

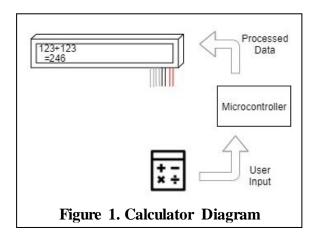
ELEC3662 - Embedded Systems Report

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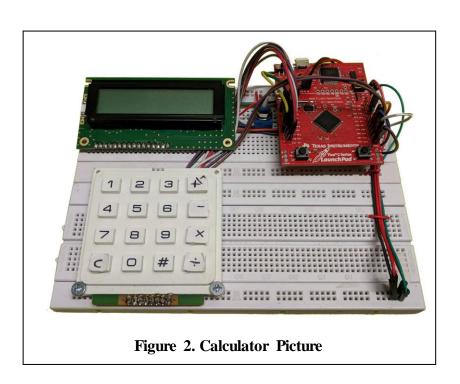
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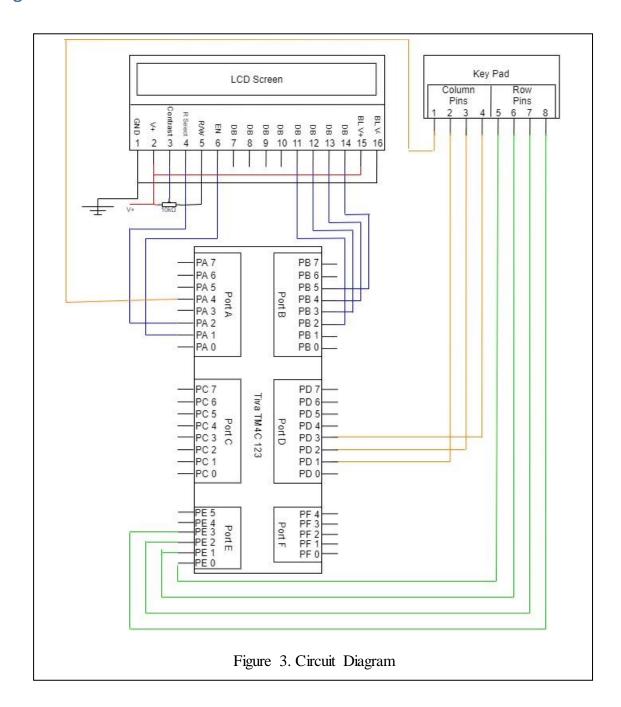
Project Outline



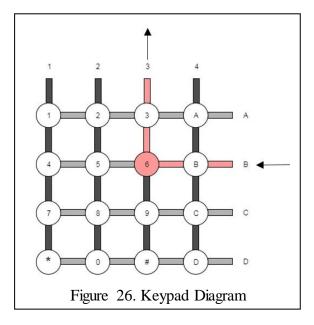
The purpose of this project was to interface a microcontroller, the Tiva TM4C123, with external hardware components. This consisted of a 16 x 2 Liquid Crystal Display (LCD) and a 4 x 4 keypad. Utilising this hardware, and the programming language 'C'. The goal was to design and implement the software to act in conjunction with the interfaced hardware to create a calculator able to perform simple mathematical calculations. With the keypad acting as an input, the user inputs numbers and operators which were then fed into the microcontroller with the resultant output being displayed on the LCD screen, a diagram of which is shown in figure 1.



Circuit Diagram



Key Pad

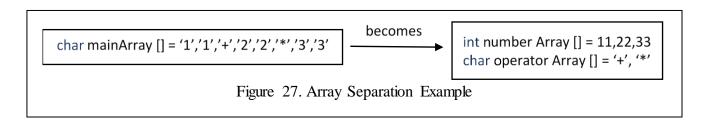


The keypad consists of a four by four matrix of buttons. It operates by sending power through each row individually, when a button is pressed it forms a connection giving the voltage a path to follow, outputting through the columns [1], shown in figure 24. With each column and row being connected to an individual pin this allows the microcontroller to turn on each column sequentially in a loop, waiting for a response on the output, this polling of the keypad reduced the average power usage as it is not needed to be constantly on. It also allows for each individual key to have a unique address, which can be used within the program to assign symbols, we can see in figure 26 that the symbol '6' has the address B3.

We achieved this programmatically by establishing a matrix of symbols and operands to match the symbols on the keypad. This was done to sync the keypads physical button addressed with the code, so button A1 would be 1:1 in the matrix, and both correspond to symbol '1'.

By utilising 'For loops' the microcontroller can scan the keypad continuously, with one loop moving through the rows, A to B to C etc. Within this is a subsequent loop within this to scan the columns, A1 to A2 etc. Simply, it scans every column for each row. This is achieved by turning the output pin for each row high individually, and then checking the input pins one by one in quick succession. Once a button press has been detected the code matches this to the symbol matrix, returning the value to a global variable to be used within another library.

Calculations

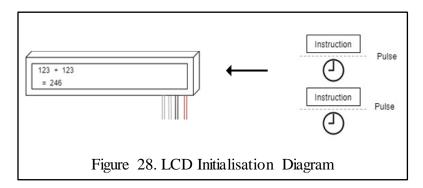


Calculations were performed at the end of a user's input phase, this was indicated by pressing the equals symbol. An interrupt was set up to detect this. To perform the required calculations the code was required to translate the pressed buttons to variables, achieved within the keypad library. These variables were then placed into an array. With each individual key press corresponding to a symbol that is subsequently stored individually within the array, meaning '11 + 1' would be stored as '1, 1, +, 1'. To perform calculations the main array is then manipulated splitting into two subset arrays, consisting of a number array and operand array. This is achieved by reading the array by checking if the stored value at each index is an integer, it does this until a non-integer (operand) is found, at which point it collates the previous indexes together to form one whole number while moving the operand to the separate array, shown in **figure 27**.

To perform the subsequent mathematical calculations inputted, while applying the rules of BIDMAS the code loops through the operand array, first counting the amount of operands then counting the amount of individual operands of each type. With this information, it can perform all the multiplications before any additions etc. Then the code takes the position of these operands within the array, and performs the desired calculation on the integers within the number array with corresponding index values, replacing those integers with the answer to the operation, before shifting the array to fill the gap. This process loops until there is only one value stored within the number array which is the calculations final answer.

A check is then performed on the answer before printing to the screen, to determine if it is negative. If so, the modulus of the answer is taken to attain a positive value. However, a flag is set which indicates to the print function to print a minus symbol before the numerical symbols.

LCD Screen



The project guidelines stated that we must use the LCD in its four-bit mode variation, this allowed for a reduction in pin usage as only a nibble was being sent. However, because of this it was required to initialise the screen in a specific way, found within the screens datasheet. [2] The entailed pulsing precise information into the screen, meaning that five pins were set to high for a brief period before being returned to zero, this was achieved programmatically by a functioned called 'EnPulse'. After which it was required to wait for a set amount of time, for the screen to register the instruction before another could be sent.

After initialisation, the screen could receive and display desired data. To display symbols on the screen, the screen had to be sent a specific pulse of information that corresponds with that symbol, predetermined by the manufacturer. A tabulated version of this was found within the datasheet and utilised. [2] Within the program this information was concatenated into a case machine, with a separate case to pulse the information into the screen for every symbol. The code would then determine which symbol was required and select the necessary case.

Within the screen library there were additional usability functions. These functions consisted of a curser go to function, which enabled the code to select a position of the curser using X and Y co-ordinates and an alternative to this referred to as 'newLine' which was a more efficient, albeit less precise version that allowed for the code to alternate between the first and second lines allowing for faster printing. A clear screen function was implemented in a similar manner to the initialisation function, pulsing pins low, waiting and repeating these steps to initiate a clear command within the screen. As the symbol selection code was structured within a case machine, it allowed for the implementation of a 'printString' function to be added. This function would cycle through a string, assigning each symbol to an array variable, then utilising the previously discussed symbol determination code to cycle through the array and case machine the string would be printed onto the screen.

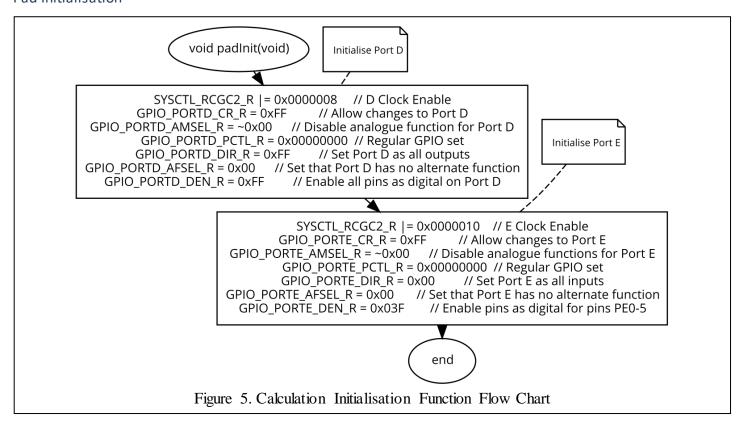
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xxxx0000	CG RAM (1)			0	a	F	<u> </u>	P					9	Ξ.	α	р
xxxx0001	(2)		!	1	А	Q	a	9				7	7	4	ä	9
xxxx0010	(3)		П	2	В	R	Ь	r			Т	4	ŋ	×	F	Θ
xxxx0011	(4)		#	3	С	5	C	s			ı	ゥ	Ŧ	ŧ	ε	00
xxxx0100	(5)		\$	4	D	T	d	t			v.	I	ŀ	Þ	μ	Ω
xxxx0101	(6)		Z	5	Ε	U	e	u			•	7	Ŧ	ı	σ	ü
xxxx0110	(7)		8,	6	F	Ų	f	V			7	Ħ	Ξ	3	ρ	Σ
xxxx0111	(8)		7	7	G	W	9	W			7	ŧ	Z	Ŧ	q	π
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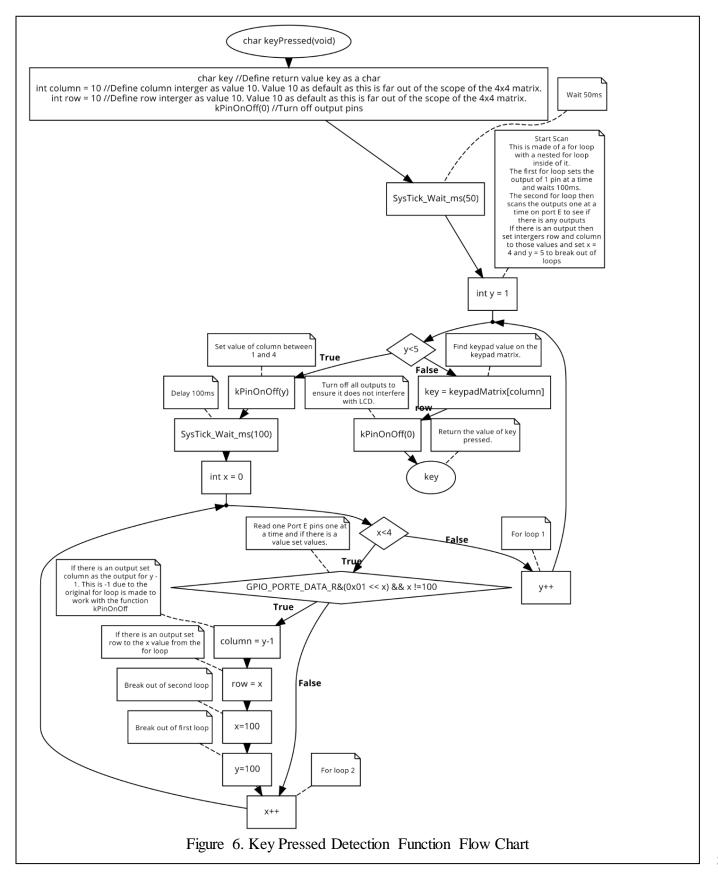
Flow Charts

Keypad Functions

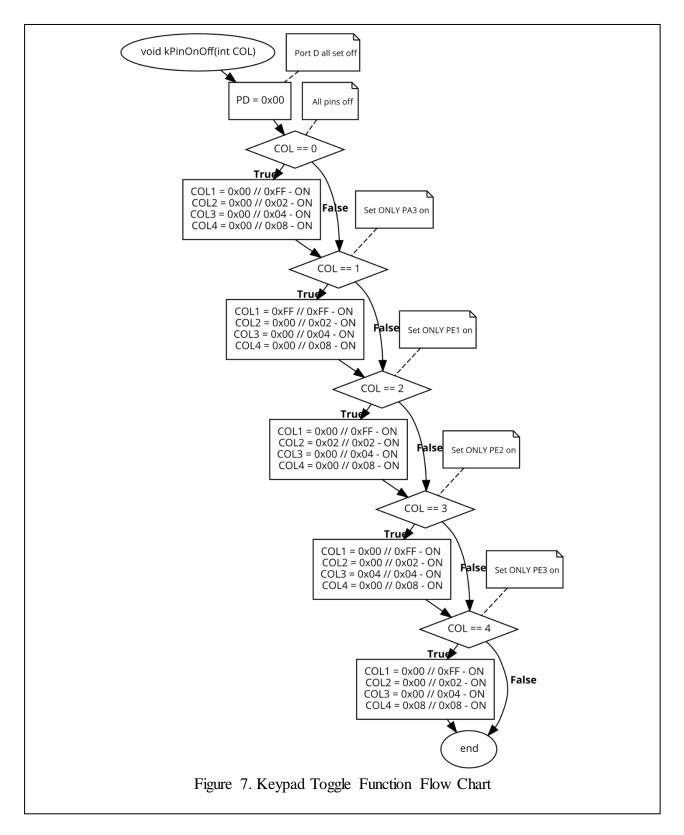
Pad Initialisation



Key Pressed Detection Function

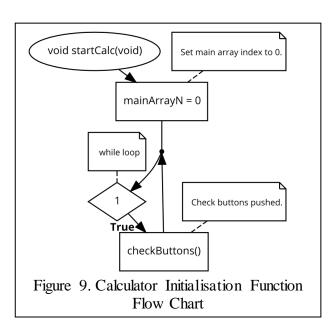


Keypad Pin Toggle Function

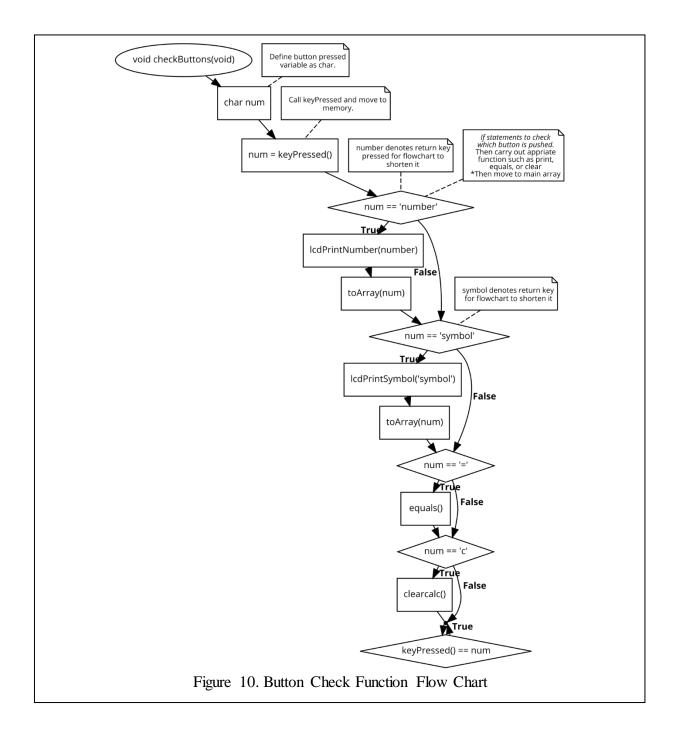


Calculation Functions

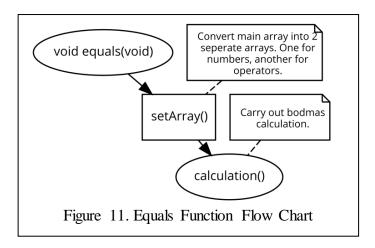
Calculator Initialisation Function



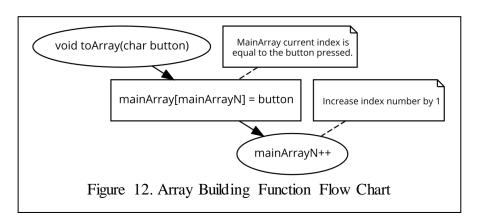
Check Button Press Function



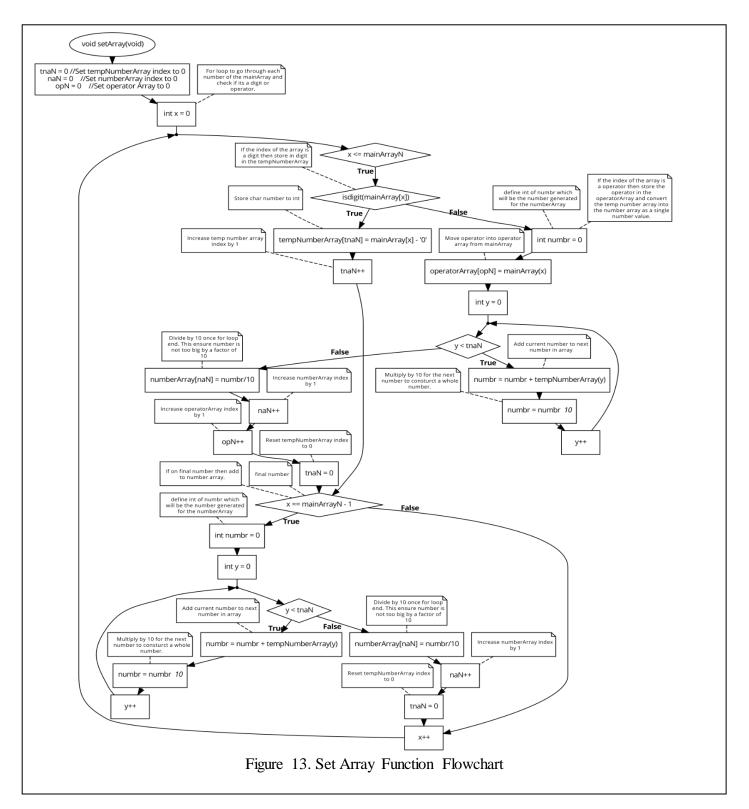
Equals Function

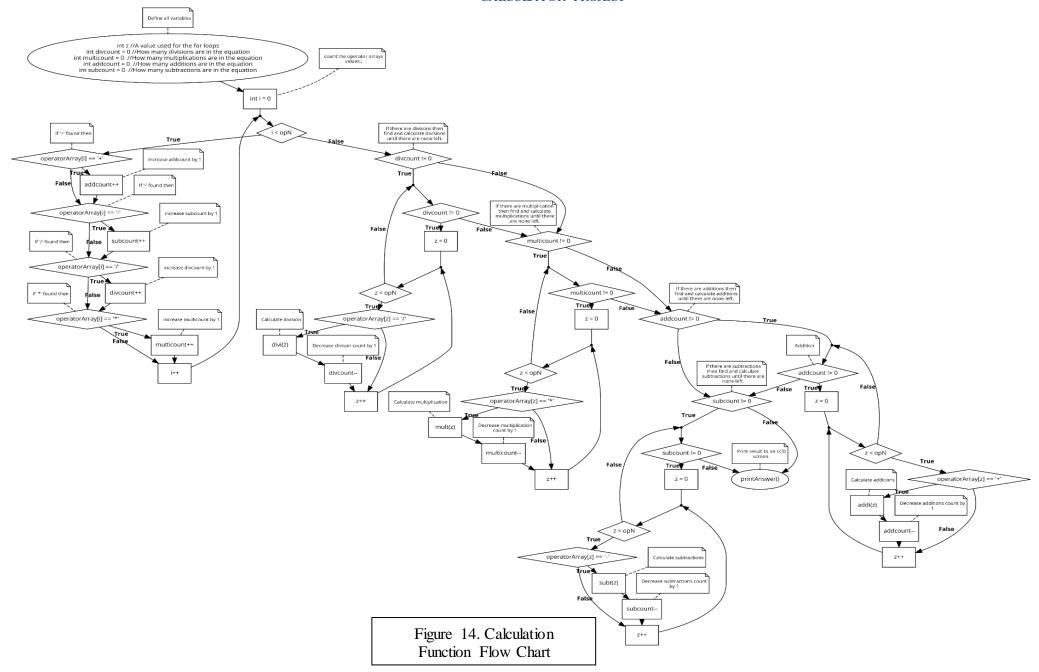


Array Building Function



Set Array Function





Operator Functions (Divide, Multiply, Addition and Subtract)

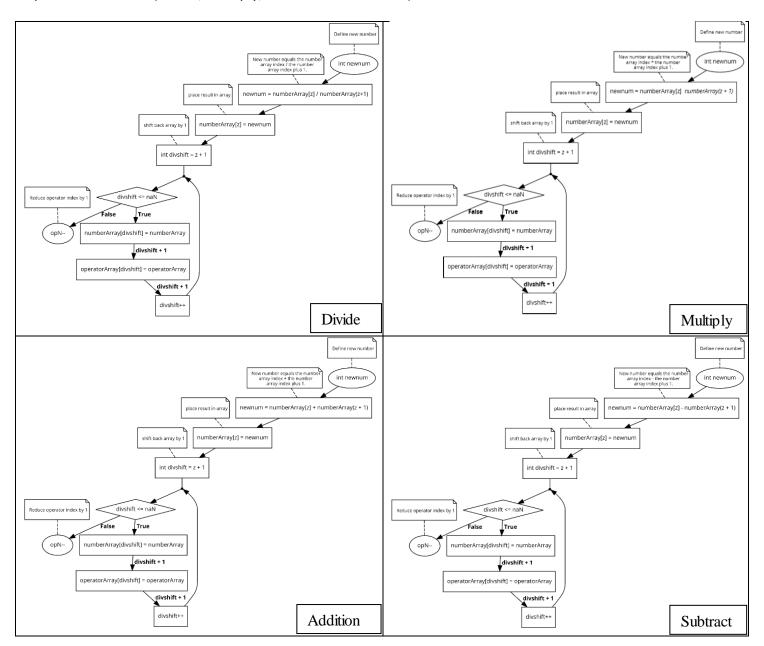
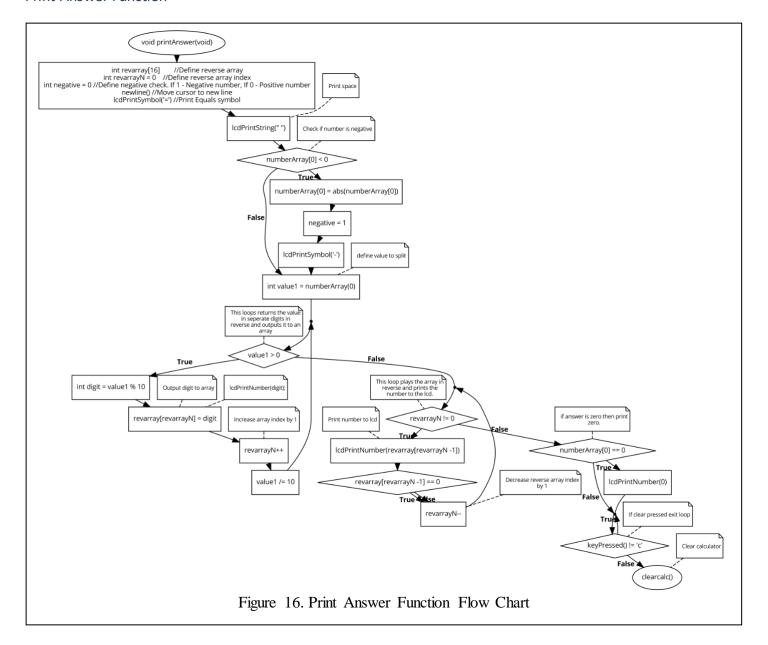
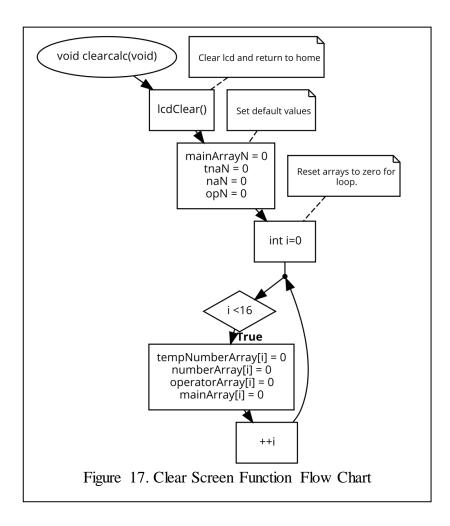


Figure 15. Operand Functions Flow Charts

Print Answer Function

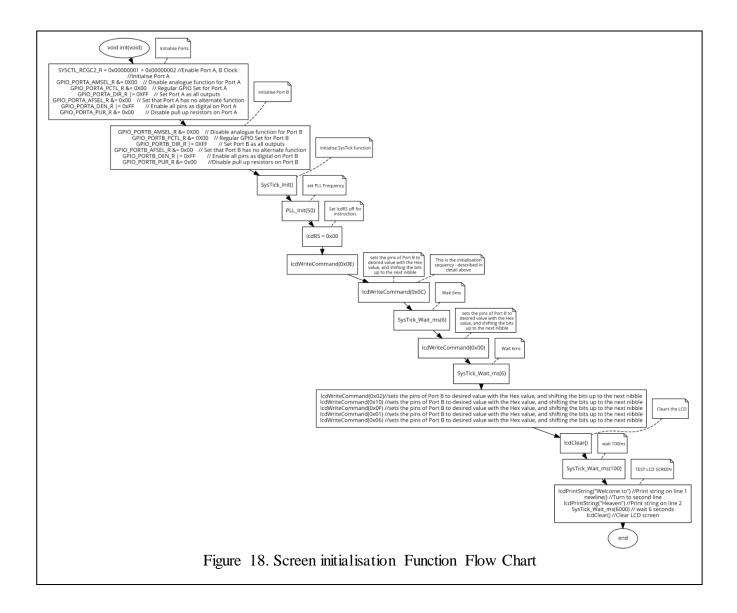


Clear Screen Function

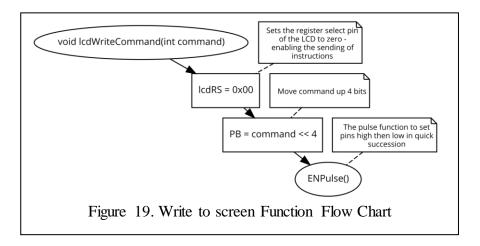


Screen Functions

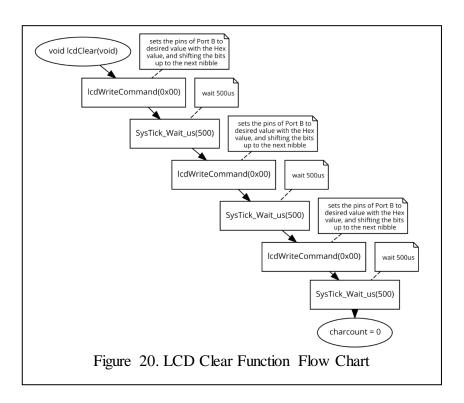
Screen Initialisation Function



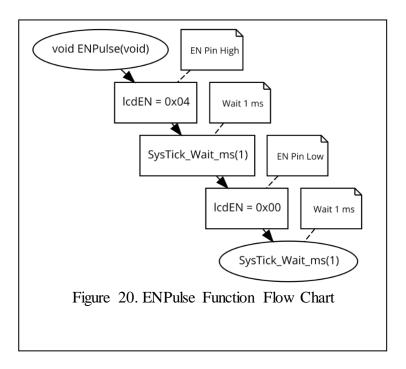
Write to Screen Function



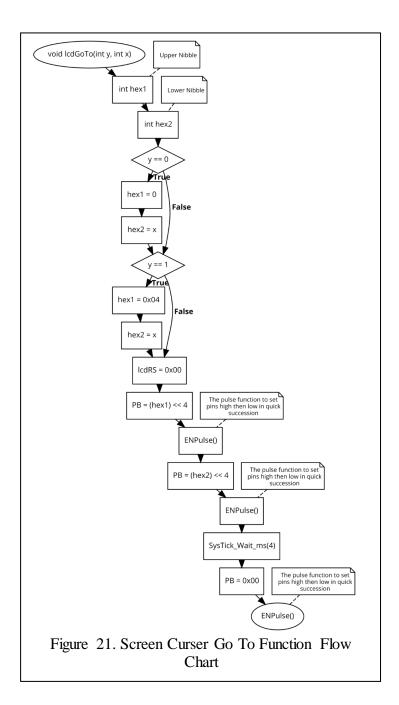
Clear Screen Function



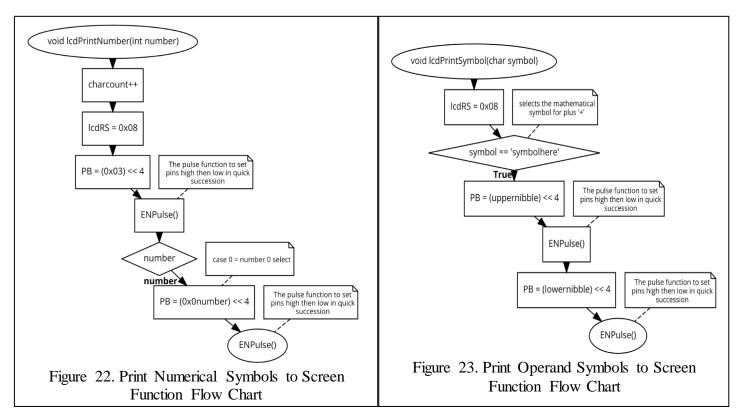
Information Pulse Function (ENPulse)

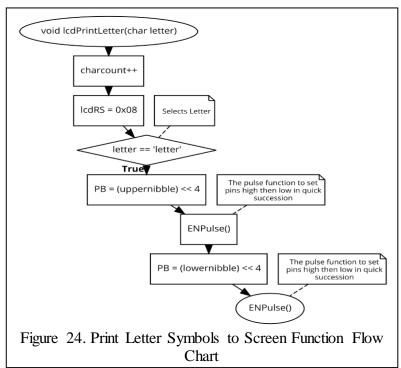


Screen Curser Go To Function

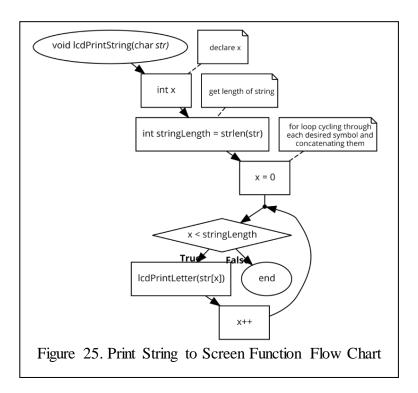


Print Symbols to Screen Functions





Print a Continuous String to the Screen Function



Testing & Issues

Several testing methods were implemented to ensure desired operation. A hardware approach was taken in the beginning, making use of an oscilloscope and multi-meter to probe the individual pins to guarantee that the code was operating as anticipated in terms of high and low timings, this was used heavily during the screen initialisation due to the specific wait lengths required. It was also useful for the identification of interference between the Keypad and Screen. Wherein when keys were pushed the screen would interpret the interference as transmitted data. The solution to this was to turn the keypad off before and LCD functions were carried out, isolating the two hardware components.

In conjunction with this, 'Print-F' functions were used throughout the code. These are functions which display the value of variable as the code operators to the console, and they were used to check the code was operating as desired, by manipulating data as expected. However, an issue arose because the compiler did not interface with the console properly, the 'Print-F' functions would cause it to crash. Our solution to this was to use an online compiler to build a simulation of the calculator which ran the code and the print functions to access the codes operation.

Several issues with the Keypad became apparent as the project progressed, one issue was the Microcontrollers Port D 0 not functioning, requiring the switch to Port A 4 (shown in the circuit diagram, figure 3). A Major issue was 'button bounce' which is when one button was pressed the code would detect several key presses, intermittently interference would emulate other keys being pressed. To overcome this, delays were added to the code, in addition to breaks within the keypads For loops each time a button was pressed. This ensured that only one button press was detected at a time. Tuning was carried out on the delays as to not detract from usability.

Conclusion

The overall project was a success. The hardware provided and required functionality provided an interesting challenge allowing for the implementation of several innovative solutions. Having to use techniques to make the code more efficient because of the microcontrollers limitations forced us to adapt our techniques and develop our coding style. Despite frustration during the project at the issues that occurred, such as interference and the difficulty to initiate the screen, this forced us to utilise and bring together the full repertoire of the code and hardware debugging techniques we have learnt throughout our course, which otherwise would have remained separate.

In retrospect underestimating the scale of the project was our biggest hindrance although we could not have predicted the issues that would occur more time should have been set aside for the initial planning of the project. Opposed to jumping in straight away hoping to have it completed as quickly as possible. We would have used this to implement more complicated features, which would have involved employing additional hardware components.

References

- [1] multicomp, "Keypad," Farnell, 2012.
- [2] Hitachi, Ltd, "HD44780U (LCD-II)," Chiyoda-ku, Tokyo 100-0004, Japan, 1998.
- [3] Texas Instruments, "TM4C123GH6PM Microcontroller," Texas Instruments, Dallas, Texas, 2013.