Microcontroller and CircuitPython background

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QT Py RP2040 microcontroller

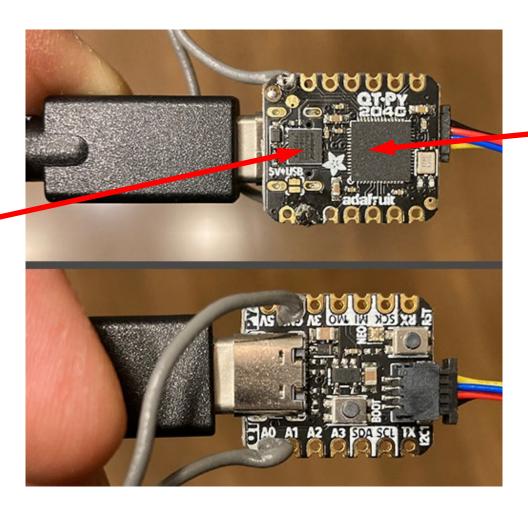
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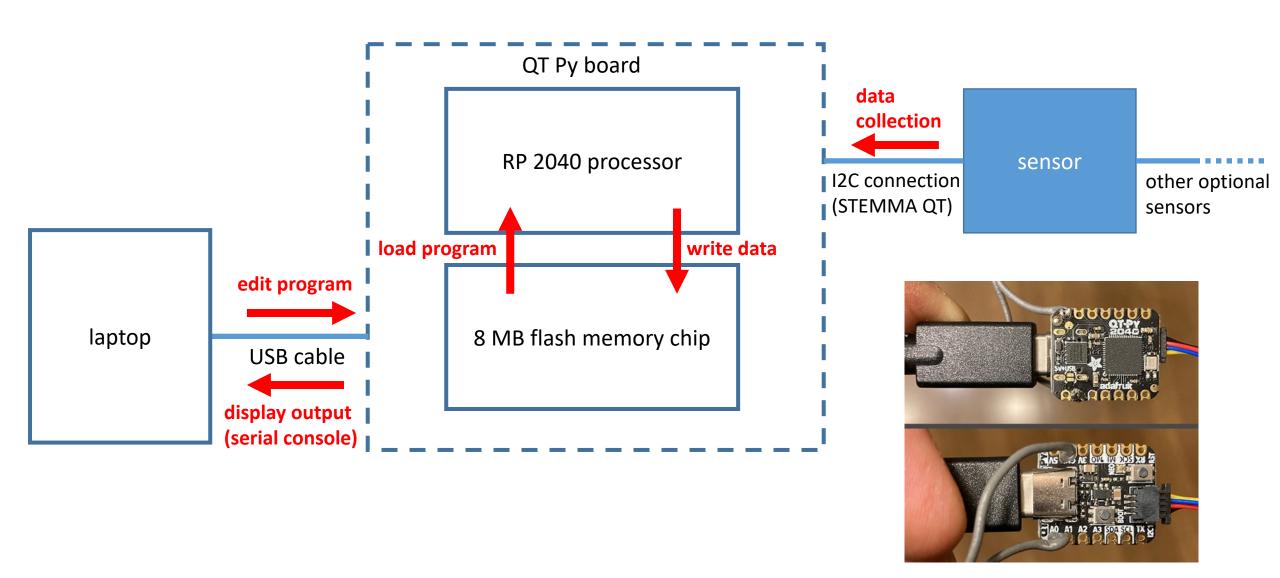
What's a microcontroller?

additional memory (8 MB flash)

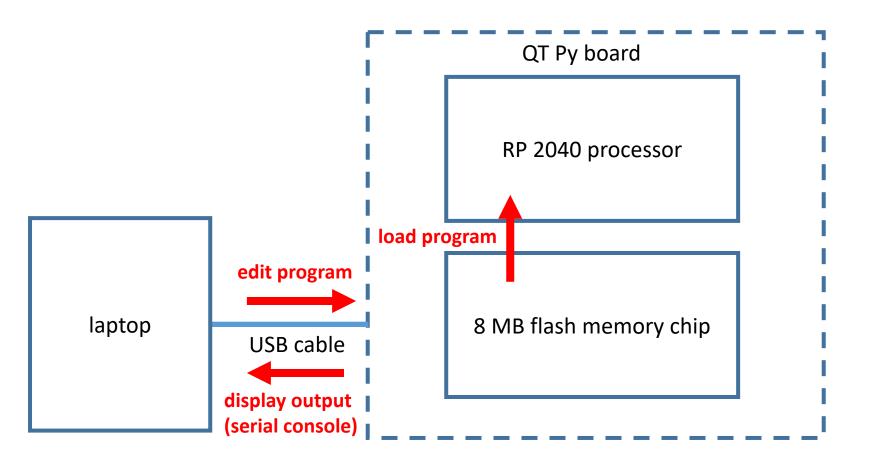


Computer-on-a-chip (RP2040 chip)

System architecture



System architecture



Connecting sensors





What is I2C?

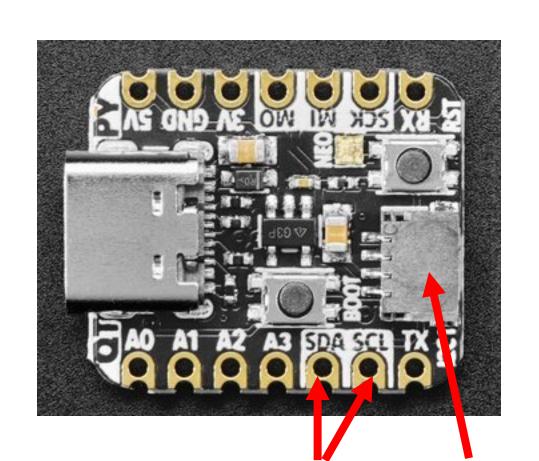
- I2C (pronounced "eye squared C") is a simple communications protocol
- It requires only 2 wires (clock and data) for communications (plus 2 power wires).
- All devices share the same 2 wires and can be chained.
- Devices are identified by a unique address (127 possible).



QT Py RP2040 using IC2 controller 1

wires (only 2 needed) HTS221 Humidity/Temp sensor address: 0x5F BMP280 Barometric Pressure sensor address: 0x76

I2C connections



QT Py RP2040 has two I2C controllers. They are accessed via:

- SDA and SCL pads on board (I2C0)
- STEMMA QT connector (I2C1)

They are addressed in code as:

- board.SCL and board.SDA (I2C0)
- board.SCL1 and board.SDA1 (I2C1)

I2C0 connections on board pads (must be soldered)

I2C1 connections on STEMMA QT connector

STEMMA QT connectors



top view



bottom view



cable firmly seated in connector (either connector can be used)

CircuitPython



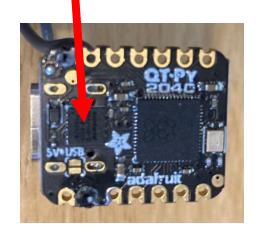
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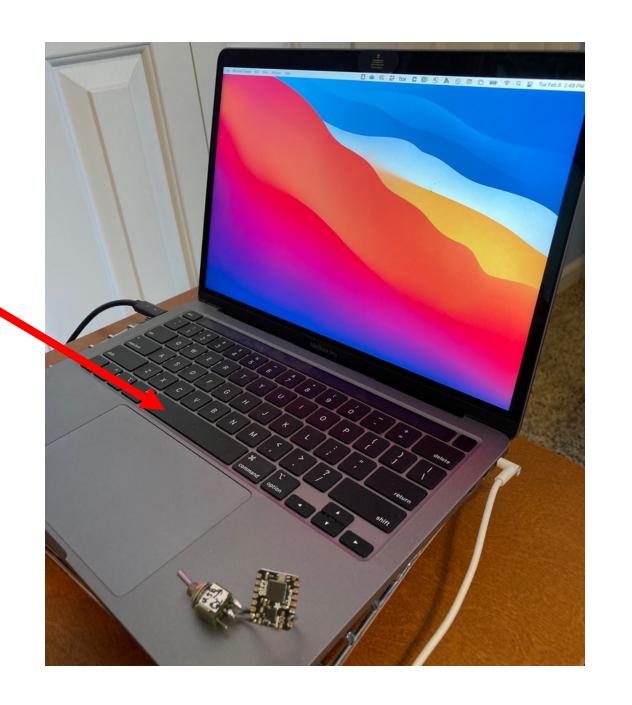
Storage requirements

Standard cPython installation: 90 MB

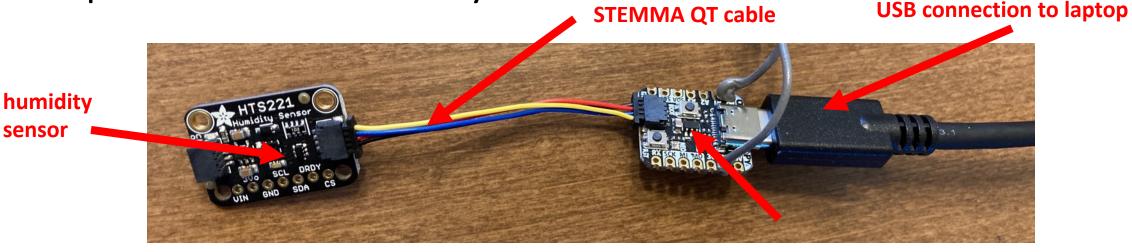
Laptop: up to 1 TB (1 million MB)

QT Py RP2040: 8 MB flash memory





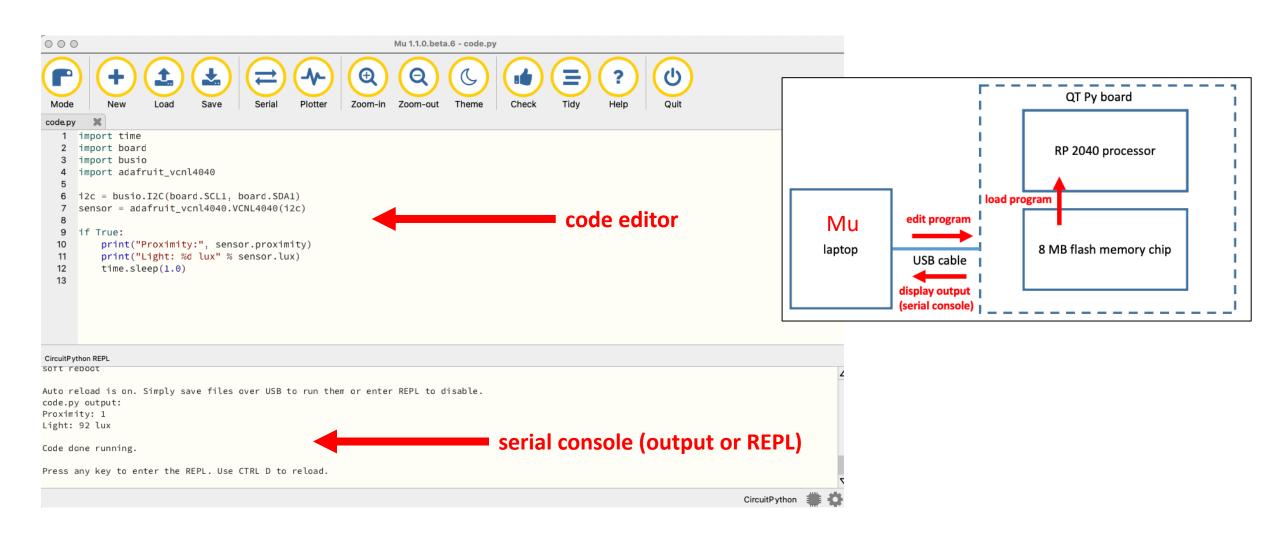
Aspects of CircuitPython



microcontroller board

- Stripped down Python language code
- Includes "operating system" for microcontroller board
- Individually installed device libraries support 300 connected devices
- Simplified communication with laptop via USB
- Automated launching of code.py file

Running CircuitPython with the Mu editor



The code.py script

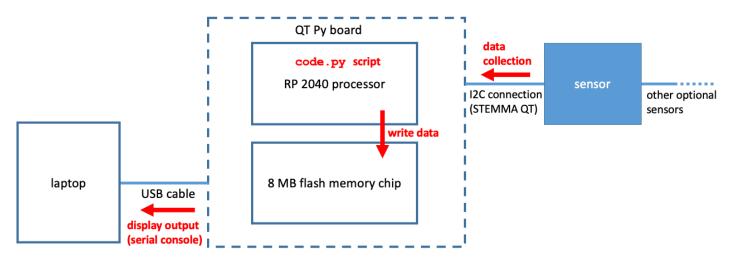


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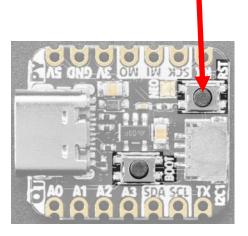
Why do we need code.py?

- No peripherals (keyboard, monitor) so no sophisticated way to "talk" with the processor.
- Once we get code.py running properly, it can manage the microcontroller without our intervention.

What does the code.py script do?



reset button (RST)



The code.py script is a special file in CircuitPython.

It controls interactions with sensors, memory, and the serial console.

It is executed when:

- the board is powered up.
- when you save something in the "drive" memory (including code.py).
- when you do a "hard reset" by pushing the reset button on the board
- when you do a "soft reset" (CTRL-D) from the console

Example: code.py for VCNL4040 proximity sensor

```
import time
import board
import adafruit_vcn14040
instantiate objects i2c = board.I2C()
sensor = adafruit_vcn14040.VCNL4040(i2c)
    read sensors
and report

while True:
    print("Proximity:", sensor.proximity)
    print("Light: %d lux" % sensor.lux)
    time.sleep(1.0)
```

Review of modules





What are modules?

- Modules are reusable code loaded from a file. "Library" is a similar term to "module".
- They're loaded as needed using an import statement.
- Modules in the standard library are ready to load.
- Modules not in the standard library must be installed.

• In standard Python, the command line installer application PIP is typically used to install modules:

pip install requests

Modules in CircuitPython

- Modules are installed manually in CircuitPython
- Download the CircuitPython Library Bundle to get all the library files for a microcontroller board.
- Library files have an .mpy extension.
- Copy manually from the lib directory in the bundle to the lib directory on your board to install.
- Modules from copied library files can be imported into a script.
- Typically, modules that need to be installed have very specific code for particular sensors.

Example: code.py for VCNL4040 proximity sensor

```
standard library modules (don't need to be installed)
import board
import adafruit vcn14040 ← module in Library Bundle (needs to be copied)
i2c = board.I2C()
                                                                                                                       (1) [∅] [⊕ ∨
                                                                                                   88 | Ⅲ Ⅲ □ □
sensor = adafruit vcn14040.VCNL4040(i2c)
                                                                                                                       adafruit_us100.mpv
                                                                                                  examples
                                                                                                                >
                                                                                                                       adafruit_vc0706.mpy
                                                                          thon-ada...v_rp2040-en_US-7.0.0.uf2 ⊘
                                                                                                  iib
                                                                                                                       adafruit_vcnl4010.mpy
                                                                                                   README.txt
                                                                          thon-bundle-7.x-mpy-20211221
                                                                                                                       adafruit_vcnl4040.mpy
                                                                         ple.py
                                                                                                  requirements
while True:
                                                                                                  VERSIONS.txt
                                                                                                                       adafruit_veml6070.mpy
                                                                                                                       adafruit veml6075.mpv
       print("Proximity:", sensor.proximity)
                                                                                                                       adafruit_veml7700.mpv
                                                                                                                       adafruit_vl53l0x.mpy
       print("Light: %d lux" % sensor.lux)
                                                                                                                       adafruit_vI53I1x.mpy
                                                                                                                       adafruit_vl6180x.mpy
       time.sleep(1.0)
                                                                                                                       adafruit vs1053.mpv
                                                                                                                     adafruit_waveform
                                                                                                                      adafruit_wiznet5k
```

adafruit_ws2801.mpy

adafruit_wsgi

What is Blinka?

- Sensors can be also be run from a laptop or a single-board computer like a Raspberry Pi.
- The Blinka library can be installed using PIP in standard CPython (Linux, Mac OS, Windows)
- It contains modules that correspond to the modules that are installed manually from the CircuitPython Library Bundle.
- Modules from Blinka are imported in the normal way.



CircuitPython objects

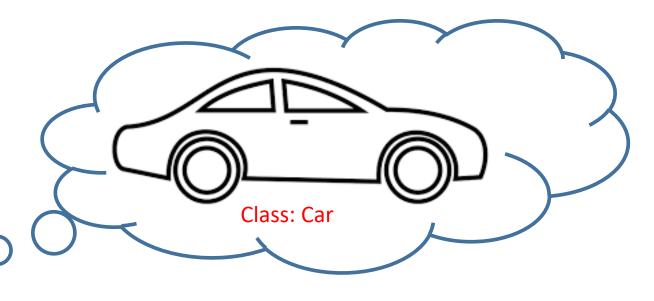


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classes and objects

Classes are abstract categories of things.

Objects are particular instances or individuals of a class.











object: toyotaPrius

object: ferrari

object: volkswagenBeetle

Instantiating a custom object

- Python has many built-in classes or object types (e.g. lists, dictionaries, strings)
- Programmers can define custom classes using Object Oriented Programming. Class names are usually capitalized.
- Creating an object of a particular class is called instantiating the object. Example:

```
sort button = Button()
```

• If the class is defined in a module, the module name must be prepended to the class name when the object is created. Example:

```
fitness_matrix = algebra.Matrix()
```

 Sometimes arguments need to be passed into the class when the object is created. Example:

```
the_raven = Poem(title='The Raven', text='Quoth the Raven, nevermore!')
```

CircuitPython code example

```
import time
import board
import busio
import adafruit vcn14040
i2c = busio.I2C(board.SCL1, board.SDA1)
sensor = adafruit vcn14040.VCNL4040(i2c)
while True:
    print("Proximity:", sensor.proximity)
    print("Light: %d lux" % sensor.lux)
    time sleep (1.0)
          the sensor object instantiated here has its
```

create an instance of the I2C class from the busio module

> arguments passed in are attributes of the board object describing the clock and data pins for I2C bus 1 (wired to the Stemma QT connector).

argument passes in the I2C object you instantiated in the previous line

create an instance of the VCNL4040 class from the adafruit vcn14040 module

attributes (.proximity, .lux) read in the code

Code for reading sensors





CircuitPython code example: fixed number of measurements

```
import time
import board
import busio
import adafruit vcn14040
i2c = busio.I2C(board.SCL1, board.SDA1)
sensor = adafruit vcn14040.VCNL4040(i2c) for loop executes code block 10 times
for reading in range (10):
                                             Access sensor object's attribute .proximity
    print("Proximity:", sensor.proximity)
    print("Light: %d lux" % sensor.lux)
    time.sleep(1.0)
                                               Access sensor object's attribute .lux
```

wait 1 second between measurements

CircuitPython code example: one measurement

```
import time
import board
import busio
import adafruit vcn14040
i2c = busio.I2C(board.SCL1, board.SDA1)
sensor = adafruit vcn14040.VCNL4040(i2c)
                       conditional code block executes one time
if True:
    print("Proximity:", sensor.proximity)
    print("Light: %d lux" % sensor.lux)
    time.sleep(1.0)
```

Infinite loops

- Normally we don't want code to run forever.
- while loops run until a condition becomes False
- We might want a sensor to run indefinitely.
- They will run forever if the condition is hard-coded to **True**
- Terminate an infinite loop using CTRL-Z or CTRL-C

CircuitPython code example: indefinite number of measurements

```
import time
import board
import busio
import adafruit vcn14040
i2c = busio.I2C(board.SCL1, board.SDA1)
sensor = adafruit vcn14040.VCNL4040(i2c)
                 while loop executes indefinitely
while True:
    print("Proximity:", sensor.proximity)
    print("Light: %d lux" % sensor.lux)
    time.sleep(1.0)
```

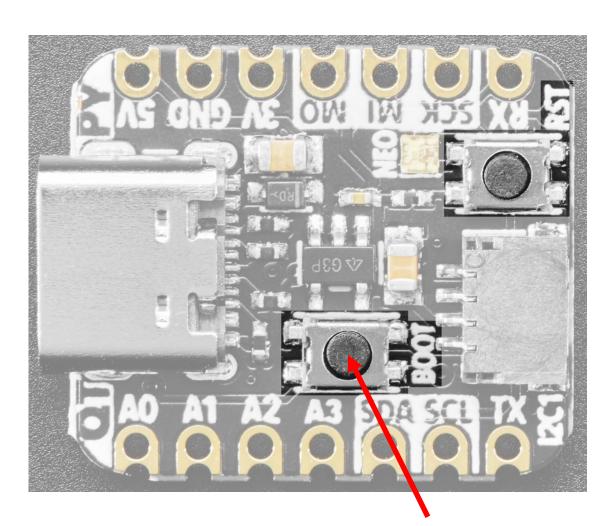
Using the Mu plotter

```
import time
                                                      (120.0,)
                                                      (120.7,)
                                                      (120.2,)
import board
                                                      (120.1,)
                                                      (120.3,)
                                                      (120.0,)
import busio
                                                      (119.9,)
                                                      (120.1,)
                                                      (120.3,)
                                                      (120.8,)
import adafruit vcn14040
i2c = busio.I2C(board.SCL1, board.SDA1)
```

```
Mu 1.1.0.beta.6 - code.py
                                                                                                        2 import board
                                                                                                        3 import busio
                                                                                                           import adafruit vcnl4040
                                                                                                           i2c = busio.I2C(board.SCL1, board.SDA1)
                                                                                                            sensor = adafruit vcnl4040.VCNL4040(i2c)
                                                                                                               #print("Proximity:", sensor.proximity)
                                                                                                               #print("Light: %d lux" % sensor.lux)
                                                                                                               # Use the following line for the plotter function
                                                                                                               print( (sensor.lux,) ) # Force the data to be represented as a 1=tuple
                                                                                                               time.sleep(0.1)
                                                                                                      CircuitPython REPL
                                                                                                                                                                                            CircuitPython Plotter
                                                                                                      (120.3,)
                                                                                                                                                                                        \triangle
                                                                                                      (120.9,)
                                                                                                      (121.0,)
                                                                                                      (120.3,)
sensor = adafruit vcn14040.VCNL4040(i2c)
```

```
while True:
    # Force the data to be represented as a 1=tuple
    print( (sensor.lux,) )
    time.sleep(0.1)
```

Triggering measurements with the BOOT button



- The BOOT button is a generalpurpose button whose use can be defined in the code.py script
- It is identified as board.BUTTON

user-defined button (BOOT)

CircuitPython code example: triggering measurements by button

```
import time
import board
import busio
import digitalio ← ← ← module for digital input and output
import adafruit vcn14040
i2c = busio.I2C(board.SCL1, board.SDA1)
sensor = adafruit vcnl4040.VCNL4040(i2c)
button.switch to input(pull=digitalio.Pull.UP) define button behavior
             access . value attribute of button object
while button.value: # will be True when button not pressed
   pass
                       code to do nothing
for reading in range (10):
   print("Proximity:", sensor.proximity)
   print("Light: %d lux" % sensor.lux)
   time.sleep(1.0)
```

Sensor with display



- Code to operate display is more complicated.
- Makes it possible to monitor sensor independently of laptop (battery operation)

Sources of information



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General reference documentation

Circuit Python reference

https://learn.adafruit.com/circuitpython-essentials/circuitpython-essentials

QT Py RP2040 microcontroller

https://learn.adafruit.com/adafruit-qt-py-2040

DiSC GitHub repository

https://github.com/HeardLibrary/digital-scholarship/tree/master/code/circuit_python

Sensor documentation on Adafruit website

- Search for device by name or part number (e.g. VCNL4040 Proximity Sensor).
- Follow link at bottom of page from "Learn" section.
- Click through to "Python & CircuitPython" page for code examples.



