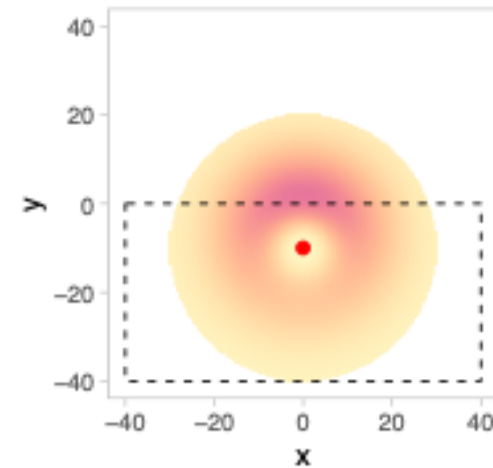
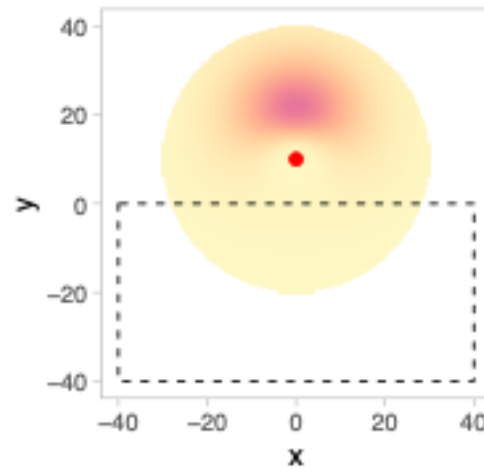


Simulate from fitted Integrated Step-Selection-Functions

Johannes Signer

Animal Movement Course 2025



Aims of this session

- Why to simulate?
- Simulate from fitted step selection functions
- Distinguish between redistribution kernel, selection-free movement kernel and movement-free habitat-selection function.

Some background reading

ECOSPHERE
AN ESA OPEN ACCESS JOURNAL

Article |  Open Access |  

Estimating utilization distributions from fitted step-selection functions

Johannes Signer , John Fieberg, Tal Avgar


First published: 11 April 2017 | <https://doi.org/10.1002/ecs2.1771> | Citations: 88

 **Methods in Ecology and Evolution**

APPLICATION |  Open Access |   

Simulating animal space use from fitted integrated Step-Selection Functions (iSSF)

J. Signer , J. Fieberg, B. Reineking, U. Schlägel, B. Smith, N. Balkenhol, T. Avgar

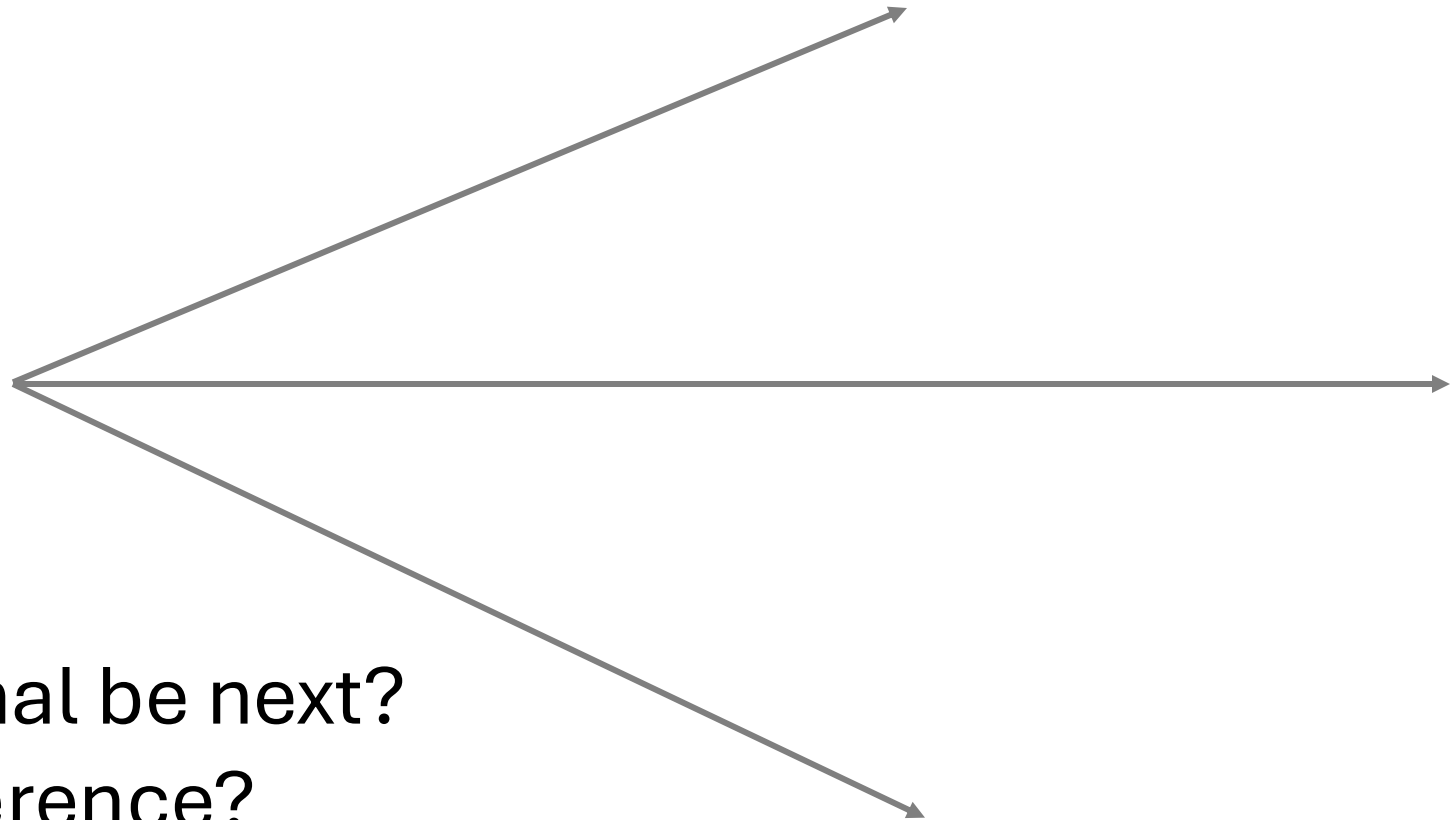
 **Journal of Animal Ecology**

RESEARCH METHODS GUIDE |  Open Access |  

How to scale up from animal movement decisions to spatiotemporal patterns: An approach via step selection

Jonathan R. Potts , Luca Börger

What is it all about?



Animal at time t

Where will the animal be next?

Does it have a preference?

Can it reach its preferred
position in space?

Animal at time $t + 1$

So, we have a fitted model

- Remember

What is the model, that we fitted:

What is the probability that the animal will be at position \mathbf{s} at the next time step $(t + \Delta t)$, given the animal is currently (t) at position \mathbf{s}' .

Movement free habitat selection function: where the animal would like to go.

Selection free movement kernel: where the animal is able to go (given constraints in movement).

$$p(\mathbf{s}, t + \Delta t | u(\mathbf{s}', t)) = \frac{w(\mathbf{X}(\mathbf{s}); \beta(\Delta t)) \phi(\theta(\mathbf{s}, \mathbf{s}'), \gamma(\Delta t))}{\underbrace{\int_{\tilde{\mathbf{s}} \in G} w(\mathbf{X}(\tilde{\mathbf{s}}); \beta(\Delta t)) \phi(\theta(\tilde{\mathbf{s}}, \mathbf{s}'), \gamma(\Delta t)) d\tilde{\mathbf{s}}}_{\text{Normalizing constant}}}$$

Let's reuse `m5` from before

- We model habitat selection for distance to forest and movement as a function of time of day.

$$(s, t + \Delta t) | u(s', t) = \frac{w(\mathbf{X}(s); \beta(\Delta t)) \phi(\theta(s, s'), \gamma(\Delta t))}{\underbrace{\int_{\tilde{s} \in G} w(\mathbf{X}(\tilde{s}); \beta(\Delta t)) \phi(\theta(\tilde{s}, s'); \gamma(\Delta t)) d\tilde{s}}_{\text{Normalizing constant}}}$$

Results of model 5

$$(\mathbf{s}, t + \Delta t) | u(\mathbf{s}', t) = \frac{w(\mathbf{X}(\mathbf{s}); \beta(\Delta t)) \phi(\theta(\mathbf{s}, \mathbf{s}'), \gamma(\Delta t))}{\underbrace{\int_{\tilde{\mathbf{s}} \in G} w(\mathbf{X}(\tilde{\mathbf{s}}); \beta(\Delta t)) \phi(\theta(\tilde{\mathbf{s}}, \mathbf{s}'); \gamma(\Delta t)) d\tilde{\mathbf{s}}}_{\text{Normalizing constant}}}$$

What next?

- We can use the output of model 5 to create a **redistribution kernel**.
- A redistribution kernel is the product of a **selection-free movement kernel** and a **movement-free habitat-selection function**.

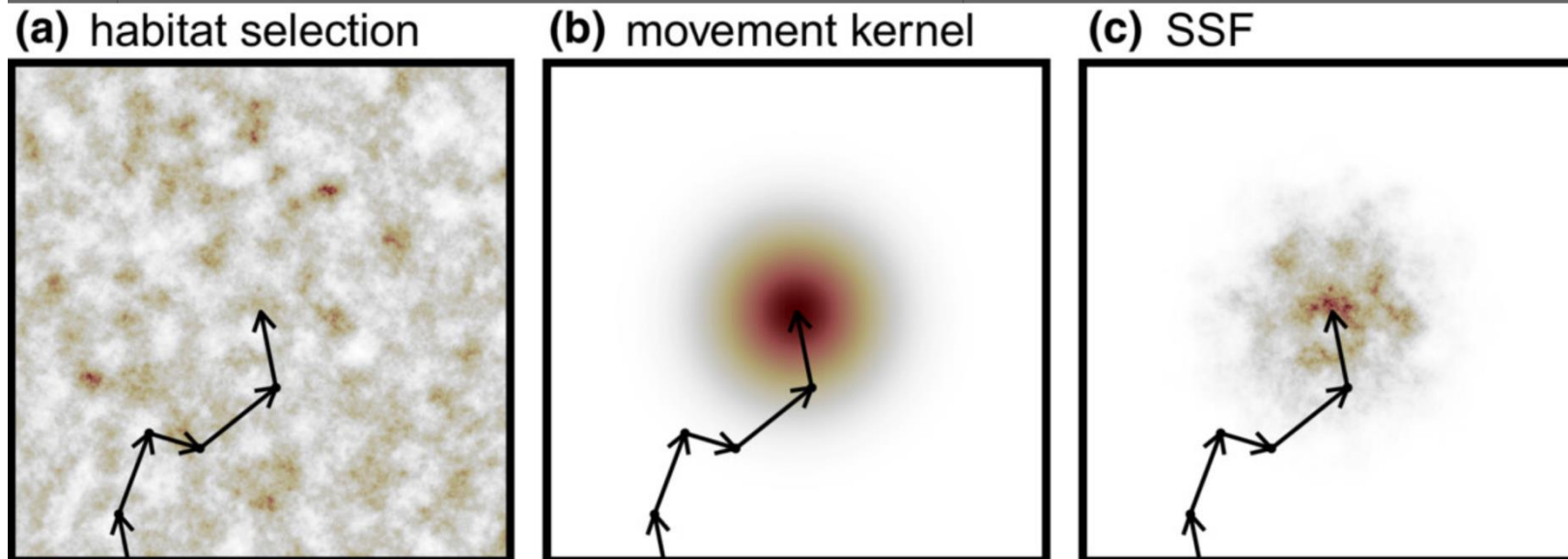
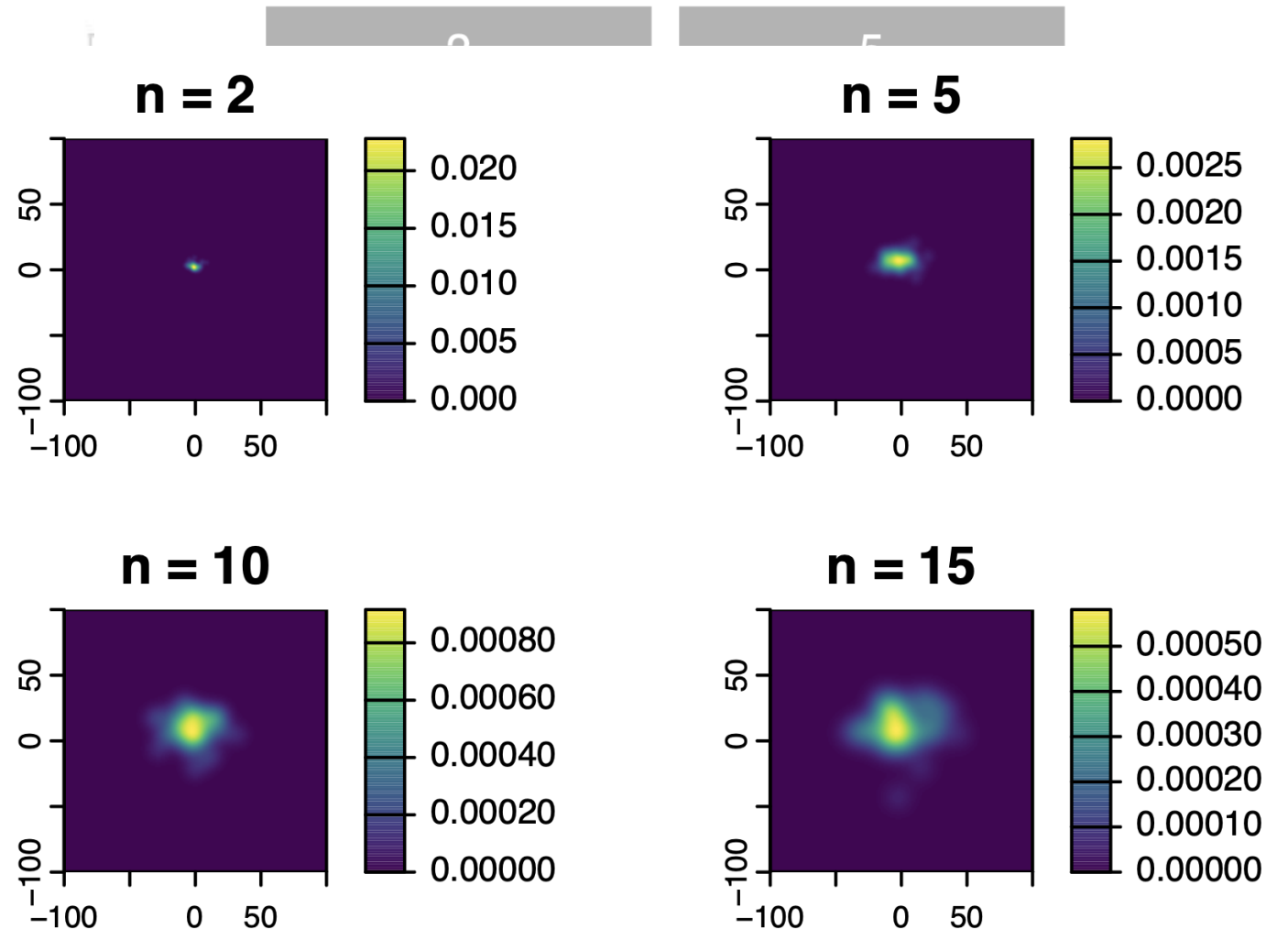


Image source: Michelot et al. 2024; MEE

What can we do with a redistribution kernel?

- Simulate an individual path by consecutively sampling from the redistribution kernel.
- Simulate space use on the long term (steady state utilization distribution [UD]) or short term space use (transient UD).



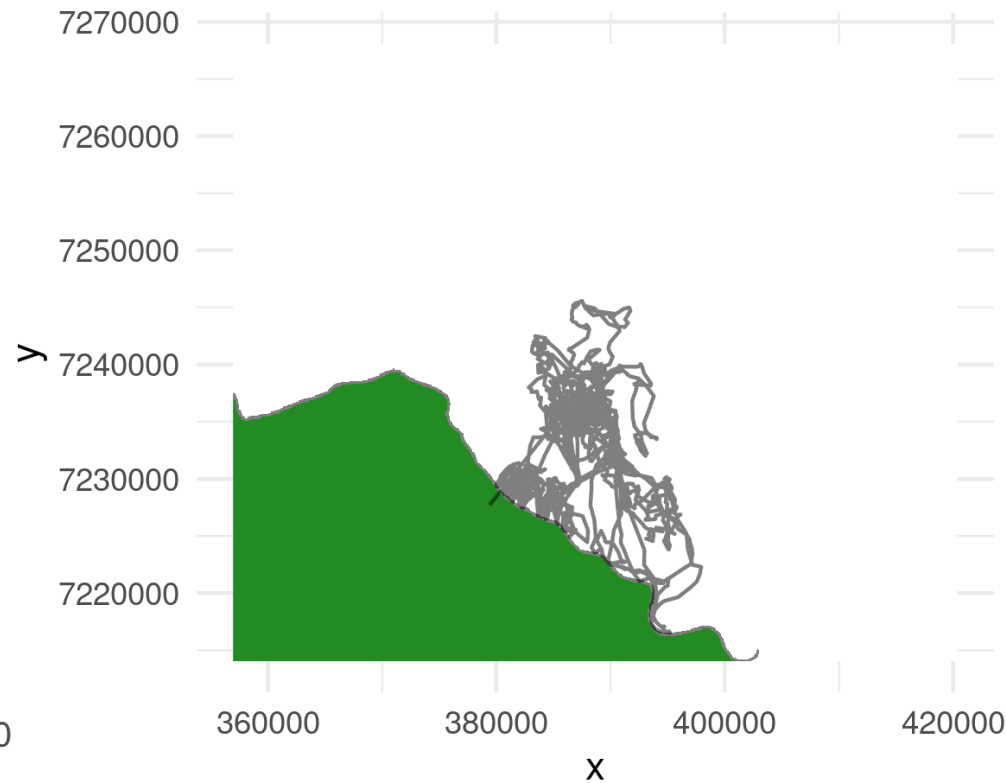
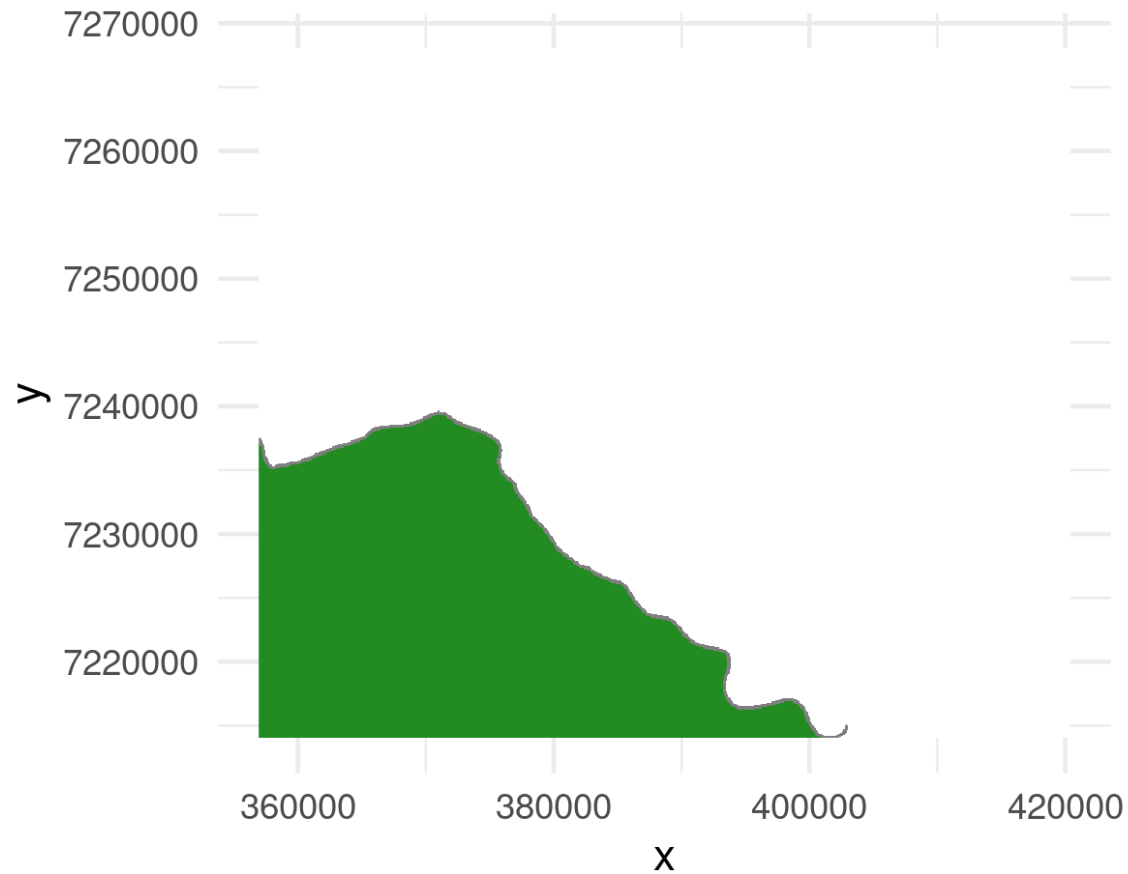
x_{-}

An example

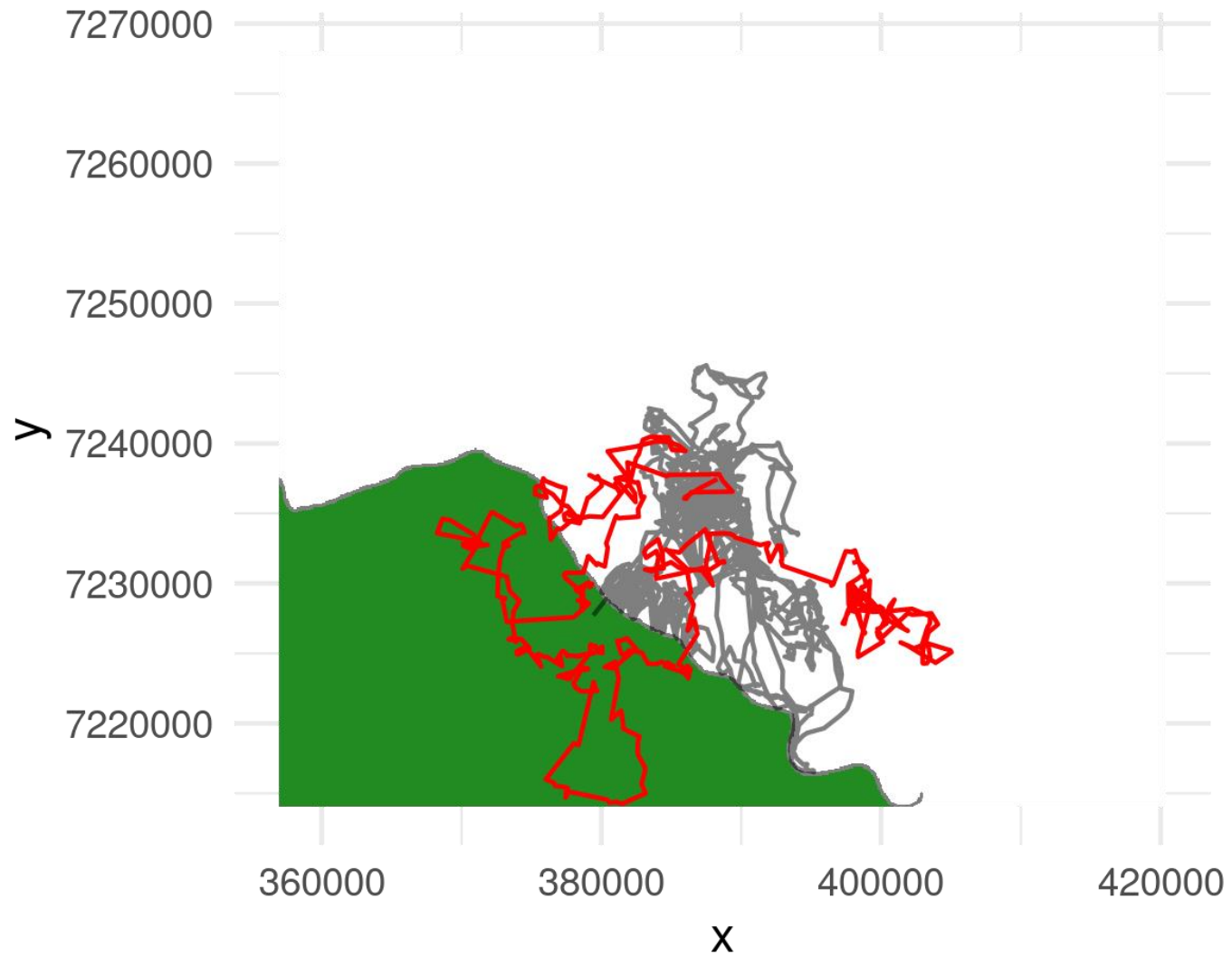
- Model movement of African buffalo. We fitted three models:

1. **Base model:** $\text{case_} \sim \cos(\text{ta_}) + \text{s1_} + \log(\text{s1_}) + \text{water_dist_end}$
2. **Home-range model:** $\text{case_} \sim \cos(\text{ta_}) + \text{s1_} + \log(\text{s1_}) + \text{water_dist_end} + \text{x2_} + \text{y2_} + \text{I}(\text{x2_}^2 + \text{y2_}^2)$
3. **River model:** $\text{case_} \sim \cos(\text{ta_}) + \text{s1_} + \log(\text{s1_}) + \text{water_dist_end} + \text{x2_} + \text{y2_} + \text{I}(\text{x2_}^2 + \text{y2_}^2) + \text{I}(\text{water_crossed_end} \neq \text{water_crossed_start})$

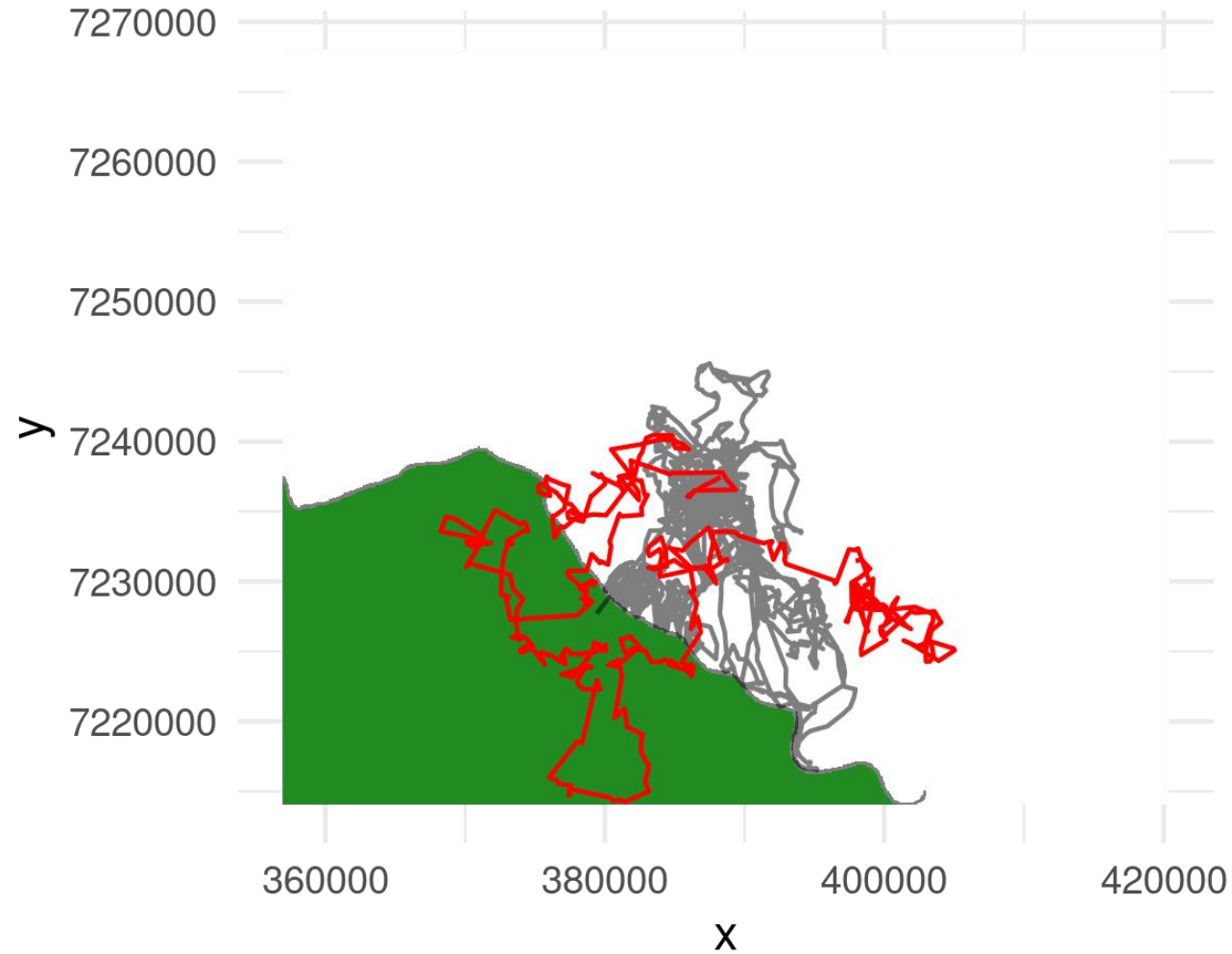
The observed data



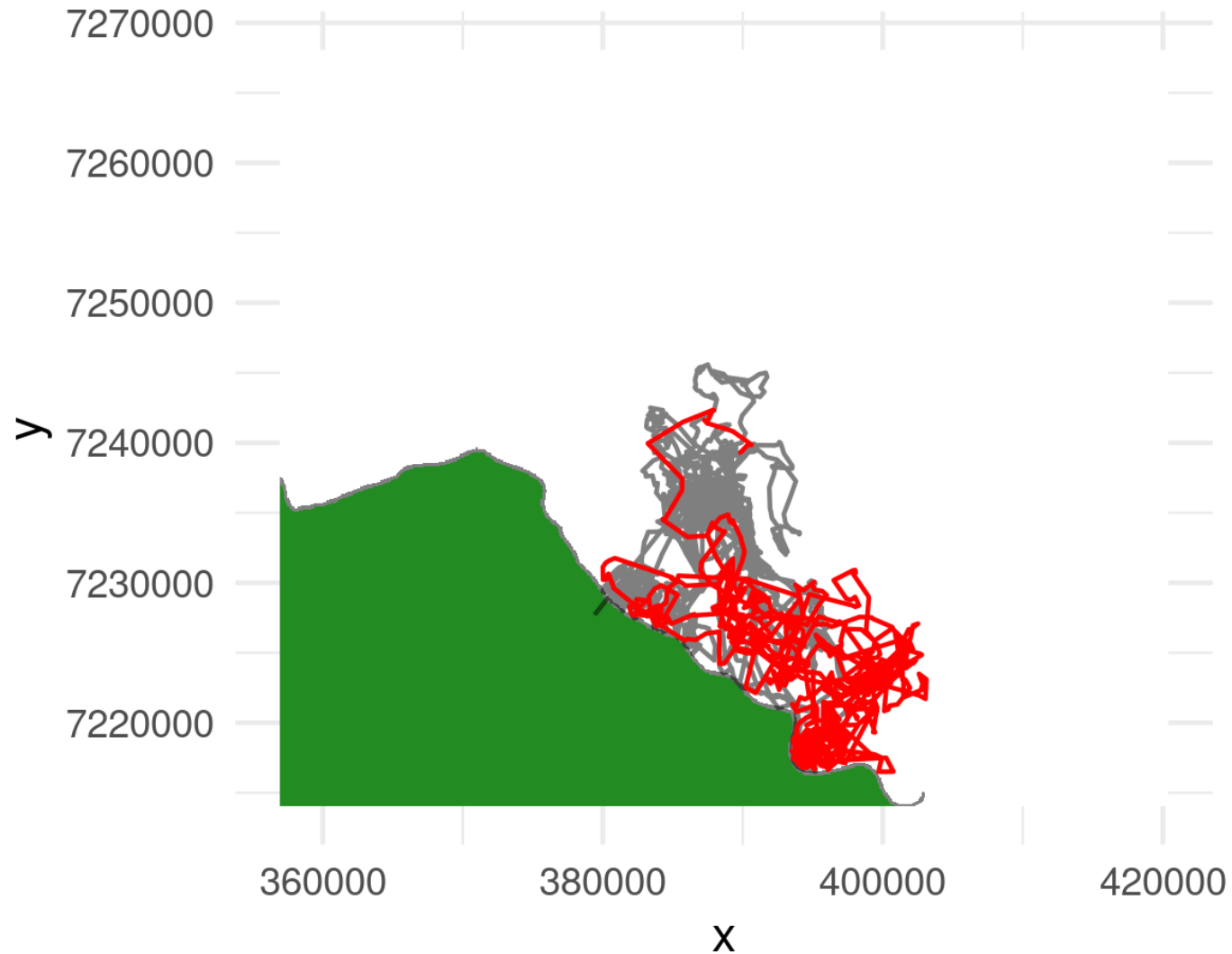
Model 1: Naïve model



Model 2: With home ranging



Model 3: With river crossing



Practical