

6.1

(a)

Recall the formula $H(t, S, q)$

$$H(t, S, q) = \sup_{\nu \in \mathcal{H}_t} E_t[S, q] \left[\int_t^T (S_u - k\nu_u) \nu_u du + Q_T^V (S_T - \alpha Q_T^V) \right]$$

By DPP, $dQ_t^V = -V_t dt$
 $dS_t = \sigma dW_t$

$$H(t, S, q) + \int_0^t (S_u - k\nu_u) \nu_u du \text{ is}$$

super martingale for all ν

is a martingale for some ν^*

By Itô's formula, define $H_t = H(t, S, q) + \int_t^T (S_u - k\nu_u) \nu_u du$

$$dH = \partial_t H dt + \partial_S H (\sigma dW_t) + \frac{1}{2} \partial_{SS} H (\sigma^2 dt)$$

$$+ \partial_q H (-V_t dt) + (S_t - k\nu_t) \nu_t$$

Now, find the drift of H_t , $dH_t = \partial_t H dt + \frac{1}{2} \sigma^2 \partial_{SS} H dt$

$$D = \begin{cases} \leq 0 & \text{for all } \nu \\ = 0 & \text{for some } \nu^* \end{cases} \quad \begin{cases} -V_t \partial_q H dt + (S_t - k\nu_t) \nu_t \\ \end{cases}$$

Now, set $S_t^* = S$, we have

$$\partial_t H + \frac{1}{2} \sigma^2 \partial_{SS} H + \sup_{\nu} \{ (S - k\nu) \nu - V \partial_q H \} = 0$$

take derivative of sup term

$$S - 2k\nu - \partial_q H = 0 \quad \nu^* = \frac{S - \partial_q H}{2k}$$

then

$$\partial_t H + \frac{1}{2} \sigma^2 \partial_{SS} H + \frac{1}{4k} (\partial_q H - S)^2 = 0$$

simplify

$$-(\partial_q H - S)^2 - 2k \sigma^2 \partial_{SS} H - 4k \partial_t H = 0$$

(c)

$\alpha \rightarrow 0$, In my intuition, I feel like time is not a factor for trading. Moreover,

We need to trade at time T .

Which makes sense if $H(T, S_T) = Q_T S_T$

a little bit

(b)

The corresponding ansatz is

$$H(t, S, q) = h_2(t) q^2 + h_1(t) q + h_0(t) + qS$$

$$\frac{\partial H}{\partial q} = 2h_2(t)q + h_1(t) + S = S - 2\alpha q \quad \text{at time } T$$

$$\frac{\partial^2 H}{\partial q^2} = 2h_2(t) = -2\alpha \quad \text{at time } T$$

$$\text{So } S - \frac{\partial H}{\partial q} = (2h_2(t)q + h_1(t))$$

$$\frac{\partial H(t, S, q)}{\partial t} = \partial_t h_2(t) q^2 + \partial_t h_1(t) q + \partial_t h_0(t)$$

$$\frac{\partial^2 H(t, S, q)}{\partial S^2} = 0$$

$$\text{then recall } \partial_t H + \frac{1}{2} \sigma^2 \partial_{SS} H + \frac{1}{4k} (\partial_q H - S)^2 = 0$$

We need to figure out $\nu^* = \frac{S - \partial_q H}{2k} = \frac{2h_2(t)q + h_1(t)}{2k}$
 find $h_1(t)$ and $h_2(t)$

$$\partial_t h_2(t) + \frac{h_2(t)}{k} = 0, \quad h_2(T) = -\alpha \quad (1)$$

$$\partial_t h_1(t) + \frac{h_1(t)}{k} = 0, \quad h_1(T) = 0 \quad (2)$$

$$\text{So } 0 = \int_t^T \frac{1}{h_1(t)} dh_1(t) = - \int_t^T \frac{1}{k} dt \quad \frac{1}{h_1(t)}$$

$$\left(\frac{1}{h_1(t)} - \frac{1}{h_1(T)} \right) = \frac{1}{k} (T - t)$$

$$h_2(t) = - \left(\frac{T-t}{k} + \frac{1}{k} \right)^{-1}$$

$$= - \left(\frac{k}{T-t+\frac{1}{k}} \right)$$

for 0, easily get that $h_1(t) = 0$ ($\ln h_1(t) \rightarrow \infty$)

$$\text{So } \nu^* = \frac{2h_2(t)q}{2k} = \frac{q}{T-t+\frac{1}{k}}$$

let us $\nu^* \rightarrow \nu_T^*$ $q \rightarrow Q_T^*$

$$\text{get } \nu_T^* = \frac{Q_T^*}{T-T+\frac{1}{k}}$$

the ansatz is

$$H(t, S, q) = -\alpha q^2 + qS$$

$$H(T, S, q) = q(S - \alpha q)$$

6.2

(a) Similar to 6.1.

recall

$$H(t, x, S, q) = \sup_v E[X_T^v + Q_T^v (S_T - \alpha Q_T^v)]$$

$$dX_t^v = (S_t - kv_t) v_t dt$$

By DPP, $H(t, x, S, q) + \int_0^t (S_u - kv_u) v_u du$
is super martingale for all v
is martingale for some v^*

By Ito formula:

$$dH_t = \partial_t H dt + \partial_x H dX_t + \partial_S H (dS)^2 + \partial_q H dq$$

$$= \partial_t H dt + \frac{1}{2} \sigma^2 \partial_{SS} H dt + (S_t - kv_t) v_t dt - \partial_q H \cdot v_t dt \quad \text{Set } S_t \rightarrow S$$

Now we find HJB Equation:

$$\partial_t H + \frac{1}{2} \sigma^2 \partial_{SS} H + \sup_v \{ (S - kv) v \partial_x H - v \partial_q H \} = 0$$

which is the same formula in (6.44) in 6.2.a

Now take the derivative

$$(S - 2kv) \partial_x H - \partial_q H = 0 \quad v^* \rightarrow v_t^*$$

$$v_t^* = - \frac{\partial_q H - S \partial_x H}{2k \partial_x H}$$

(b) recall $H(t, S, \alpha, q) = x + h(t) q^2 + qS$

$$\frac{dH}{dq} = 2qh(t) + S \quad \begin{matrix} \text{when} \\ t=T \\ h(T) = -\alpha \end{matrix}$$

$$\frac{dH}{dx} = 1 \quad \frac{dH}{dq} - S = 2q \cdot h(t)$$

$$\text{then} \quad \partial_{SS} H = 0$$

$$\partial_t H = \partial_t h(t) \cdot q^2$$

$$(S - kv) v \partial_x H - v \partial_q H = \frac{(\partial_q H - S \partial_x H)^2}{4k \partial_x H}$$

recall HJB and we get

$$\partial_t h(t) \cdot q^2 + \frac{(\partial_q H - S \partial_x H)^2}{4k \partial_x H} = 0$$

$$\text{So } \partial_t h(t) \cdot q^2 + \frac{(\partial_q H - S \partial_x H)^2}{4k} = 0$$

$$\partial_t h(t) q^2 \frac{4h(t) q^2}{4k} = 0$$

$$\text{So } \partial_t h(t) + \frac{1}{k} h(t) = 0$$

$$\int_t^T \frac{1}{h(u)} dh(u) = \int_t^T -\frac{1}{k} du$$

$$\Rightarrow h(t) = - \left(\frac{k}{T-t+\frac{1}{2}} \right) \quad v^* \rightarrow v_t^*$$

$$\text{So } v_t^* = \frac{2qh(t)}{2k} \quad q \rightarrow \alpha_t^*$$

$$\rightarrow v_t^* = \frac{\alpha_t^*}{T-t+\frac{1}{2}}$$