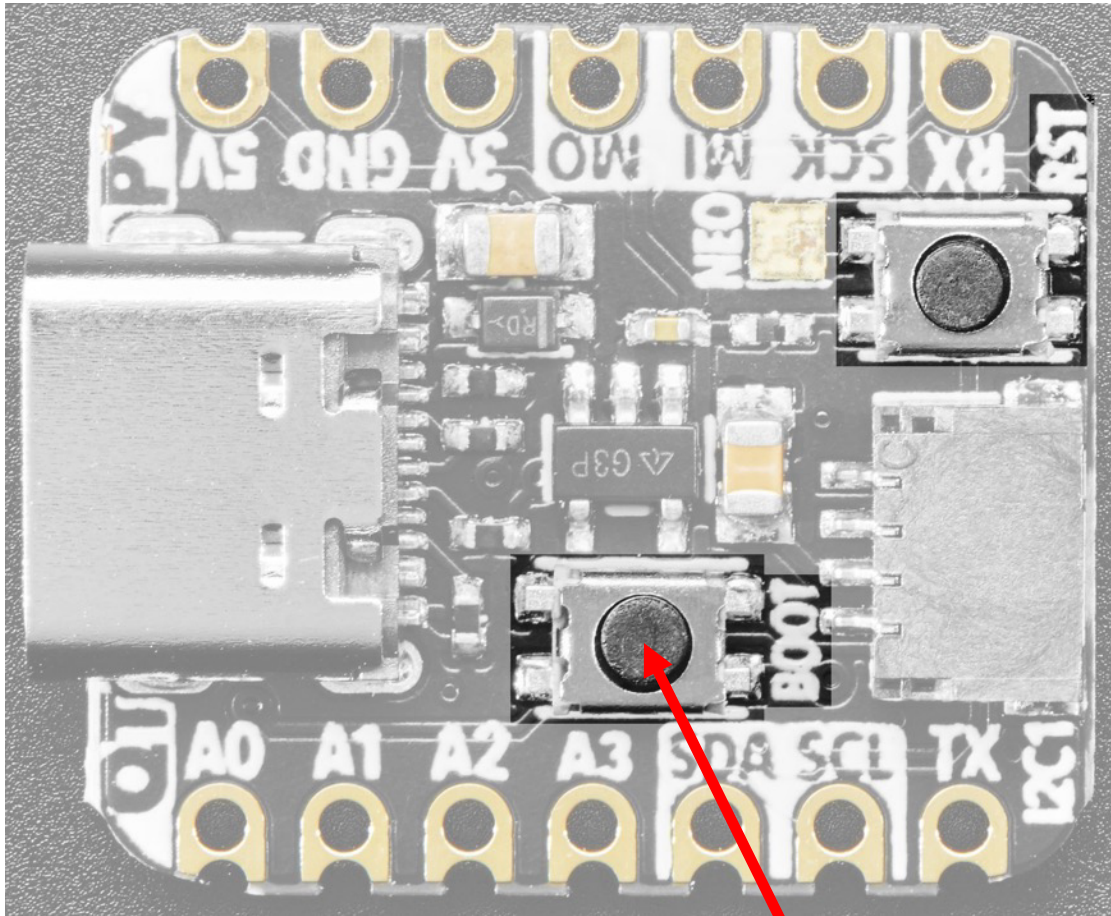
CircuitPython code example: indefinite number of measurements

```
import time
import board
import busio
import adafruit_vcnl4040

i2c = busio.I2C(board.SCL1, board.SDA1)
sensor = adafruit_vcnl4040.VCNL4040(i2c)

while True:  while loop executes indefinitely
    print("Proximity:", sensor.proximity)
    print("Light: %d lux" % sensor.lux)
    time.sleep(1.0)
```

Triggering measurements with the BOOT button



user-defined
button (BOOT)

- The **BOOT** button is a general-purpose button whose use can be defined in the **code.py** script
- It is identified as **board.BUTTON**

CircuitPython code example: triggering measurements by button

```
import time
import board
import busio
import digitalio ← module for digital input and output
import adafruit_vcnl4040

i2c = busio.I2C(board.SCL1, board.SDA1)
sensor = adafruit_vcnl4040.VCNL4040(i2c)
button = digitalio.DigitalInOut(board.BUTTON) ← instantiate button object
button.switch_to_input(pull=digitalio.Pull.UP) ← define button behavior

    ← access .value attribute of button object
while button.value: # will be True when button not pressed
    pass ← code to do nothing
for reading in range(10):
    print("Proximity:", sensor.proximity)
    print("Light: %d lux" % sensor.lux)
    time.sleep(1.0)
```

website: vanderbi.lt/codegraf

Sources of information



Jean & Alexander Heard
LIBRARIES

General reference documentation

- Circuit Python reference

<https://learn.adafruit.com/circuitpython-essentials/circuitpython-essentials>

- QT Py RP2040 microcontroller

<https://learn.adafruit.com/adafruit-qt-py-2040>

Sensor documentation on Adafruit website

- Search for device by name or part number (e.g. VCNL4040 Proximity Sensor).
- Follow link at bottom of page from "Learn" section.
- Click through to "Python & CircuitPython" page for code examples.

