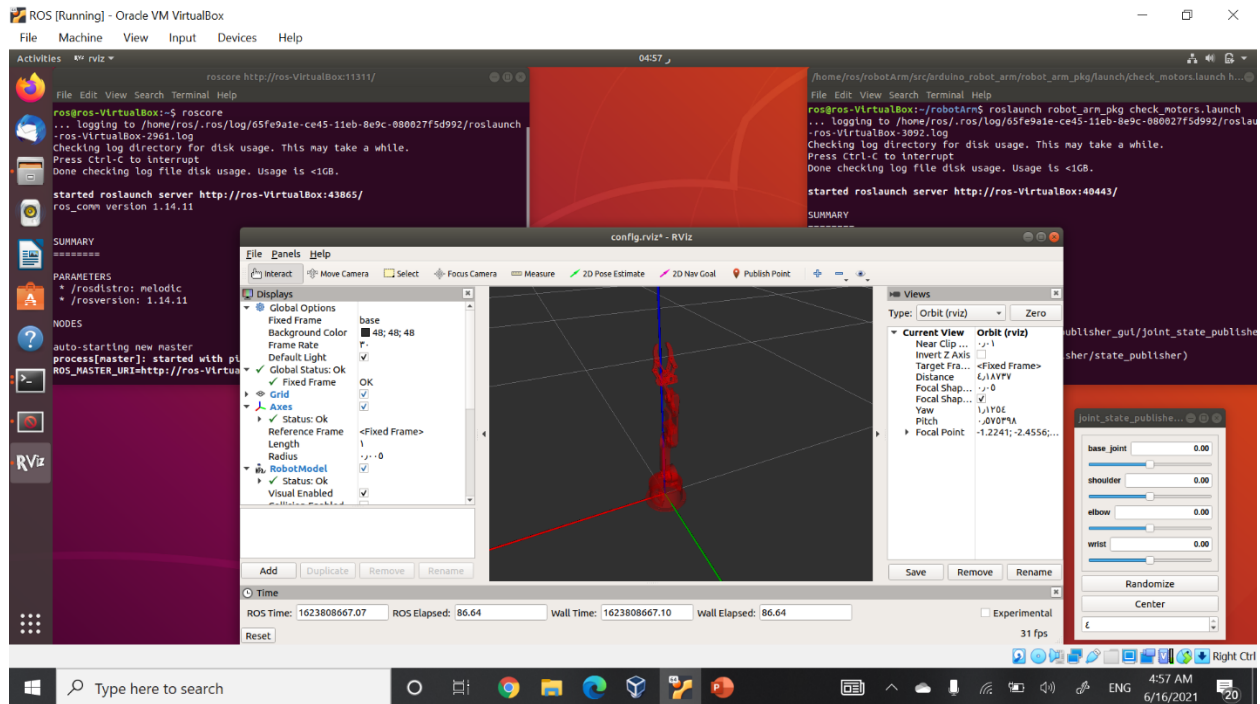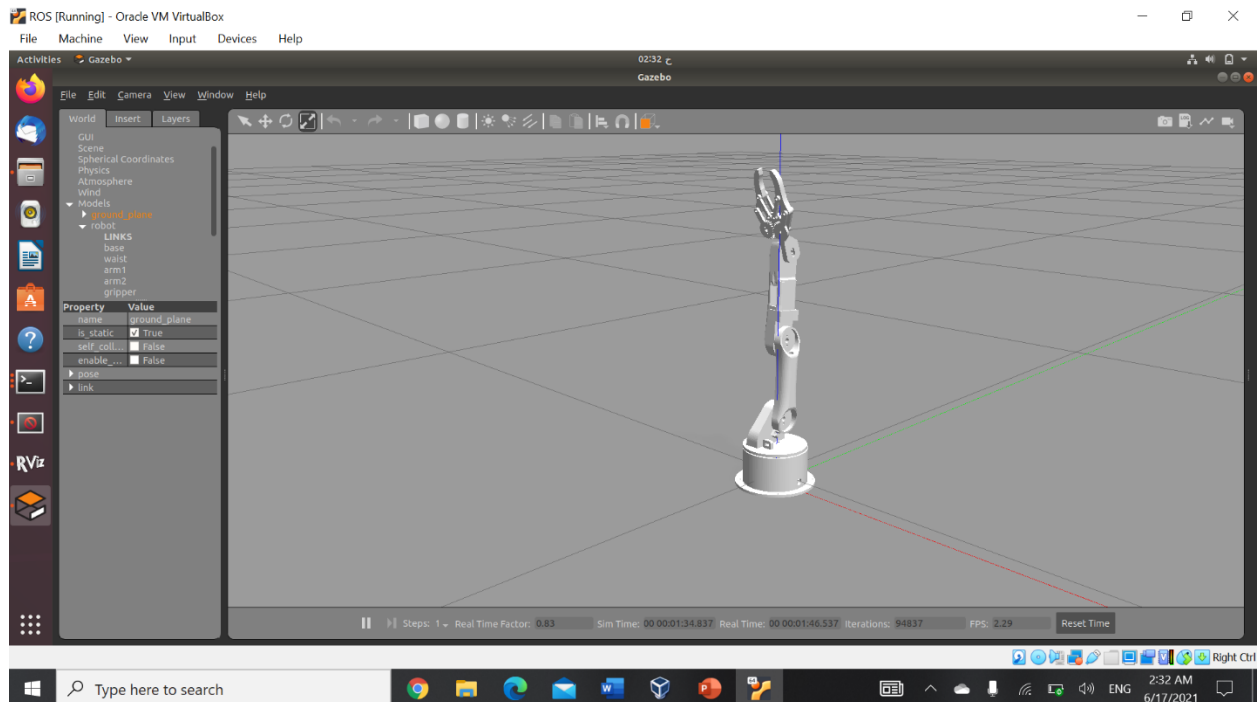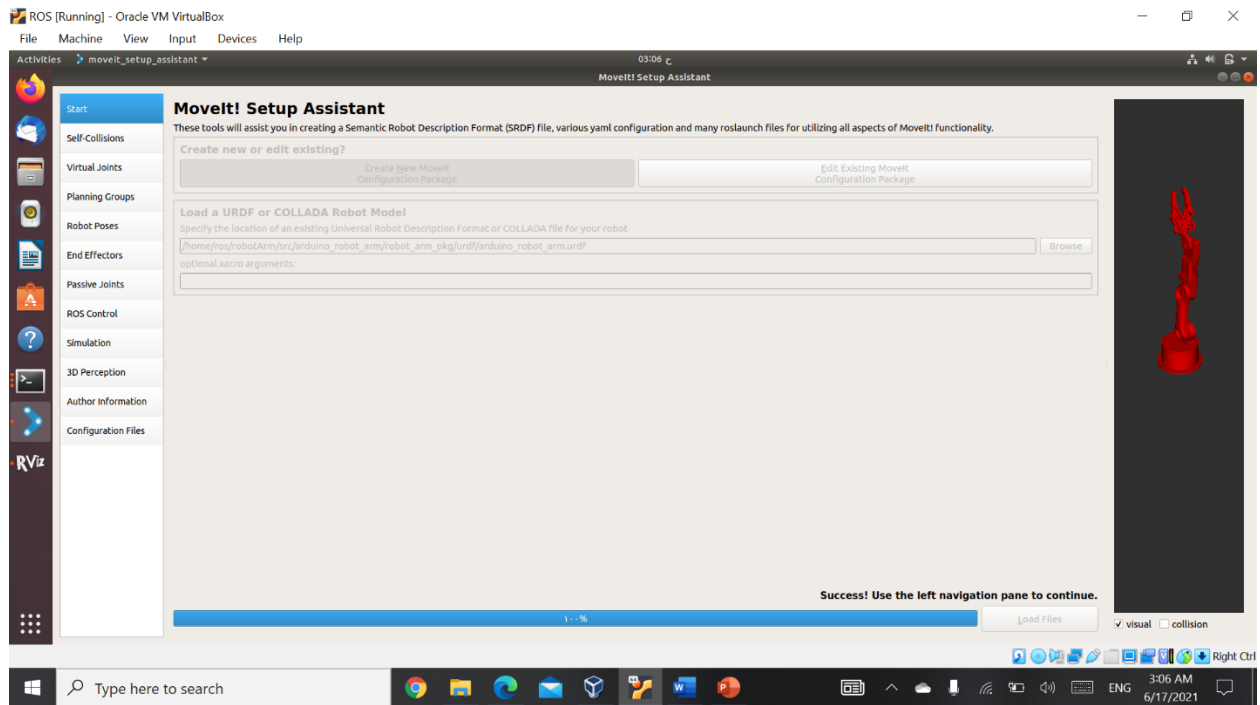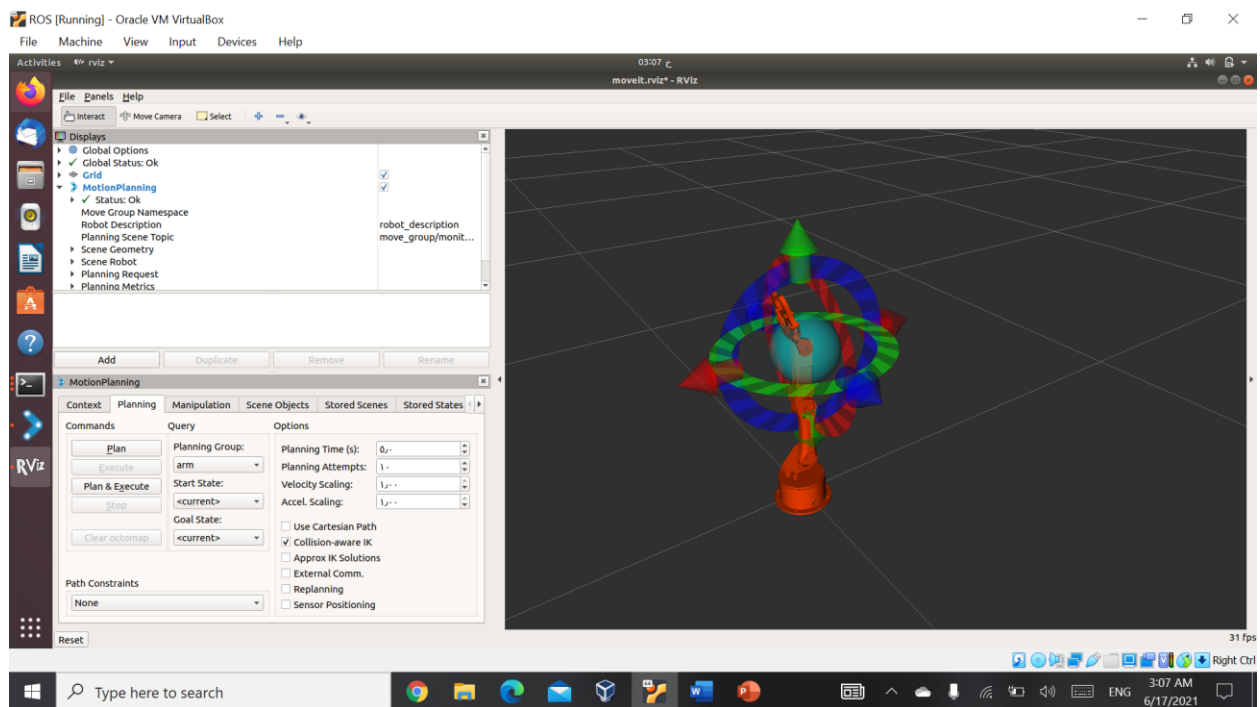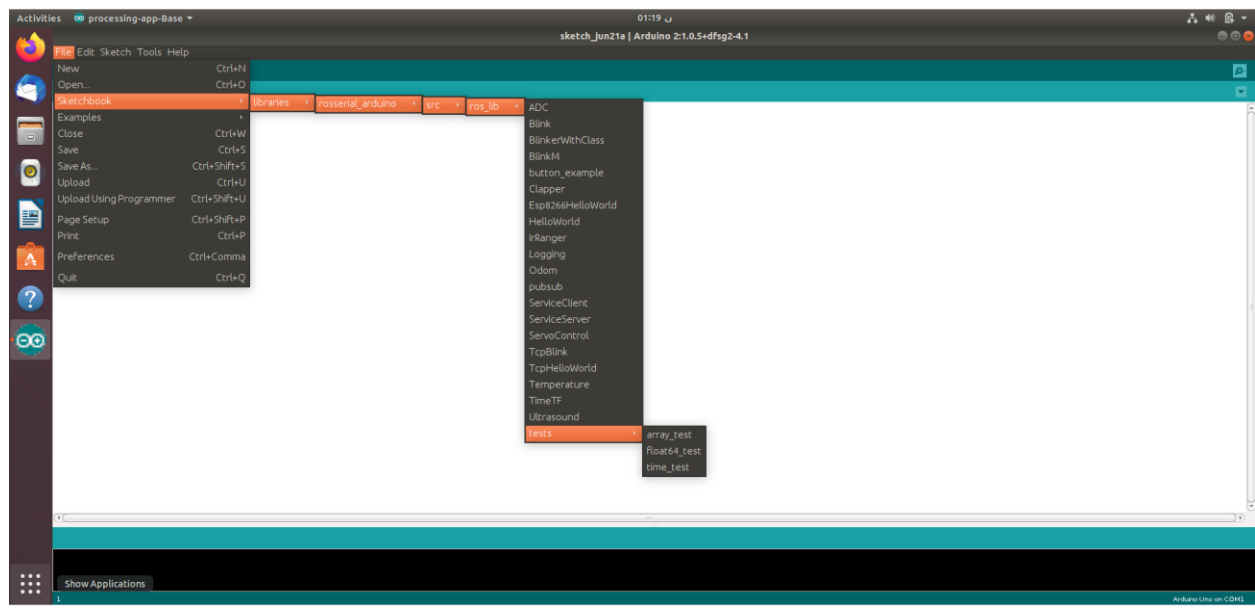# Outputs:-

Figure 1 Rviz

Figure 2 Gazebo

Figure 3 MoveIt

Figure 4 MoveIt with RViz

Figure 5 Arduino IDE with ros_lib